

# Generative adversarial networks

Hakan Bilen

Machine Learning Practical - MLP Lecture 16

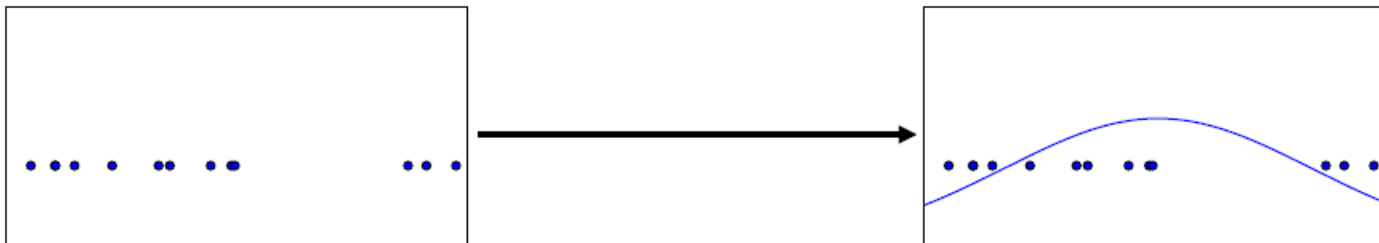
11 February 2019

<http://www.inf.ed.ac.uk/teaching/courses/mlp/>

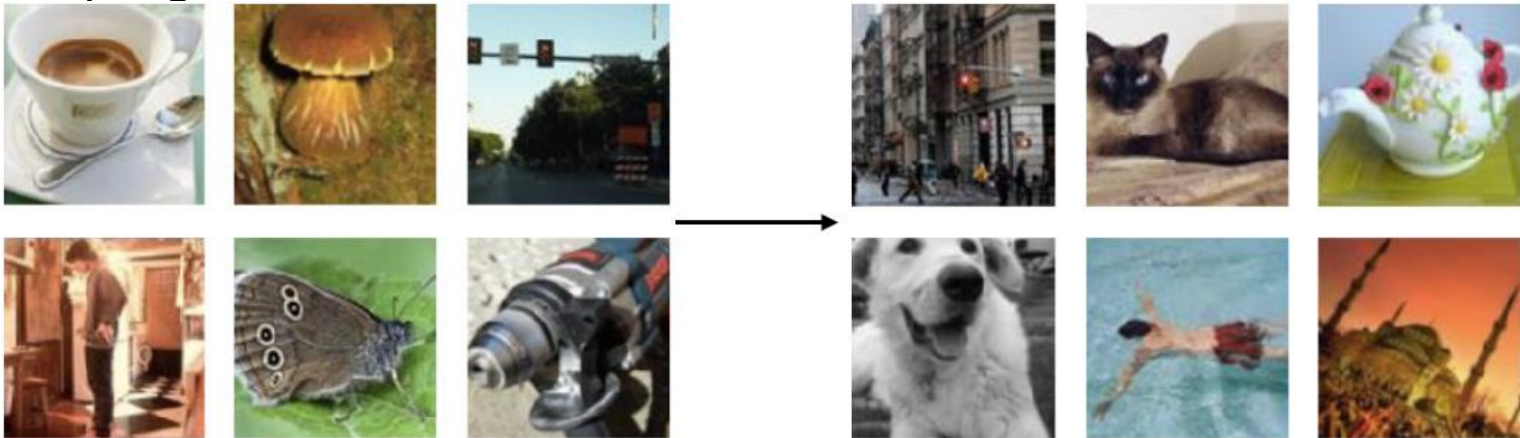
Slide credits: Ian Goodfellow

# Generative modeling

- Density estimation



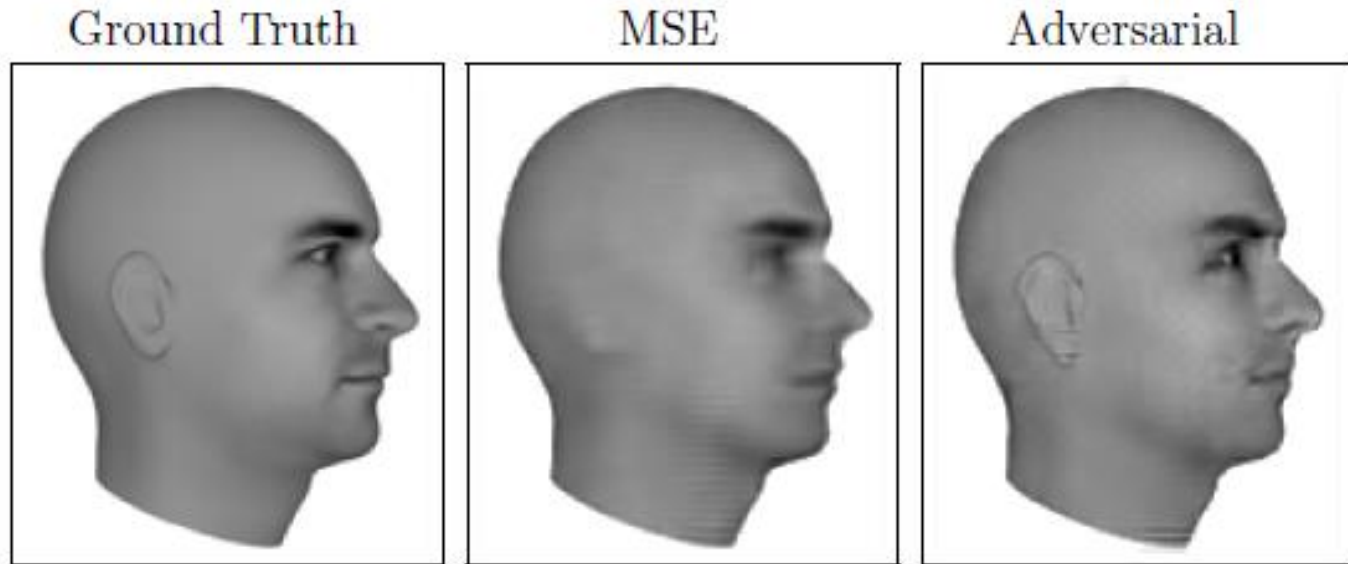
- Sample generation



# Why are generative models useful?

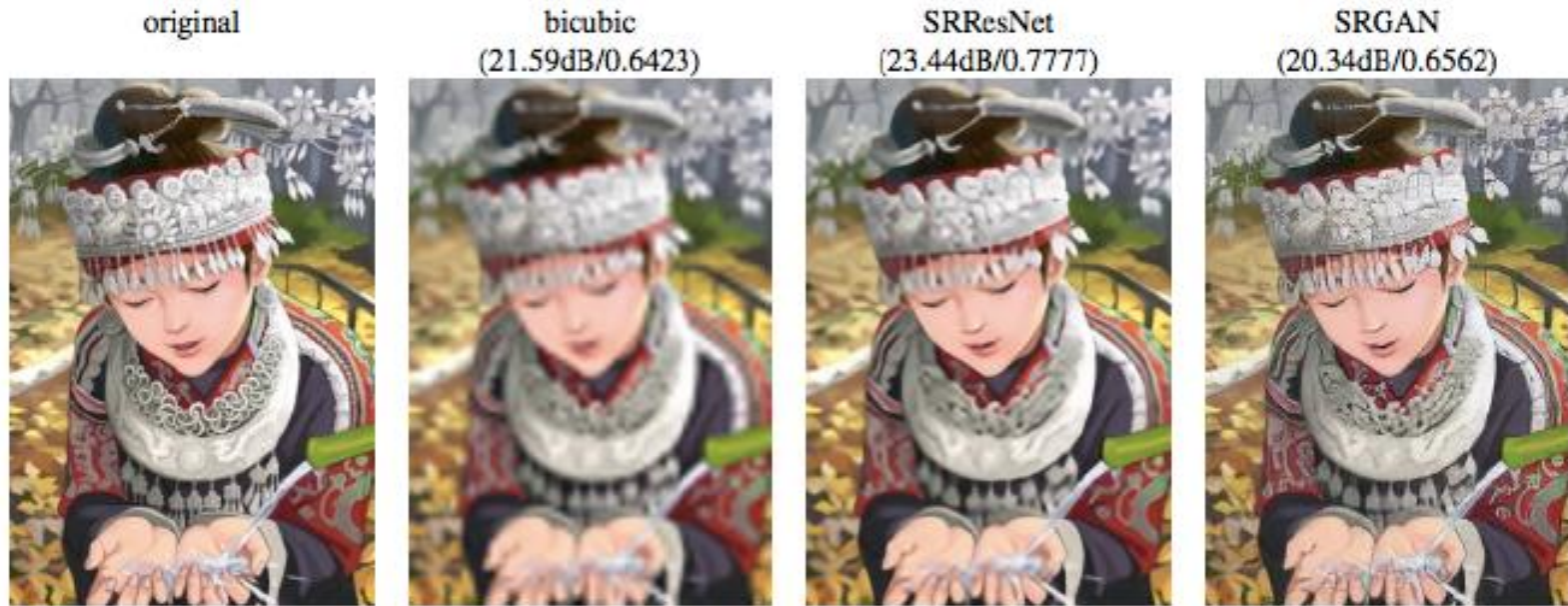
- Test of our intellectual ability to use high dimensional probability distributions
- Learn from simulated data and transfer it to real world
- Complete missing data (including multi-modal)
- Realistic generation tasks (image and speech)

# Next video frame prediction

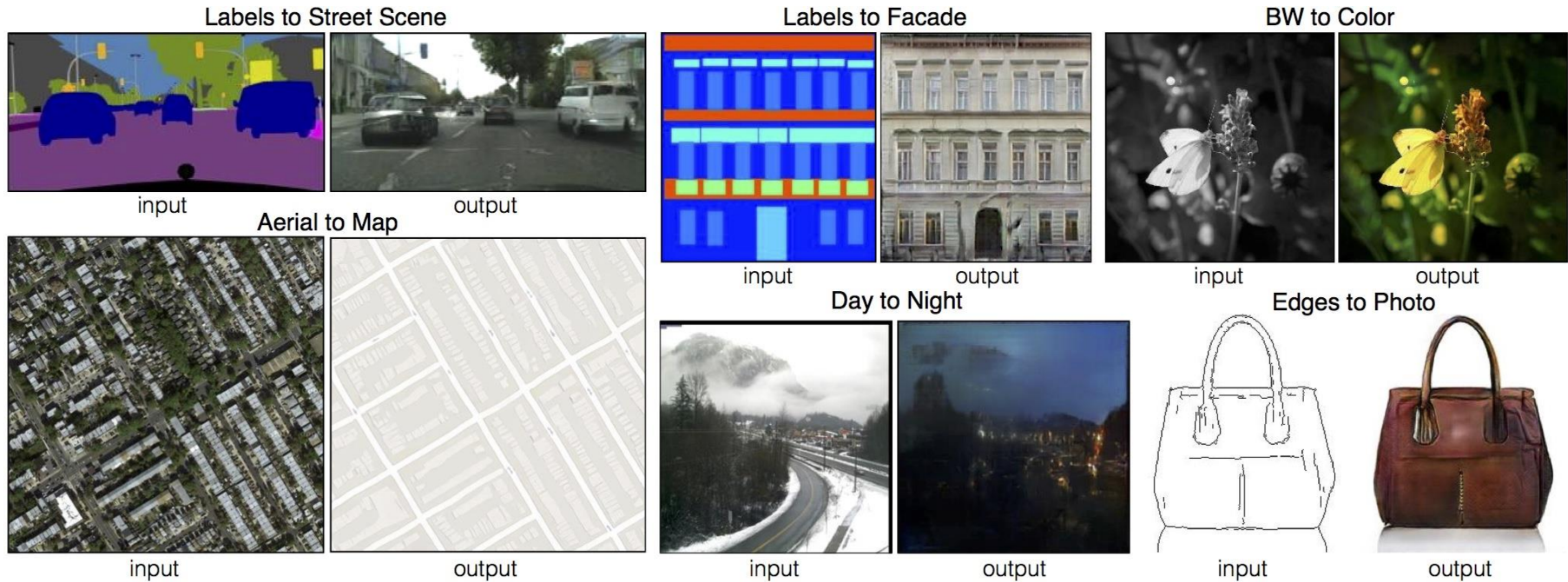


Lotter et al 2016

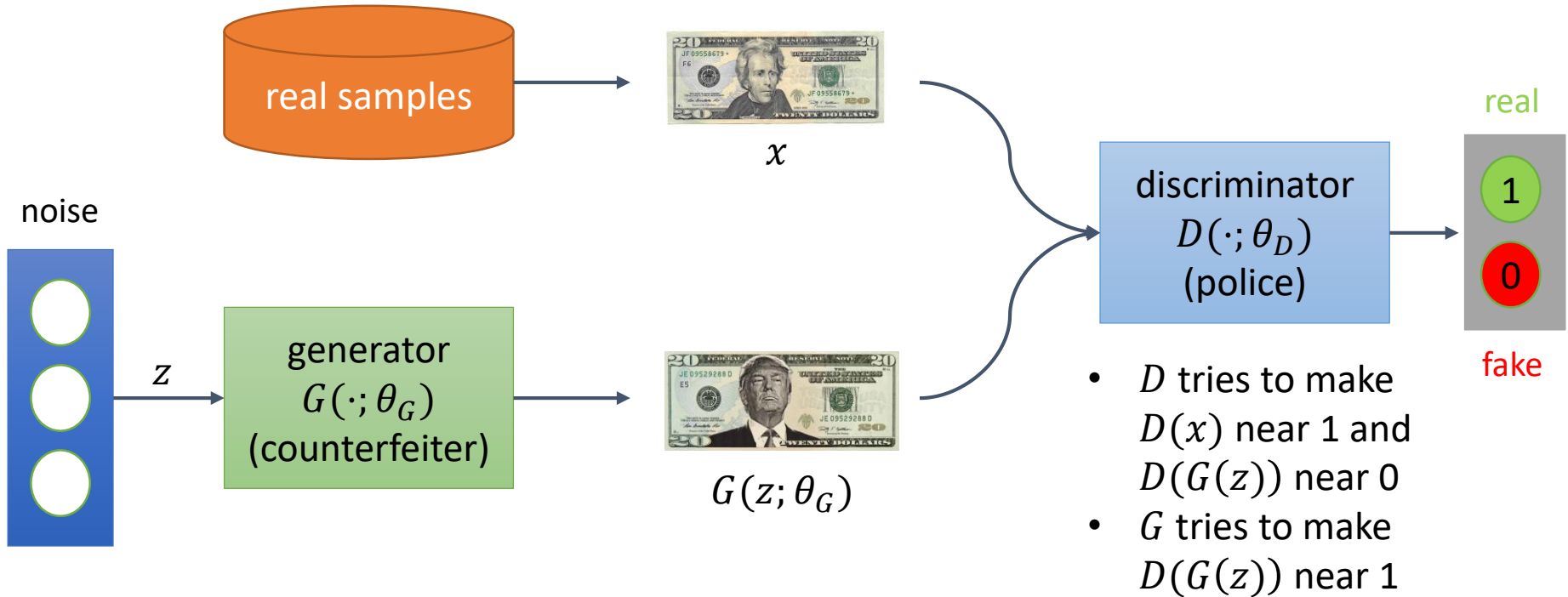
# Photo-realistic super-resolution



# Image-to-image translation



# Generative adversarial networks



# Minimax game

$$V(\theta_G, \theta_D) = \frac{1}{2} \mathbb{E}_{x \sim p_{data}} \log D(x; \theta_D) + \frac{1}{2} \mathbb{E}_{z \sim p_z} \log (1 - D(G(z; \theta_G)))$$

- $\min_{\theta_G} \max_{\theta_D} V(\theta_G, \theta_D)$
- $D$  wishes to maximise  $V(\theta_G, \theta_D)$  and controls  $\theta_D$
- $G$  wishes to minimise  $V(\theta_G, \theta_D)$  and controls  $\theta_G$
- Solution to optimization at local minimum
- Game of two players with a solution at Nash equilibrium



# Non-saturating game

$$J^D = -\frac{1}{2} \mathbb{E}_{x \sim p_{data}} \log D(x; \theta_D) - \frac{1}{2} \mathbb{E}_{z \sim p_z} \log \left( 1 - D(G(z; \theta_G)) \right)$$

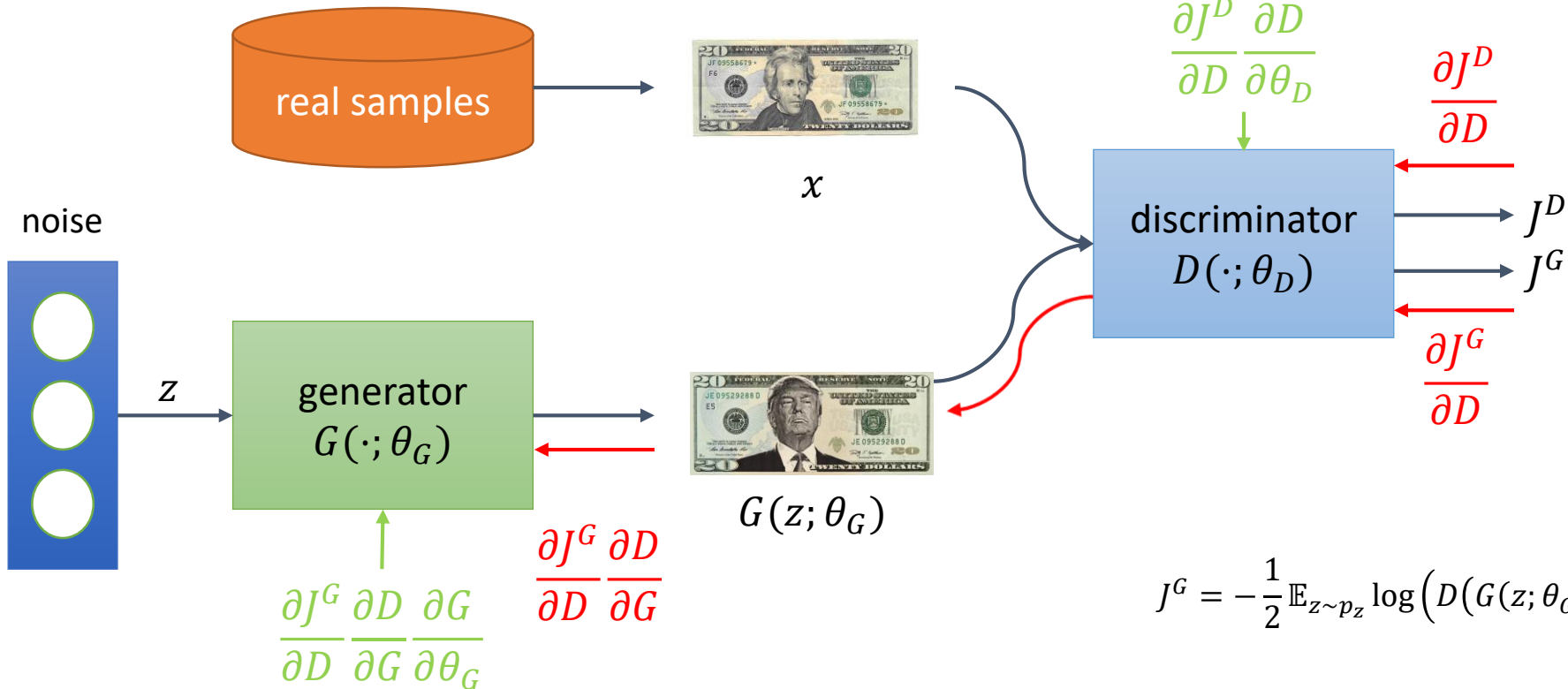
$$J^G = \frac{1}{2} \mathbb{E}_{z \sim p_z} \log \left( 1 - D(G(z; \theta_G)) \right)$$

- Problem: when  $D$  successfully rejects generator samples, generator's gradient vanishes

- Solution:

$$J^G = -\frac{1}{2} \mathbb{E}_{z \sim p_z} \log \left( D(G(z; \theta_G)) \right)$$

# Training GANs

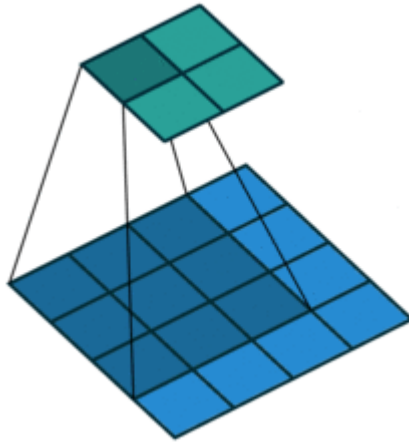


$$J^D = -\frac{1}{2} \mathbb{E}_{x \sim p_{data}} \log D(x; \theta_D) - \frac{1}{2} \mathbb{E}_{z \sim p_z} \log (1 - D(G(z; \theta_G)))$$

$$J^G = -\frac{1}{2} \mathbb{E}_{z \sim p_z} \log (D(G(z; \theta_G)))$$

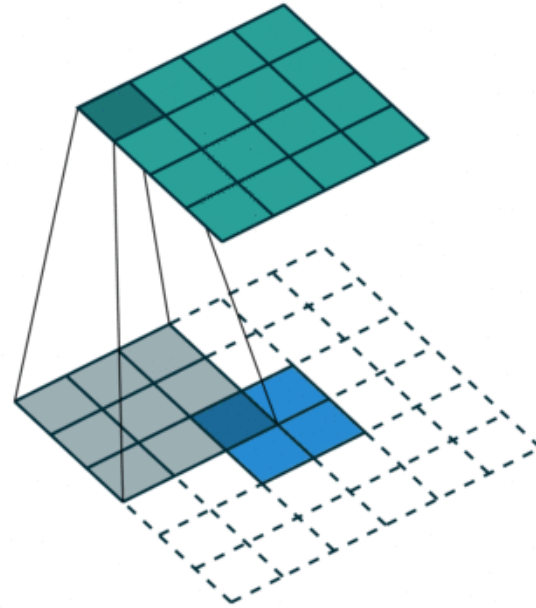
# Review: Transposed convolution (deconv)

Convolution



Stride=1

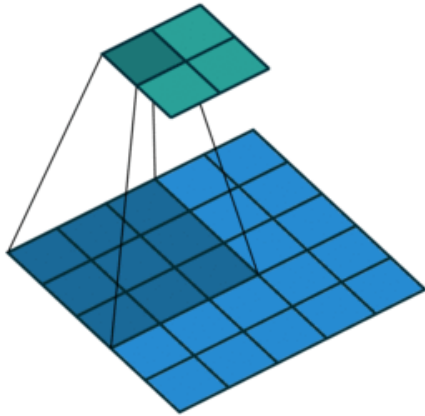
Transpose convolution



Stride=1

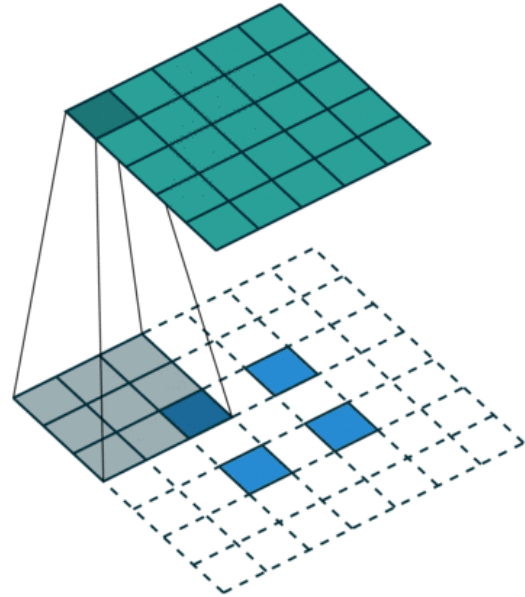
# Review: Transposed convolution (deconv)

Convolution



Stride=2

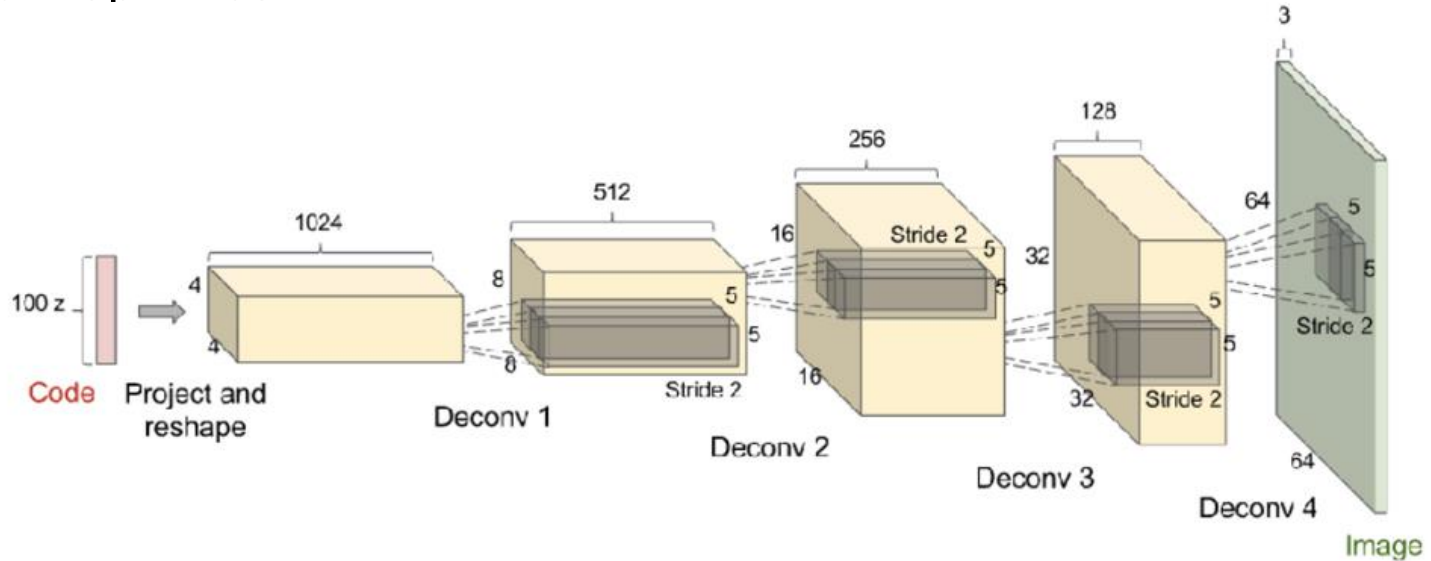
Transpose convolution



Stride=2

# DCGAN (generator) architecture

- Deconv weights are learned
- Deconvs are batch normalized
- No fully connected layer
- Adam optimiser

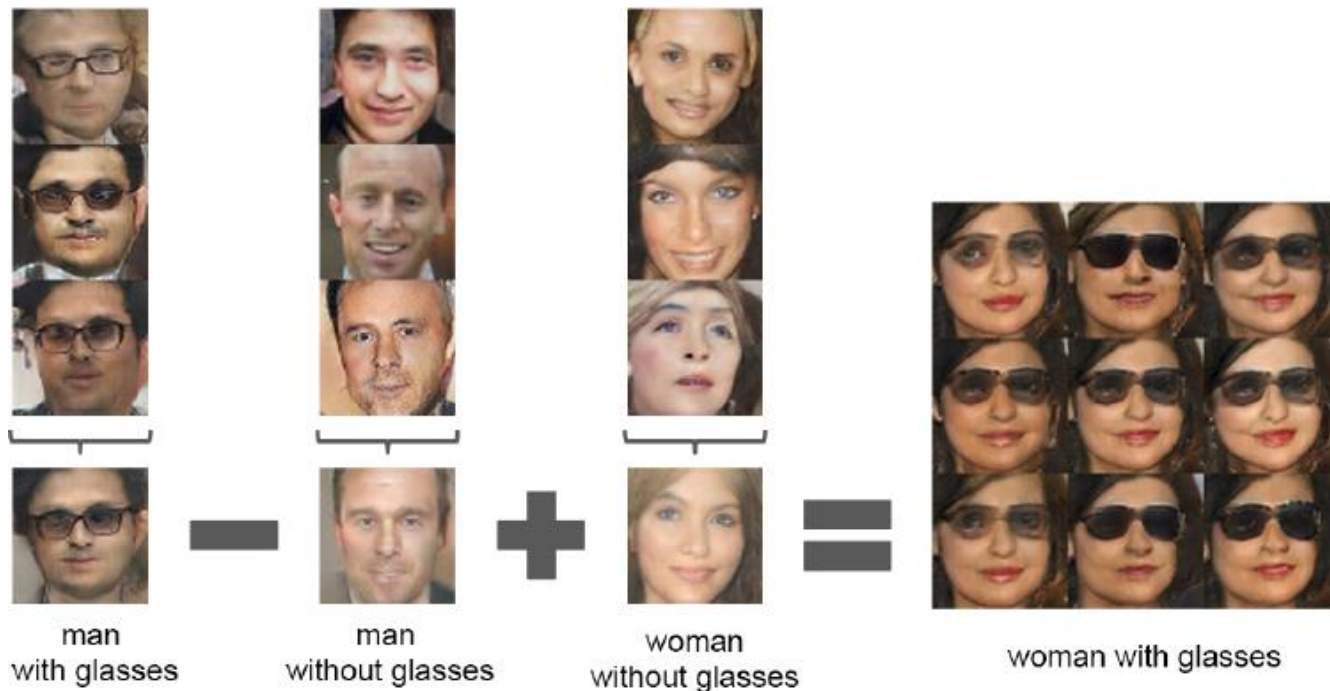


# DCGAN for LSUN bedrooms



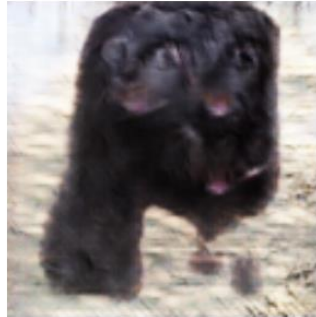
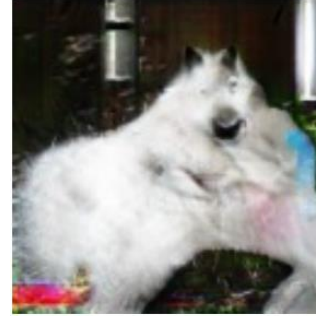
High quality images on restricted domain

# Vector arithmetic on face samples

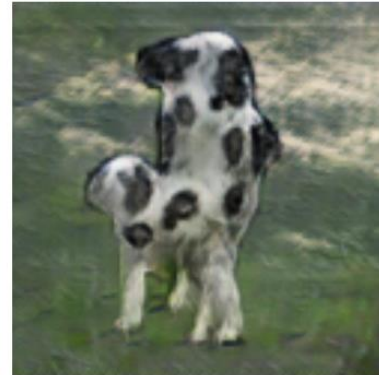


Semantically meaningful latent space

# Problems with counting and global structure



(Goodfellow 2016)





# Question

Is it a good solution for the generator to always produce only one real image?

# Mode collapse



- Another failure mode is for the generator to collapse to a single mode
- If the generator learns to render only one realistic object, this can be enough to fool the discriminator

# Measuring GAN performance

Ask humans to distinguish between generated data and real data

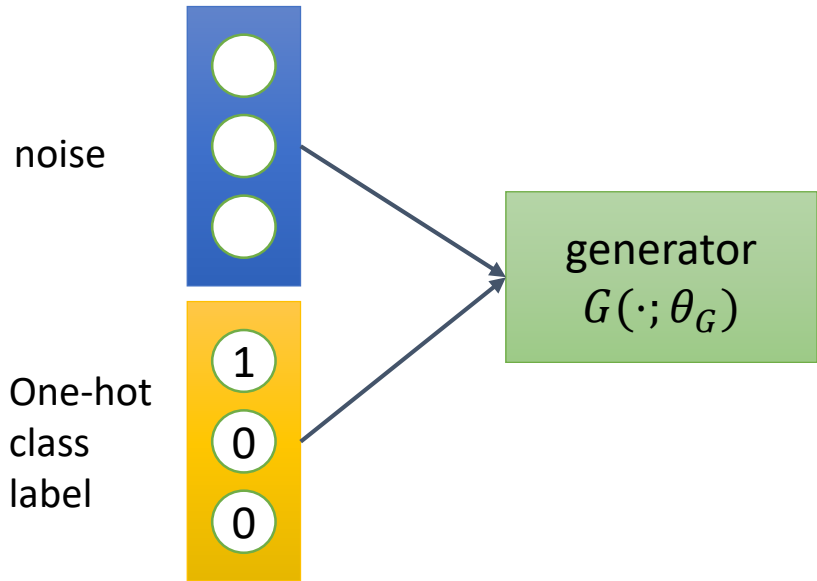
- Subjective, requires training to spot flaws

Automating the evaluation (Inception score):

1. **Image quality:** images should contain meaningful objects (few dominant objects)
    - Feed images to Inception Net to obtain conditional label distribution  $p(y|x)$
    - For each generated image, entropy over classes  $\sum_y p(y|x) \log p(y|x)$  should be low
  2. **Diversity:** the model should generate varied images (balanced over classes)
    - Entropy over generated images  $\int p(y|x = G(z)) dz$  should be high
- Combining two requirements (“how different is the score distribution for a generated image from the overall class balance?”)

$$E_x KL(p(y|x) || p(y)) = \sum_{x \in X} p(y|x) \log \frac{p(y|x)}{p(y)}$$

# Class-conditional GANs

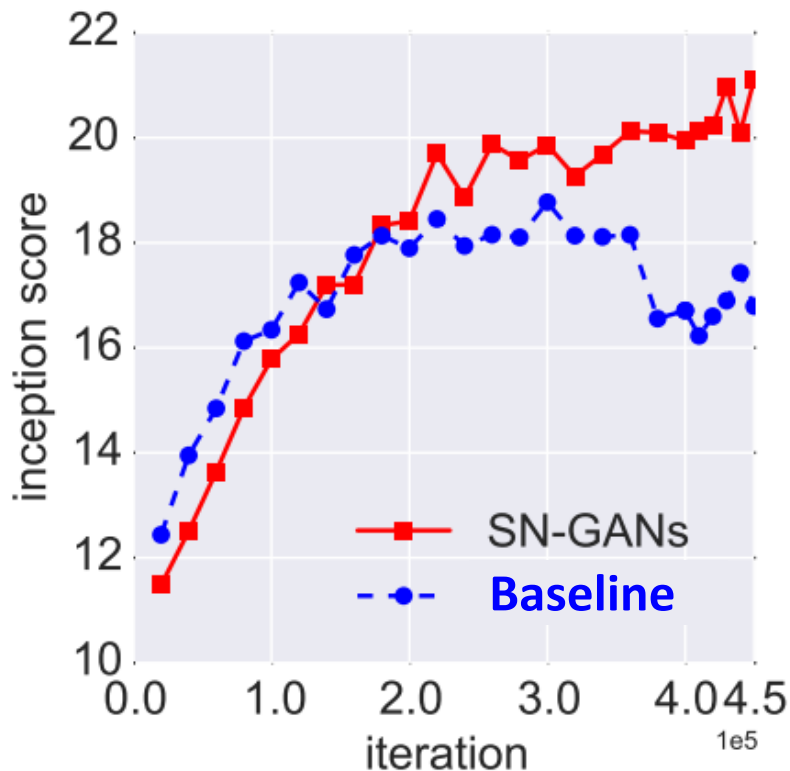


- Add class information in latent code  $z$
- It is not unsupervised anymore

# Spectral normalization

- GAN training can be unstable
- **Culprit:** Gradient updates for G are unbounded
- **Observation:** First layer weights of G are ill-behaved when the training is unstable
- **Solution:** Apply spectral norm
- Spectral norm is the square root of the maximum eigenvalue of  $W^T W$

- $\sigma(W) = \max \frac{\|Wh\|_2}{\|h\|_2} \rightarrow W/\sigma(W)$



# Scaling up GANs

## BigGAN

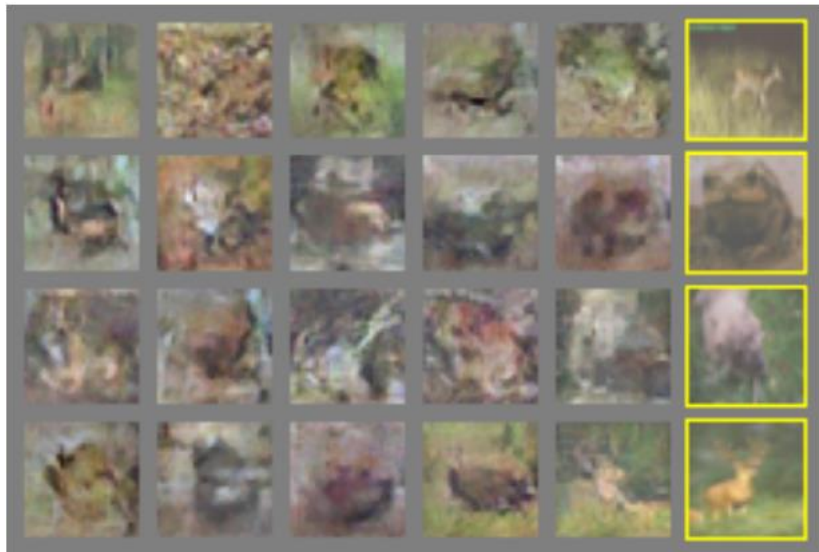
- bigger mini-batch sizes (2048)
- more number of filter channels (~50% more)
- larger dataset (292 million images with 8.5k images, 512 TPU cores!)

## improvements in

- state-of-the-art around 35% in Inception Score
- high-resolution images (512x512)



# 2014 to 2019



[Goodfellow et al. \(2014\).](#)



Figure 5: Samples generated by our model at  $256 \times 256$  resolution. Sample sheets are available [here](#).



Figure 6: Additional samples generated by our model at  $512 \times 512$  resolution.

[Brock et al. \(2019\).](#)

# Summary

- Generative models
- Training GANs
- DCGAN Architecture
- (Open) challenges
- Improvements



# Reading material

## Recommended

- [Goodfellow et al, \(2014\). Generative adversarial nets. NeurIPS.](#)
- Longer version [Goodfellow, \(2016\). NIPS 2016 Tutorial: Generative Adversarial Networks.](#)

## Extra

- [Radford et al, S. \(2015\). Unsupervised representation learning with deep convolutional generative adversarial networks.](#)
- [Salimans et al, S. \(2016\). Improved Techniques for Training GANs. NeurIPS.](#)
- [Miyato et al. \(2018\). Spectral Normalization for GANs. ICLR.](#)
- [Brock et al. \(2019\). Large Scale GAN Training for High Fidelity Natural Image Synthesis. ICLR.](#)

# Coursework 2 overview

- Almost everyone did a very good job, code passed the unit tests, reports were well written and structured 😊
- Most people
  - successfully incorporated residual connections, BN to fix the “broken” network 😊,
  - further improved the results by adding L2 regularization and data augmentation 😊,
  - failed to analytically reason about the failed training and to show quantitative proof 😞.
- Some people failed to show the relation between the vanishing gradient problem and residual connection/BN 😞

# Coursework 3

- Motivation and introduction to the project
- Research questions and project objectives
- Data set and task
- Methodology
- Baseline experiments (and any further experiments that have been done so far)
- Interim conclusions
- Plan for the remainder of the project, including discussion of risks, backup plans

# Additional feedback for coursework

- Marking and moderating the coursework was **many** hours of work, both for Pavlos, Antreas and me, and a team of markers
- We strongly believe in treating everyone same
- Marking for report vs exam
- We will not be addressing issues that fall under Academic Judgement:
  - including discussion around whether a specific contribution is worth x amount of credit,
  - whether the marking was too strict/lenient,
  - comparing with colleagues, and similar issues,
  - very long descriptions (>2-3 sentences per objection point)
  - rude and sentimental emails
- We will be focussing first on obvious errors that you believe you have spotted