Introduction to Theoretical Computer Science

Lecture 6: Universal RMs, Halting, and Turing

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Firstly, we need an *encoding*.

Encoding an RM

We have registers $R_0 \ldots R_{m-1}$ and the program $I_0 \ldots I_{n-1}$.

Pairing

Recall that pairing functions allow us to pack multiple numbers $\langle a, b \rangle$ into one number.

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$$
\begin{aligned}
\ulcorner INC(i) \urcorner &= \langle 0, i \rangle \\
\ulcorner DECJZ(i, j) \urcorner &= \langle 1, i, j \rangle \\
\ulcorner P \urcorner &= \langle \ulcorner I_0 \urcorner, \ldots, \ulcorner I_{n-1} \urcorner \rangle \\
\ulcorner R \urcorner &= \langle R_0, \ldots, R_{m-1} \rangle \\
\ulcorner M \urcorner &= \langle \ulcorner P \urcorner, \ulcorner R \urcorner \rangle
\end{aligned}
$$

Exercise: Write an RM program that, given such an encoding, computes its result, if any (very tedious but achievable).

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- Suppose H is such an RM, which takes a machine coding $\ulcorner M \urcorner$ in R_0 and halts with 1 if M halts, and halts with 0 if M doesn't halt.
- Construct a new machine $L = (P_L, R_0 \dots)$ which, given a program $\ulcorner P \urcorner$, runs H on [the program with itself as input], i.e. the machine $(P, \ulcorner P \urcorner)$, and loops iff it halts.

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Contradiction!

If L halts on $\ulcorner P_L \urcorner$ that means that H says that $(P_L, \ulcorner P_L \urcorner)$ loops.
If L loops on $\ulcorner P_L \urcorner$ that means that H says that $(P_L, \ulcorner P_L \urcorner)$ halts.

Diagonalization

We saw Cantor's proof of the uncountability of infinite-length binary strings in the last lecture. This proof is another example of the same principle, which is called *diagonalization*.

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Example (Gödel's first incompleteness theorem)

If a logic is capable of expressing basic (Peano) arithmetic, we can encode the provability of statements in the logic itself. Then, by the same diagonalisation trick, we can encode the statement *"This statement is not provable"* in the logic. If it is true, then it is not provable and thus the logic is *incomplete*. If it is false, then it is provable and thus the logic is *inconsistent*.

Consequences

We have sketched an argument that there are some programs that *cannot* be decided by register machines.

But what about *other* machines?

Turing Machines Reprisal

Recall a Turing Machine from prior courses. It is a machine with finite control, like an NFA or PDA, but with access to an unbounded *tape* $t_0 t_1 \dots$ for storage. In each transition, we read and write to the tape, and move the tape head left or right.

Definition

A *Turing Machine* is a 7-tuple $\left(Q, \Sigma, \Gamma, \delta, q_0, q_{\text{accept}}, q_{\text{reject}} \right)$:

- Q : states
- Σ : input symbols
- $\Gamma \supseteq \Sigma$: *tape* symbols, including a blank symbol $\sqcup$.
- $\delta : Q \times \Gamma \to Q \times \Gamma \times \{-1, +1\}$
- $q_0, q_{\text{accept}}, q_{\text{reject}} \in Q$: start, accept, reject states.

Exercise: Construct a TM to recognise $\{0^n 1^n 2^n \mid n \in \mathbb{N}\}$

Programming Turing Machines

More examples are given in Sipser, ch. 3.

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Exercise: Design a TM to simulate an RM
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Upshot

The halting argument applies to TMs just as to RMs!

Extensions to Turing Machines

Do these modifications affect the expressivity of the machine?

- Adding the ability to stay put, i.e.:

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This means that for any model of computation we can think of, there are limits to what we can compute. Some problems are fundamentally *uncomputable* by any means. More on this next week.