



# *Logic Programming: Term manipulation, Meta-Programming*

Alan Smaill

Oct 22, 2015

- ▶ Reminder of term manipulation predicates
  - ▶ `var/1`, `functor/2` etc
- ▶ Meta-programming
  - ▶ `call/1`
  - ▶ symbolic programming
  - ▶ Prolog in Prolog

- ▶ `var/1` holds if argument is Prolog variable, when called.
- ▶ `nonvar/1` holds if argument is **not** a variable when called (ground, or partially instantiated)
- ▶ None of these affect binding.

- ▶ `number/1: -89, 1.007`
- ▶ `integer/1: -89, 6000`
- ▶ `float/1: 0.1, 67.6543`
- ▶ `atom/1: a,f,g1567`
- ▶ `atomic/1: a,f,g1567,1.007,-89`

Can test for whether terms are identical:

- ▶ The `==/2` operator tests whether two terms are exactly identical,
- ▶ Including variable names! (No unification!)

```
?- X == X.
```

```
yes
```

```
?- X == Y.
```

```
no
```

- ▶ `\==/2`: tests that two terms are not identical

?- `X \== X.`

no

?- `X \== Y.`

yes

- ▶ Keep track of all possible solutions, try shortest ones first
- ▶ Maintain a “queue” of solutions

```
 bfs([[Node|Path],_], [Node|Path]) :-  
     goal(Node).  
 bfs([Path|Paths], S) :-  
     extend(Path,NewPaths),  
     append(Paths,NewPaths,Paths1),  
     bfs(Paths1,S).  
 bfs_start(N,P) :- bfs([[N]],P).
```

Here is a more efficient way, using difference lists —  
the first two arguments to `bfs_dl/2` are thus a (difference) list of lists, and the associated difference list variable.

```
bfs_dl([[Node|Path] | _], _, [Node|Path]) :-  
    goal(Node).  
bfs_dl([Path|Paths], Z, Solution) :-  
    extend(Path,NewPaths),  
    append(NewPaths,Z1,Z),  
    Paths \== Z1, %% (Paths,Z1) is not empty DL  
    bfs_dl(Paths,Z1,Solution).  
  
bfs_dl_start(N,P) :- bfs_dl([[N] | X],X,P).
```

`\==` checks if terms `Paths,Z1` are identical as terms



For the `\==/2` test, recall that the empty difference list is represented as a pair `X/X` with two occurrences of the **same** variable.

Notice that, although the new version uses the usual `append/3`, its first argument is the list of new paths, not the list of current paths, which is usually much larger.

call/1:

- ▶ Given a Prolog term G, solve it as a goal

```
?- call(append([1],[2],X)).  
X = [1,2].
```

```
?- read(X), call(X).  
|: member(Y,[1,2]).  
X = member(1,[1,2])
```

...allows some devious things.

```
callwith(P,Args) :-  
    Atom =.. [P|Args], call(Atom).  
  
map(P, [], []).  
map(P, [X|Xs], [Y|Ys]) :-  
    callwith(P, [X,Y]), map(P,Xs,Ys)  
  
plusone(N,M) :- M is N+1.  
  
?- map(plusone, [1,2,3,4,5], L).  
L = [2,3,4,5,6].
```

## Propositions

```
prop(true).  
prop(false).  
prop(and(P,Q)) :- prop(P), prop(Q).  
prop(or(P,Q)) :- prop(P), prop(Q).  
prop(imp(P,Q)) :- prop(P), prop(Q).  
prop(not(P)) :- prop(P).
```

```
simp(and(true,P),P).  
simp(or(false,P),P).  
simp(imp(P,false), not(P)).  
simp(imp(true,P), P).  
simp(and(P,Q), and(P1,Q)) :- simp(P,P1).  
simp(and(P,Q), and(P,Q1)) :- simp(Q,Q1).  
...
```

- ▶ Given a formula, find a satisfying assignment for the atoms in it;
- ▶ Assume atoms given  $[p_1, \dots, p_n]$ .
- ▶ A valuation is a list  $[(p_1, \text{true} | \text{false}), \dots]$ .

```
gen([], []).  
gen([P|Ps], [(P,V)|PVs]) :-  
    (V=true;V=false),  
    gen(Ps,PVs).
```

```
sat(V,true).
sat(V,and(P,Q)) :- sat(V,P), sat(V,Q).
sat(V,or(P,Q)) :- sat(V,P) ; sat(V,Q).
sat(V,imp(P,Q)) :- \+(sat(V,P))
                    ; sat(V,Q).
sat(V,not(P)) :- \+(sat(V,P)).
sat(V,P) :- atom(P),
           member((P,true),V).
```

- ▶ Generate a valuation
- ▶ Test whether it satisfies Q

```
satisfy(Ps,Q,V) :- gen(Ps,V),  
                  sat(V,Q).
```

- ▶ On failure, this backtracks & tries another valuation.

This exploits logic programming search in a useful and concise way.



- ▶ Represent definite clauses

```
rule(Head, [Body, . . . . , Body]) .
```

- ▶ A Prolog interpreter in Prolog:

```
prolog(Goal) :- rule(Goal, Body),  
                prologs(Body)
```

```
prologs([]) .
```

```
prologs([Goal|Goals]) :- prolog(Goal),  
                        prologs(Goals) .
```

## Example

---

```
rule(p(X,Y), [q(X), r(Y)]).  
rule(q(1), []).  
rule(r(2), []).  
rule(r(3), []).
```

```
?- prolog(p(X,Y)).  
X = 1  
Y = 2
```

- ▶ Prolog interpreter already runs programs. . .
- ▶ Self-interpretation is interesting because we can **examine** or **modify** behaviour of interpreter.

```
rule_pf(p(1,2), [], rule1).  
rule_pf(p(X,Y), [q(X), r(Y)], rule2(X,Y)).  
rule_pf(q(1), [], rule3).  
rule_pf(r(2), [], rule4).  
rule_pf(r(3), [], rule5).
```

Now we can produce proof trees showing which rules were used:

```
prolog_pf(Goal, [Tag|Proof]) :-  
    rule_pf(Goal, Body, Tag),  
    prologs_pf(Body, Proof).  
prologs_pf([], []).  
prologs_pf([Goal|Goals], [Proof|Proofs]) :-  
    prolog_pf(Goal, Proof),  
    prologs_pf(Goals, Proofs).
```

*“Is there a proof of  $p(1,2)$  that doesn't use rule 1?”*

```
?- prolog_pf(p(1,2),Prf),  
    \+(in_proof(rule1,Prf)).
```

```
Prf = [rule2,[rule3, rule4]].
```

- ▶ Iterative deepening interpreter:  
as we saw for general search, we can:
  - search exhaustively to a given depth;
  - if no solution found, increase depth bound and recurse.

This way, we are assured to find a solution if there is one.

Prolog implementations allow inspections of the internal knowledge base of facts and rules.

To make use of this, need to make relevant predicates “dynamic”, e.g. by having a directive:

```
:- dynamic(foo/2).
```

```
foo(a,1).
```

```
foo(b,Y) :- foo(a,X), Y = X + 1.
```

The `clause/2` predicate then allows us to inspect clauses matching a given head pattern:

- ▶ returns an explicit `true` for an empty body (head is a fact).
- ▶ returns body as atom, or as compound term made up of pairs  $(X, Y)$ .



We can query for clause information:

```
| ?- clause(foo(X,Y),Body).  
X = a,  
Y = 1,  
Body = true ? ;  
X = b,  
Body = (foo(a,_A),Y=_A+1) ;  
no
```

We can even query with more instantiated pattern:

```
| ?- clause(foo(c,Y), Body).  
no  
| ?- clause(foo(a,Y), Body).  
Y = 1,  
Body = true ?
```

We can give depth-bounded search for goals tagged with a depth bound, as follows:

```
solve( true/_ ) :- !.                %% base case
solve( (A,B) ) :- solve(A), solve(B).%% pair of goals
solve( Q/N ) :- 0<N, M is N-1,
                %% unify with head of a clause;
                %% note change of depth.
                clause( Q, Body ),
                tag(Body,M,Tagged),
                solve( Tagged ).

%% tag(+,+,?) distributes depth label to subgoals
```



Now use iterative deepening wrapper:

```
idsolve(Query) :- idsolve(Query,0).
idsolve(Query,N) :-
    tag(Query,N,QQ), solve(QQ),
    write('Solution found during search to depth '),
    write(N).
idsolve(Query,N) :-
    M is N+1, write('Searching at depth '),
    write(M),nl,
    idsolve(Query,M).
```

Now look at cases where depth-first execution may be problematic, and compare `?- Query.` with `?- idsolve(Query).`

- ▶ Where looping occurs, so losing solutions (incompleteness): iterative deepening search will find solutions (given enough resources).
- ▶ Where solutions with short derivations are found only after solutions with longer derivations: iterative deepening will find the former before the latter.

**BUT** iterative deepening itself will loop if there is no solution!

- ▶ Tracing  
Can implement `trace/1` this way
- ▶ Declarative debugging
  - ▶ Given an error in output, “zoom in” on input rules that were used
  - ▶ These are likely to be the ones with problems

For more on this, see LPN, ch. 9, and Bratko, ch. 23