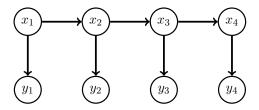
Exercises for the tutorials: 2(a-c) and 4(a-b).

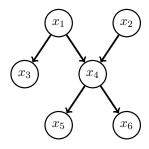
The other exercises are for self-study and exam preparation. All material is examinable unless otherwise mentioned.

Exercise 1. Conversion to factor graphs

- (a) Draw an undirected graph and an undirected factor graph for $p(x_1, x_2, x_3) = p(x_1)p(x_2)p(x_3|x_1, x_2)$
- (b) Draw an undirected factor graph for the directed graphical model defined by the graph below.

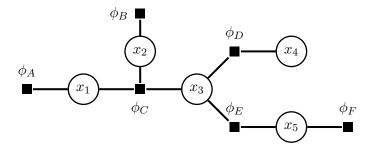


(c) Draw the moralised graph and an undirected factor graph for directed graphical models defined by the graph below (this kind of graph is called a polytree: there are no loops but a node may have more than one parent).



Exercise 2. Sum-product message passing

We here re-consider the factor tree from the lecture on exact inference.



Let all variables be binary, $x_i \in \{0,1\}$, and the factors be defined as follows:

		$\overline{x_1}$	x_2	x_3	ϕ_C								
		0 1	0 0	0 0	$\frac{4}{2}$	$\overline{x_3}$	x_4	ϕ_D	$\overline{x_3}$	x_5	ϕ_E		
$x_1 \phi_A$	$x_2 \phi_B$	0	1	0	2	0	0	8	0	0	3	x_5	ϕ_F
0 2	0 4	1	1	0	6	1	0	2	1	0	6	0	1
1 4	1 4	0	0	1	2	0	1	2	0	1	6	1	8
		1	0	1	6	1	1	6	1	1	3		
		0	1	1	6								
		1	1	1	4								

- (a) Mark the graph with arrows indicating all messages that need to be computed for the computation of $p(x_1)$.
- (b) Compute the messages that you have identified.

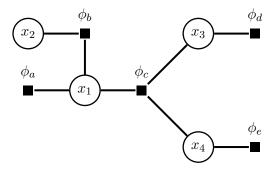
 Assuming that the computation of the messages is scheduled according to a common clock, group the messages together so that all messages in the same group can be computed in
- (c) What is $p(x_1 = 1)$?

parallel during a clock cycle.

- (d) Draw the factor graph corresponding to $p(x_1, x_3, x_4, x_5 | x_2 = 1)$ and provide the numerical values for all factors.
- (e) Compute $p(x_1 = 1|x_2 = 1)$, re-using messages that you have already computed for the evaluation of $p(x_1 = 1)$.

Exercise 3. Sum-product message passing

The following factor graph represents a Gibbs distribution over four binary variables $x_i \in \{0, 1\}$.



The factors ϕ_a, ϕ_b, ϕ_d are defined as follows:

	x_1	x_2	ϕ_b			
$x_1 \phi_a$	0	0	5	•	x_3	ϕ_d
0 2	1	0	2		0	1
1 1	0	1	2		1	2
	1	1	6			

and $\phi_c(x_1, x_3, x_4) = 1$ if $x_1 = x_3 = x_4$, and is zero otherwise.

For all questions below, justify your answer:

- (a) Compute the values of $\mu_{x_2 \to \phi_b}(x_2)$ for $x_2 = 0$ and $x_2 = 1$.
- (b) Assume the message $\mu_{x_4 \to \phi_c}(x_4)$ equals

$$\mu_{x_4 \to \phi_c}(x_4) = \begin{cases} 1 & \text{if } x_4 = 0\\ 3 & \text{if } x_4 = 1 \end{cases}$$

Compute the values of $\phi_e(x_4)$ for $x_4=0$ and $x_4=1$.

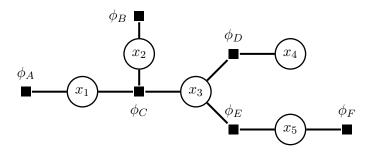
- (c) Compute the values of $\mu_{\phi_c \to x_1}(x_1)$ for $x_1 = 0$ and $x_1 = 1$.
- (d) The message $\mu_{\phi_b \to x_1}(x_1)$ equals

$$\mu_{\phi_b \to x_1}(x_1) = \begin{cases} 7 & \text{if } x_1 = 0\\ 8 & \text{if } x_1 = 1 \end{cases}$$

What is the probability that $x_1 = 1$, i.e. $p(x_1 = 1)$?

Exercise 4. Max-sum message passing

We here compute most probable states for the factor graph and factors below.



Let all variables be binary, $x_i \in \{0,1\}$, and the factors be defined as follows:

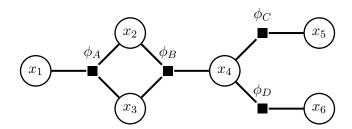
		$\overline{x_1}$	x_2	x_3	ϕ_C	-							
		0	0 0	0	4 2	$\overline{x_3}$	x_4	ϕ_D	$\overline{x_3}$	x_5	ϕ_E		
$x_1 \phi_A$	$x_2 \phi_B$	0	1	0	2	0	0	8	0	0	3	x_5	ϕ_F
0 2	0 4	1	1	0	6	1	0	2	1	0	6	0	1
1 4	1 4	0	0	1	2	0	1	2	0	1	6	1	8
		1	0	1	6	1	1	6	1	1	3		
		0	1	1	6				-				
		1	1	1	4								

(a) Will we need to compute the normalising constant Z to determine $\operatorname{argmax}_{\mathbf{x}} p(x_1, \dots, x_5)$?

- (b) Compute $\operatorname{argmax}_{x_1, x_2, x_3} p(x_1, x_2, x_3 | x_4 = 0, x_5 = 0)$ via max-sum message passing.
- (c) Compute $\operatorname{argmax}_{x_1,\dots,x_5} p(x_1,\dots,x_5)$ via max-sum message passing with x_1 as root.
- (d) Compute $\operatorname{argmax}_{x_1,\dots,x_5} p(x_1,\dots,x_5)$ via max-sum message passing with x_3 as root.

Exercise 5. Choice of elimination order in factor graphs

Consider the following factor graph, which contains a loop:



Let all variables be binary, $x_i \in \{0,1\}$, and the factors be defined as follows:

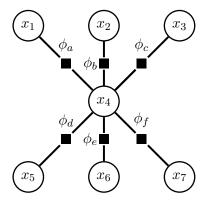
x_1	x_2	x_3	ϕ_A	_	x_2	x_3	x_4	ϕ_B
0	0	0	4	•	0	0	0	2 2
	0 1	$0 \\ 0$	$\frac{2}{2}$		0	0 1	0	$\frac{2}{4}$
1	1	0	6		1	1	0	2
)	0	1	2		0	0	1	6
L	0	1	6		1	0	1	8
0	1	1	6		0	1	1	4
1	1	1	4		1	1	1	2

- (a) Draw the factor graph corresponding to $p(x_2, x_3, x_4, x_5 \mid x_1 = 0, x_6 = 1)$ and give the tables defining the new factors $\phi_A^{x_1=0}(x_2, x_3)$ and $\phi_D^{x_6=1}(x_4)$ that you obtain.
- (b) Find $p(x_2 \mid x_1 = 0, x_6 = 1)$ using the elimination ordering (x_4, x_5, x_3) :
 - (i) Draw the graph for $p(x_2, x_3, x_5 \mid x_1 = 0, x_6 = 1)$ by marginalising x_4 Compute the table for the new factor $\tilde{\phi}_4(x_2, x_3, x_5)$
 - (ii) Draw the graph for $p(x_2, x_3 \mid x_1 = 0, x_6 = 1)$ by marginalising x_5 Compute the table for the new factor $\tilde{\phi}_{45}(x_2, x_3)$
 - (iii) Draw the graph for $p(x_2 \mid x_1 = 0, x_6 = 1)$ by marginalising x_3 Compute the table for the new factor $\tilde{\phi}_{453}(x_2)$
- (c) Now determine $p(x_2 \mid x_1 = 0, x_6 = 1)$ with the elimination ordering (x_5, x_4, x_3) :
 - (i) Draw the graph for $p(x_2, x_3, x_4, | x_1 = 0, x_6 = 1)$ by marginalising x_5 Compute the table for the new factor $\tilde{\phi}_5(x_4)$

- (ii) Draw the graph for $p(x_2, x_3 \mid x_1 = 0, x_6 = 1)$ by marginalising x_4 Compute the table for the new factor $\tilde{\phi}_{54}(x_2, x_3)$
- (iii) Draw the graph for $p(x_2 \mid x_1 = 0, x_6 = 1)$ by marginalising x_3 Compute the table for the new factor $\tilde{\phi}_{543}(x_2)$
- (d) Which variable ordering, (x_4, x_5, x_3) or (x_5, x_4, x_3) do you prefer?

Exercise 6. Choice of elimination order in factor graphs

We would like to compute the marginal $p(x_1)$ by variable elimination for a joint pmf represented by the following factor graph. All variables x_i can take K different values.



- (a) A friend proposes the elimination order $x_4, x_5, x_6, x_7, x_3, x_2$, i.e. to do x_4 first and x_2 last. Explain why this is computationally inefficient.
- (b) Propose an elimination ordering that achieves $O(K^2)$ computational cost per variable elimination and explain why it does so.