



Scalar Algorithms: Colour Mapping

Visualisation – Lecture 6

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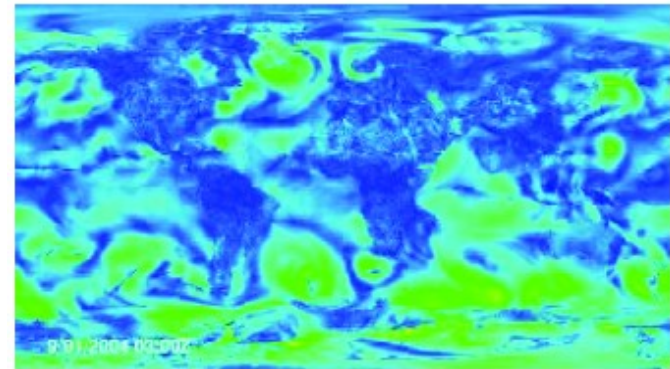
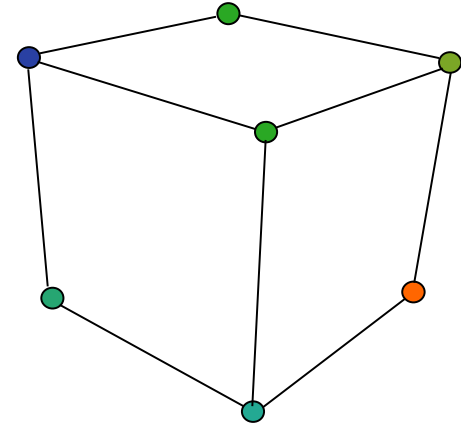
Institute for Perception, Action & Behaviour
School of Informatics





From last lecture

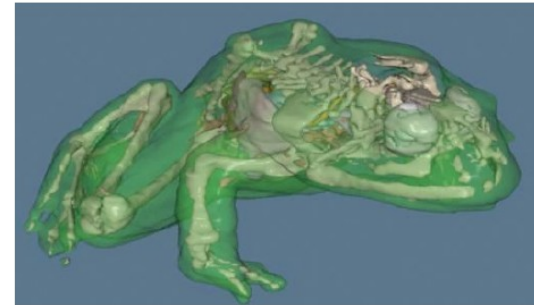
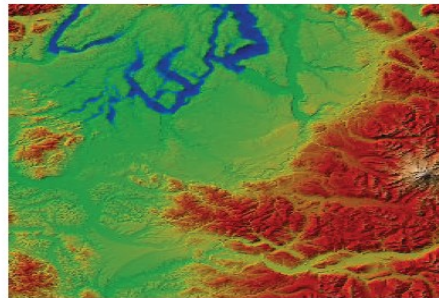
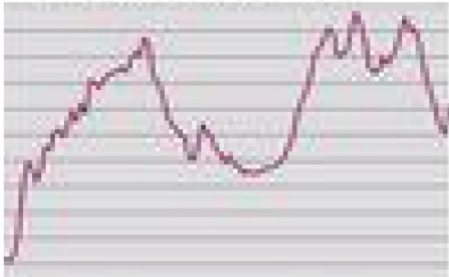
- Data representation
 - structure + **value**
 - structure = topology & geometry
 - value = attribute
- Attribute Classification
 - **scalar** (today)
 - vector
 - tensor





Scalar Algorithms

- **Scalar data : single value** at each location
- Structure of data set may be 1D, 2D or 3D+



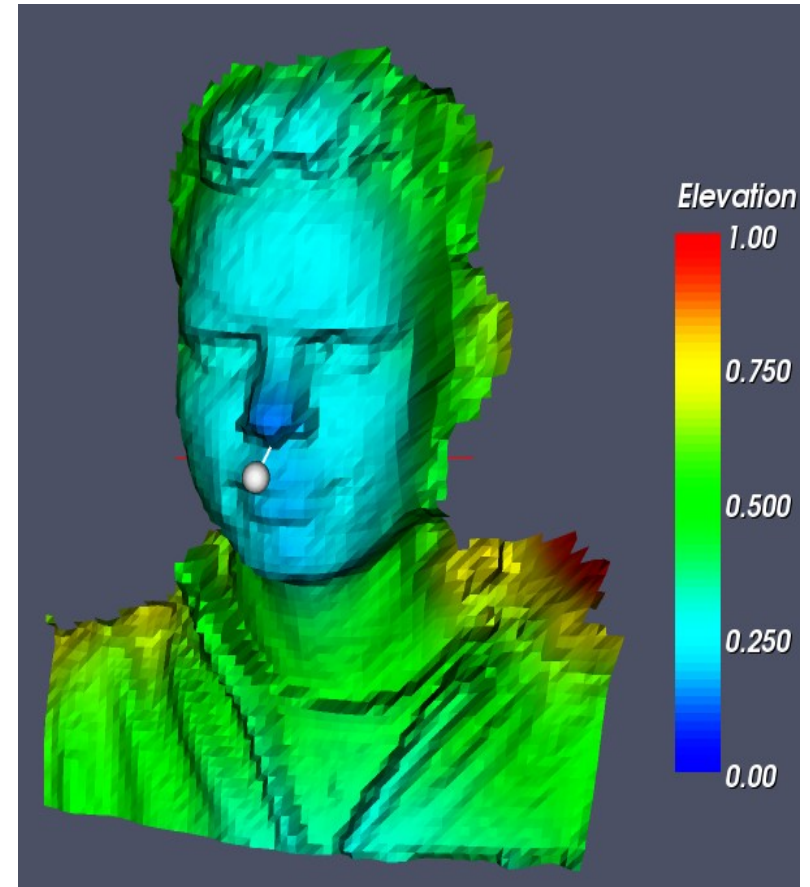
- we want to visualise the **scaler within this structure**
- Two fundamental algorithms
 - colour mapping (**transformation** : value \rightarrow colour)
 - contouring (**transformation** : value transition \rightarrow contour)





Colour Mapping

- Map **scalar value to colour range** for display
 - e.g.
 - scalar value = height / max elevation
 - colour range = blue → red
- **Colour Look-up Tables (LUT)**
 - provide scalar to colour conversion
 - scalar values = indices into LUT





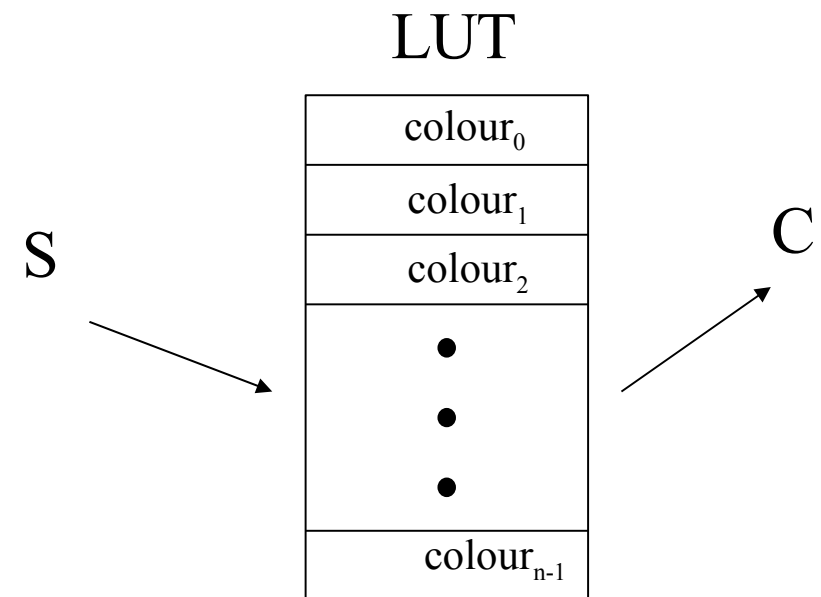
Colour LUT

- **Assume**

- scalar values S_i in range $\{\text{min} \rightarrow \text{max}\}$
- n unique colours, $\{\text{colour}_0 \dots \text{colour}_{n-1}\}$ in LUT

- **Define mapped colour C :**

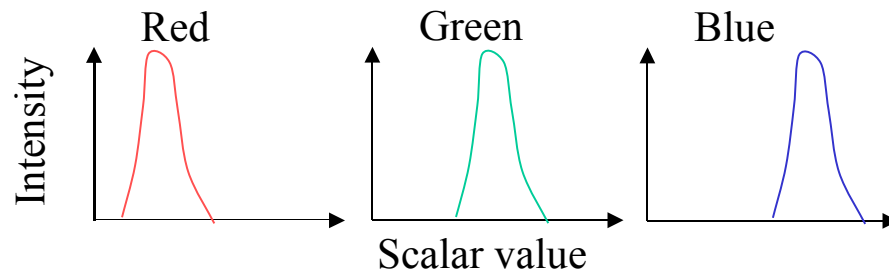
- if $S < \text{min}$ then $C = \text{colour}_{\text{min}}$
- if $S > \text{max}$ then $C = \text{colour}_{\text{max}}$
- else
- For ($j = 0; j < n ; j++$)
 - if ($C_j \text{ min} < S < C_j \text{ max}$) $C = C_j$



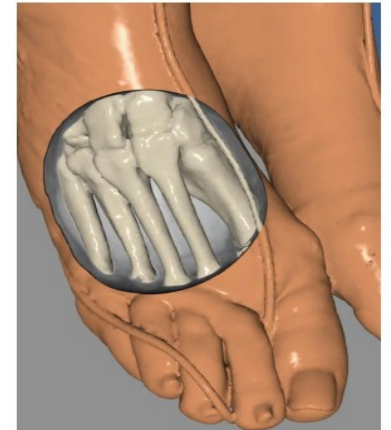


Colour Transfer Function

- More general form of colour LUT
 - scalar value S ; colour value C
 - **colour transfer function** : $f(S) = C$
 - Any functional expression can map scalar value into intensity values for colour components



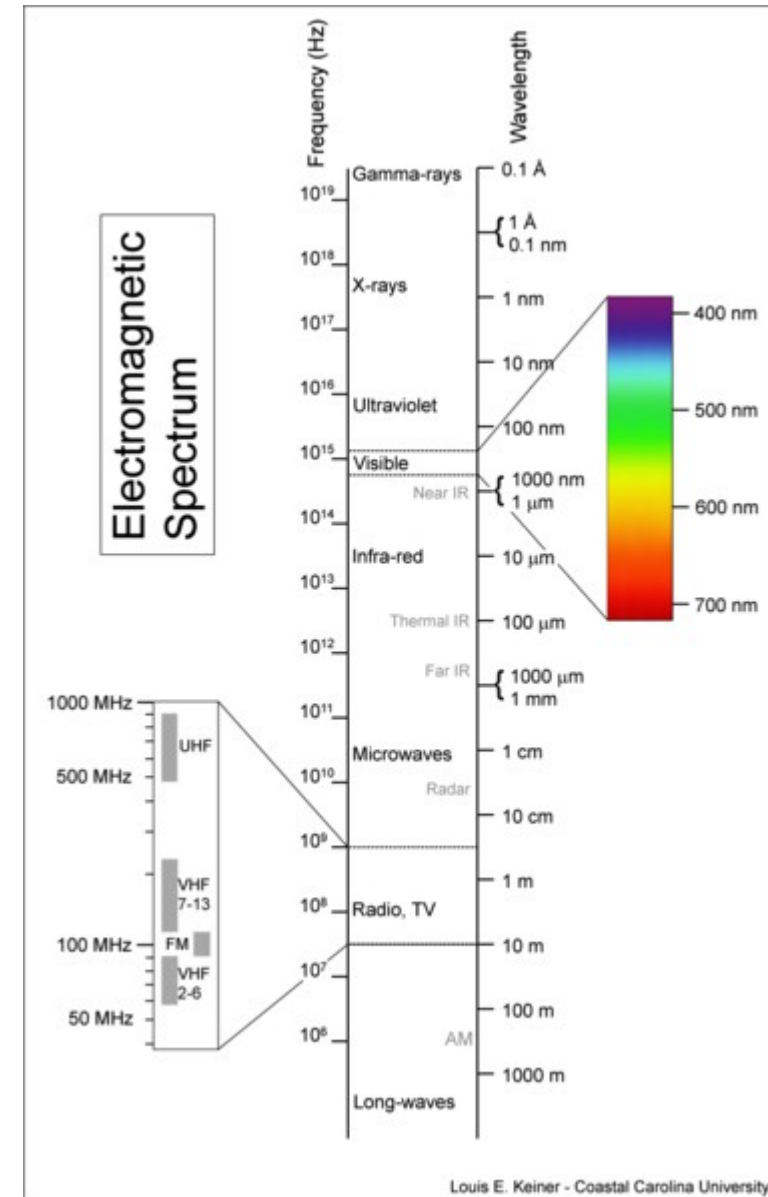
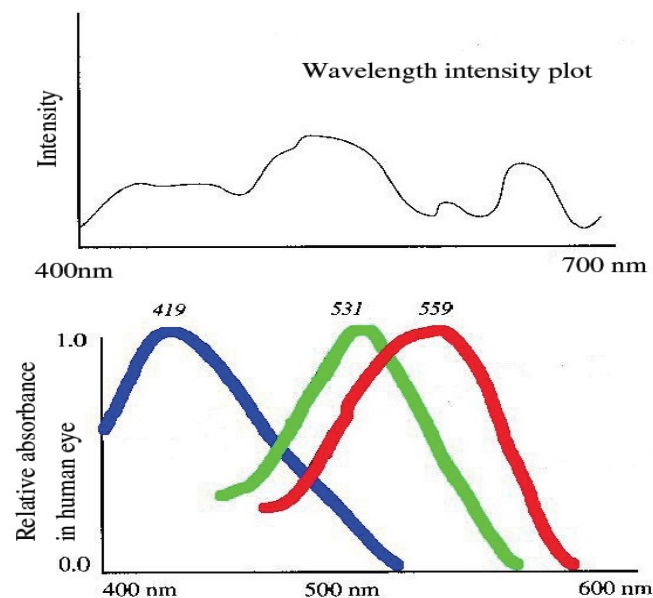
- e.g. define $f()$ to convert densities to realistic skin/bone/tissue colours





Colour Components

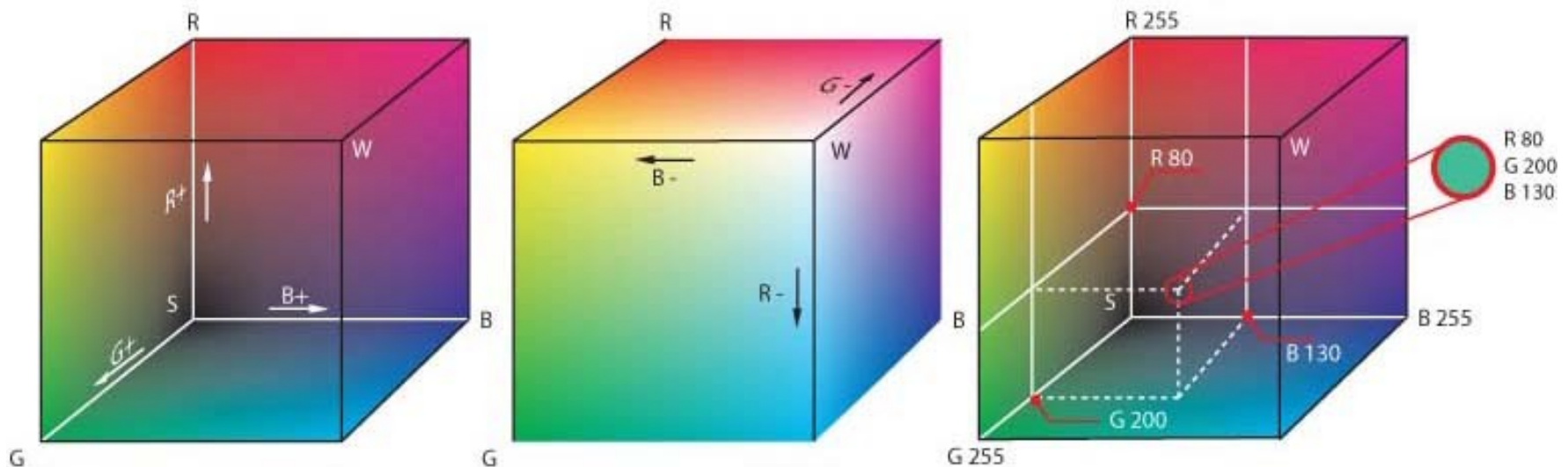
- **Electromagnetic (EM) spectrum** visible to humans
 - continuous range 400-700nm
 - 3 type of receptors (cones) in eye for R, G, B.
- So we can use the **RGB model in CG** for visualization





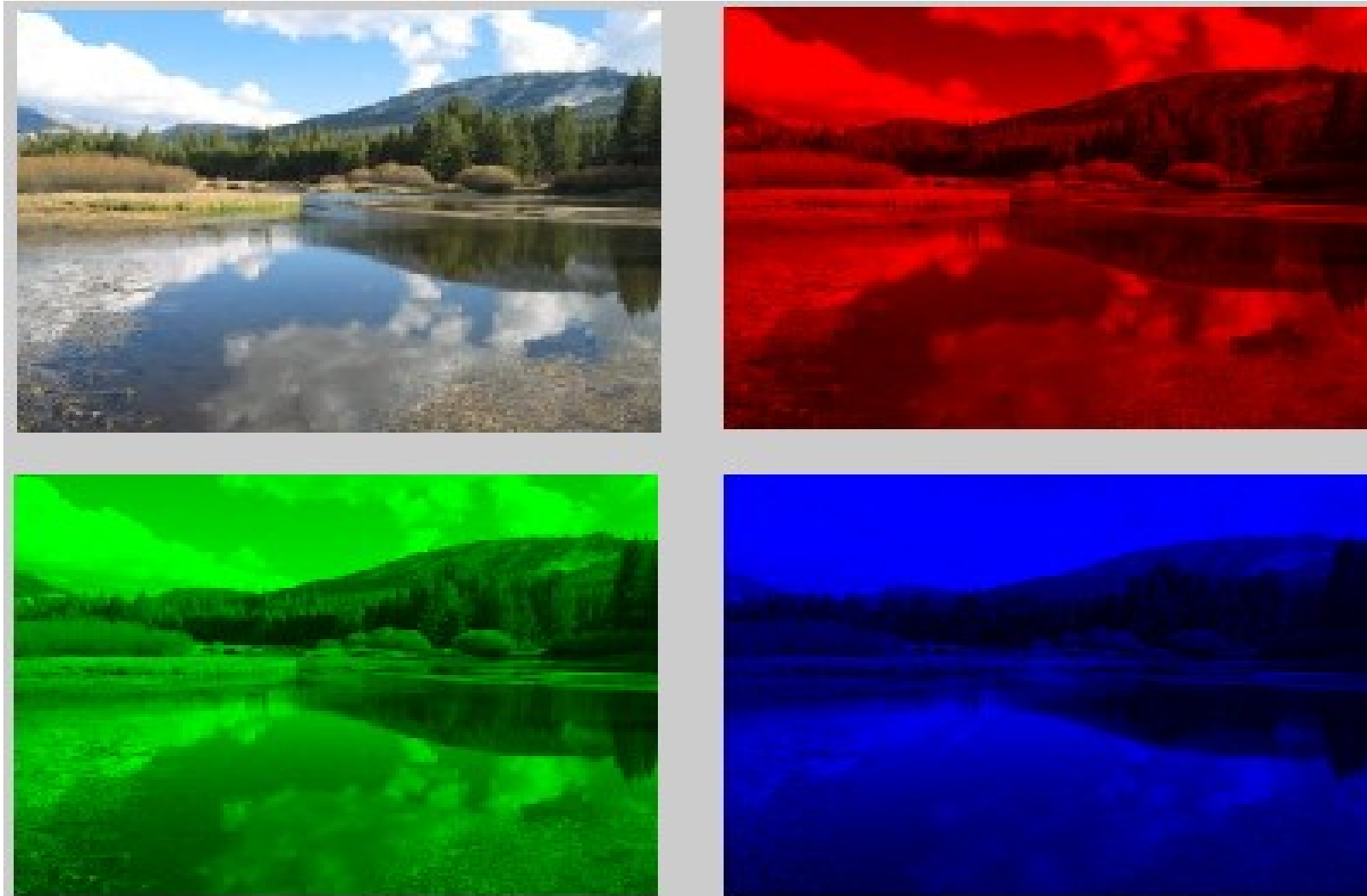
Colour Spaces - RGB

- Colours represented as R,G,B intensities
 - **3D colour space** (cube) with axes R, G and B
 - each axis $0 \rightarrow 1$ (below scaled to 0-255 for 1 byte per colour channel)
 - Black = (0,0,0) (origin); White = (1,1,1) (opposite corner)





Example : RGB image



RGB Channel Separation





Colour Spaces - Greyscale

- **Linear combination of R, G, B**

- $\text{Greyscale} = (R + G + B) / 3$



- **Defined as linear range**

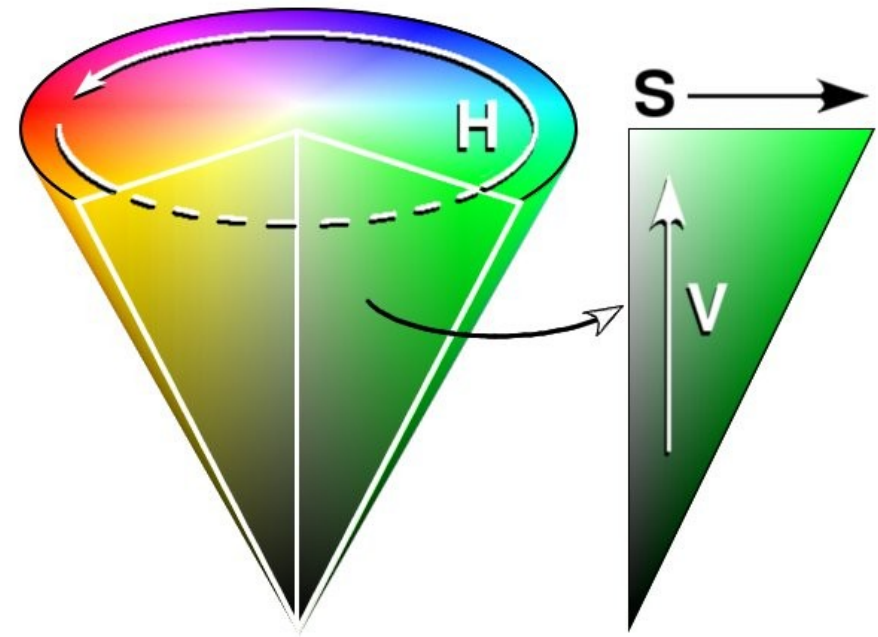
- easy to map linear scalar range to grayscale intensity
 - can **enhance structural detail in visualisation**
 - The shading effect is emphasized
 - as distraction of colour is removed
 - **not really using full graphics capability**
 - **lose colour associations** : e.g. red=bad/hot, green=safe, blue=cold





HSV

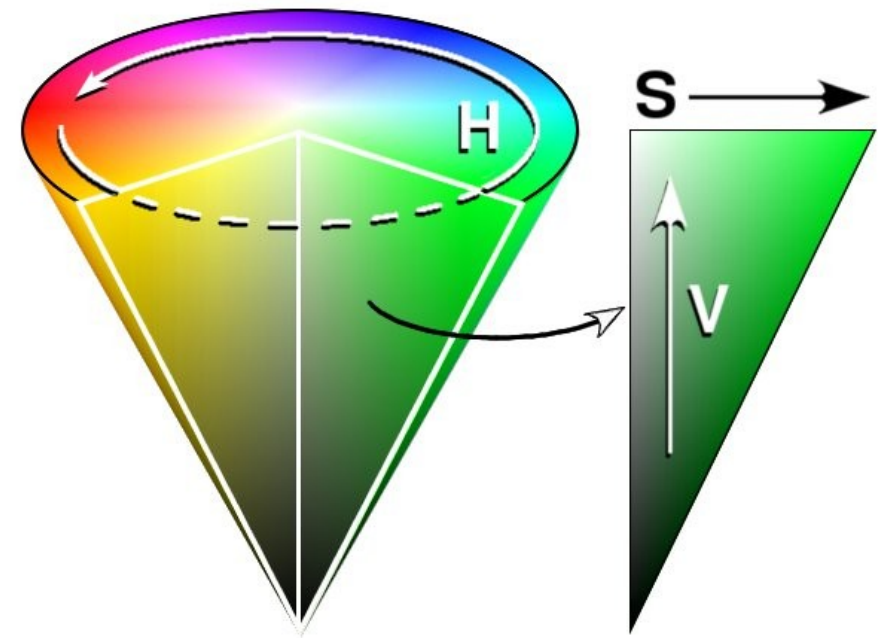
- HSV encapsulates information about a color in terms that are more familiar to humans:
 - *What color is it?*
 - *How vibrant is it?*
 - *How light or dark is*





Colour spaces - HSV

- **Colour represented in H,S,V parametrised space**
 - commonly modelled as a cone
- **H (Hue)** = dominant wavelength of colour
 - **colour type** {e.g. red, blue, green...}
- **S (Saturation)** = amount of Hue present
 - “vibrancy” or **purity of colour**
- **V (Value)** = brightness of colour
 - **brightness** of the colour

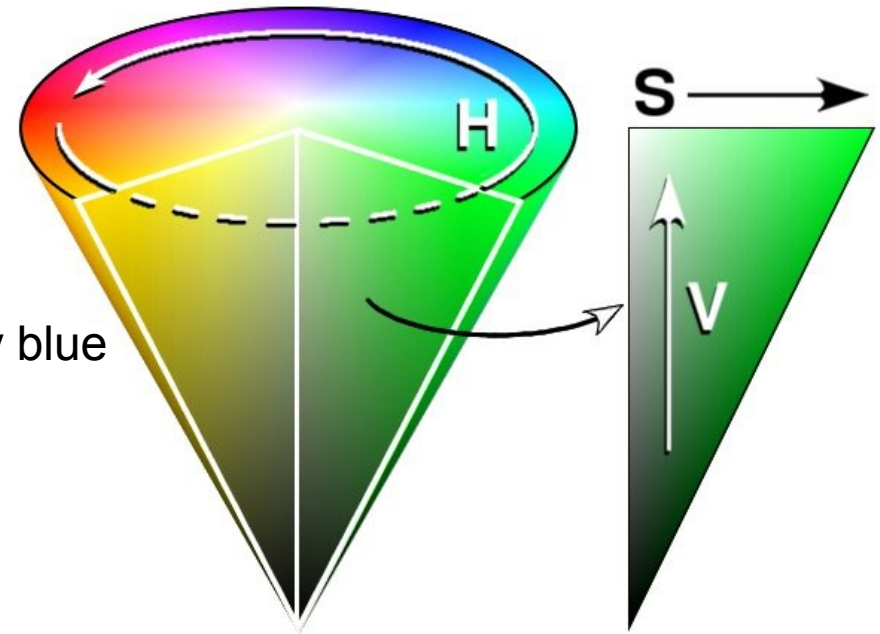




Colour spaces - HSV

- **HSV Component Ranges**

- **Hue** = $0 \rightarrow 360^\circ$
- **Saturation** = $0 \rightarrow 1$
 - e.g. for Hue \approx blue
0.5 = sky colour; 1.0 = primary blue
- **Value** = $0 \rightarrow 1$ (amount of light)
 - e.g. 0 = black, 1 = bright



- **All can be scaled to $0 \rightarrow 100\%$ (i.e. min \rightarrow max)**
 - use hue range for colour gradients
 - **very useful for scalar visualisation with colour maps**

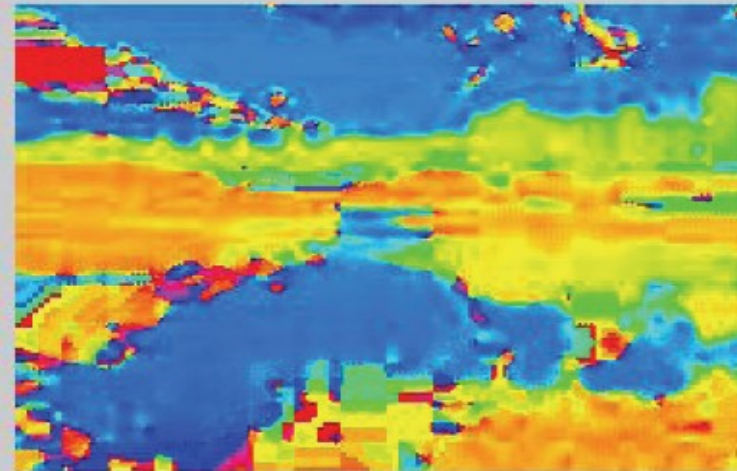




Example : HSV image components



RGB Camera Image



Hue (Saturation = 1.0, Variance = 1.0)



Saturation (as greyscale intensity)



Variance (as greyscale intensity)





Different Colour LUT

- Visualising gas density in a combustion chamber

- **Scalar** = gas density
- **Colour Map** =

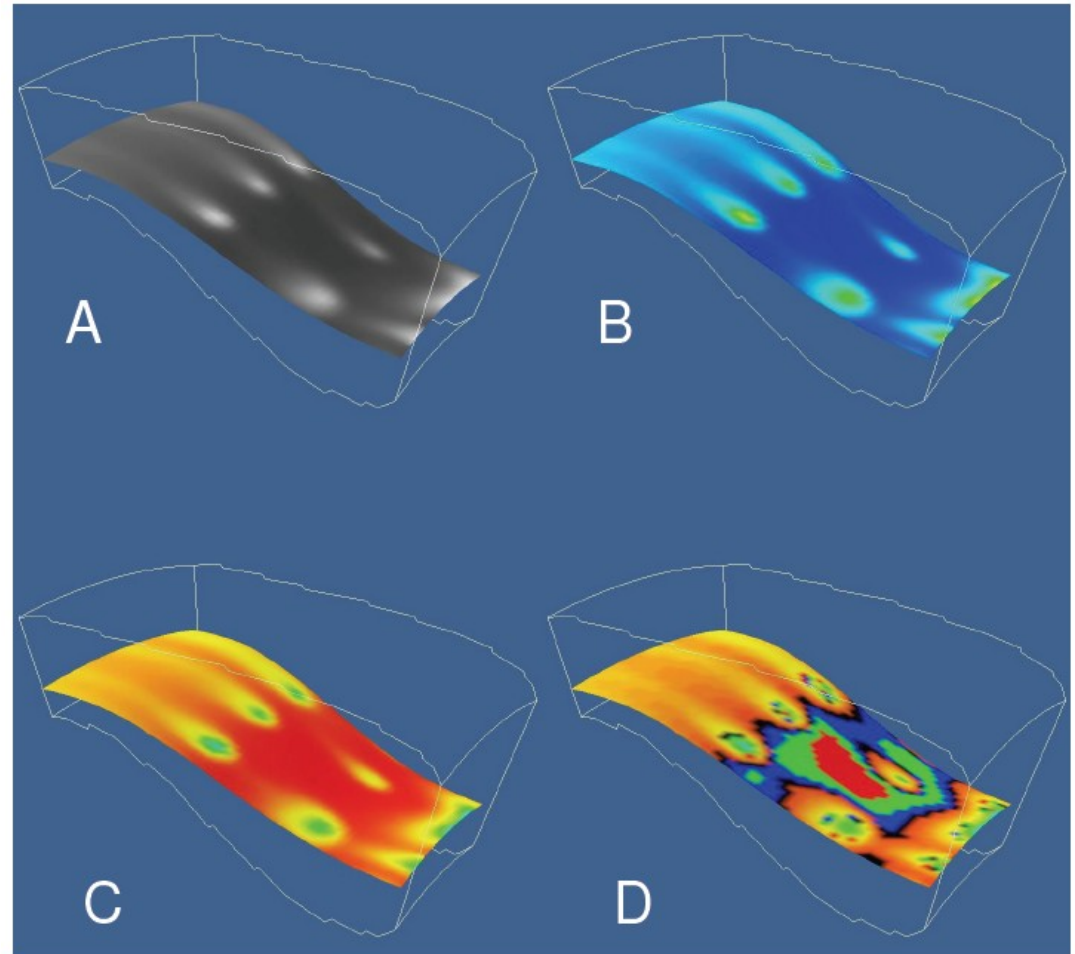
A: grayscale

B: hue range blue to red

C: hue range red to blue

D: specifically designed transfer function

- *highlights contrast*





Colour Table Design

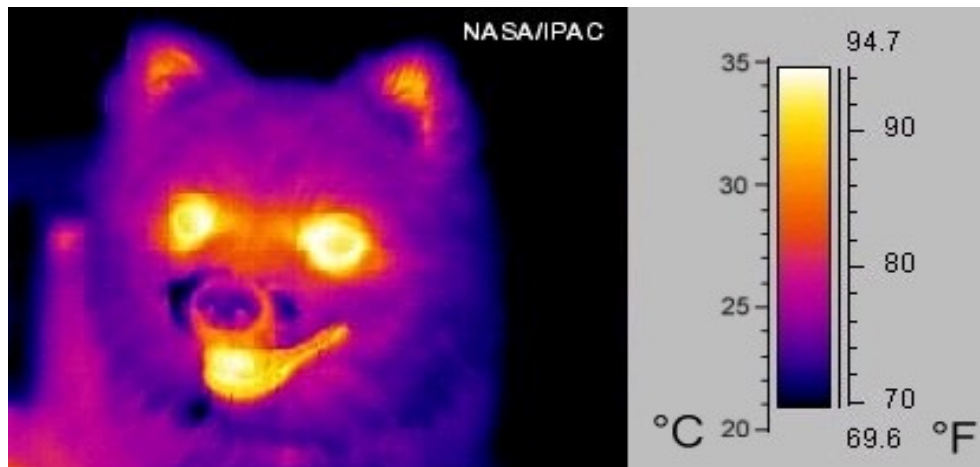
- Key focus of colour table design
 - **emphasize important features / distinctions**
 - **minimise extraneous detail**
- Often task specific
 - consider application (e.g. temperature change, use hue red to blue)
 - consider viewer (**colour associations**, colour blindness, lighting environment)
 - ***Rainbow colour maps*** – rapid change in colour hue representing a ‘rainbow’ of colours.
shows small gradients well as colours change quickly.





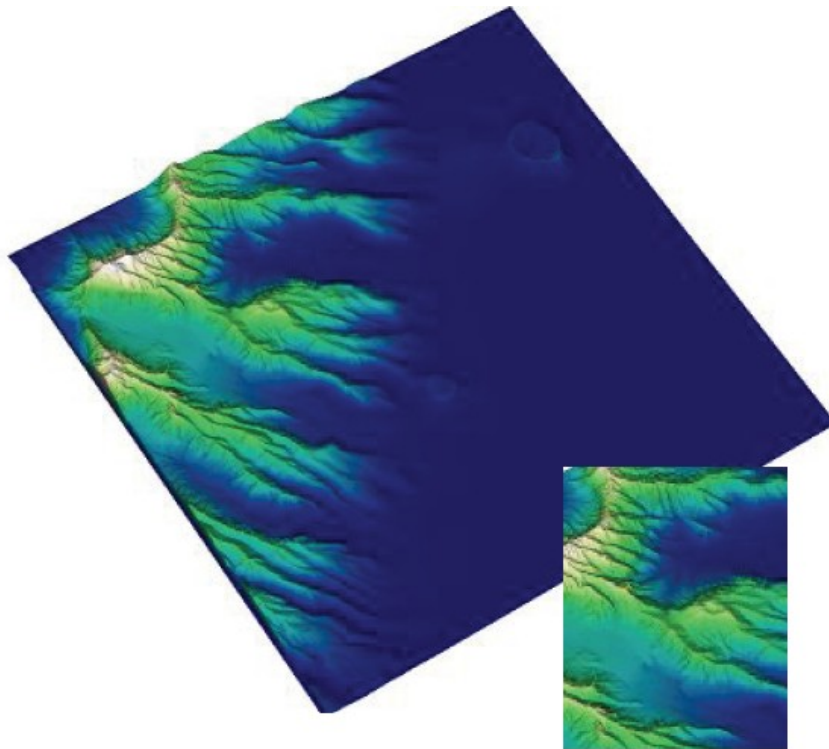
Examples – 2D colour images

- Infra-red intensity viewed as Hue
 - received from sensor as 2D array of infra-red readings
 - visualise as colour image using colour mapping



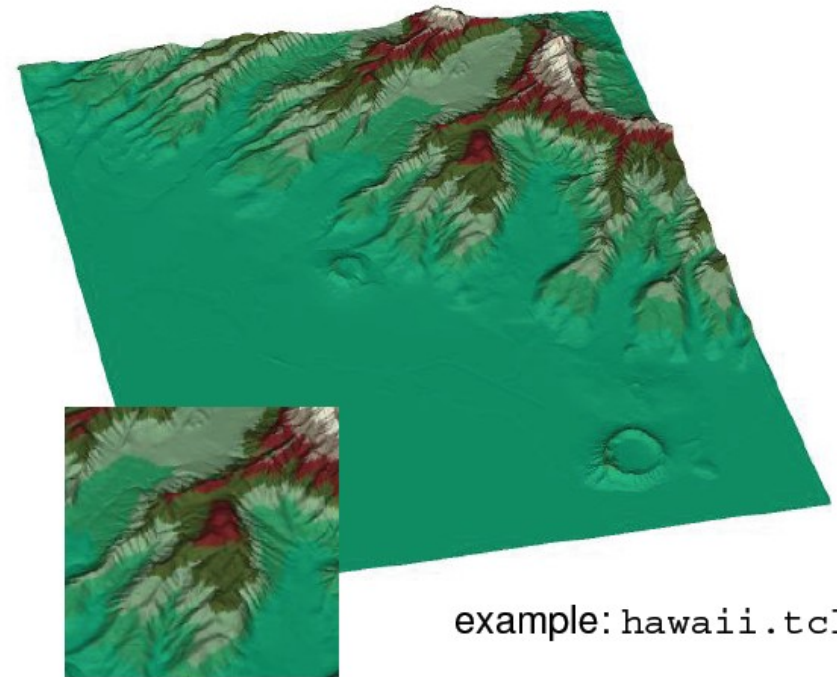


Examples – 3D Height Data



HSV based colour transfer function

- continuous transition of height represented



example: hawaii.tcl

8 colour limited lookup table

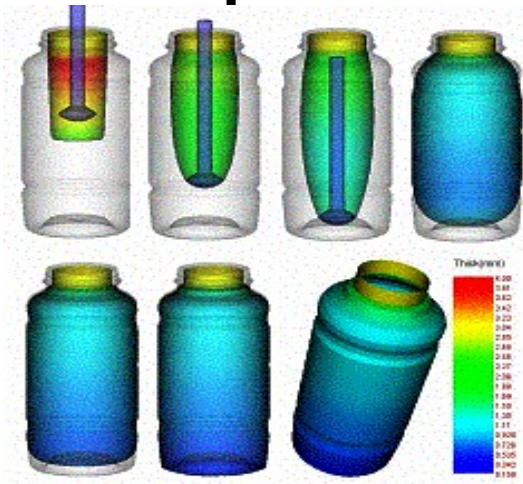
- discrete height transitions
- **rainbow type effect**





Colour Mapping

- Linear or 1D mapping process
- Use to map colour onto surfaces, images, volumes (>1D)



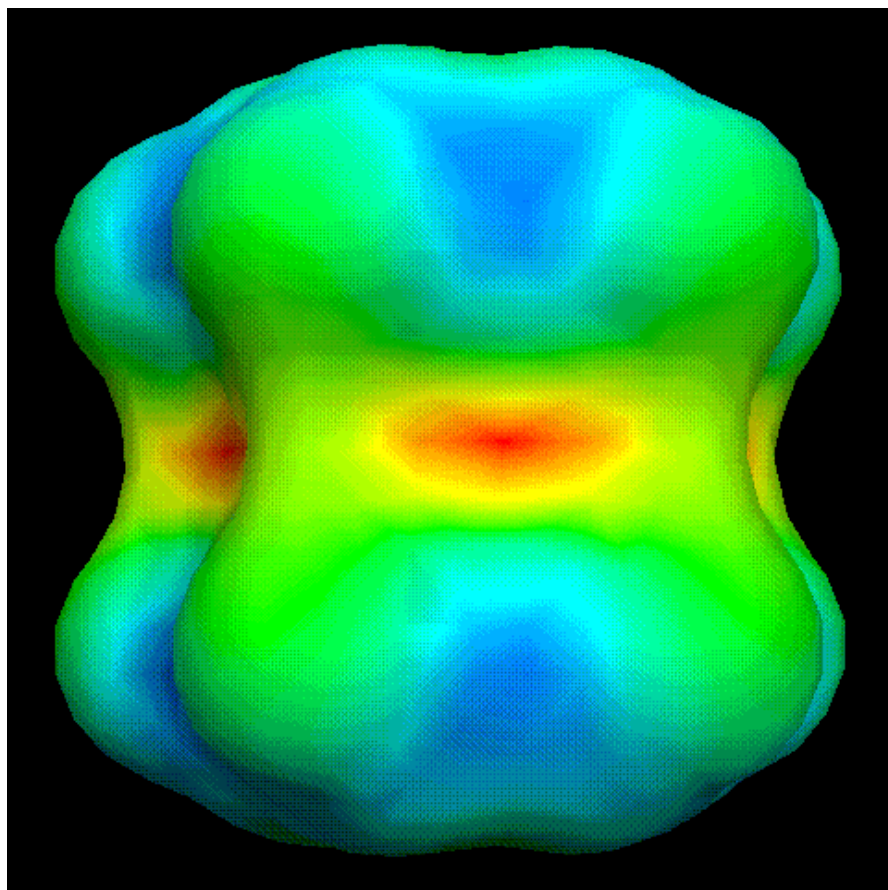
Visualisation of a blow-moulding process.
Colour indicates wall thickness.

- Theoretically 3 channels of information are available:
 - H, S and V
 - But V (brightness) frequently used for shading, important for visualising 3D shape. Normally H and S only used.



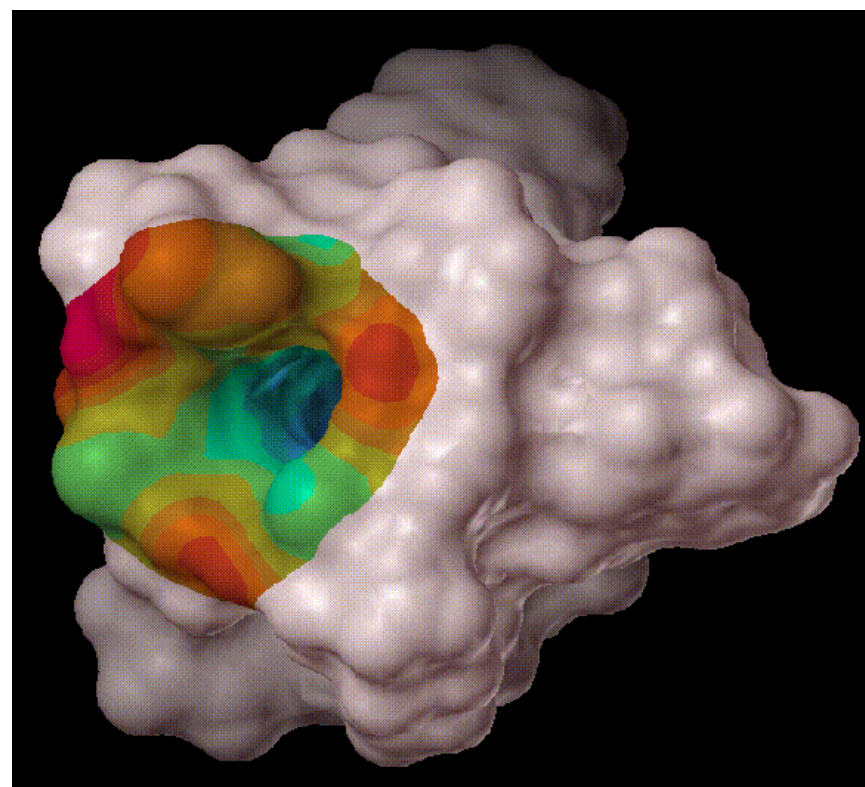


Molecular visualisations



Two variables visualised relating to electric properties

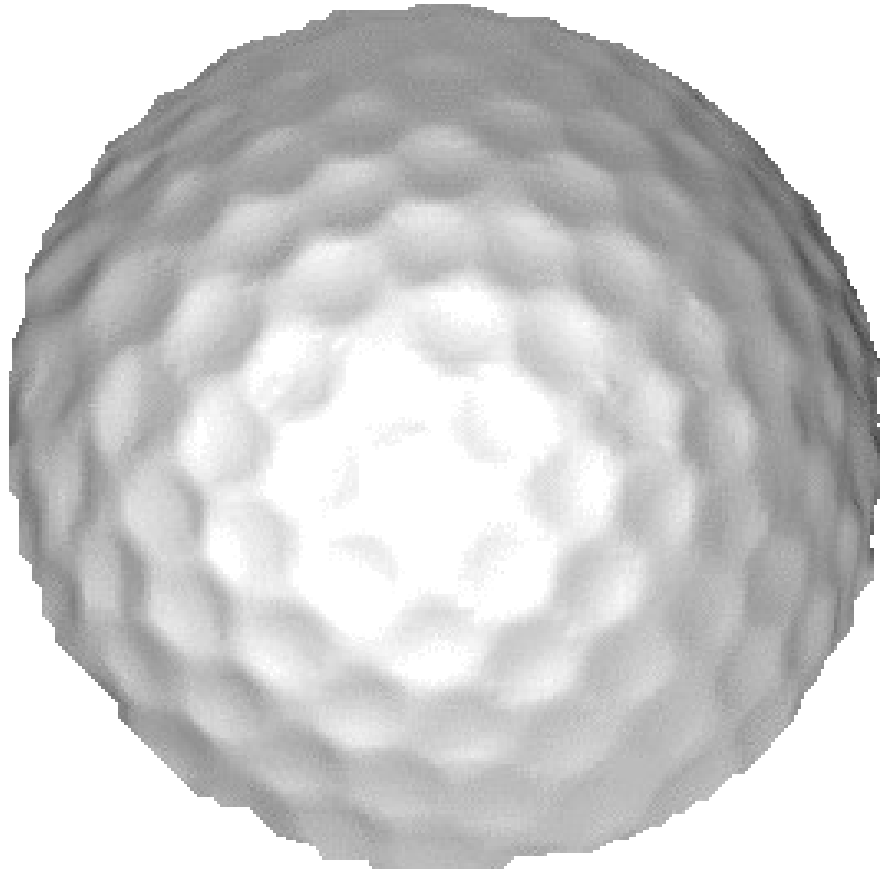
- mapped to **Hue and Saturation**





Example : Colour Transfer Function

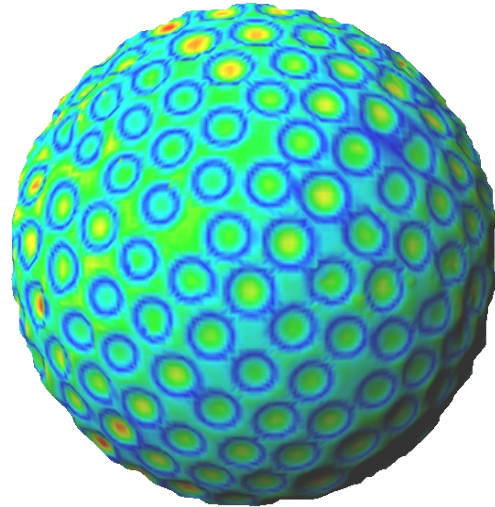
- **Question :** Are the dimples on this golfball evenly distributed?





Example : Colour Transfer Function

- **Answer** : No. *Why* ? Improves flight characteristics.



- **Visualisation technique** : colour map each point based on distance (scalar) from regular sphere





VTK : Colour Mapping

- To create a new LUT object with a name lut:

```
vtkLookupTable lut
```

- To set the colour range in the HSV colourspace:

```
lut SetHueRange start finish
```

```
lut SetSaturationRange start finish
```

```
lut SetValueRange start finish
```

– range = [0,1]

- Also define specific N colour lookup table

see `hawaii.tcl` example





Summary

- Introduction to **scalar data**
- **Colour maps**
 - colour **LUT**
 - **colour transfer functions**
 - **RGB** and **HSV** colour spaces
 - design issues
- VTK : colour maps & blood flow example

