Lecture 16:

Computation Tree Logic (CTL)

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Introducing CTL

Basic Algorithms for CTL

CTL and Fairness; computing strongly connected components

Basic Decision Diagrams

Tool demonstration: SMV

LTL (linear-time logic)

- Describes properties of individual executions.
- Semantics defined as a set of executions.

CTL (computation tree logic)

- Describes properties of a *computation tree*: formulas can reason about many executions at once. (CTL belongs to the family of *branching-time logics*.)
- Semantics defined in terms of states.

Let $\mathcal{T} = \langle S, \rightarrow, s^0 \rangle$ be a transition system. Intuitively, the computation tree of \mathcal{T} is the acyclic unfolding of \mathcal{T} .

Formally, we can define the unfolding as the least (possibly infinite) transition system $\langle U, \rightarrow', u^0 \rangle$ with a labelling $I: U \rightarrow S$ such that

 $u^{0} \in U$ and $I(u^{0}) = s^{0}$;

if $u \in U$, I(u) = s, and $s \to s'$ for some u, s, s', then there is $u' \in U$ with $u \to u'$ and I(u') = s';

 u^0 does not have a direct predecessor, and all other states in U have exactly one direct predecessor.

Note: For model checking CTL, the construction of the computation tree will not be necessary. However, this definition serves to clarify the concepts behind CTL.

A transition system and its computation tree (labelling / given in blue):



CTL = Computation-Tree Logic

Combines temporal operators with quantification over runs

Operators have the following form:



We define a minimal syntax first. Later we define additional operators with the help of the minimal syntax.

Let *AP* be a set of atomic propositions: The set of CTL formulas over *AP* is as follows:

if $a \in AP$, then *a* is a CTL formula;

if ϕ_1, ϕ_2 are CTL formulas, then so are

 $\neg \phi_1, \qquad \phi_1 \lor \phi_2, \qquad \mathbf{EX} \phi_1, \qquad \mathbf{EG} \phi_1, \qquad \phi_1 \mathbf{EU} \phi_2$

CTL: Semantics

Let $\mathcal{K} = (S, \rightarrow, s^0, AP, \nu)$ be a Kripke structure.

We define the semantic of every CTL formula ϕ over *AP* w.r.t. \mathcal{K} as a set of states $[\![\phi]\!]_{\mathcal{K}}$, as follows:

 $\begin{bmatrix} a \end{bmatrix}_{\mathcal{K}} = \nu(a) \quad \text{for } a \in AP$ $\begin{bmatrix} \neg \phi_1 \end{bmatrix}_{\mathcal{K}} = S \setminus \llbracket \phi_1 \rrbracket_{\mathcal{K}}$ $\begin{bmatrix} \phi_1 \lor \phi_2 \rrbracket_{\mathcal{K}} = \llbracket \phi_1 \rrbracket_{\mathcal{K}} \cup \llbracket \phi_2 \rrbracket_{\mathcal{K}}$ $\begin{bmatrix} \mathbf{EX} \phi_1 \rrbracket_{\mathcal{K}} = \{ s \mid \text{there is a } t \text{ s.t. } s \to t \text{ and } t \in \llbracket \phi_1 \rrbracket_{\mathcal{K}} \}$ $\begin{bmatrix} \mathbf{EG} \phi_1 \rrbracket_{\mathcal{K}} = \{ s \mid \text{there is a run } \rho \text{ with } \rho(0) = s$ $and \rho(i) \in \llbracket \phi_1 \rrbracket_{\mathcal{K}} \text{ for all } i \ge 0 \}$ $\llbracket \phi_1 \mathbf{EU} \phi_2 \rrbracket_{\mathcal{K}} = \{ s \mid \text{there is a run } \rho \text{ with } \rho(0) = s \text{ and } k \ge 0 \text{ s.t.}$ $\rho(i) \in \llbracket \phi_1 \rrbracket_{\mathcal{K}} \text{ for all } i < k \text{ and } \rho(k) \in \llbracket \phi_2 \rrbracket_{\mathcal{K}} \}$ We say that \mathcal{K} satisfies ϕ (denoted $\mathcal{K} \models \phi$) iff $s^0 \in \llbracket \phi \rrbracket_{\mathcal{K}}$.

We declare two formulas equivalent (written $\phi_1 \equiv \phi_2$) iff for every Kripke structure \mathcal{K} we have $\llbracket \phi_1 \rrbracket_{\mathcal{K}} = \llbracket \phi_2 \rrbracket_{\mathcal{K}}$.

In the following, we omit the index \mathcal{K} from $\llbracket \cdot \rrbracket_{\mathcal{K}}$ if \mathcal{K} is understood.

Other logical and temporal operators (e.g. \rightarrow), **ER**, **AR**, ... may also be defined.

We use the following computation tree as a running example (with varying distributions of red and black states):



In the following slides, the topmost state satisfies the given formula if the black states satisfy p and the red states satisfy q.

















Solving nested formulas: Is $s_0 \in \llbracket AF AG x \rrbracket$?



To compute the semantics of formulas with nested operators, we first compute the states satisfying the innermost formulas; then we use those results to solve progressively more complex formulas.

In this example, we compute **[x]**, **[AG x]**, and **[AF AG x]**, in that order.

Bottom-up method (1): Compute **[x]**



Bottom-up method (2): Compute [[AG x]]



Bottom-up method (3): Compute **[AF AG** *x***]**



Example: Dining Philosophers



Five philosophers are sitting around a table, taking turns at thinking and eating.

We shall express a couple of properties in CTL. Let us assume the following atomic propositions:

- $e_i \cong$ philosopher *i* is currently eating
- $f_i \cong$ philosopher *i* has just finished eating

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\mathrm{AG}\,\neg(e_1\wedge e_4)
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"Whenever philosopher 4 has finished eating, he cannot eat again until philosopher 3 has eaten."

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\operatorname{AG} \neg (e_1 \wedge e_4)
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"Whenever philosopher 4 has finished eating, he cannot eat again until philosopher 3 has eaten."

 $\operatorname{AG}(f_4 \rightarrow (\neg e_4 \operatorname{AW} e_3))$

"Philosopher 2 will be the first to eat."

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\mathrm{AG}\,\neg(e_1\wedge e_4)
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"Whenever philosopher 4 has finished eating, he cannot eat again until philosopher 3 has eaten."

 $\operatorname{AG}(f_4 \rightarrow (\neg e_4 \operatorname{AW} e_3))$

"Philosopher 2 will be the first to eat."

 $\neg(e_1 \lor e_3 \lor e_4 \lor e_5) \operatorname{AU} e_2$

CTL and LTL have a large overlap, i.e. properties expressible in both logics. Examples:

Invariants (e.g., "p never holds.")

AG $\neg p$ or $G \neg p$

Reactivity ("Whenever p happens, eventually q will happen.")

 $\operatorname{AG}(\rho \to \operatorname{AF} q)$ or $\operatorname{G}(\rho \to \operatorname{F} q)$

CTL considers the whole computation tree whereas LTL only considers individual runs. Thus CTL allows to reason about the *branching behaviour*, considering multiple possible runs at once. Examples:

The CTL property AG EF p ("reset property") is not expressible in LTL.

The CTL property AF AX p distinguishes the following two systems, but the LTL property F X p does not:



Even though CTL considers the whole computation tree, its state-based semantics is subtly different from LTL. Thus, there are also properties expressible in LTL but not in CTL. Examples:

The LTL property **F G p** is not expressible in CTL:



 $\mathcal{K} \models \mathbf{F} \mathbf{G} \boldsymbol{\rho} \quad \text{but} \quad \mathcal{K} \not\models \mathbf{A} \mathbf{F} \mathbf{A} \mathbf{G} \boldsymbol{\rho}$

Also, fairness conditions are not directly expressible in CTL:

 $(\mathbf{G} \mathbf{F} \boldsymbol{\rho}_1 \land \mathbf{G} \mathbf{F} \boldsymbol{\rho}_2) \to \phi$

However, as we shall see later, there is another way to extend CTL with fairness conditions.

Conclusion: The expressiveness of CTL and LTL is incomparable; there is an overlap, and each logic can express properties that the other cannot.

Remark: There is a logic called CTL* that combines the expressiveness of CTL and LTL. However, we will not deal with it in this course.