# IRDS: Bonus Slides

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#### Hello there

I will not present these slides in class.

Next lecture we will discuss how to choose features for learning algorithms.

This means you need to understand a bit about learning algorithms.

There are just an outline of topics that will help you to appreciate the next lecture.

#### These slides:

- List a few representative algorithms
- What you should know about them
- With links to readings to learn about them

To be ready for the next lecture, what you really need:

- to know how the classifiers represent the decision boundary
- not the algorithm for how the classifier is learnt
  - (good to know, but not necessary for next lecture)

### List of Algorithms

(with readings)

Here are the ones we will "discuss"

- Linear regression
  - Fitting nonlinear functions by adding basis functions
  - BRML Sec 17.1, 17.2
- Logistic regression
  - BRML Sec 17.4
  - (just first few pages, don't worry about training algorithms)
- k-nearest neighbour
  - BRML Sec 14.1, 14.2
- Decision trees
  - HTF Sec 9.2

#### Why these?

- practical
- have different types of decision boundaries
  - so representative for purposes of next lecture

#### Key to previous slide

- BRML: Barber. Bayesian Reasoning and Machine Learning. CUP, 2012. <a href="http://web4.cs.ucl.ac.uk/staff/D.Barber/pmwiki/pmwiki.php?n=Brml.HomePage">http://web4.cs.ucl.ac.uk/staff/D.Barber/pmwiki/pmwiki.php?n=Brml.HomePage</a>
- HTF: Hastie, Tibshirani, and Friedman. The Elements of Statistical Learning 2nd ed, Springer, 2009. <a href="http://statweb.stanford.edu/~tibs/ElemStatLearn/">http://statweb.stanford.edu/~tibs/ElemStatLearn/</a>

## Linear regression

Let  $\mathbf{x} \in \mathbb{R}^d$  denote the feature vector. Trying to predict  $y \in \mathbb{R}$ 

Simplest choice a linear function. Define parameters  $\mathbf{w} \in \mathbb{R}^d$ 

$$\hat{y} = f(\mathbf{x}, \mathbf{w}) = \mathbf{w}^{\top} \mathbf{x} = \sum_{j=1}^{d} w_j x_j$$

(to keep notation simple assume that always  $x_d = 1$ )

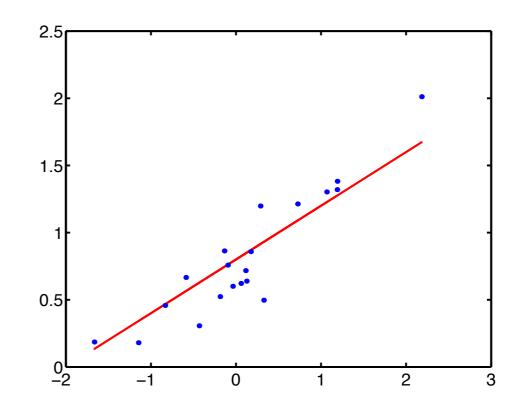
Given a data set

$$\mathbf{x}^{(1)} \dots \mathbf{x}^{(N)}, y^{(1)}, \dots, y^{(N)}$$

find the best parameters

$$\min_{\mathbf{w}} \sum_{i=1}^{N} \left( y^{(i)} - \mathbf{w}^{\top} \mathbf{x}^{(i)} \right)^{2}$$

which can be solved easily (but I won't say how)



## Nonlinear regression

What if we want to learn a nonlinear function?

Trick: Define new features, e.g., for scalar x, define  $\phi(x) = (1, x, x^2)^{\top}$ 

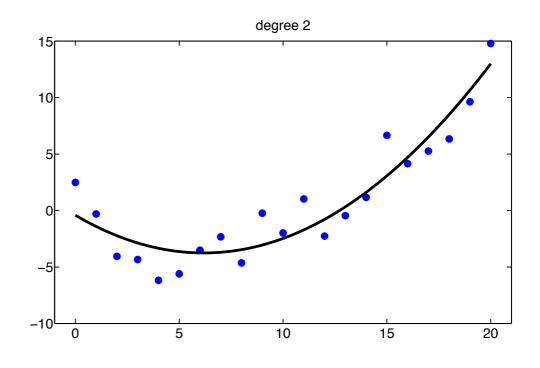
$$\hat{y} = f(\mathbf{x}, \mathbf{w}) = \mathbf{w}^{\top} \phi(\mathbf{x})$$

this is still linear in w

To find parameters, the minimisation problem is now

$$\min_{\mathbf{w}} \sum_{i=1}^{N} \left( y^{(i)} - \mathbf{w}^{\top} \phi(\mathbf{x}^{(i)}) \right)^{2}$$

exactly the same form as before (because **x** is fixed) so still just as easy



# Logistic regression

(a classification method, despite the name)

Linear regression was easy.

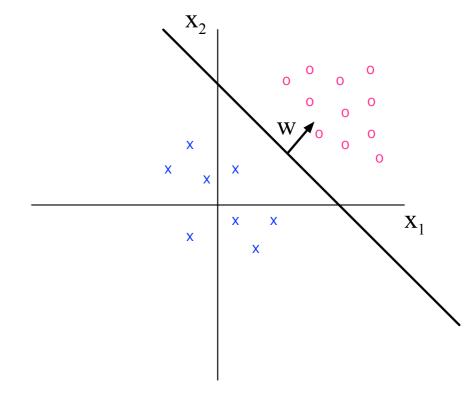
Can we do linear classification too?

Define a discriminant function

$$f(\mathbf{x}, \mathbf{w}) = \mathbf{w}^{\top} \mathbf{x}$$

Then predict using

$$y = \begin{cases} 1 & \text{if } f(\mathbf{x}, \mathbf{w}) \ge 0\\ 0 & \text{otherwise} \end{cases}$$



yields linear decision boundary

Can get class probabilities from this idea, using logistic regression:

$$p(y = 1|\mathbf{x}) = \frac{1}{1 + \exp\{-\mathbf{w}^{\top}\mathbf{x}\}}$$

(to show decision boundaries same, compute log odds  $\log \frac{p(y=1|\mathbf{x})}{p(y=0|\mathbf{x})}$ 

#### K-Nearest Neighbour

#### simple method for classification or regression

Define a distance function between feature vectors  $D(\mathbf{x}, \mathbf{x}')$ 

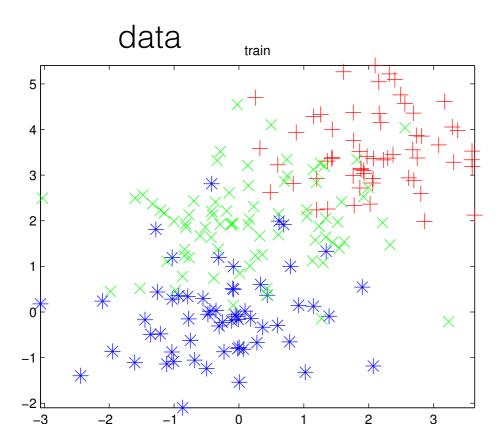
To classify a new feature vector **x** 

- 1. Look through your training set. Find the K closest points. Call them  $N_K(\mathbf{x})$  (this is **memory-based** learning.)
- 2. Return the majority vote.
- 3. If you want a probability, take the proportion

$$p(y = c | \mathbf{x}) = \frac{1}{K} \sum_{(y', \mathbf{x}') \in N_K(\mathbf{x})} \mathbb{I}\{y' = c\}$$

(the running time of this algorithm is terrible. See IAML for better indexing.)

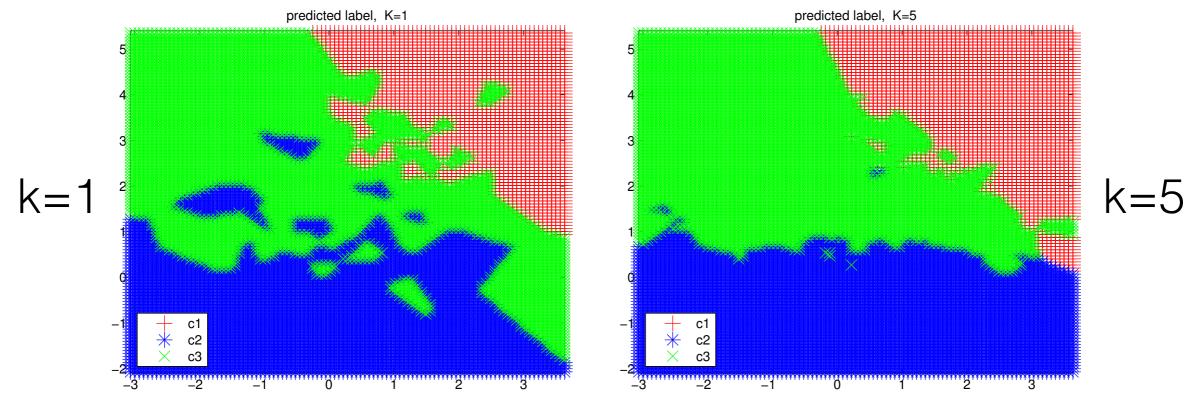
#### K-Nearest Neighbour



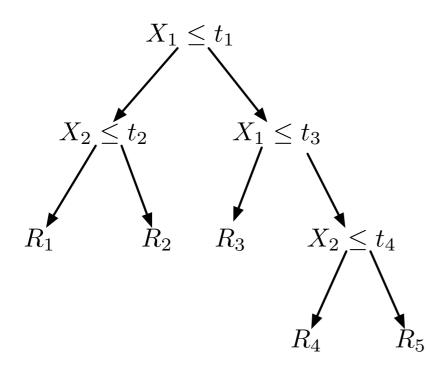
Decision boundaries can be highly nonlinear

The bigger the K, the smoother the boundary

This is **nonparametric**: the complexity of the boundary varies depending on the amount of training data



#### **Decision Trees**



Can be used for classification or regression

Can handle discrete or continuous features

Interpretable but tend not to work as well as other methods.

