

Generalization

$$E_{\text{gen}} = \mathbb{E}_{p(x, y)} [L(y, f(x))] \quad \checkmark \text{ Loss function}$$

$$\approx \frac{1}{M} \sum_{m=1}^M L(y^{(m)}, f(x^{(m)}))$$

$$= E_{\text{test}}$$

Assume: M held-out test examples $x^{(m)}, y^{(m)} \sim p(x, y)$

Model $f(\cdot)$ and $\{x^{(m)}, y^{(m)}\}$ independent

\Rightarrow Model not chosen using E_{test}

Validation / Development set(s) to make choices

Eg, fit w on training set for $\lambda = 0.1, 1, 10$,

Pick from these 3 models using validation los.

\rightarrow "Fit λ to validation set"



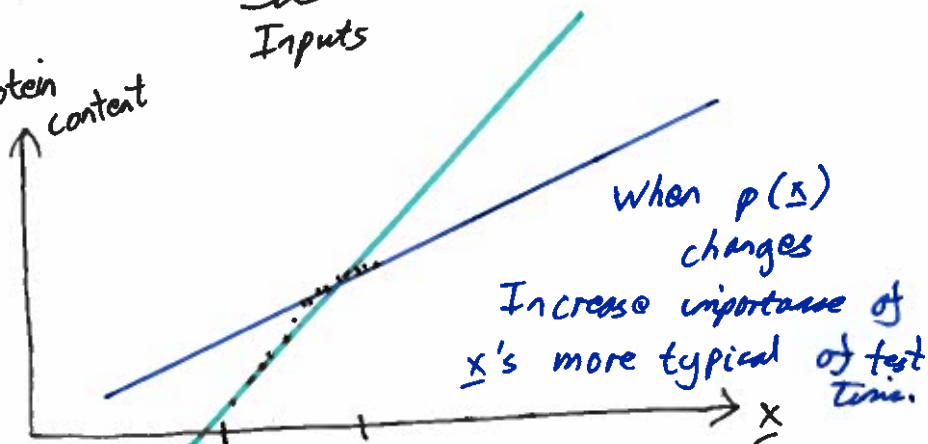
How do we deal with $p(\underline{x}, y)$ changing?

Answer: it depends

$$p(\underline{x}, y) = \underbrace{p(\underline{x})}_{\text{Inputs}} p(y|\underline{x})$$

Noisy mapping
between inputs
and outputs

y , protein
content



→ Training \underline{x} 's ←

Genome of wheat

→ Test \underline{x} 's ←

What $p(y|\underline{x})$ changes?

Need some information about change...

More data in future, or more "inputs" to model, eg. time

Amos Storkey has review

How do we avoid fitting test set?

- Reduce amount we look at test set
also at validation set.
or have huge validation set
- More than one validation set?

k-fold cross validation



Train data
Split into k
pieces.

validation
training

Average validation scores across folds

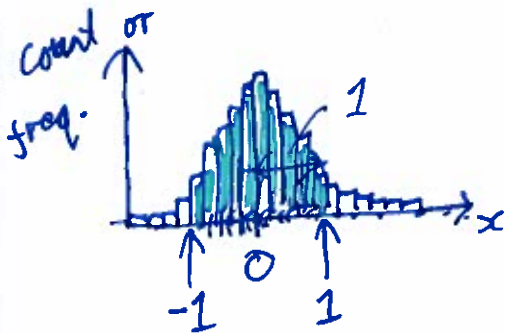
Gaussian (Univariate)

Draw 10^6 values

$$x_n \sim N(0, 1)$$

↖ randn

↑
mean



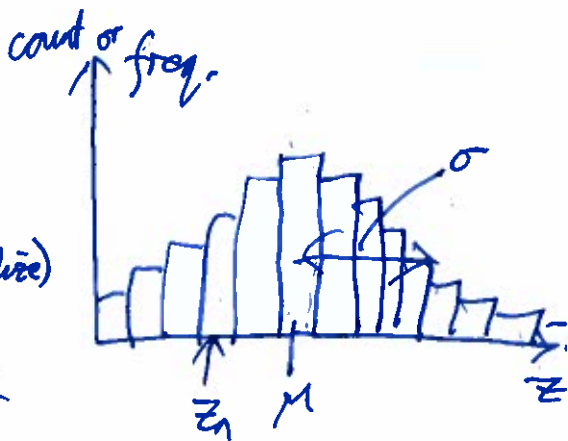
~ 68% of area
within ± 1

~ 95% within ± 2

$$z_n = \sigma x_n + \mu$$

$$x_n = \frac{z_n - \mu}{\sigma}$$

(standardize)



Variance of z points

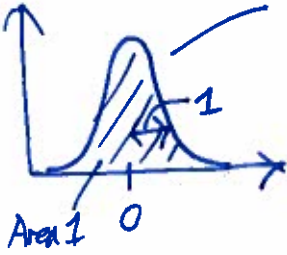
is σ^2

Mean of points is μ

$$z_n \sim N(\mu, \sigma^2)$$

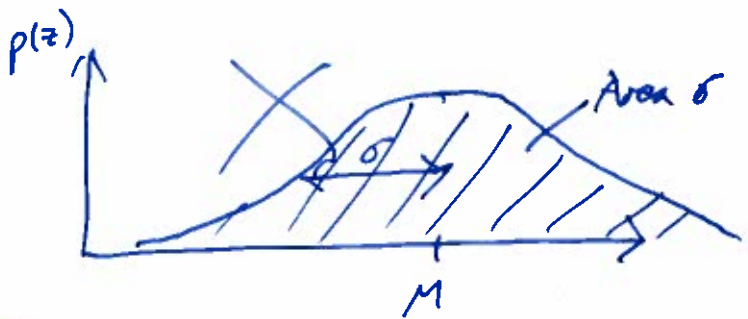
variance ↗

$p(x)$

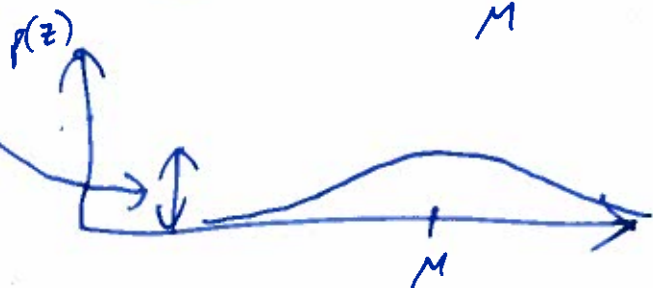


$$p(x) = N(x; 0, 1) = \frac{1}{\sqrt{2\pi}} e^{-x^2/2}$$

$$p(z) = N(z; \mu, \sigma^2) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{1}{2}\left(\frac{z-\mu}{\sigma}\right)^2}$$

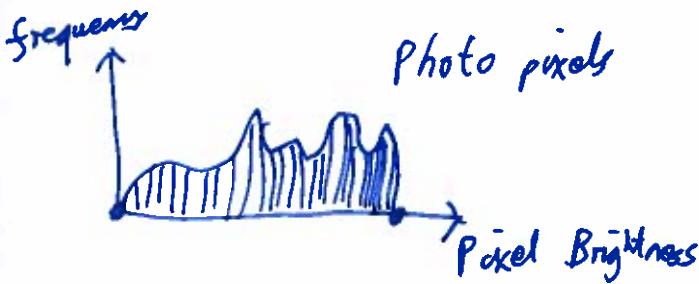


decrease by σ



"Jacobian of the transform"

Not every distribution is Gaussian



Central Limit Theorem (CLT)

If x is a sum of

N (many)

independent outcomes

each finite mean and variance

$x \rightarrow$ Gaussian, as $N \rightarrow \infty$