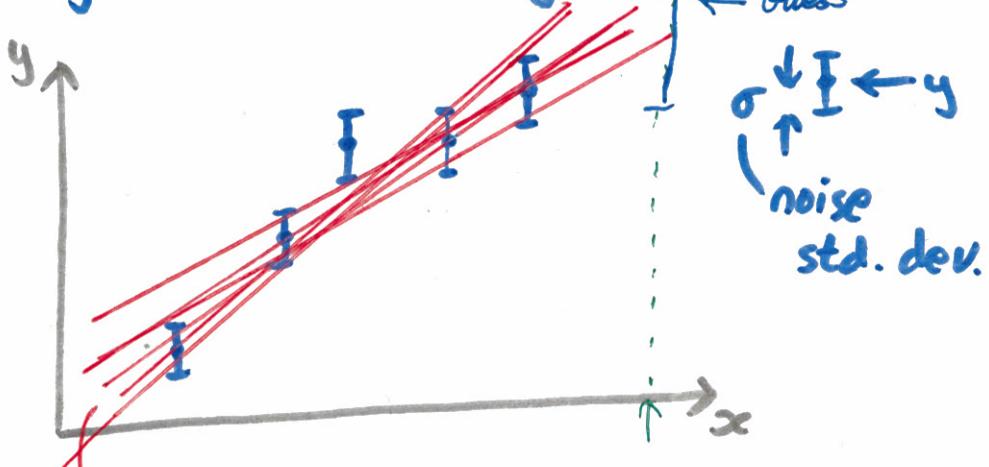
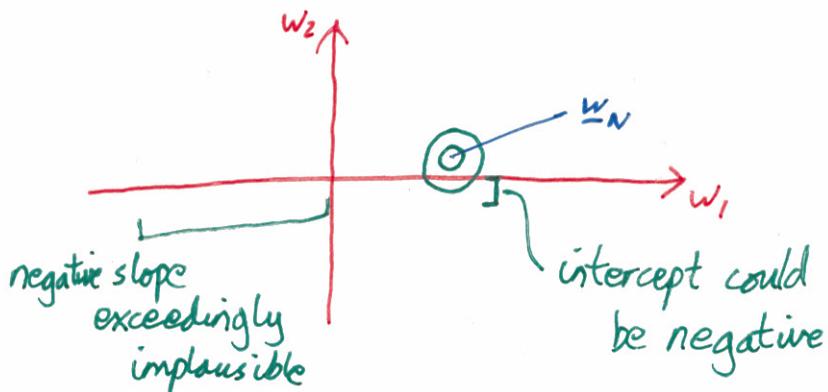


Bayesian Linear Regression



Posterior distribution gives plausibility of fits:



B | B
②

B | W
①

W | W
③

3 cards

Pick card at random

Pick a random side

Observe $x_1 = B$ observation of side 1

Q) $P(x_2 = W | x_1 = B)$?

Prob. other side of card is white

- A) $\frac{1}{3}$ B) $\frac{1}{2}$ C) $\frac{2}{3}$ D) other

~~Z)~~ ^{to}
~~Don't~~
know

What not to do

$$P(x_2 = w | x_1 = B) = \frac{P(x_1 = B | x_2 = w) P(x_2 = w)}{P(x_1 = B)}$$

Don't know!

First step: write down model

Picked a card:

$$P(c) = \begin{cases} Y_3 & c=1 \\ Y_3 & c=2 \\ Y_3 & c=3 \end{cases} \quad \begin{matrix} B|W \\ B|B \\ W|W \end{matrix}$$

Observed face 1:

$$P(x_1 = B | c) = \begin{cases} Y_2 & c=1 \\ 1 & c=2 \\ 0 & c=3 \end{cases}$$

Inference

$$P(c | x_1 = B) \propto p(x_1 = B | c) P(c)$$

$$\propto \begin{cases} Y_2 & c=1 \\ 1 & c=2 \\ 0 & c=3 \end{cases}$$

$$= \begin{cases} Y_3 & c=1 \\ 2/3 & c=2 \end{cases}$$

Aside : another example



6 sided
Die



D10
Ten sided
Die



D100
100-sided
Die.

Pick random die:

Roll it \rightarrow get an 8.

Making a prediction

$$\begin{aligned}
 P(x_2=w|x_1=B) &= \sum_{C \in \{1, 2, 3\}} P(x_2=w, c|x_1=B) \\
 &= \sum_c P(x_2=w|x_1=B, c) P(c|x_1=B) \\
 &= \frac{1}{3}
 \end{aligned}
 \quad (\text{sum rule}) \quad (\text{Product Rule})$$

Prediction for Linear Regression

What's Train. Data $\{\mathbf{x}, y\}$

$$\begin{aligned}
 p(y|\mathbf{x}, D) &= \int p(y, \underline{w}|\mathbf{x}, D) d\underline{w} \\
 &= \int \underbrace{p(y|\mathbf{x}, \underline{w}, D)}_{N(y; \underline{w}^T \mathbf{x}, \sigma^2)} \underbrace{p(\underline{w}|D, \mathbf{x})}_{\text{Posterior over weights}} d\underline{w} \\
 &\quad (\text{sum rule}) \\
 &\quad (\text{Product rule})
 \end{aligned}$$

$N(y; \underline{w}^T \mathbf{x}, \sigma^2)$
↑
noise var.

$N(\underline{w}; \underline{w}_N, V_N)$

$$P(y|\underline{x}, D) = \underbrace{\int p(y, \underline{w}|\underline{x}, D) d\underline{w}}_{\text{Joint Gaussian on } y, \underline{w}}$$

→ = $N\left(\begin{bmatrix} \underline{w} \\ y \end{bmatrix}; \begin{bmatrix} \underline{w}_N \\ m_y \end{bmatrix}, \begin{bmatrix} V_N & \Sigma_{y,\underline{w}} \\ \Sigma_{y,\underline{w}} & \sigma_y^2 \end{bmatrix}\right)$

$= N(y; \underbrace{m_y, \sigma_y^2}_{\text{Lots of work to identify these.}})$

...
YUCK!

Instead

$$y = f(\underline{x}) + v, \quad v \sim N(0, \sigma^2)$$

What do we believe about f value

$$f = \underline{w}^\top \underline{x} = \underline{x}^\top \underline{w}$$

Beliefs are Gaussian

Beliefs about
 $p(\underline{w} | D) = N(\underline{w}; \underline{w}_N, V_N)$

$$p(f | D_x) = N(f; \underline{x}^\top \underline{w}_N; \underline{x}^\top V_N \underline{x})$$

Beliefs about prediction

$$p(y | D_x) = N(y; \underbrace{\underline{x}^\top \underline{w}_N}_{\text{Posterior mean weights}}; \underline{x}^\top V_N \underline{x} + \sigma^2)$$

Posterior mean
weights