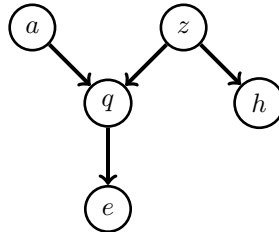


Exercise 1. *More on ordered and local Markov properties, d-separation*

We continue with the investigation of the graph below

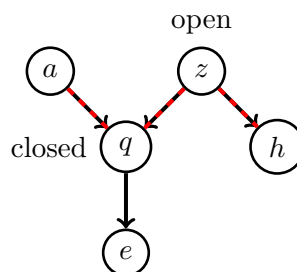


- (a) Why can the ordered or local Markov property not be used to check whether $a \perp\!\!\!\perp h \mid e$ may hold?

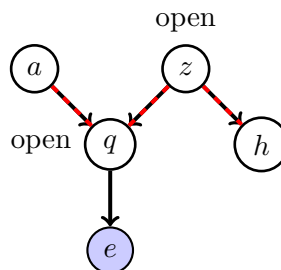
Solution. The independencies that follow from the ordered or local Markov property require conditioning on parent sets. However, e is not a parent of any node so that the above independence assertion cannot be checked via the ordered or local Markov property.

- (b) Use d-separation to check whether $a \perp\!\!\!\perp h \mid e$ holds.

Solution. The trail from a to h is shown below in red together with the default states of the nodes along the trail.



Conditioning on e opens the q node since q is in a collider configuration on the path.



The trail from a to h is thus active, which means that the relationship does not hold because $a \not\perp\!\!\!\perp h \mid e$ for some distributions that factorise over the graph.

- (c) The independency relations obtained via the ordered and local Markov property include $a \perp\!\!\!\perp \{z, h\}$. Verify the independency using d-separation.

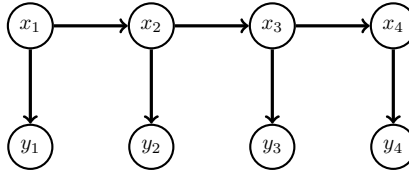
Solution. All paths from a to z or h pass through the node q that forms a head-head connection along that trail. Since neither q nor its descendant e is part of the conditioning set, the trail is blocked and the independence relation follows.

(d) Determine the Markov blanket of z .

Solution. The Markov blanket is given by the parents, children, and co-parents. Hence: $\text{MB}(z) = \{a, q, h\}$.

Exercise 2. Hidden Markov models

This exercise is about directed graphical models that are specified by the following DAG:



These models are called “hidden” Markov models because we typically assume to only observe the y_i and not the x_i that follow a Markov model.

(a) Show that all probabilistic models specified by the DAG factorise as

$$p(x_1, y_1, x_2, y_2, \dots, x_4, y_4) = p(x_1)p(y_1|x_1)p(x_2|x_1)p(y_2|x_2)p(x_3|x_2)p(y_3|x_3)p(x_4|x_3)p(y_4|x_4)$$

Solution. From the definition of directed graphical models it follows that

$$p(x_1, y_1, x_2, y_2, \dots, x_4, y_4) = \prod_{i=1}^4 p(x_i | \text{pa}(x_i)) \prod_{i=1}^4 p(y_i | \text{pa}(y_i)).$$

The result is then obtained by noting that the parent of y_i is given by x_i for all i , and that the parent of x_i is x_{i-1} for $i = 2, 3, 4$ and that x_1 does not have a parent ($\text{pa}(x_1) = \emptyset$).

(b) Derive the independencies implied by the ordered Markov property with the topological ordering $(x_1, y_1, x_2, y_2, x_3, y_3, x_4, y_4)$

Solution.

$$y_i \perp\!\!\!\perp x_1, y_1, \dots, x_{i-1}, y_{i-1} \mid x_i \quad x_i \perp\!\!\!\perp x_1, y_1, \dots, x_{i-2}, y_{i-2}, y_{i-1} \mid x_{i-1}$$

(c) Derive the independencies implied by the ordered Markov property with the topological ordering $(x_1, x_2, \dots, x_4, y_1, \dots, y_4)$.

Solution. For the x_i , we use that for $i \geq 2$: $\text{pre}(x_i) = \{x_1, \dots, x_{i-1}\}$ and $\text{pa}(x_i) = x_{i-1}$. For the y_i , we use that $\text{pre}(y_1) = \{x_1, \dots, x_4\}$, that $\text{pre}(y_i) = \{x_1, \dots, x_4, y_1, \dots, y_{i-1}\}$ for $i > 1$, and that $\text{pa}(y_i) = x_i$. The ordered Markov property then gives:

$$\begin{array}{ll} x_3 \perp\!\!\!\perp x_1 \mid x_2 & x_4 \perp\!\!\!\perp \{x_1, x_2\} \mid x_3 \\ y_1 \perp\!\!\!\perp \{x_2, x_3, x_4\} \mid x_1 & y_2 \perp\!\!\!\perp \{x_1, x_3, x_4, y_1\} \mid x_2 \\ y_3 \perp\!\!\!\perp \{x_1, x_2, x_4, y_1, y_2\} \mid x_3 & y_4 \perp\!\!\!\perp \{x_1, x_2, x_3, y_1, y_2, y_3\} \mid x_4 \end{array}$$

Exercise 3. More on the chest clinic (based on Barber's exercise 3.3)

The directed graphical model in Figure 1 is the “Asia” example of Lauritzen and Spiegelhalter (1988). It concerns the diagnosis of lung disease (T =tuberculosis or L =lung cancer). In this model, a visit to some place in A =Asia is thought to increase the probability of tuberculosis.

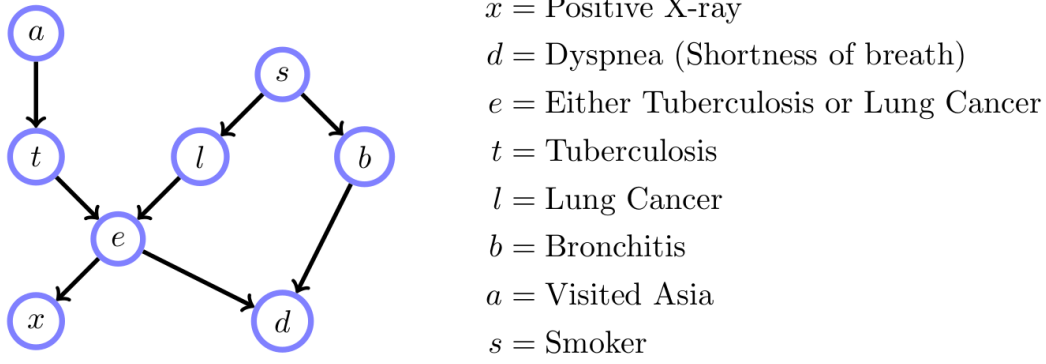


Figure 1: Graphical model for Exercise 3 (Barber Figure 3.15).

(a) Explain which of the following independence relationships hold for all distributions that factorise over the graph.

1. $a \perp\!\!\!\perp s \mid l$

Solution.

- There are two trails from a to s : (a, t, e, l, s) and (a, t, e, d, b, s)
- The trail (a, t, e, l, s) features a collider node e that blocks the trail (the trail is also blocked by l).
- The trail (a, t, e, d, b, s) is blocked by the collider node d .
- All trails are blocked so that the independence relation holds.

2. $a \perp\!\!\!\perp s \mid l, d$

Solution.

- There are two trails from a to s : (a, t, e, l, s) and (a, t, e, d, b, s)
- The trail (a, t, e, l, s) features a collider node e that is opened by the conditioning variable d but the l node is closed by the conditioning variable l : the trail is blocked

- The trail (a, t, e, d, b, s) features a collider node d that is opened by conditioning on d . On this trail, e is not in a head-head (collider) configuration) so that all nodes are open and the trail active.
- Hence, the independence relation does generally not hold.

(b) Let g be a (deterministic) function of x and t . Is the expected value $\mathbb{E}[g(x, t) \mid l, b]$ equal to $\mathbb{E}[g(x, t) \mid l]$?

Solution. The question boils down to checking whether $x, t \perp\!\!\!\perp b \mid l$. For the independence relation to hold, all trails from both x and t to b need to be blocked by l .

- For x , we have the trails (x, e, l, s, b) and (x, e, d, b)
- Trail (x, e, l, s, b) is blocked by l
- Trail (x, e, d, b) is blocked by the collider configuration of node d .
- For t , we have the trails (t, e, l, s, b) and (t, e, d, b)
- Trail (t, e, l, s, b) is blocked by l .
- Trail (t, e, d, b) is blocked by the collider configuration of node d .

As all trails are blocked we have $x, t \perp\!\!\!\perp b \mid l$ and $\mathbb{E}[g(x, t) \mid l, b] = \mathbb{E}[g(x, t) \mid l]$.

Exercise 4. *Independencies*

This exercise is on further properties and characterisations of statistical independence.

(a) Without using d -separation, show that $x \perp\!\!\!\perp \{y, w\} \mid z$ implies that $x \perp\!\!\!\perp y \mid z$ and $x \perp\!\!\!\perp w \mid z$.
Hint: use the definition of statistical independence in terms of the factorisation of pmfs/pdfs.

Solution. We consider the joint distribution $p(x, y, w \mid z)$. By assumption

$$p(x, y, w \mid z) = p(x \mid z)p(y, w \mid z) \quad (\text{S.1})$$

We have to show that $x \perp\!\!\!\perp y \mid z$ and $x \perp\!\!\!\perp w \mid z$. For simplicity, we assume that the variables are discrete valued. If not, replace the sum below with an integral.

To show that $x \perp\!\!\!\perp y \mid z$, we marginalise $p(x, y, w \mid z)$ over w to obtain

$$p(x, y \mid z) = \sum_w p(x, y, w \mid z) \quad (\text{S.2})$$

$$= \sum_w p(x \mid z)p(y, w \mid z) \quad (\text{S.3})$$

$$= p(x \mid z) \sum_w p(y, w \mid z) \quad (\text{S.4})$$

Since $\sum_w p(y, w \mid z)$ is the marginal $p(y \mid z)$, we have

$$p(x, y \mid z) = p(x \mid z)p(y \mid z), \quad (\text{S.5})$$

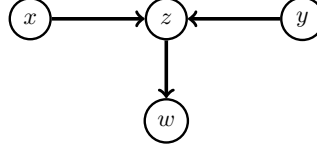
which means that $x \perp\!\!\!\perp y \mid z$.

To show that $x \perp\!\!\!\perp w \mid z$, we similarly marginalise $p(x, y, w \mid z)$ over y to obtain $p(x, w \mid z) = p(x \mid z)p(w \mid z)$, which means that $x \perp\!\!\!\perp w \mid z$.

- (b) For the directed graphical model below, show that the following two statements hold without using d-separation:

$$x \perp\!\!\!\perp y \quad \text{and} \quad (1)$$

$$x \not\perp\!\!\!\perp y \mid w \quad (2)$$



The exercise shows that not only conditioning on a collider node but also on one of its descendants activates the trail between x and y . You can use the result that $x \perp\!\!\!\perp y \mid w \Leftrightarrow p(x, y, w) = a(x, w)b(y, w)$ for some non-negative functions $a(x, w)$ and $b(y, w)$.

Solution. The graphical model corresponds to the factorisation

$$p(x, y, z, w) = p(x)p(y)p(z|x, y)p(w|z).$$

For the marginal $p(x, y)$ we have to sum (integrate) over all (z, w)

$$p(x, y) = \sum_{z, w} p(x, y, z, w) \quad (\text{S.6})$$

$$= \sum_{z, w} p(x)p(y)p(z|x, y)p(w|z) \quad (\text{S.7})$$

$$= p(x)p(y) \sum_{z, w} p(z|x, y)p(w|z) \quad (\text{S.8})$$

$$= p(x)p(y) \underbrace{\sum_z p(z|x, y)}_1 \underbrace{\sum_w p(w|z)}_1 \quad (\text{S.9})$$

$$= p(x)p(y) \quad (\text{S.10})$$

Since $p(x, y) = p(x)p(y)$ we have $x \perp\!\!\!\perp y$.

For $x \not\perp\!\!\!\perp y \mid w$, compute $p(x, y, w)$ and use the result $x \perp\!\!\!\perp y \mid w \Leftrightarrow p(x, y, w) = a(x, w)b(y, w)$.

$$p(x, y, w) = \sum_z p(x, y, z, w) \quad (\text{S.11})$$

$$= \sum_z p(x)p(y)p(z|x, y)p(w|z) \quad (\text{S.12})$$

$$= p(x)p(y) \underbrace{\sum_z p(z|x, y)p(w|z)}_{k(x, y, w)} \quad (\text{S.13})$$

Since $p(x, y, w)$ cannot be factorised as $a(x, w)b(y, w)$, the relation $x \perp\!\!\!\perp y \mid w$ cannot generally hold.