



Visualisation : Course Review

Visualisation – Lecture 18

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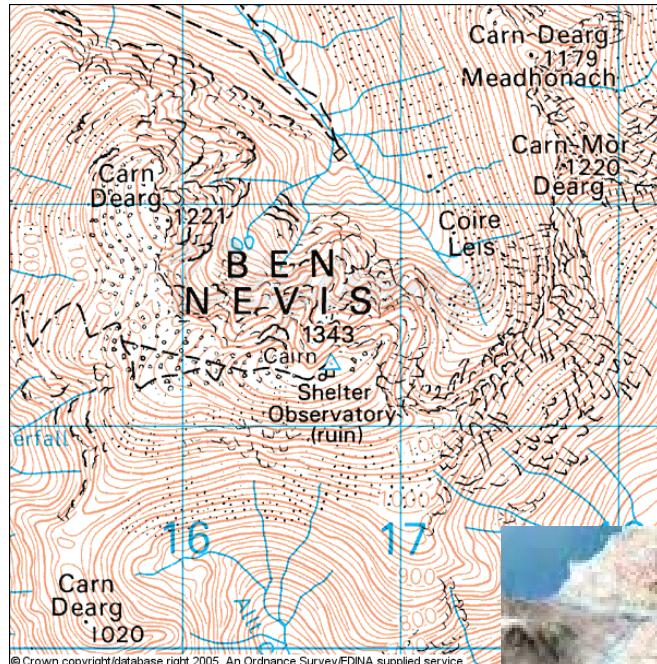
The Science of Visualisation

- Conversion of numbers → images
 - people are :
 - poor at raw numerical data analysis
 - good at robust analysis of visual stimuli
 - *convert numerical analysis into visual analysis*

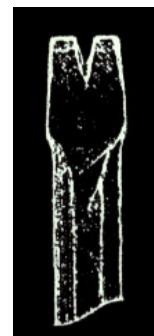
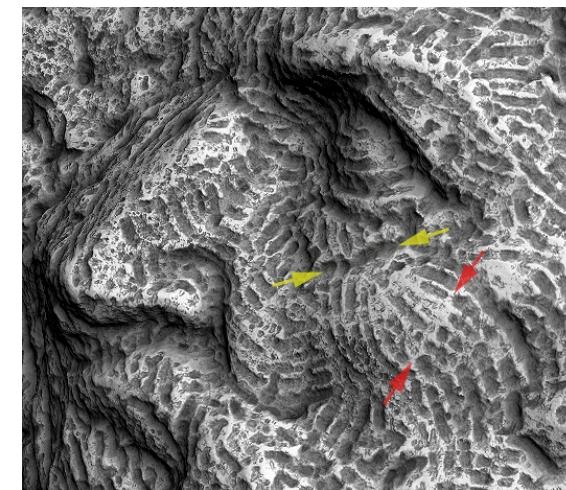
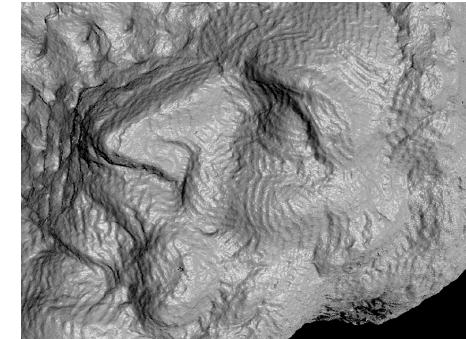
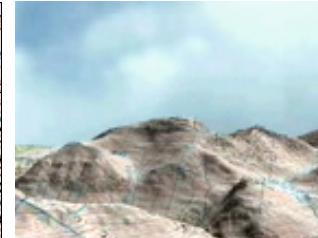
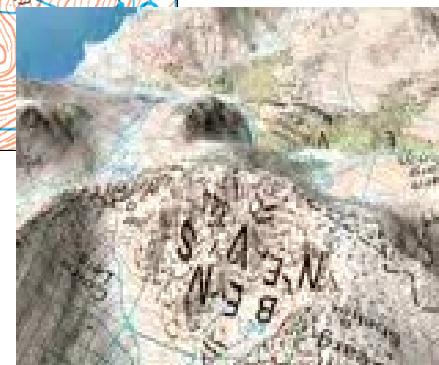




Why do we need visualisation?



Ben Nevis Fly Through:
<http://www.ordnancesurvey.co.uk>



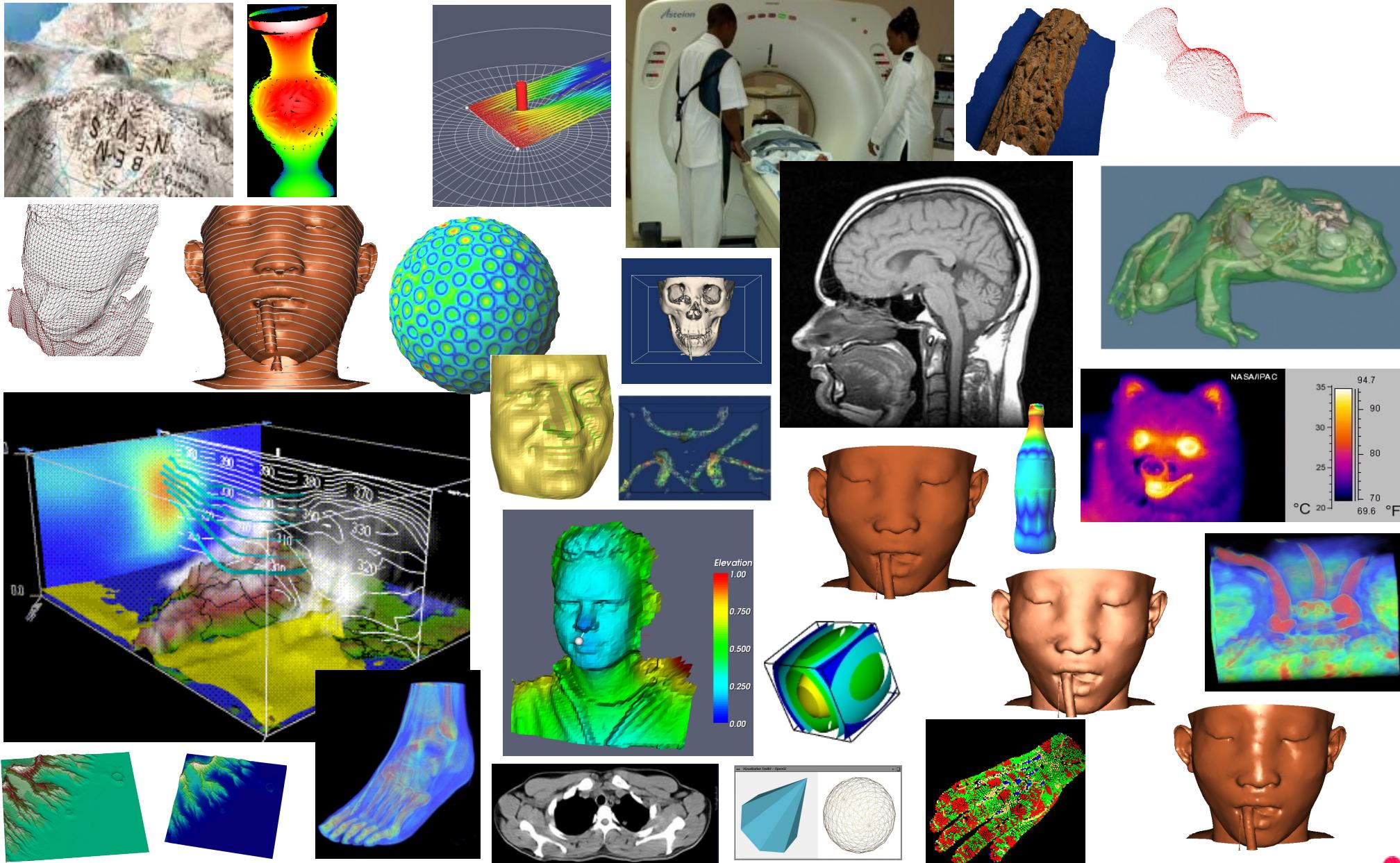
Stanford's Digital Michaelangelo Project <http://graphics.stanford.edu/projects/mich/>

- The extraction of *knowledge* from numbers
- Graphically exploring numbers in order to gain understanding and new knowledge - *interaction*





Visualisation Problems





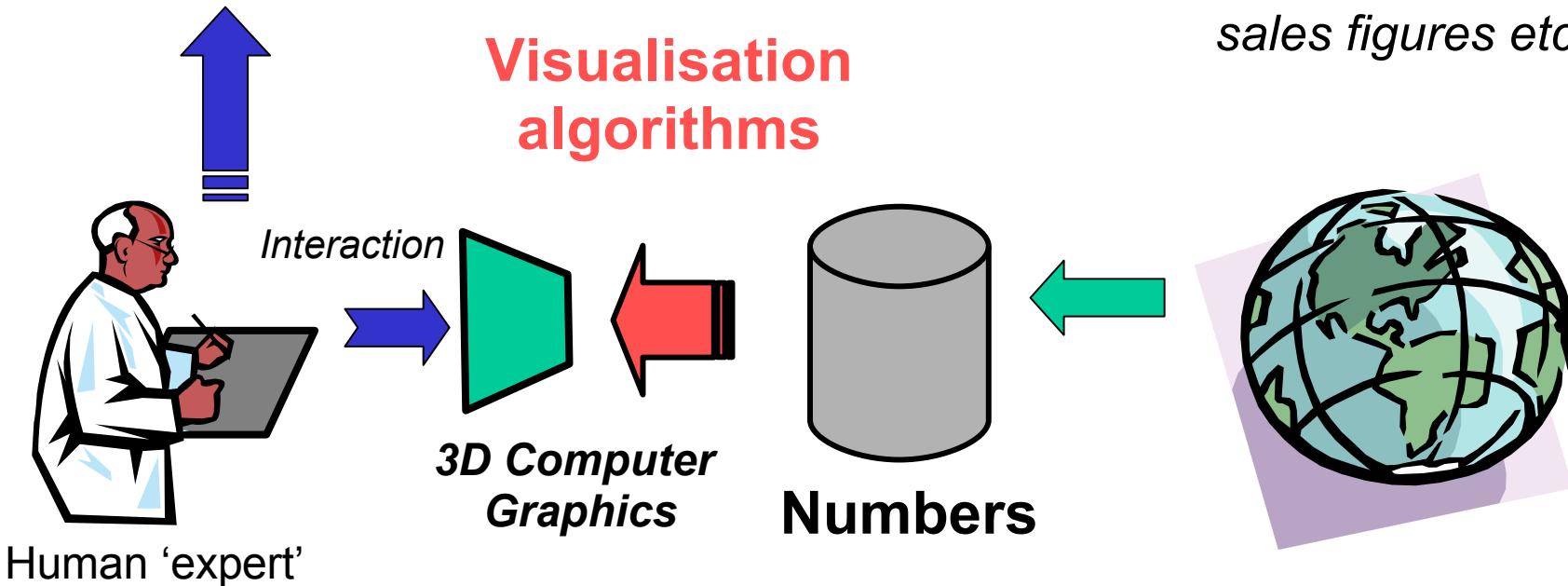
The visualisation process

- the effective presentation of knowledge



Knowledge

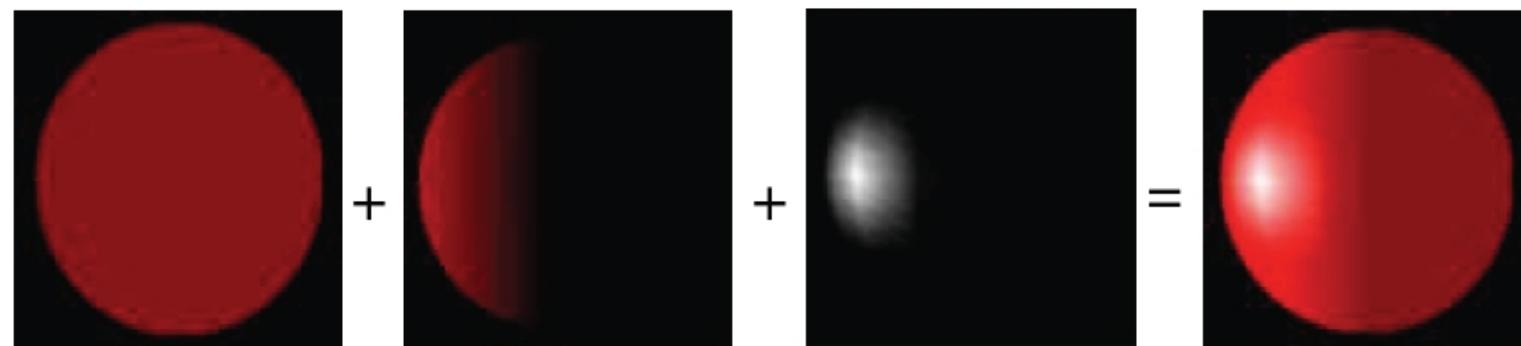
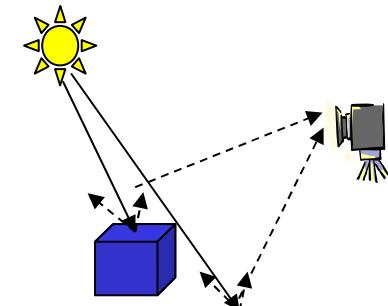
(Scientific papers, business strategy,
a medical diagnosis etc).





3D Computer Graphics

- our **primary tool** in computer based visualisation
- object **representation** : polygon surface meshes
- object **illumination** : ambient, diffuse, specular
- **camera model** : world to display transformation



Ambient
(colour)

Diffuse
(directional)

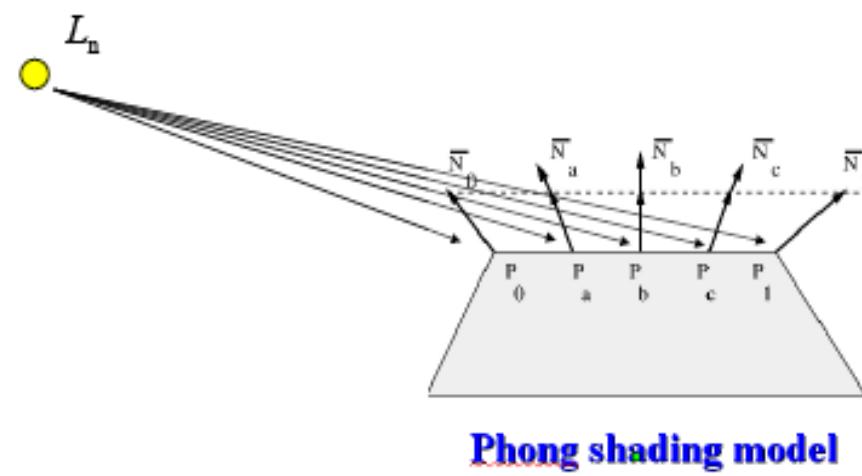
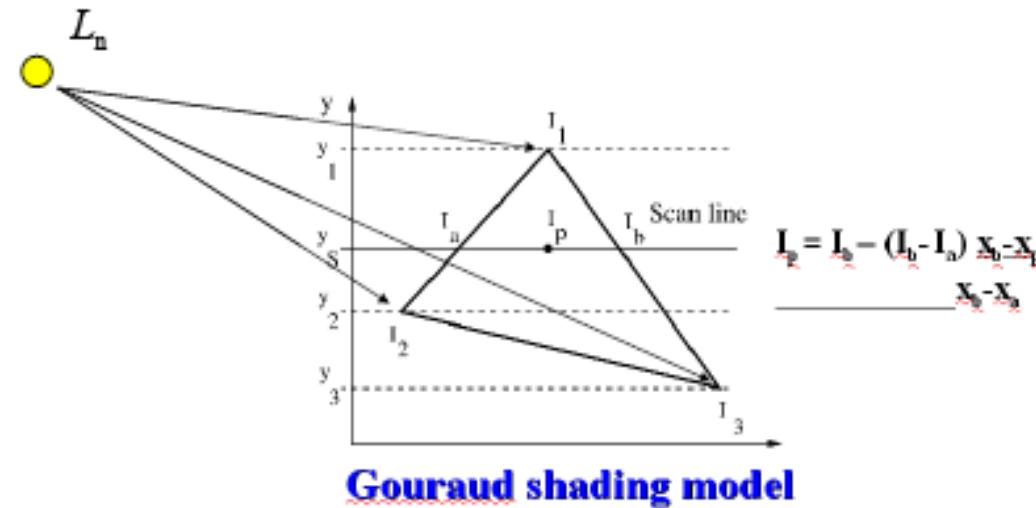
Specular
(highlights)

R_c





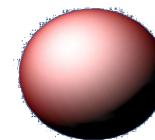
Gouraud & Phong Shading



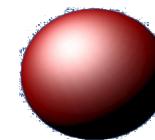


Graphics

- Various factors that change the appearance



$sp=4$



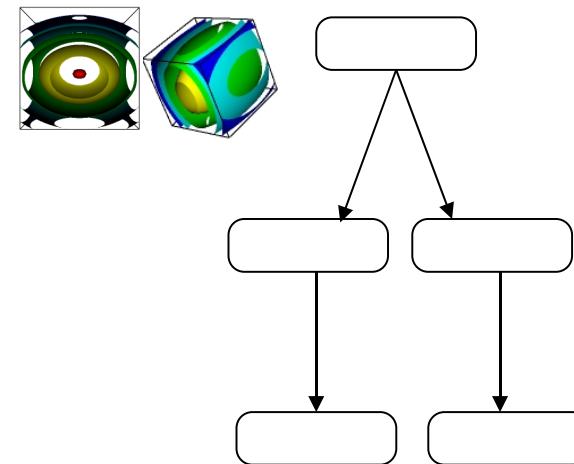
$sp=100$





Visualisation Systems

- **Visualisation Pipeline**
 - **data objects, process objects, data flow**
 - **design:** *connectivity, execution control, memory models*

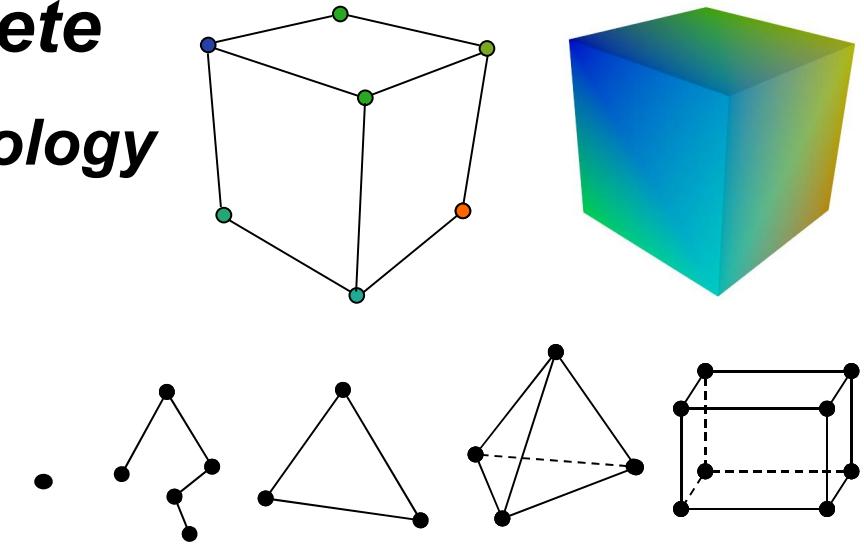




Data Representation - Basics

In order to *visualise* we have to *represent* :

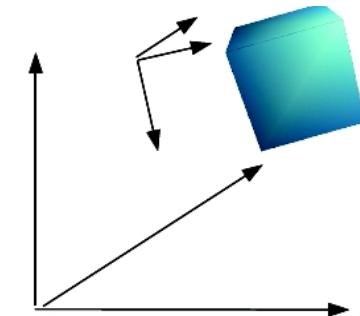
- Remember : ***data is discrete***
 - use *interpolation* over *topology*
- ***Data has.....***
 - ***topological dimension***
 - ***structure & value***
 - *structure = topology & geometry*
 - *value = attribute data*
 - ***Topology & Geometry***



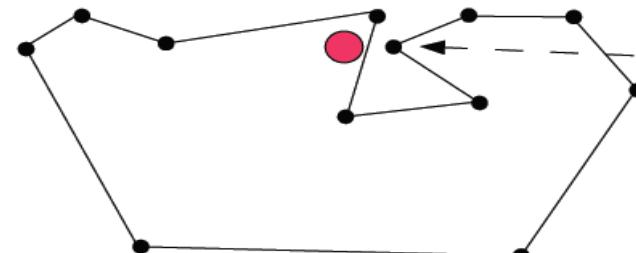
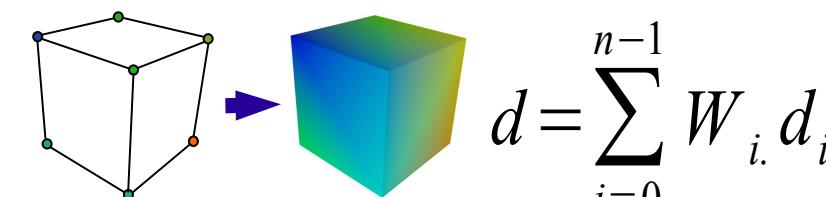


Data Representation - Advanced

- Global & Local Co-ordinates
 - Local: topological & parametric co-ordinates
 - transforms



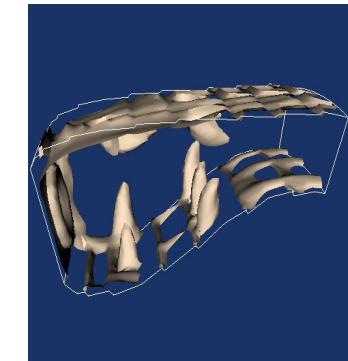
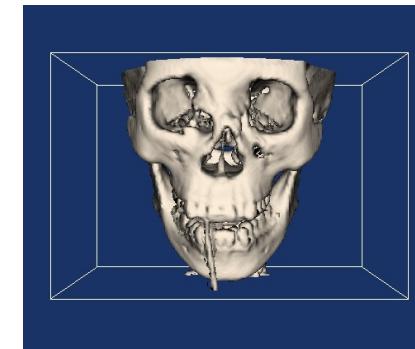
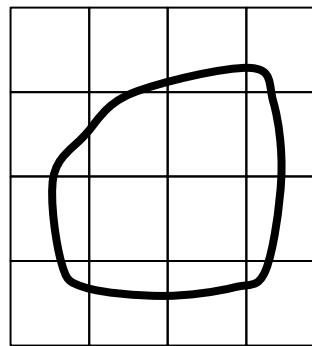
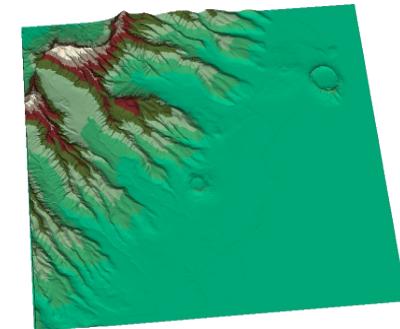
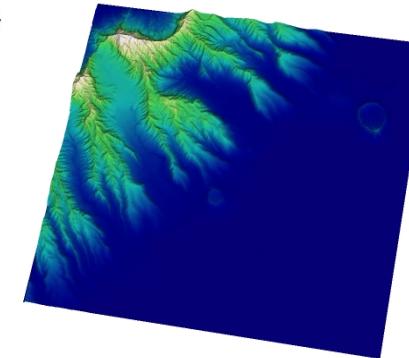
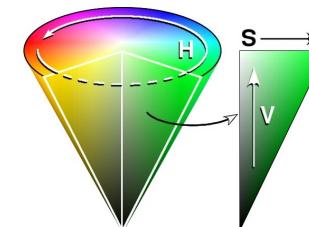
- Interpolation :
 - **Interpolate the value attribute data over a cell by weighted sum of attribute data at discrete cell points**
 - **How to do the interpolation for complex shapes?**





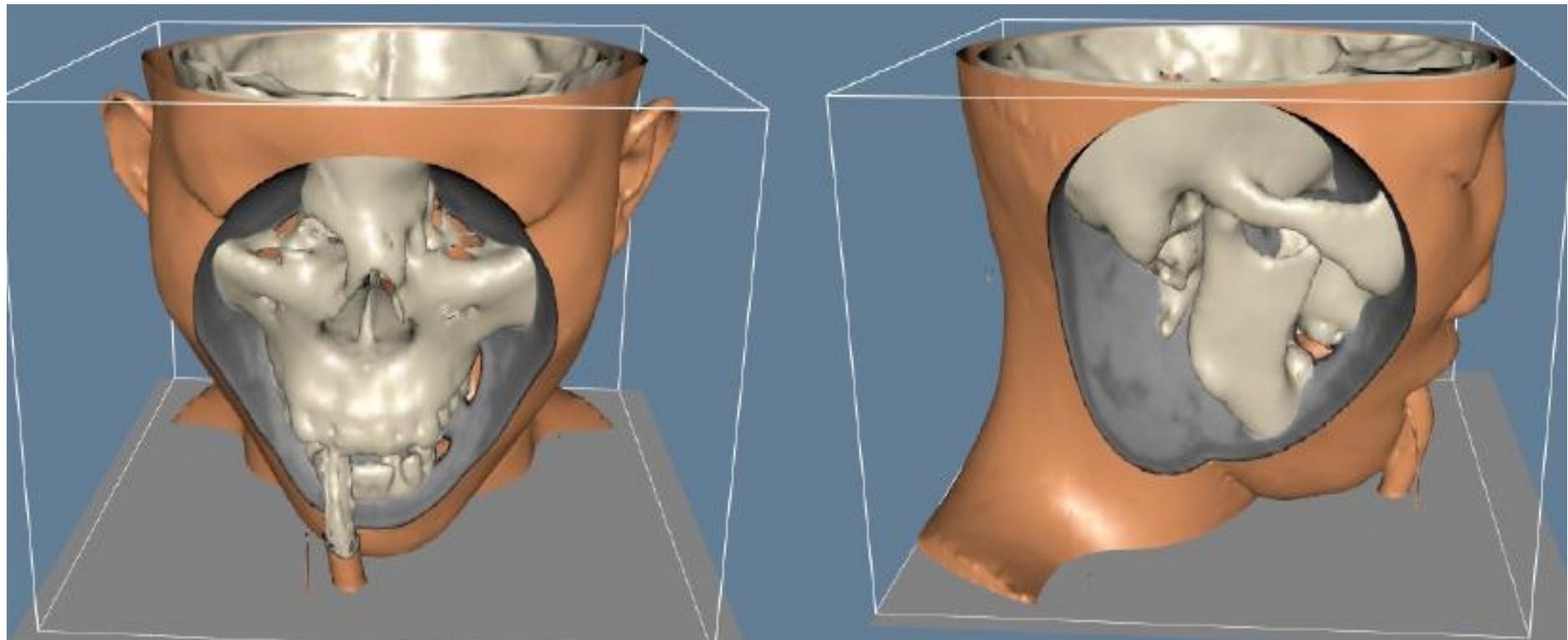
Scalar Visualisation

- **Scalar data** : single value at each location
- **Colour Mapping**
 - HSV colour space
 - LUT or transfer function
- **Contouring**
 - Marching Squares (2D), **Marching Cubes** (3D)



Scalar Visualisation - Example

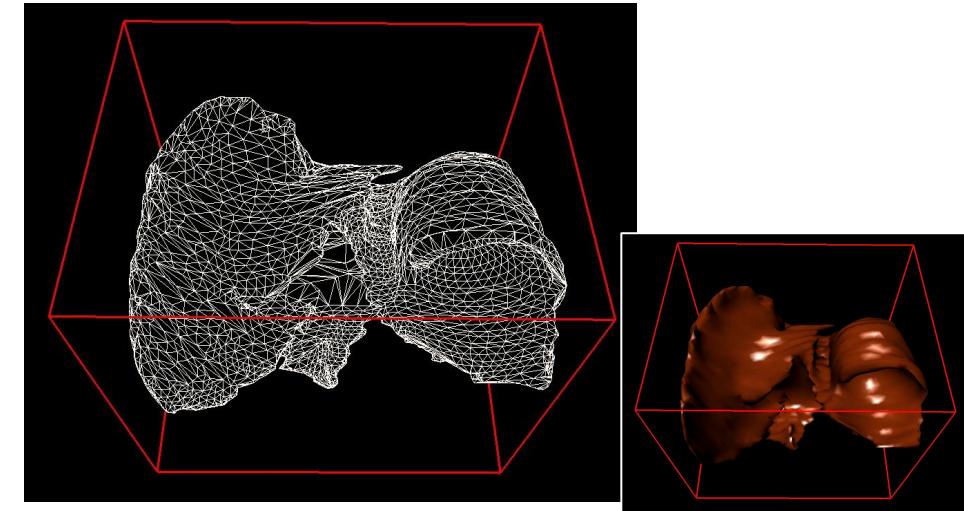
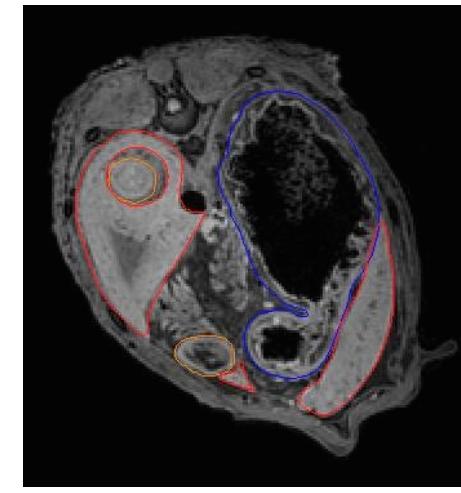
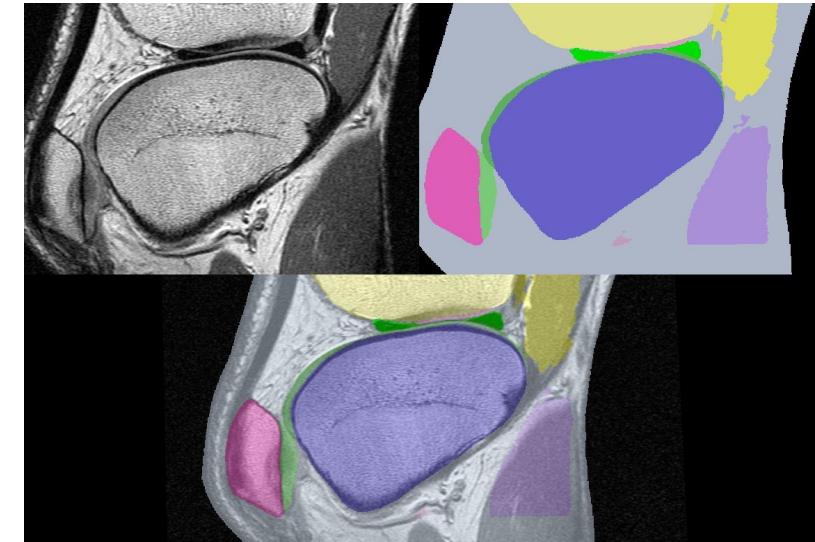
- Combing **contouring** (Marching Cubes)
with **colour mapping** (skin/bones tones)
(from CT scanner, scalar = density)





Contouring with MRI

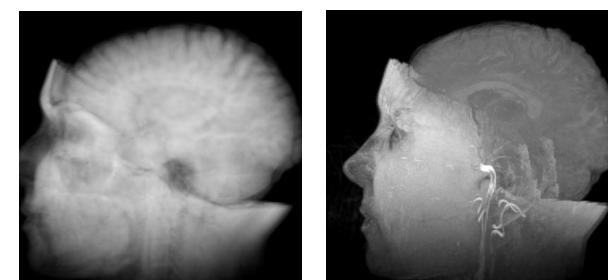
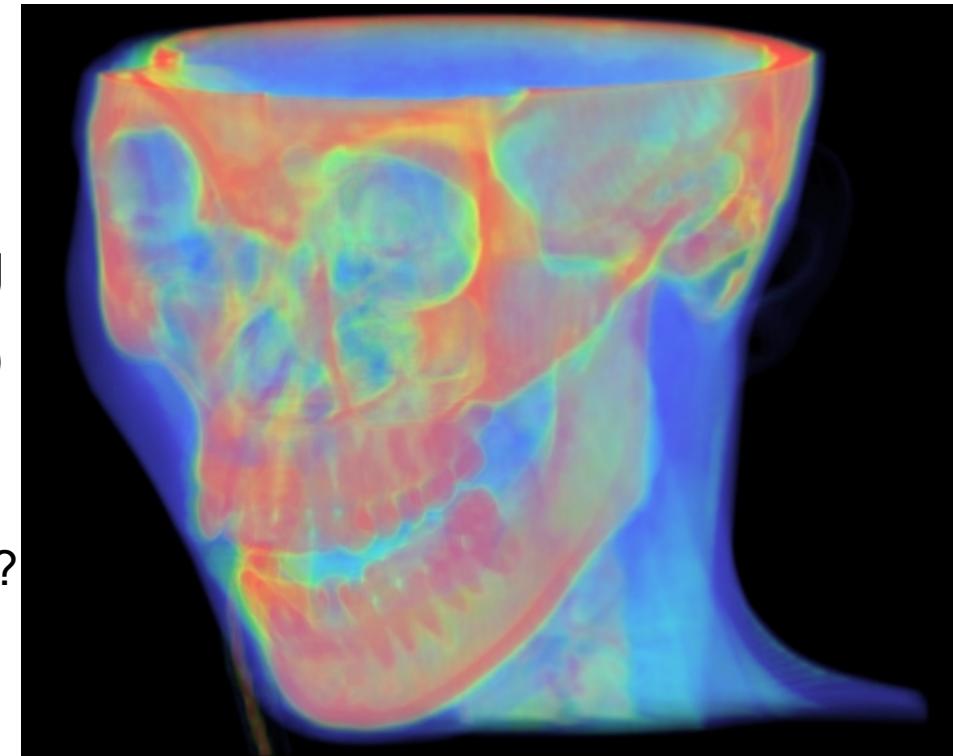
- MRI data is different
 - requires image processing to extract structures
 - use NAUGES algorithm to reconstruct surfaces





Volume Visualisation

- Alternatively we can use **volume rendering**....
 - **scalar volumetric data**
 - render using **transparency**
 - **Image Order Volume Rendering**
 - **Composite Intensity Projection (CIP)**
 - **Maximum Intensity Projection (MIP)**
intensity transfer functions
 - What is the advantage of each method?
 - **ray casting with opacity**

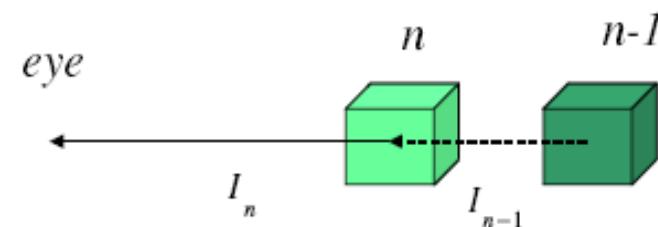




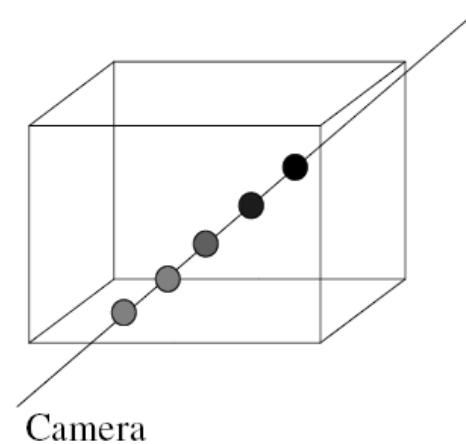
Rendering with Transparency

- Back-to-front ray casting

$$I_n = A_n E_n + (1 - A_n) I_{n-1}$$



- Front-to-back ray casting

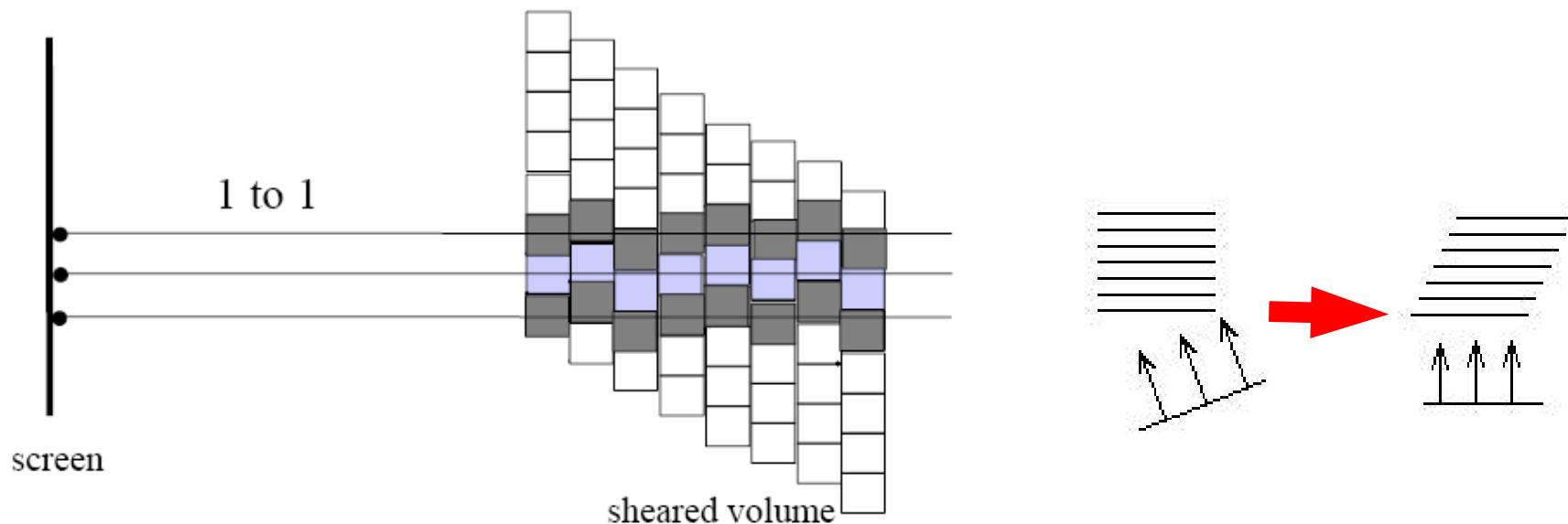


New alpha = Current Alpha + (1-Current Alpha) * Accumulated Alpha



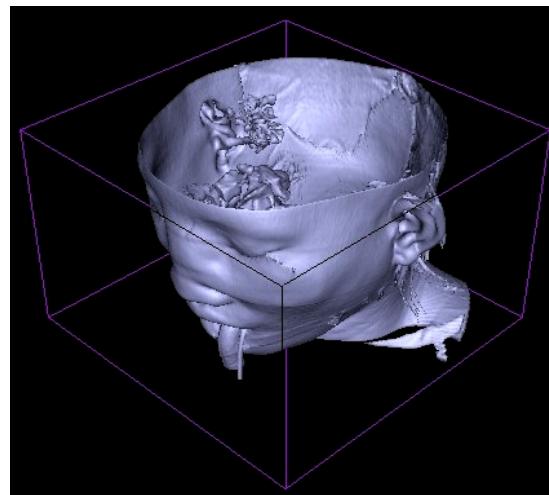
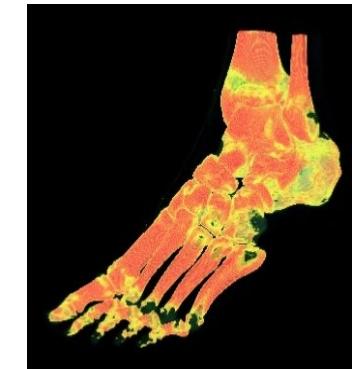
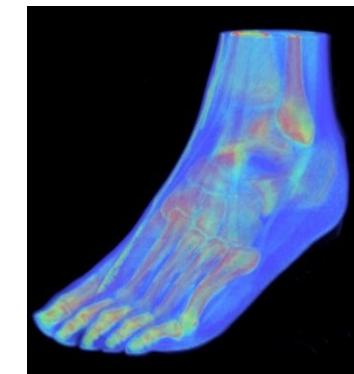
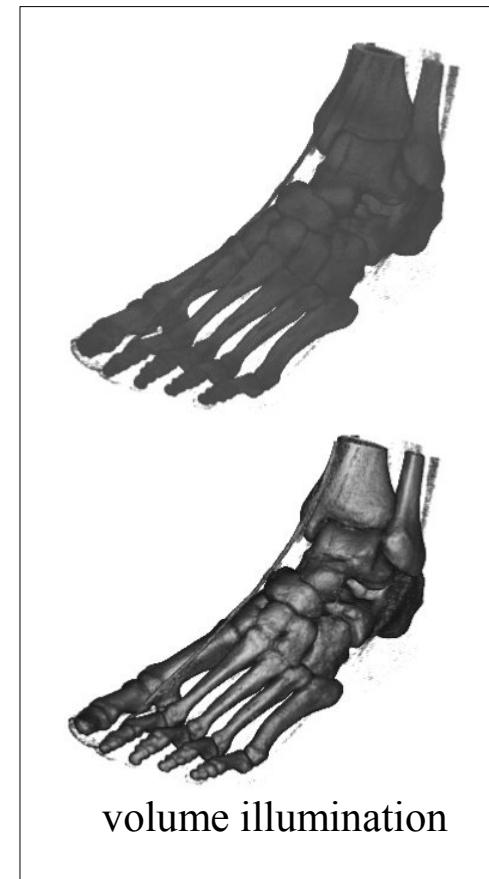
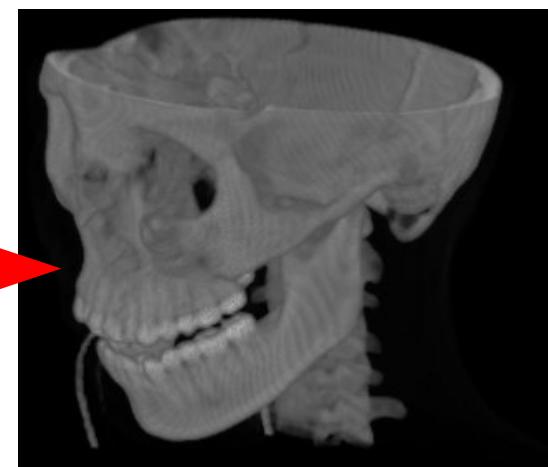
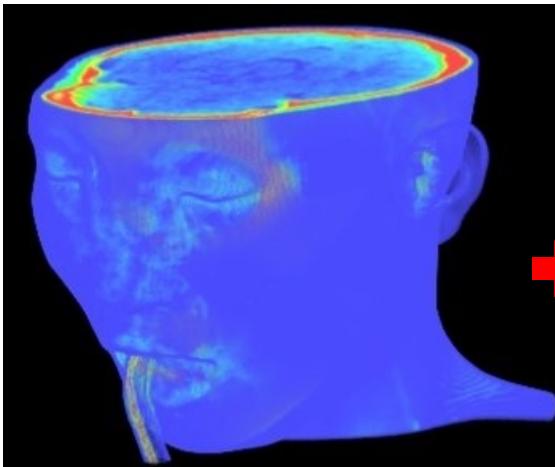
Volume Rendering

- Advanced Volume Rendering
 - shear-warp algorithm
 - shear volume so rays remain perpendicular
 - ray casting in sheared space

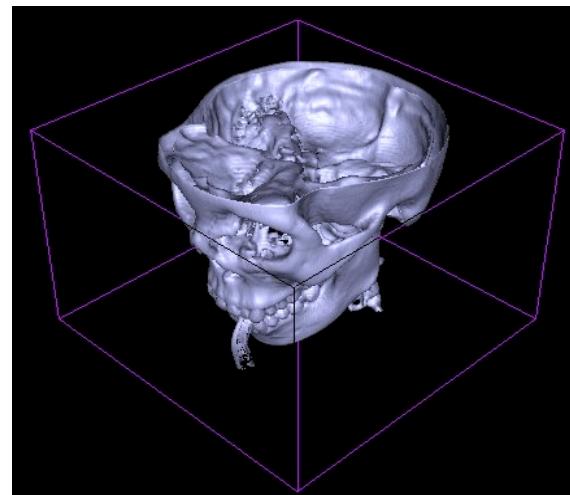




Volume colour / opacity & illumination



280 CT units



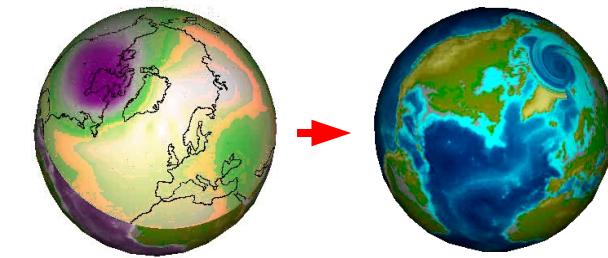
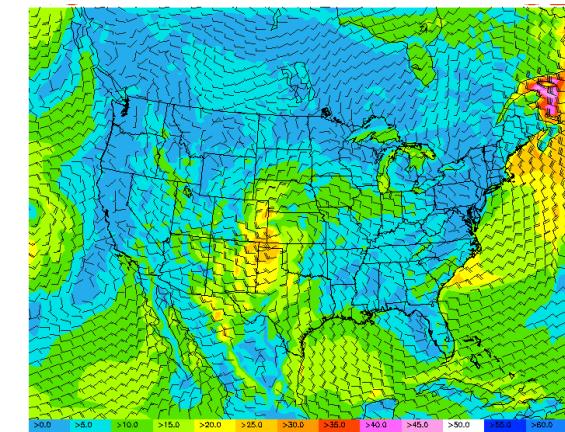
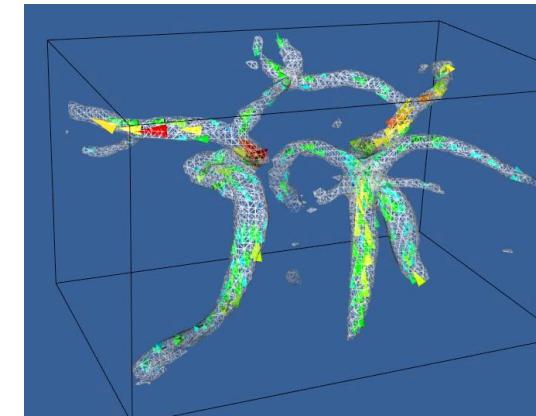
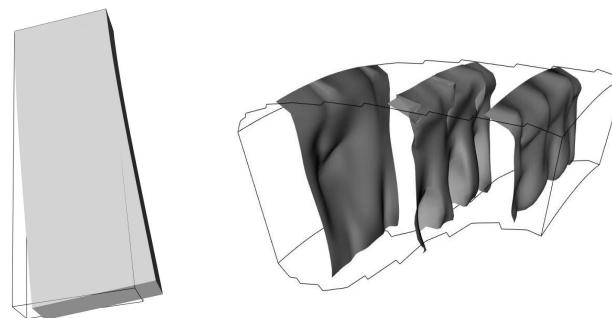
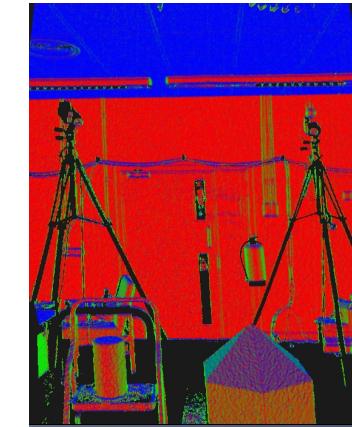
1200 CT units





Vector Visualisation

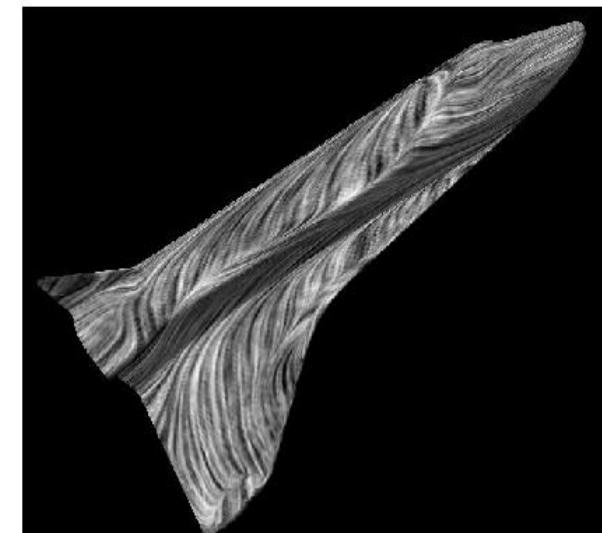
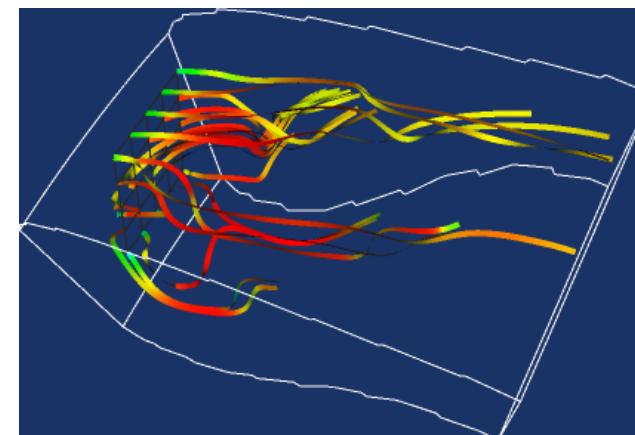
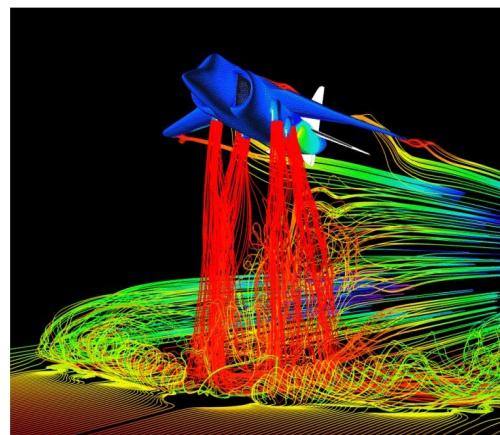
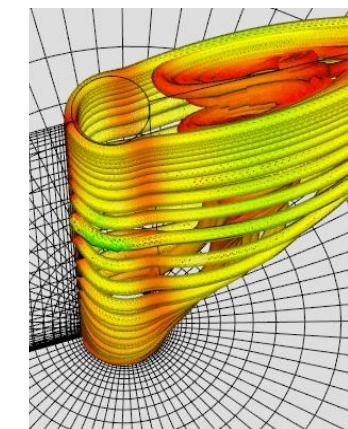
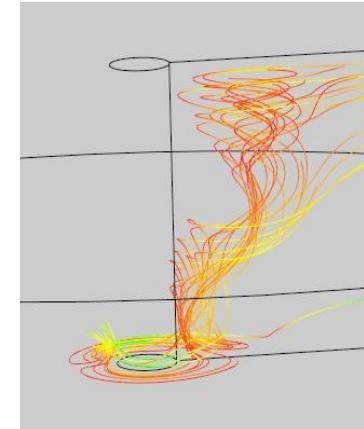
- **Local View** : visualise flow wrt fixed point
 - oriented lines, hedgehogs & glyphs
 - colour mapping vector components
 - warping
 - displacement plots
 - animation





Vector Field & Flow Visualisation

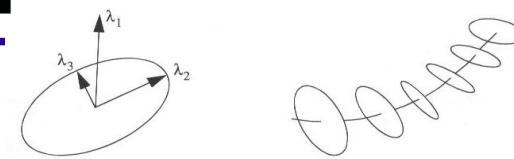
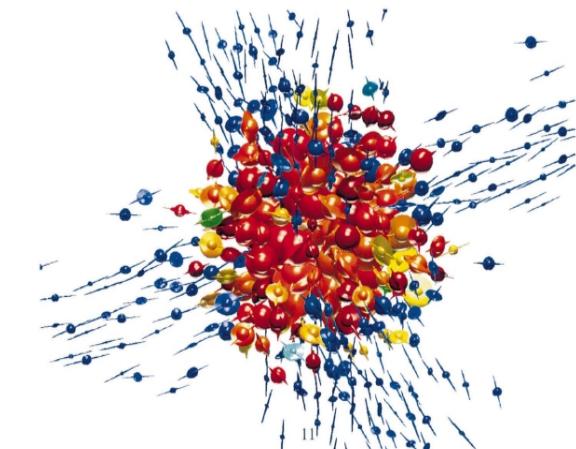
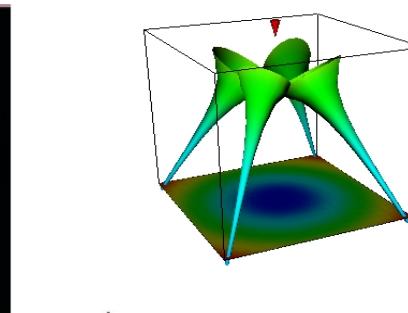
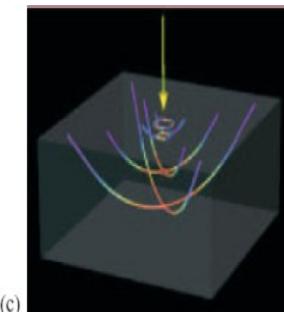
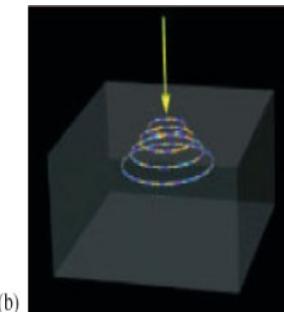
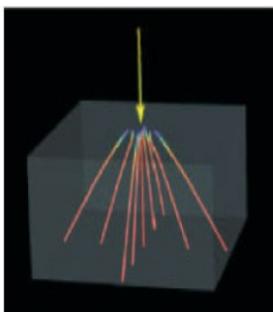
- **Streaklines** : unsteady flow
- **Streamlines** : steady flow
 - visualising transport
- Extension : stream **ribbons** & **surfaces**
- Image based methods : **LIC**





Tensor Visualisation

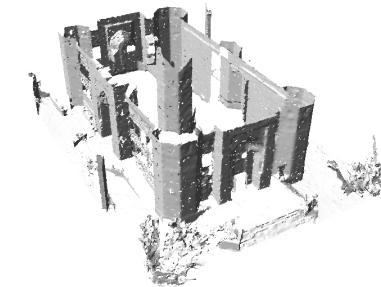
- **Tensor** : table of rank k in \mathbb{R}^n
 - source : ***stress, strain and MRI***
- Limited to **rank 2 tensors in \mathbb{R}^3**
 - obtain eigen vectors and values from **eigenanalysis**
 - **result** : 3 orthogonal vector fields
 - 3D glyphs (ellipsoids)
 - vector methods
 - **Stream lines, Hyper-streamlines**



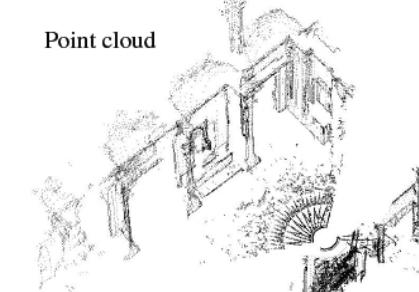


Seeing the real world

- Environment & Object Capture
 - **stereo vision & laser scanning techniques**



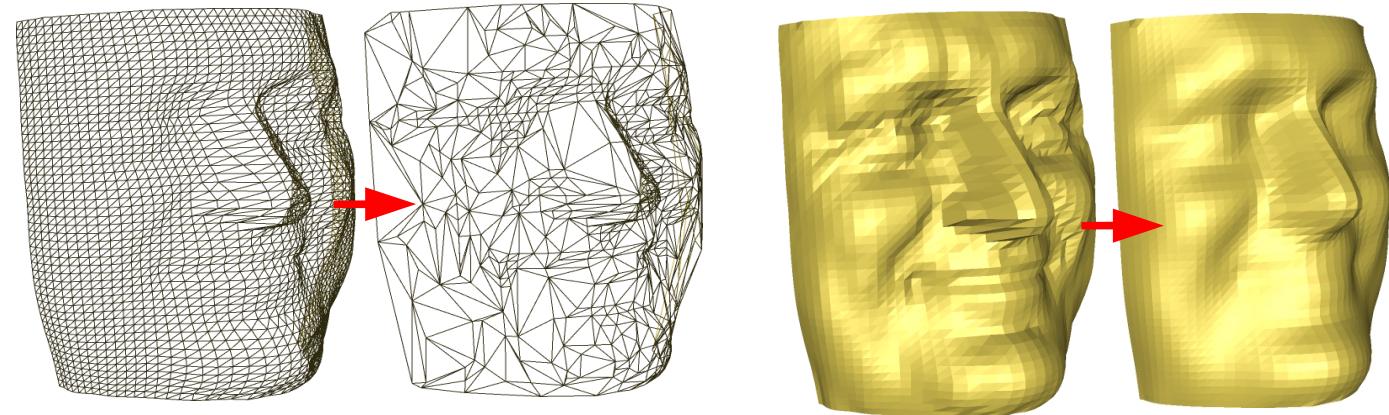
Point cloud





Processing the data

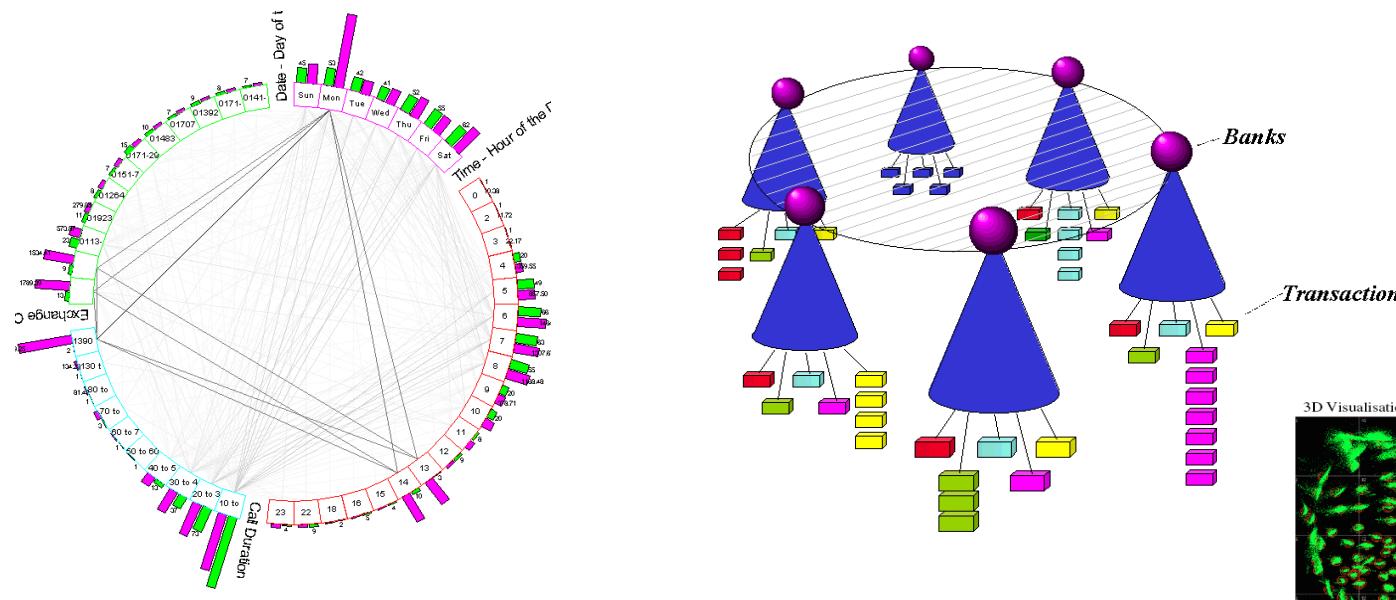
- After capturing the data we need to process the data
 - **Registration**
 - **Conversion of point clouds to surface meshes**
 - **decimation**
 - **smoothing**



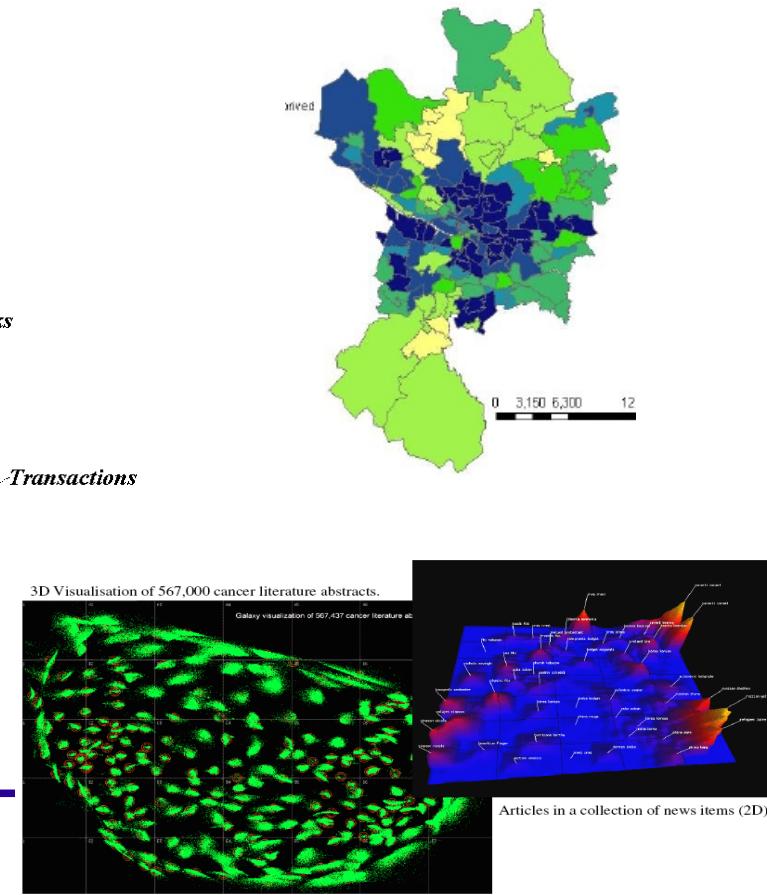


Visualising Abstract Information

- constructing topology in otherwise disjoint data measurements for visualisation : **information visualisation**
- Visualisation of **Connectivity**
 - identify complex relationships – “**visual data mining**”
- Also : **geo-spatial, documents**



Taku Komura





Theme : data representation & transformation

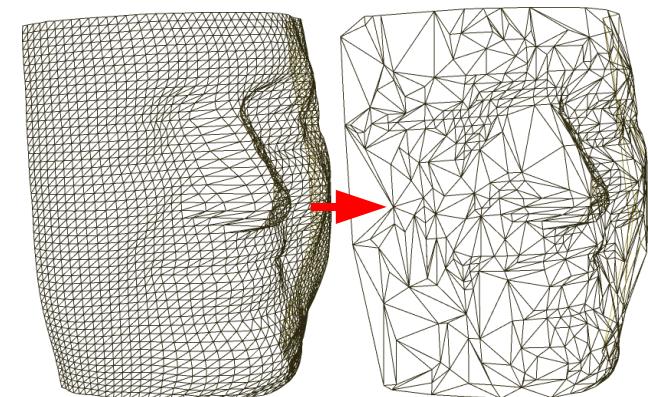
- What is our **data representation** ?
 - **topology / geometry / attribute** type
 - *topology determines interpolation*
- How can we **transform that representation in order to visualise** the information it contains ?
 - scalars to {colour | opacity | iso-surface }
 - vectors to {lines | glyphs | displacement }
 - tensors to {vectors (!) | glyphs | }
 -





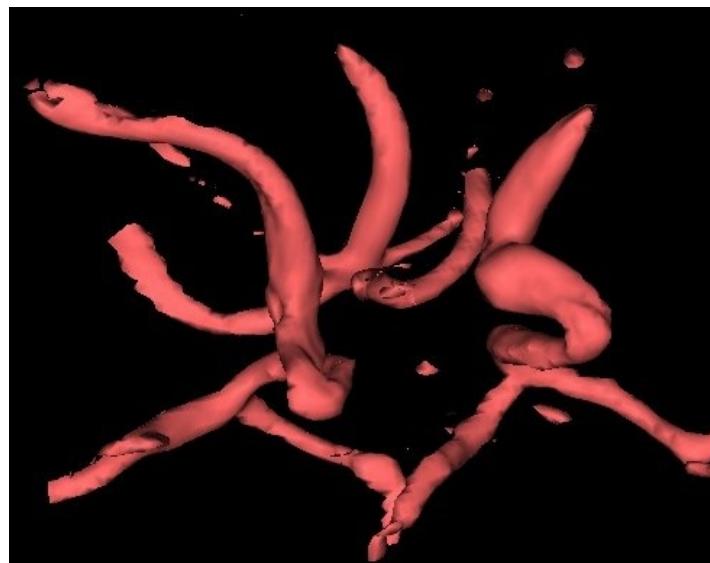
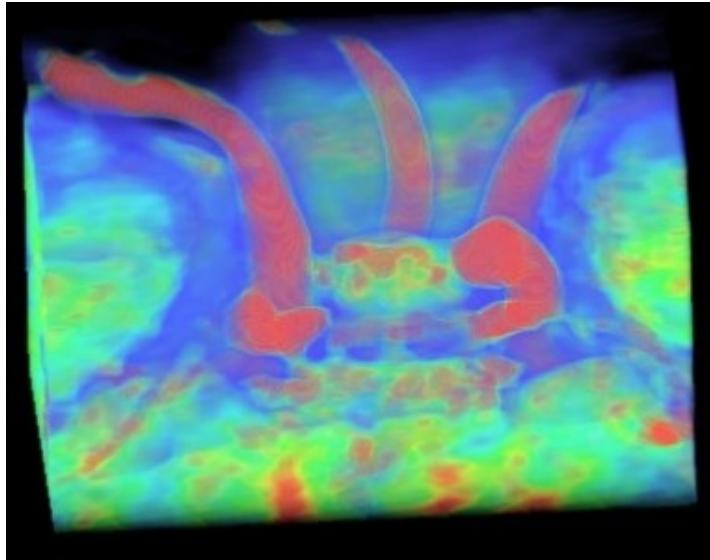
Theme : *doing it efficiently*

- Typical visualisation problem:
 - “I have a **HUGE DATASET** and I want it **NOW, RIGHT NOW in REAL-TIME**”
 - *why ? - interaction is real-time*
- We have to **think about efficiency**
 - **of representation**
 - *data reduction strategies*
 - **of transformation**
 - *efficient interpolation, rendering*

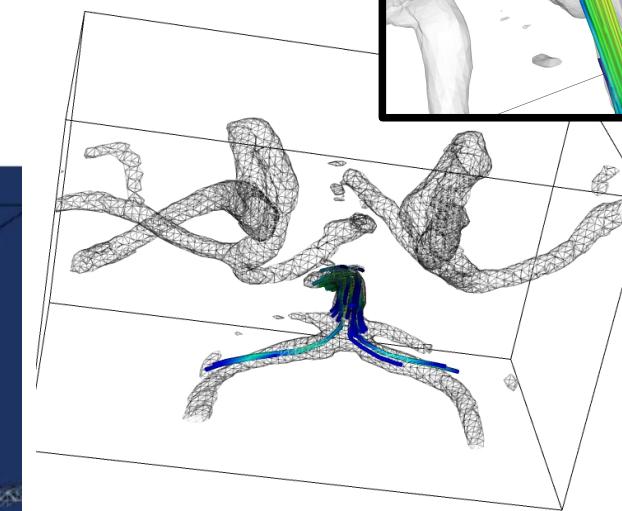
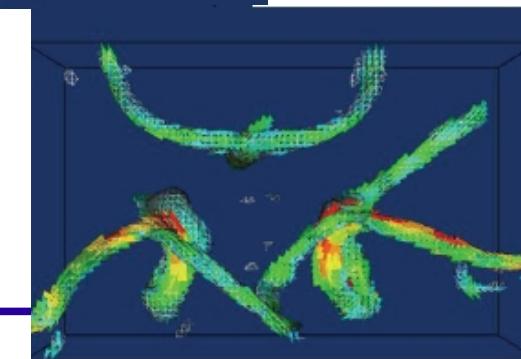
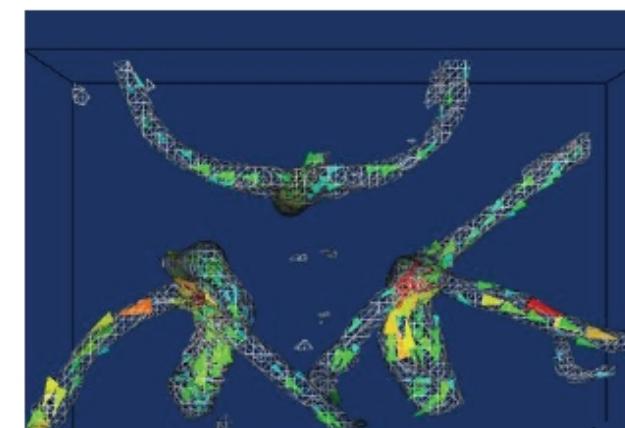




Putting it all together e.g. arteries



- Same data visualised using multiple different methods
 - which is best?





VIS exam

- Examinable course content:
 - **all material** presented in lectures is examinable
 - if it appears in a lecture note, it is examinable
 - **you will not** have to write VTK code in the exam
- What to revise ? : **everything**
- *Reading* : textbook reading and web links are provided **to aid your understanding of the examinable lecture content**





What you *should* have learned ?

- How do we **design effective visualisation systems** ?
 - ***Think*** : data representation / transformation / architecture
- What is the **best visualisation technique for a particular problem**?
 - ***Think*** : *What are we trying to see in the data?*
- What are the **limitations of a particular visualisation technique**?
- What **aspects of a problem influence visualisation** ?
 - ***Think*** : data size / dimensionality / structure / attributes





Final Course Notices

- **Lecture Notes** (& background reading / VTK examples)
 - <http://www.inf.ed.ac.uk/teaching/courses/vis/#notes>
- **Current Assignment**
 - <http://www.inf.ed.ac.uk/teaching/courses/vis/#assignments>
 - **Due 9nd April @ 5pm**
 - *N.B. different UG4 / MSc versions*





Thanks a lot!!!

