## Independencies and Undirected Graphs

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Spring Semester 2020

## Recap

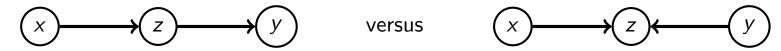
- ► The number of free parameters in probabilistic models increases with the number of random variables involved.
- Making statistical independence assumptions reduces the number of free parameters that need to be specified.
- Starting with the chain rule and an ordering of the random variables, we used statistical independencies to simplify the representation.
- We thus obtained a factorisation in terms of a product of conditional pdfs that we visualised as a DAG.
- In turn, we used DAGs to define sets of distributions ("directed graphical models").
- We discussed independence properties satisfied by the distributions, d-separation, and the equivalence to the factorisation.

# The directionality in directed graphical models

So far we mainly exploited the property

$$\mathbf{x} \perp \!\!\!\perp \mathbf{y} \mid \mathbf{z} \Longleftrightarrow p(\mathbf{y}|\mathbf{x},\mathbf{z}) = p(\mathbf{y}|\mathbf{z})$$

- ▶ But when working with p(y|x,z) we impose an ordering or directionality from x and z to y.
- Directionality matters in directed graphical models



- ▶ In some cases, directionality is natural but in others we do not want to choose one direction over another.
- We now discuss how to represent probability distributions and independencies in a symmetric manner without assuming a directionality or ordering of the variables.

## Program

- 1. Representing probability distributions without imposing a directionality between the random variables
- 2. Separation in undirected graphs and statistical independencies

## Program

- 1. Representing probability distributions without imposing a directionality between the random variables
  - Factorisation and statistical independence
  - Gibbs distributions
  - Visualising Gibbs distributions with undirected graphs
  - Conditioning corresponds to removing nodes and edges from the graph
- 2. Separation in undirected graphs and statistical independencies

## Further characterisation of statistical independence

From tutorials: For non-negative functions  $a(\mathbf{x}, \mathbf{z}), b(\mathbf{y}, \mathbf{z})$ :

$$\mathbf{x} \perp \!\!\!\perp \mathbf{y} \mid \mathbf{z} \Longleftrightarrow p(\mathbf{x}, \mathbf{y}, \mathbf{z}) = a(\mathbf{x}, \mathbf{z})b(\mathbf{y}, \mathbf{z})$$

- ▶ More general version of p(x, y, z) = p(x|z)p(y|z)p(z)
- ▶ No directionality or ordering of the variables is imposed.
- ▶ Unconditional version: For non-negative functions  $a(\mathbf{x}), b(\mathbf{y})$ :

$$\mathbf{x} \perp \!\!\!\perp \mathbf{y} \Longleftrightarrow p(\mathbf{x}, \mathbf{y}) = a(\mathbf{x})b(\mathbf{y})$$

- ► The important point is the factorisation of  $p(\mathbf{x}, \mathbf{y}, \mathbf{z})$  into two factors:
  - if the factors share a variable z, then we have conditional independence,
  - if not, we have unconditional independence.

# Further characterisation of statistical independence

▶ Since p(x, y, z) must sum (integrate) to one, we must have

$$\sum_{\mathbf{x},\mathbf{y},\mathbf{z}} a(\mathbf{x},\mathbf{z}) b(\mathbf{y},\mathbf{z}) = 1$$

Normalisation condition often ensured by re-defining  $a(\mathbf{x}, \mathbf{z})b(\mathbf{y}, \mathbf{z})$ :

$$p(\mathbf{x}, \mathbf{y}, \mathbf{z}) = \frac{1}{Z} \phi_A(\mathbf{x}, \mathbf{z}) \phi_B(\mathbf{y}, \mathbf{z}) \qquad Z = \sum_{\mathbf{x}, \mathbf{y}, \mathbf{z}} \phi_A(\mathbf{x}, \mathbf{z}) \phi_B(\mathbf{y}, \mathbf{z})$$

- Z: normalisation constant (related to partition function, see later)
- $\phi_i$ : factors (also called potential functions). Do generally not correspond to (conditional) probabilities. They measure "compatibility", "agreement", or "affinity"

#### What does it mean?

$$\mathbf{x} \perp \!\!\!\perp \mathbf{y} \mid \mathbf{z} \Longleftrightarrow p(\mathbf{x}, \mathbf{y}, \mathbf{z}) = \frac{1}{Z} \phi_A(\mathbf{x}, \mathbf{z}) \phi_B(\mathbf{y}, \mathbf{z})$$

" $\Rightarrow$ " If we want our model to satisfy  $\mathbf{x} \perp \!\!\! \perp \mathbf{y} \mid \mathbf{z}$  we should write the pdf (pmf) as

$$p(\mathbf{x}, \mathbf{y}, \mathbf{z}) \propto \phi_A(\mathbf{x}, \mathbf{z}) \phi_B(\mathbf{y}, \mathbf{z})$$

"\( = \)" If the pdf (pmf) can be written as  $p(\mathbf{x}, \mathbf{y}, \mathbf{z}) \propto \phi_A(\mathbf{x}, \mathbf{z}) \phi_B(\mathbf{y}, \mathbf{z})$  then we have  $\mathbf{x} \perp \!\!\! \perp \mathbf{y} \mid \mathbf{z}$ 

equivalent for unconditional version

# Example

Consider 
$$p(x_1, x_2, x_3, x_4) \propto \phi_1(x_1, x_2)\phi_2(x_2, x_3)\phi_3(x_4)$$

What independencies does p satisfy?

We can write

$$p(x_1, x_2, x_3, x_4) \propto \underbrace{[\phi_1(x_1, x_2)\phi_2(x_2, x_3)]}_{\tilde{\phi}_1(x_1, x_2, x_3)} [\phi_3(x_4)]$$
$$\propto \tilde{\phi}_1(x_1, x_2, x_3)\phi_3(x_4)$$

so that  $x_4 \perp \!\!\! \perp x_1, x_2, x_3$ .

► Integrating out x<sub>4</sub> gives

$$p(x_1, x_2, x_3) = \int p(x_1, x_2, x_3, x_4) dx_4 \propto \phi_1(x_1, x_2) \phi_2(x_2, x_3)$$

so that  $x_1 \perp \!\!\! \perp x_3 \mid x_2$ 

#### Gibbs distributions

 Example is a special case of a class of pdfs/pmfs that factorise as

$$p(x_1,\ldots,x_d)=\frac{1}{Z}\prod_c\phi_c(\mathcal{X}_c)$$

- $\lambda_c \subseteq \{x_1,\ldots,x_d\}$
- $\phi_c$  are non-negative factors (potential functions) Do generally not correspond to (conditional) probabilities. They measure "compatibility", "agreement", or "affinity"
- ▶ Z is a normalising constant so that  $p(x_1, ..., x_d)$  integrates (sums) to one.
- Known as Gibbs (or Boltzmann) distributions
- $\tilde{p}(x_1,\ldots,x_d)=\prod_c\phi_c(\mathcal{X}_c)$  is an example of an unnormalised model:  $\tilde{p}\geq 0$  but does not necessarily integrate (sum) to one.

# Energy-based model

▶ With  $\phi_c(\mathcal{X}_c) = \exp(-E_c(\mathcal{X}_c))$ , we have equivalently

$$p(x_1,\ldots,x_d)=\frac{1}{Z}\exp\left[-\sum_c E_c(\mathcal{X}_c)\right]$$

 $\triangleright \sum_c E_c(\mathcal{X}_c)$  is the energy of the configuration  $(x_1, \ldots, x_d)$ . low energy  $\iff$  high probability

## Example

Other examples of Gibbs distributions:

$$p(x_1, ..., x_6) \propto \phi_1(x_1, x_2, x_4) \phi_2(x_2, x_3, x_4) \phi_3(x_3, x_5) \phi_4(x_3, x_6)$$

$$p(x_1, ..., x_6) \propto \phi_1(x_1, x_2) \phi_2(x_2, x_3) \phi_3(x_2, x_5) \phi_4(x_1, x_4) \phi_5(x_4, x_5)$$

$$\phi_6(x_5, x_6) \phi_7(x_3, x_6)$$
?

#### Independencies?

In principle, the independencies follow from

$$\mathbf{x} \perp \!\!\!\perp \mathbf{y} \mid \mathbf{z} \Longleftrightarrow \rho(\mathbf{x}, \mathbf{y}, \mathbf{z}) \propto \phi_A(\mathbf{x}, \mathbf{z}) \phi_B(\mathbf{y}, \mathbf{z})$$

with appropriately defined factors  $\phi_A$  and  $\phi_B$ .

But the mathematical manipulations of grouping together factors and integrating variables out become unwieldy.

Let us use graphs to better see what's going on.

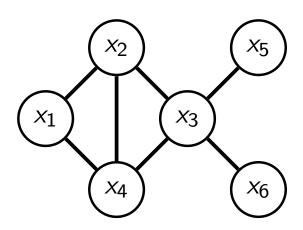
# Visualising Gibbs distributions with undirected graphs

$$p(x_1,\ldots,x_d) \propto \prod_c \phi_c(\mathcal{X}_c)$$

- $\triangleright$  Node for each  $x_i$
- For all factors  $\phi_c$ : draw an undirected edge between all  $x_i$  and  $x_j$  that belong to  $\mathcal{X}_c$
- ▶ Results in a fully-connected subgraph for all  $x_i$  that are part of the same factor (this subgraph is called a clique).

#### Example:

Graph for  $p(x_1, ..., x_6) \propto \phi_1(x_1, x_2, x_4) \phi_2(x_2, x_3, x_4) \phi_3(x_3, x_5) \phi_4(x_3, x_6)$ 



# Effect of conditioning

Let  $p(x_1, ..., x_6) \propto \phi_1(x_1, x_2, x_4) \phi_2(x_2, x_3, x_4) \phi_3(x_3, x_5) \phi_4(x_3, x_6)$ .

- What is  $p(x_1, x_2, x_4, x_5, x_6 | x_3 = \alpha)$ ?
- By definition  $p(x_1, x_2, x_4, x_5, x_6 | x_3 = \alpha)$

$$= \frac{p(x_{1}, x_{2}, x_{3} = \alpha, x_{4}, x_{5}, x_{6})}{\int p(x_{1}, x_{2}, x_{3} = \alpha, x_{4}, x_{5}, x_{6}) dx_{1} dx_{2} dx_{4} dx_{5} dx_{6}}$$

$$= \frac{\phi_{1}(x_{1}, x_{2}, x_{4}) \phi_{2}(x_{2}, \alpha, x_{4}) \phi_{3}(\alpha, x_{5}) \phi_{4}(\alpha, x_{6})}{\int \phi_{1}(x_{1}, x_{2}, x_{4}) \phi_{2}(x_{2}, \alpha, x_{4}) \phi_{3}(\alpha, x_{5}) \phi_{4}(\alpha, x_{6}) dx_{1} dx_{2} dx_{4} dx_{5} dx_{6}}$$

$$= \frac{1}{Z(\alpha)} \phi_{1}(x_{1}, x_{2}, x_{4}) \phi_{2}^{\alpha}(x_{2}, x_{4}) \phi_{3}^{\alpha}(x_{5}) \phi_{4}^{\alpha}(x_{6})$$

- ▶ Gibbs distribution with derived factors  $\phi_i^{\alpha}$  of reduced domain and new normalisation "constant"  $Z(\alpha)$
- ▶ Note that  $Z(\alpha)$  depends on the conditioning value  $\alpha$ .

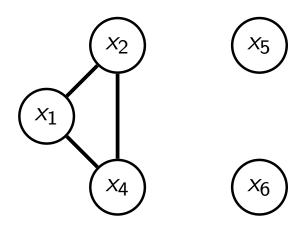
# Effect of conditioning

Let 
$$p(x_1, ..., x_6) \propto \phi_1(x_1, x_2, x_4) \phi_2(x_2, x_3, x_4) \phi_3(x_3, x_5) \phi_4(x_3, x_6)$$
.

• Conditional  $p(x_1, x_2, x_4, x_5, x_6 | x_3 = \alpha)$  is

$$\frac{1}{Z(\alpha)}\phi_1(x_1,x_2,x_4)\phi_2^{\alpha}(x_2,x_4)\phi_3^{\alpha}(x_5)\phi_4^{\alpha}(x_6)$$

 Conditioning on variables removes the corresponding nodes and connecting edges from the undirected graph



## Program

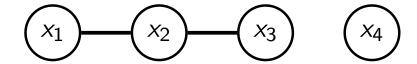
- 1. Representing probability distributions without imposing a directionality between the random variables
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## Program

- 1. Representing probability distributions without imposing a directionality between the random variables
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  - Separation in undirected graphs
  - Statistical independencies from graph separation
  - Global Markov property

# Relating graph properties to independencies

- ► Consider  $p(x_1, x_2, x_3, x_4) \propto \phi_1(x_1, x_2)\phi_2(x_2, x_3)\phi_3(x_4)$  from before
- We have seen:
  - $x_4 \perp \!\!\! \perp x_1, x_2, x_3$
  - $\triangleright$   $x_1 \perp \!\!\!\perp x_3 \mid x_2$
- Graph:

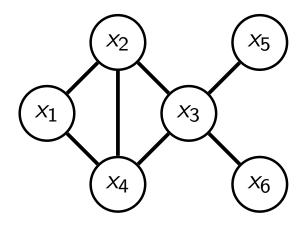


- In the graph,  $x_4$  is separated from  $x_1, x_2, x_3$ . Starting at  $x_4$ , we cannot reach  $x_1, x_2$ , or  $x_3$  (and vice versa). In other words, all trails from  $x_4$  to  $x_1, x_2, x_3$  are "blocked".
- In the graph,  $x_1$  and  $x_3$  are separated by  $x_2$ . In other words, all trails from  $x_1$  to  $x_3$  are blocked by  $x_2$  (when removing  $x_2$  from the graph, we cannot reach  $x_3$  from  $x_1$  and vice versa)

# Relating graph properties to independencies

Example:  $p(x_1,...,x_6) \propto \phi_1(x_1,x_2,x_4)\phi_2(x_2,x_3,x_4)\phi_3(x_3,x_5)\phi_4(x_3,x_6)$ 

Graph:



- ▶  $x_3$  separates  $\{x_1, x_2, x_4\}$  and  $\{x_5, x_6\}$ In other words,  $x_3$  blocks all trails from  $\{x_1, x_2, x_4\}$  to  $\{x_5, x_6\}$
- ▶ Do we have  $x_1, x_2, x_4 \perp \!\!\! \perp x_5, x_6 \mid x_3$ ?

# Relating graph properties to independencies

$$p(x_1,\ldots,x_6) \propto \phi_1(x_1,x_2,x_4)\phi_2(x_2,x_3,x_4)\phi_3(x_3,x_5)\phi_4(x_3,x_6)$$

- ▶ Do we have  $x_1, x_2, x_4 \perp \!\!\! \perp x_5, x_6 \mid x_3$ ?
- Group the factors

$$p(x_1,\ldots,x_6) \propto \underbrace{\phi_1(x_1,x_2,x_4)\phi_2(x_2,x_3,x_4)}_{\phi_A(x_1,x_2,x_4,x_3)} \underbrace{\phi_3(x_3,x_5)\phi_4(x_3,x_6)}_{\phi_B(x_5,x_6,x_3)}$$

Takes the form

$$p(\mathbf{x}, \mathbf{y}, \mathbf{z}) \propto \phi_A(\mathbf{x}, \mathbf{z}) \phi_B(\mathbf{y}, \mathbf{z})$$

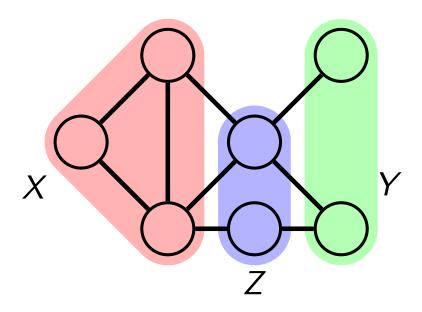
with 
$$\mathbf{x} = (x_1, x_2, x_4), \ \mathbf{y} = (x_5, x_6), \ \mathbf{z} = x_3$$

► Hence:  $x_1, x_2, x_4 \perp \!\!\!\perp x_5, x_6 \mid x_3$  holds indeed.

# Separation in undirected graphs

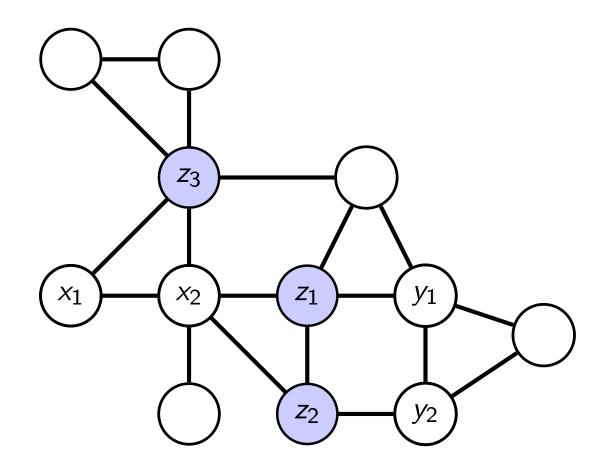
Let X, Y, Z be three disjoint set of nodes in an undirected graph.

- $\blacktriangleright$  X and Y are separated by Z if every trail from any node in X to any node in Y passes through at least one node of Z.
- ► In other words:
  - all trails from X to Y are blocked by Z
  - ightharpoonup removing Z from the graph leaves X and Y disconnected.
  - $\triangleright$  Nodes are valves; open by default but closed when part of Z.



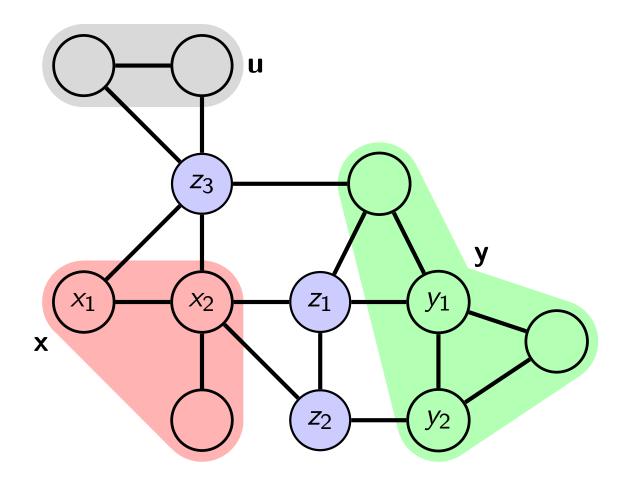
Assume  $p(x_1, ..., x_d) \propto \prod_c \phi_c(\mathcal{X}_c)$ , with  $\mathcal{X}_c \subset \{x_1, ..., x_d\}$  can be visualised as the graph below.

Do we have  $x_1, x_2 \perp \!\!\!\perp y_1, y_2 \mid z_1, z_2, z_3$ ?



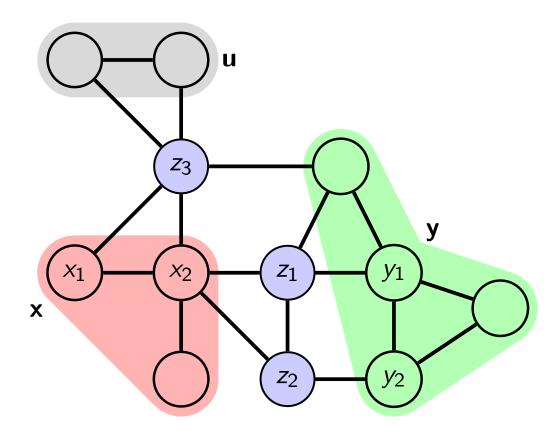
Assume  $p(x_1, ..., x_d) \propto \prod_c \phi_c(\mathcal{X}_c)$ , with  $\mathcal{X}_c \subset \{x_1, ..., x_d\}$  can be visualised as the graph below.

Do we have  $\mathbf{x} \perp \mathbf{y} \mid z_1, z_2, z_3$ ?



- ▶ With  $\mathbf{z} = (z_1, z_2, z_3)$ , all  $x_i$  belong to one of the  $\mathbf{x}, \mathbf{y}, \mathbf{z}$ , or  $\mathbf{u}$ .
- ▶ We thus have  $p(x_1,...,x_d) = p(\mathbf{x},\mathbf{y},\mathbf{z},\mathbf{u})$  and we can group the factors  $\phi_c$  together so that

$$p(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}) \propto \phi_1(\mathbf{x}, \mathbf{z}) \phi_2(\mathbf{y}, \mathbf{z}) \phi_3(\mathbf{u}, \mathbf{z})$$



► Integrating (summing) out **u** gives

$$p(\mathbf{x}, \mathbf{y}, \mathbf{z}) = \sum_{\mathbf{u}} p(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u})$$
 (1)

$$\propto \sum_{\mathbf{u}} \phi_1(\mathbf{x}, \mathbf{z}) \phi_2(\mathbf{y}, \mathbf{z}) \phi_3(\mathbf{u}, \mathbf{z})$$
 (2)

(distributive law) 
$$\propto \phi_1(\mathbf{x}, \mathbf{z})\phi_2(\mathbf{y}, \mathbf{z}) \sum_{\mathbf{u}} \phi_3(\mathbf{u}, \mathbf{z})$$
 (3)

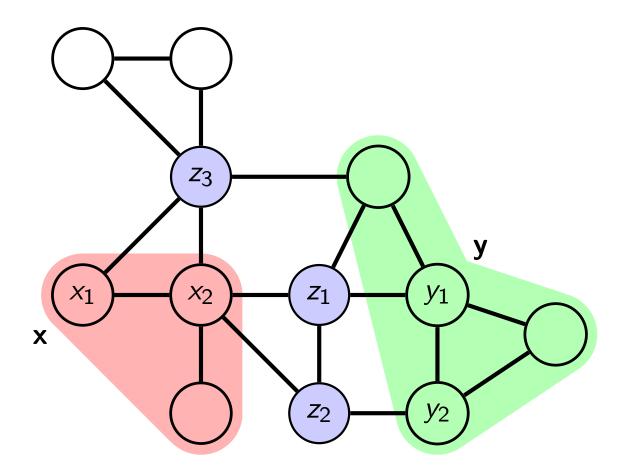
$$\propto \phi_1(\mathbf{x}, \mathbf{z})\phi_2(\mathbf{y}, \mathbf{z})\tilde{\phi}(\mathbf{z})$$
 (4)

$$\propto \phi_A(\mathbf{x}, \mathbf{z})\phi_B(\mathbf{y}, \mathbf{z})$$
 (5)

► And  $p(\mathbf{x}, \mathbf{y}, \mathbf{z}) \propto \phi_A(\mathbf{x}, \mathbf{z}) \phi_B(\mathbf{y}, \mathbf{z})$  means  $\mathbf{x} \perp \!\!\! \perp \mathbf{y} \mid \mathbf{z}$ 

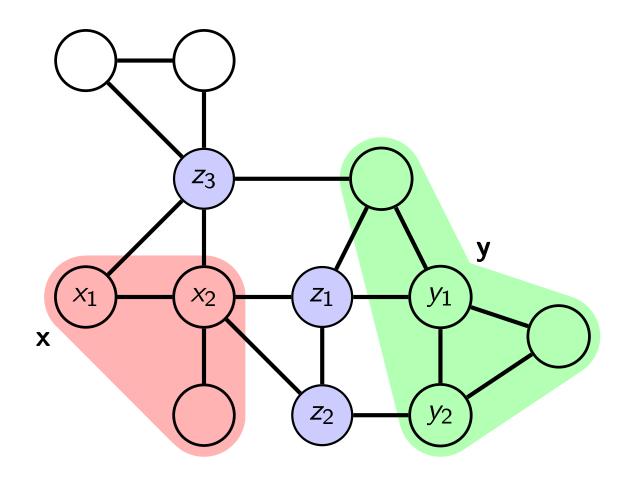
Assume  $p(x_1, ..., x_d) \propto \prod_c \phi_c(\mathcal{X}_c)$ , with  $\mathcal{X}_c \subset \{x_1, ..., x_d\}$  can be visualised as the graph below.

We have shown that if  $\mathbf{x}$  and  $\mathbf{y}$  are separated by  $\mathbf{z}$ , then  $\mathbf{x} \perp \!\!\! \perp \mathbf{y} \mid \mathbf{z}$ .

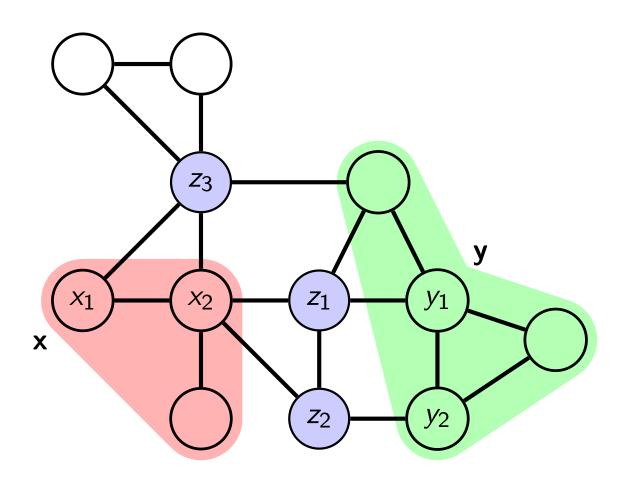


Assume  $p(x_1, ..., x_d) \propto \prod_c \phi_c(\mathcal{X}_c)$ , with  $\mathcal{X}_c \subset \{x_1, ..., x_d\}$  can be visualised as the graph below.

So do we have  $x_1, x_2 \perp \!\!\!\perp y_1, y_2 \mid z_1, z_2, z_3$ ?



- From tutorial:  $x \perp \!\!\!\perp \{y, w\} \mid z \text{ implies } x \perp \!\!\!\perp y \mid z$
- ► Hence  $\mathbf{x} \perp \!\!\! \perp \mathbf{y} \mid z_1, z_2, z_3$  implies  $x_1, x_2 \perp \!\!\! \perp y_1, y_2 \mid z_1, z_2, z_3$ .



# Summary

#### Theorem:

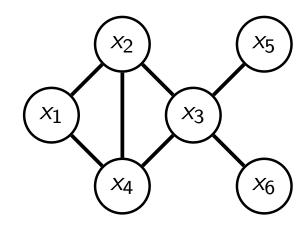
Let G be the undirected graph for  $p(x_1, \ldots, x_d) \propto \prod_c \phi_c(\mathcal{X}_c)$ , and X, Y, Z three disjoint subsets of  $\{x_1, \ldots, x_d\}$ . If X and Y are separated by Z in G, then p is such that  $X \perp\!\!\!\perp Y \mid Z$ .

#### Remarks:

- 1. the theorem allows us to read out (conditional) independencies from the undirected graph
- 2. the independencies detected by graph separation are "true positives". But  $p(x_1, \ldots, x_d)$  may satisfy additional independencies that are not captured by graph separation. (not a "if and only if" statement. Consider e.g. the example that we used to illustrate that d-connected variables may be independent)
- We say that  $p(x_1, ..., x_d)$  satisfies the global Markov property relative to G.

# Example

- $p(x_1,\ldots,x_6) \propto \phi_1(x_1,x_2,x_4)\phi_2(x_2,x_3,x_4)\phi_3(x_3,x_5)\phi_4(x_3,x_6)$
- Graph



Example independencies:

$$x_1 \perp \!\!\! \perp \{x_3, x_5, x_6\} \mid x_2, x_4 \qquad x_2 \perp \!\!\! \perp x_6 \mid x_3 \qquad x_5 \perp \!\!\! \perp x_6 \mid x_3$$

$$x_2 \perp \!\!\! \perp x_6 \mid x_3$$

$$x_5 \perp \!\!\! \perp x_6 \mid x_3$$

## Program recap

- 1. Representing probability distributions without imposing a directionality between the random variables
  - Factorisation and statistical independence
  - Gibbs distributions
  - Visualising Gibbs distributions with undirected graphs
  - Conditioning corresponds to removing nodes and edges from the graph
- 2. Separation in undirected graphs and statistical independencies
  - Separation in undirected graphs
  - Statistical independencies from graph separation
  - Global Markov property