

*Exercises for the tutorials: 2 and 4.*

*The other exercises are for self-study and exam preparation. All material is examinable unless otherwise mentioned.*

**Exercise 1. *Visualising and analysing Gibbs distributions via undirected graphs***

We here consider the Gibbs distribution

$$p(x_1, \dots, x_5) \propto \phi_{12}(x_1, x_2)\phi_{13}(x_1, x_3)\phi_{14}(x_1, x_4)\phi_{23}(x_2, x_3)\phi_{25}(x_2, x_5)\phi_{45}(x_4, x_5)$$

- Visualise it as an undirected graph.
- What are the neighbours of  $x_3$  in the graph?
- Do we have  $x_3 \perp\!\!\!\perp x_4 \mid x_1, x_2$ ?
- What is the Markov blanket of  $x_4$ ?
- On which minimal set of variables  $A$  do we need to condition to have  $x_1 \perp\!\!\!\perp x_5 \mid A$ ?

**Exercise 2. *Factorisation and independencies for undirected graphical models***

Consider the undirected graphical model defined by the graph in Figure 1.

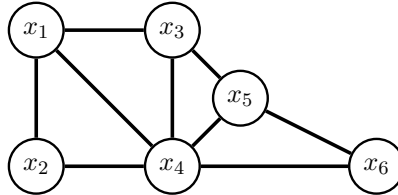
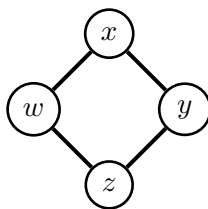


Figure 1: Graph for Exercise 2

- What is the set of Gibbs distributions that is induced by the graph?
- Let  $p$  be a pdf that factorises according to the graph. Does  $p(x_3|x_2, x_4) = p(x_3|x_4)$  hold?
- Explain why  $x_2 \perp\!\!\!\perp x_5 \mid x_1, x_3, x_4, x_6$  holds for all distributions that factorise over the graph.
- Assume you would like to approximate  $\mathbb{E}(x_1x_2x_5 \mid x_3, x_4)$ , i.e. the expected value of the product of  $x_1$ ,  $x_2$ , and  $x_5$  given  $x_3$  and  $x_4$ , with a sample average. Do you need to have joint observations for all five variables  $x_1, \dots, x_5$ ?

**Exercise 3. Factorisation and independencies for undirected graphical models**

Consider the undirected graphical model defined by the following graph, sometimes called a diamond configuration.



- (a) How do the pdfs/pmfs of the undirected graphical model factorise?
- (b) List all independencies that hold for the undirected graphical model.

**Exercise 4. Factorisation from the Markov blankets I**

Assume you know the following Markov blankets for all variables  $x_1, \dots, x_4, y_1, \dots, y_4$  of a pdf or pmf  $p(x_1, \dots, x_4, y_1, \dots, y_4)$ .

$$\text{MB}(x_1) = \{x_2, y_1\} \quad \text{MB}(x_2) = \{x_1, x_3, y_2\} \quad \text{MB}(x_3) = \{x_2, x_4, y_3\} \quad \text{MB}(x_4) = \{x_3, y_4\} \quad (1)$$

$$\text{MB}(y_1) = \{x_1\} \quad \text{MB}(y_2) = \{x_2\} \quad \text{MB}(y_3) = \{x_3\} \quad \text{MB}(y_4) = \{x_4\} \quad (2)$$

Assuming that  $p$  is positive for all possible values of its variables, how does  $p$  factorise?

**Exercise 5. Factorisation from the Markov blankets II**

We consider the same setup as in Exercise 4 but we now assume that we do not know all Markov blankets but only

$$\text{MB}(x_1) = \{x_2, y_1\} \quad \text{MB}(x_2) = \{x_1, x_3, y_2\} \quad \text{MB}(x_3) = \{x_2, x_4, y_3\} \quad \text{MB}(x_4) = \{x_3, y_4\} \quad (3)$$

Without inserting more independencies than those specified by the Markov blankets, draw the graph over which  $p$  factorises and state the factorisation. (Again assume that  $p$  is positive for all possible values of its variables).

**Exercise 6. Undirected graphical model with pairwise potentials**

We here consider Gibbs distributions where the factors only depend on two variables at a time. The probability density or mass functions over  $d$  random variables  $x_1, \dots, x_d$  then take the form

$$p(x_1, \dots, x_d) \propto \prod_{i \leq j} \phi_{ij}(x_i, x_j)$$

Such models are sometimes called pairwise Markov networks.

- (a) Let  $p(x_1, \dots, x_d) \propto \exp(-\frac{1}{2} \mathbf{x}^\top \mathbf{A} \mathbf{x} - \mathbf{b}^\top \mathbf{x})$  where  $\mathbf{A}$  is symmetric and  $\mathbf{x} = (x_1, \dots, x_d)^\top$ . What are the corresponding factors  $\phi_{ij}$  for  $i \leq j$ ?
- (b) For  $p(x_1, \dots, x_d) \propto \exp(-\frac{1}{2} \mathbf{x}^\top \mathbf{A} \mathbf{x} - \mathbf{b}^\top \mathbf{x})$ , show that  $x_i \perp\!\!\!\perp x_j \mid \{x_1, \dots, x_d\} \setminus \{x_i, x_j\}$  if the  $(i, j)$ -th element of  $\mathbf{A}$  is zero.

**Exercise 7. Restricted Boltzmann machine (based on Barber Exercise 4.4)**

The restricted Boltzmann machine is an undirected graphical model for binary variables  $\mathbf{v} = (v_1, \dots, v_n)^\top$  and  $\mathbf{h} = (h_1, \dots, h_m)^\top$  with a probability mass function equal to

$$p(\mathbf{v}, \mathbf{h}) \propto \exp\left(\mathbf{v}^\top \mathbf{W} \mathbf{h} + \mathbf{a}^\top \mathbf{v} + \mathbf{b}^\top \mathbf{h}\right), \quad (4)$$

where  $\mathbf{W}$  is a  $n \times m$  matrix. Both the  $v_i$  and  $h_i$  take values in  $\{0, 1\}$ . The  $v_i$  are called the “visibles” variables since they are assumed to be observed while the  $h_i$  are the hidden variables since it is assumed that we cannot measure them.

- (a) Use graph separation to show that the joint conditional  $p(\mathbf{h}|\mathbf{v})$  factorises as

$$p(\mathbf{h}|\mathbf{v}) = \prod_{i=1}^m p(h_i|\mathbf{v}).$$

- (b) Show that

$$p(h_i = 1|\mathbf{v}) = \frac{1}{1 + \exp\left(-b_i - \sum_j W_{ji}v_j\right)} \quad (5)$$

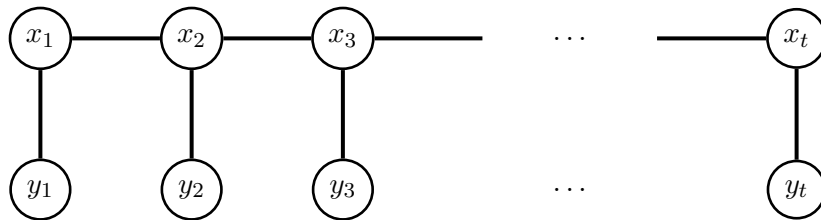
where  $W_{ji}$  is the  $(ji)$ -th element of  $\mathbf{W}$ , so that  $\sum_j W_{ji}v_j$  is the inner product (scalar product) between the  $i$ -th column of  $\mathbf{W}$  and  $\mathbf{v}$ .

- (c) Use a symmetry argument to show that

$$p(\mathbf{v}|\mathbf{h}) = \prod_i p(v_i|\mathbf{h}) \quad \text{and} \quad p(v_i = 1|\mathbf{h}) = \frac{1}{1 + \exp\left(-a_i - \sum_j W_{ij}h_j\right)}$$

**Exercise 8. Hidden Markov models and change of measure**

Consider the following undirected graph for a hidden Markov model where the  $y_i$  correspond to observed (visible) variables and the  $x_i$  to unobserved (hidden/latent) variables.



The graph implies the following factorisation

$$p(x_1, \dots, x_t, y_1, \dots, y_t) \propto \phi_1^y(x_1, y_1) \prod_{i=2}^t \phi_i^x(x_{i-1}, x_i) \phi_i^y(x_i, y_i), \quad (6)$$

where the  $\phi_i^x$  and  $\phi_i^y$  are non-negative factors.

Let us consider the situation where  $\prod_{i=2}^t \phi_i^x(x_{i-1}, x_i)$  equals

$$f(\mathbf{x}) = \prod_{i=2}^t \phi_i^x(x_{i-1}, x_i) = f_1(x_1) \prod_{i=2}^t f_i(x_i|x_{i-1}), \quad (7)$$

with  $\mathbf{x} = (x_1, \dots, x_t)$  and where the  $f_i$  are (conditional) pdfs. We thus have

$$p(x_1, \dots, x_t, y_1, \dots, y_t) \propto f_1(x_1) \prod_{i=2}^t f_i(x_i | x_{i-1}) \prod_{i=1}^t \phi_i^y(x_i, y_i). \quad (8)$$

- (a) Provide a factorised expression for  $p(x_1, \dots, x_t | y_1, \dots, y_t)$
- (b) Draw the undirected graph for  $p(x_1, \dots, x_t | y_1, \dots, y_t)$
- (c) Show that if  $\phi_i^y(x_i, y_i)$  equals the conditional pdf of  $y_i$  given  $x_i$ , i.e.  $p(y_i | x_i)$ , the marginal  $p(x_1, \dots, x_t)$ , obtained by integrating out  $y_1, \dots, y_t$  from (8), equals  $f(\mathbf{x})$ .
- (d) Compute the normalising constant for  $p(x_1, \dots, x_t | y_1, \dots, y_t)$  and express it as an expectation over  $f(\mathbf{x})$ .
- (e) Express the expectation of a test function  $h(\mathbf{x})$  with respect to  $p(x_1, \dots, x_t | y_1, \dots, y_t)$  as a reweighted expectation with respect to  $f(\mathbf{x})$ .