

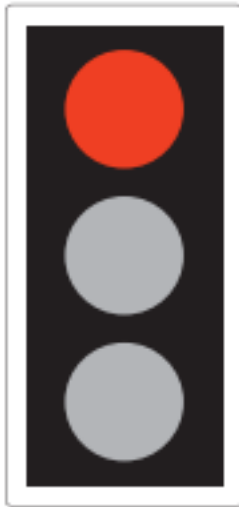
# Computation and Logic

## Traffic Lights

Michael Fourman  
@mp4man



# Traffic Light Signals



RED means 'Stop'. Wait behind the stop line on the carriageway



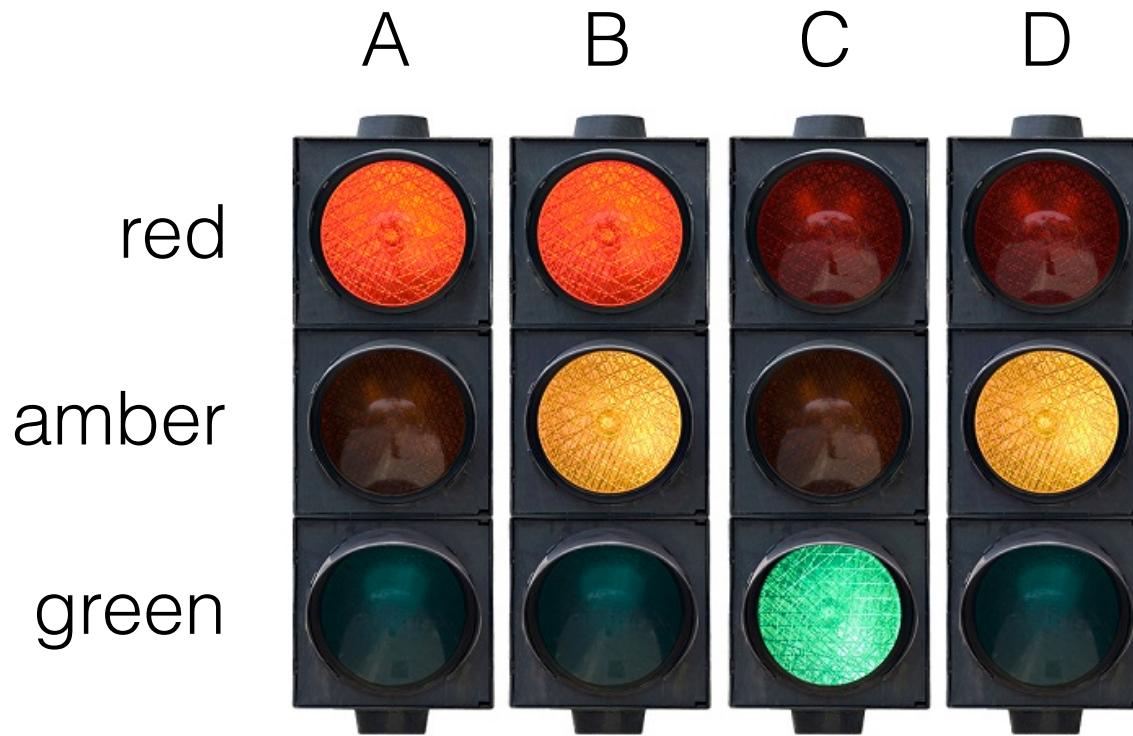
RED AND AMBER also means 'Stop'. Do not pass through or start until GREEN shows



GREEN means you may go on if the way is clear. Take special care if you intend to turn left or right and give way to pedestrians who are crossing

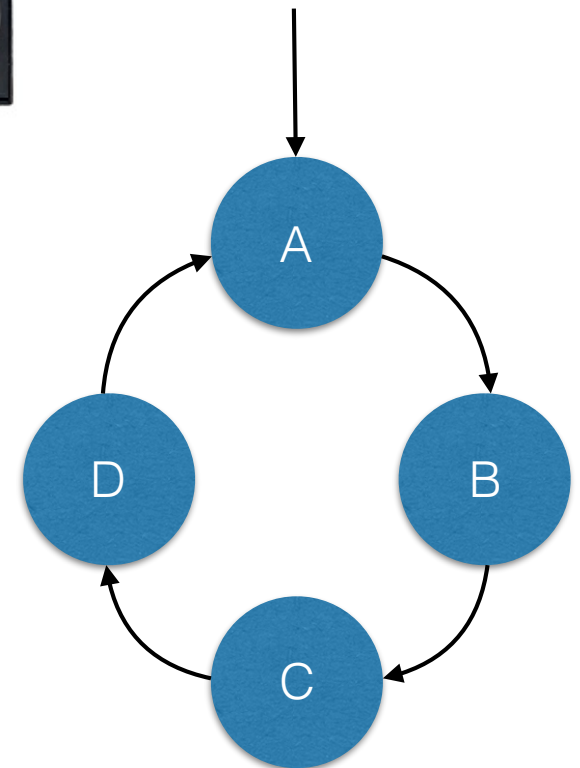


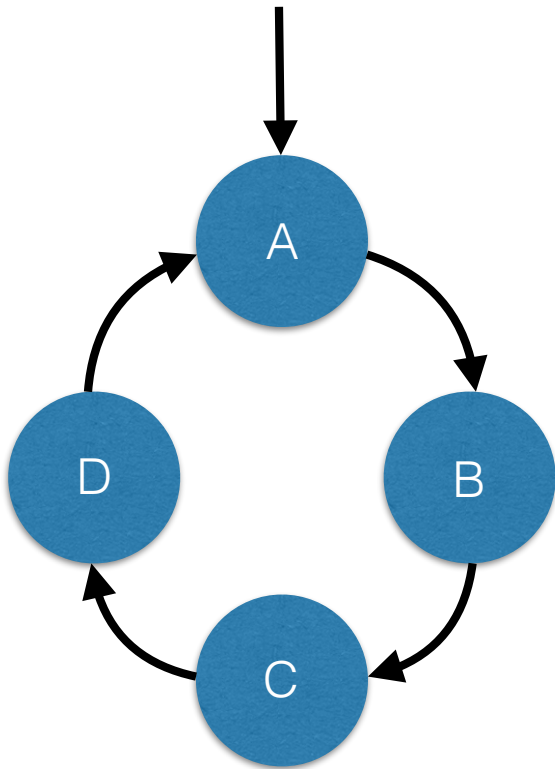
AMBER means 'Stop' at the stop line. You may go on only if the AMBER appears after you have crossed the stop line or are so close to it that to pull up might cause an accident



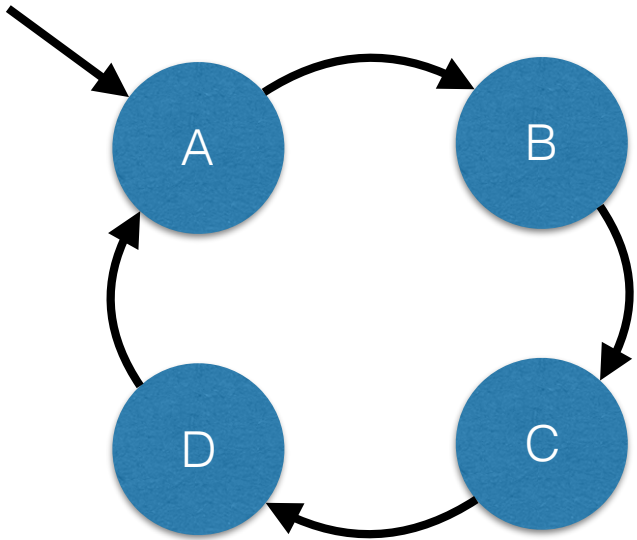
# logic & computation

red iff A or B  
amber iff B or D  
green iff C

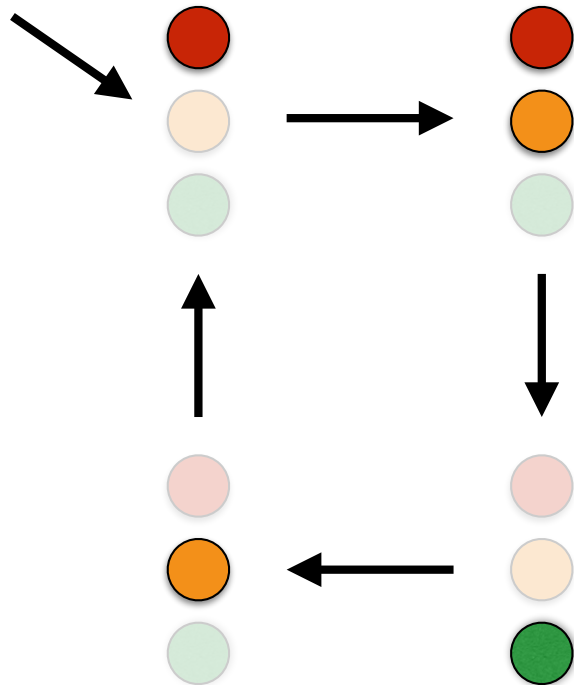




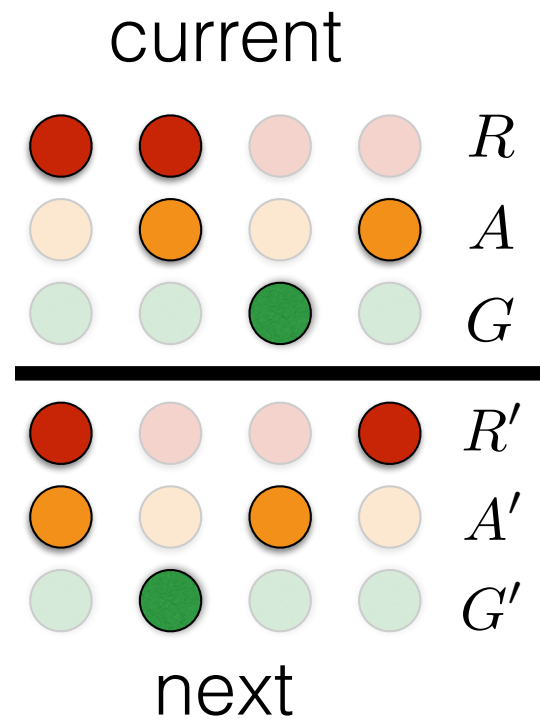
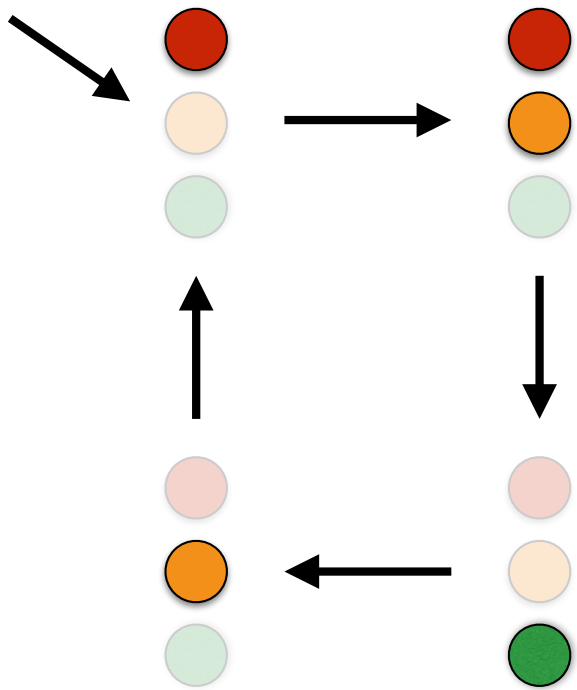
current			
A	B	C	D
<hr/>			
B	C	D	A
next			



current			
A	B	C	D
B	C	D	A
next			



current				
●	●	●	●	<i>R</i>
●	●	●	●	<i>A</i>
●	●	●	●	<i>G</i>
●	●	●	●	<i>R'</i>
●	●	●	●	<i>A'</i>
●	●	●	●	<i>G'</i>
next				

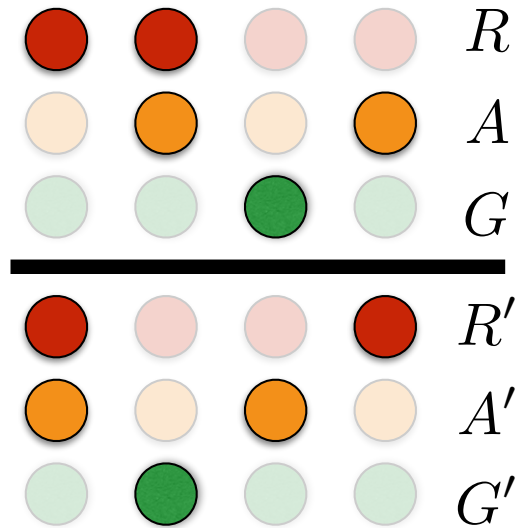


$$R' = R \text{ xor } A = R \oplus A$$

$$A' = \text{not } A = \neg A$$

$$G' = R \text{ and } A = R \wedge A$$

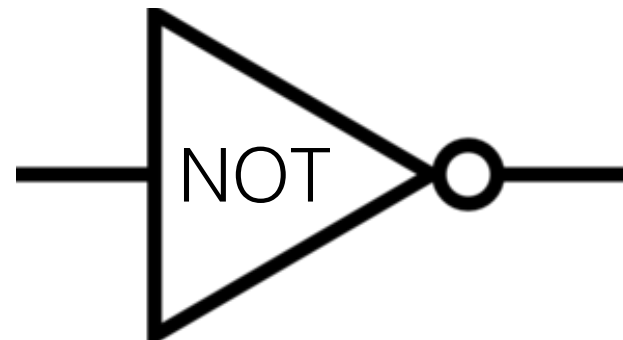
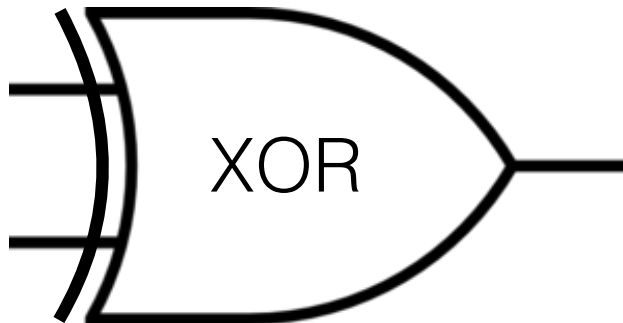
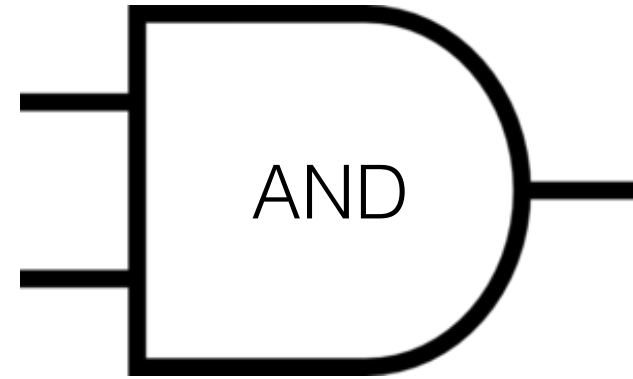
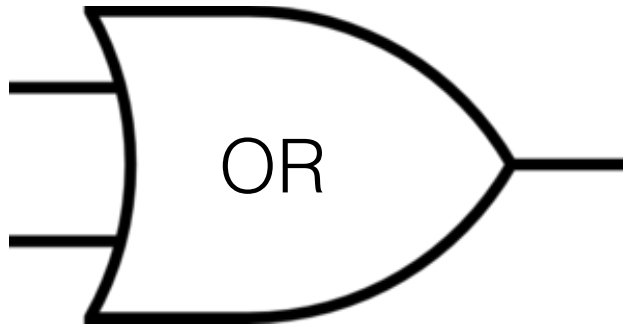
current



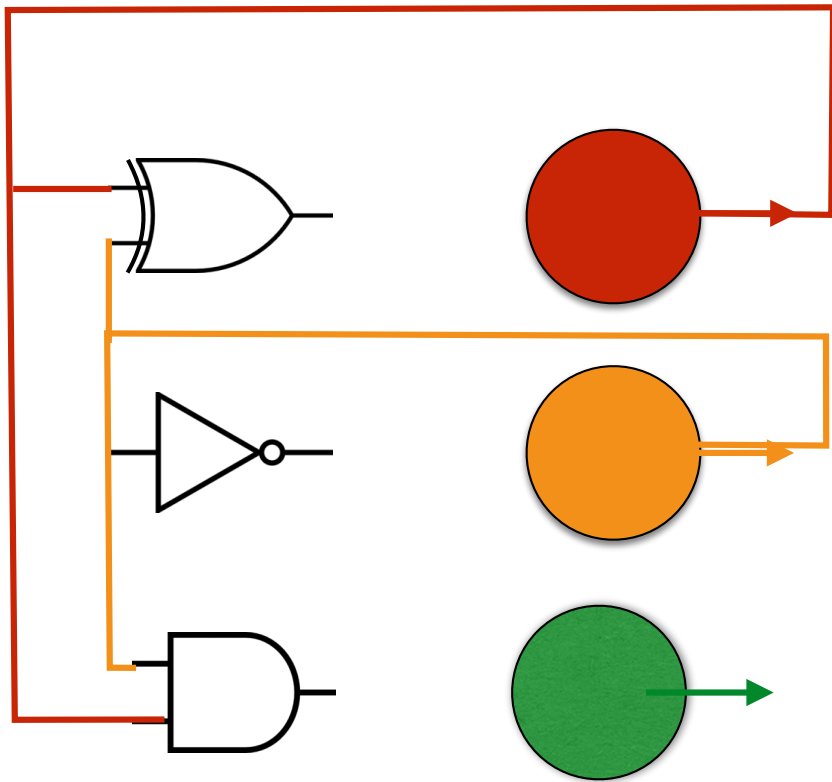
next

<i>R</i>	<i>A</i>	$R \wedge A$	$R \oplus A$
0	0	0	0
0	1	0	1
1	0	0	1
1	1	1	0

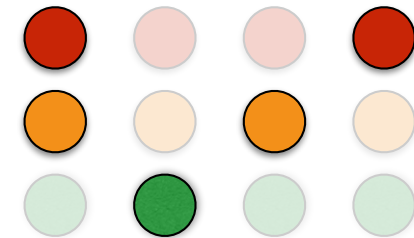
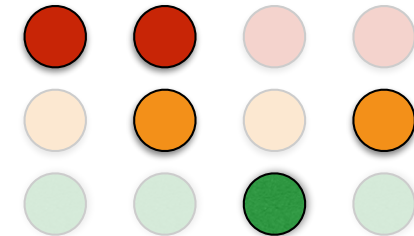
<i>A</i>	$\neg A$
0	1
1	0







current

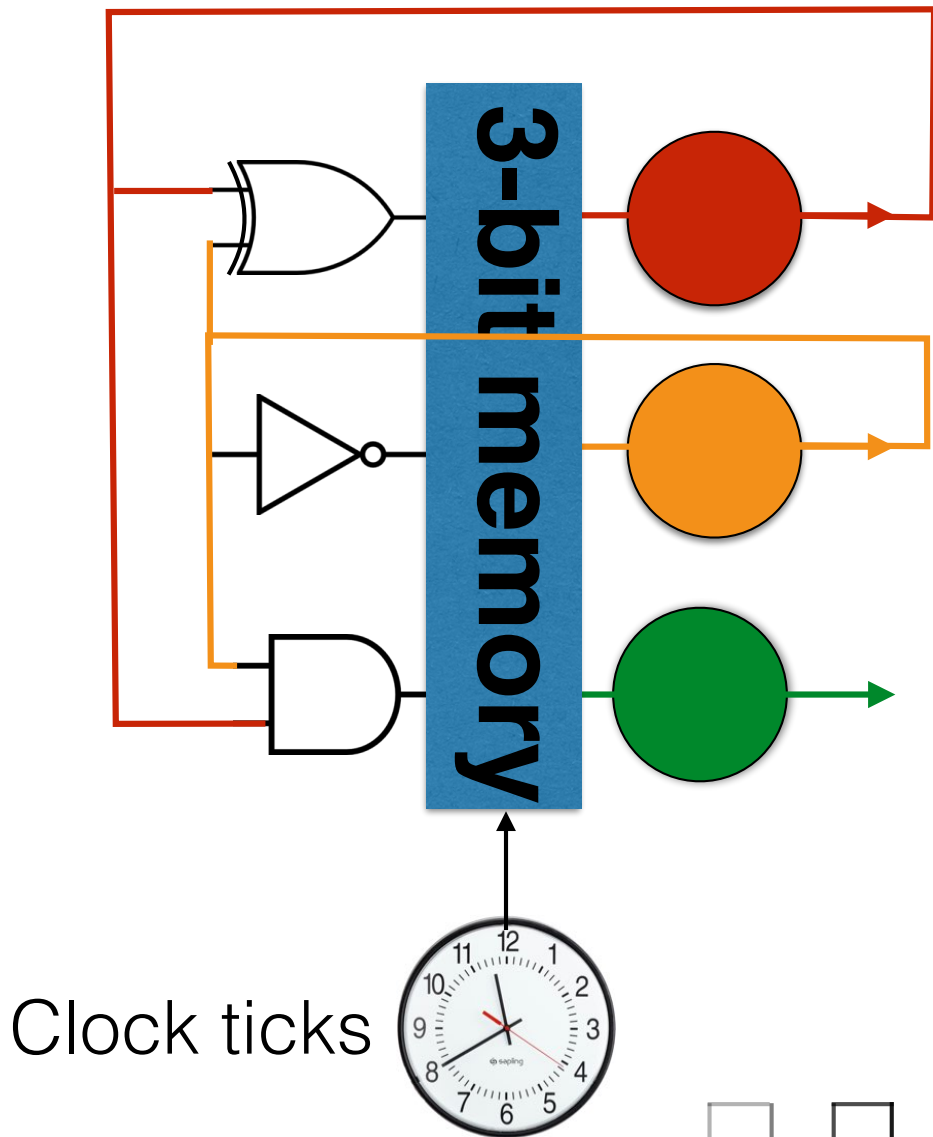


next

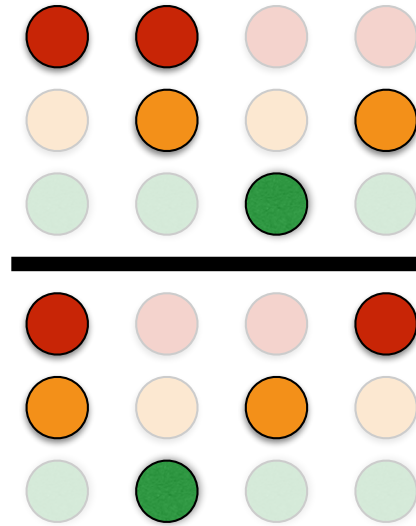
$$R' = R \text{ xor } A$$

$$A' = \text{not } A$$

$$G' = R \text{ and } A$$



current



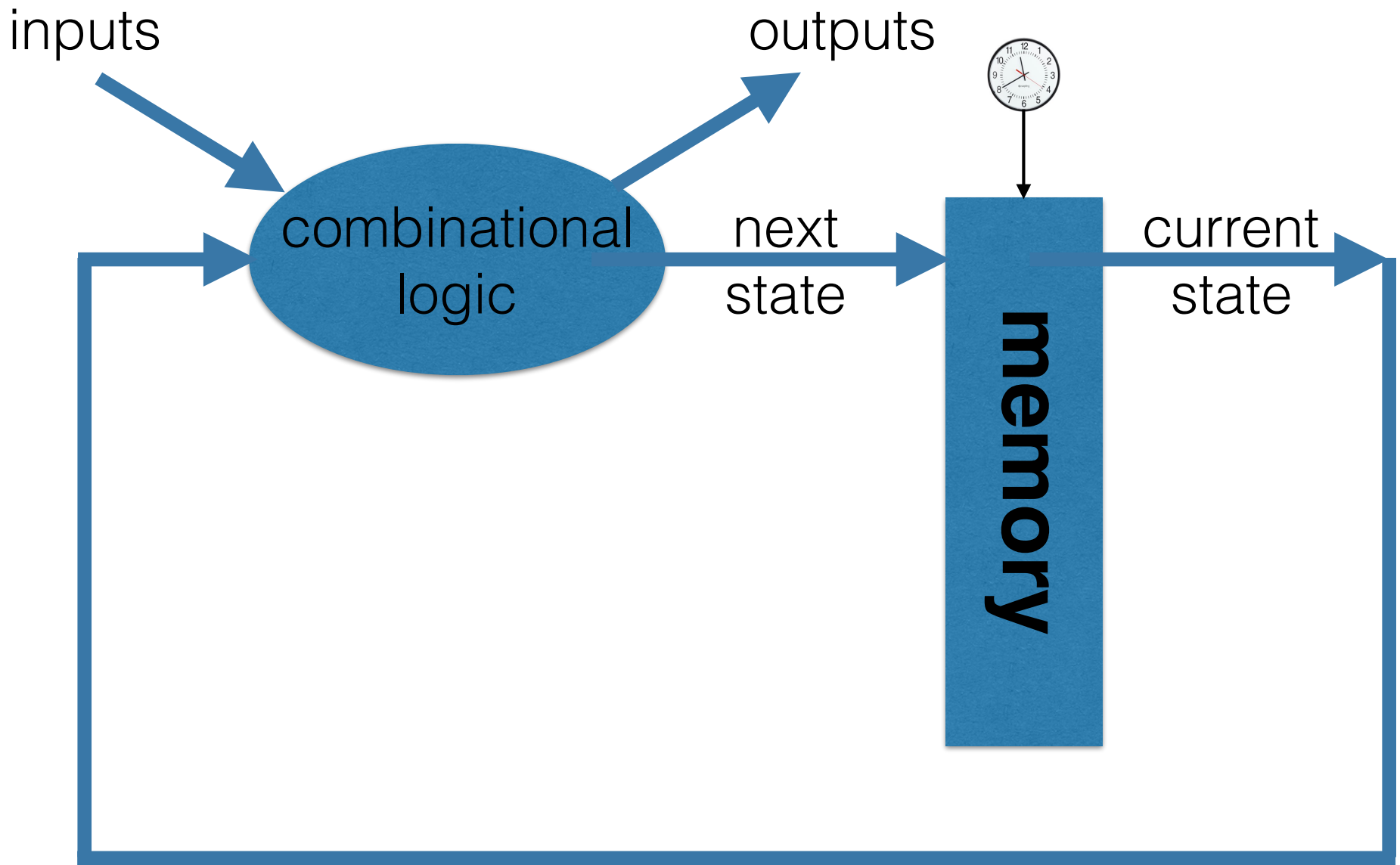
next

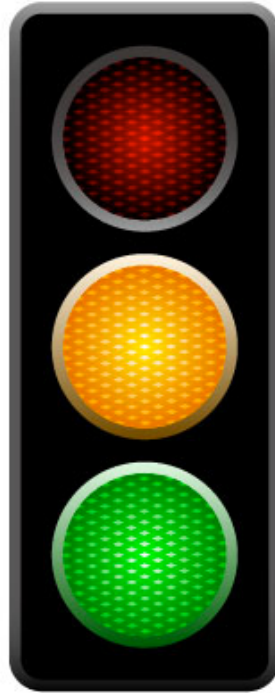
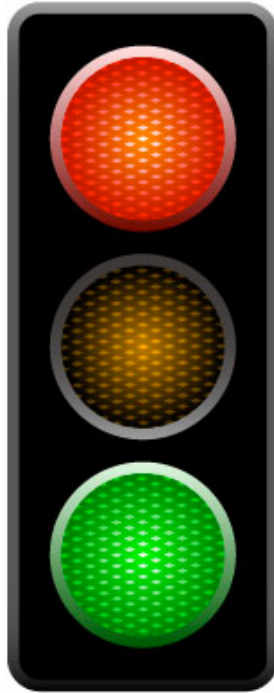
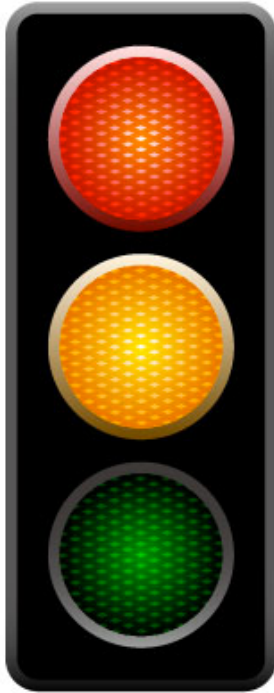
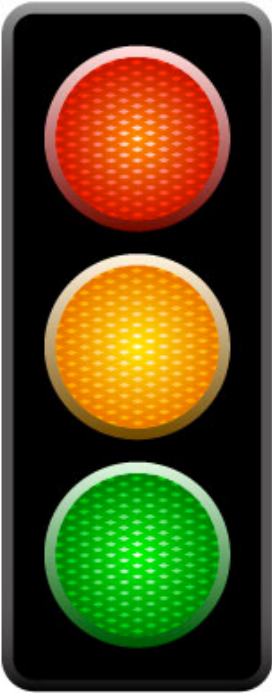
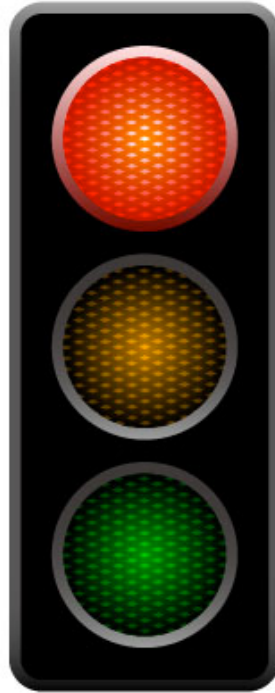
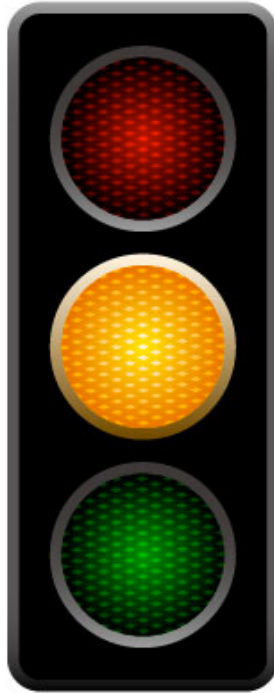
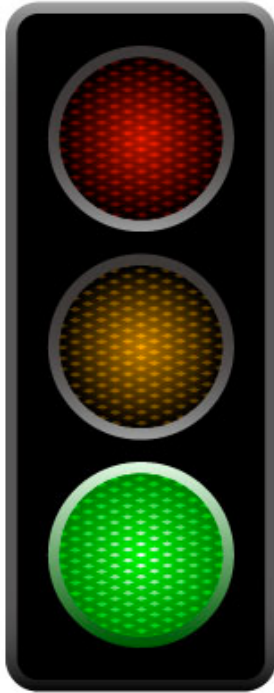
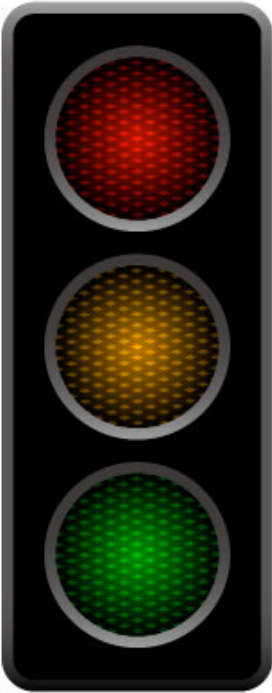
$$R' = R \text{ xor } A$$

$$A' = \text{not } A$$

$$G' = R \text{ and } A$$

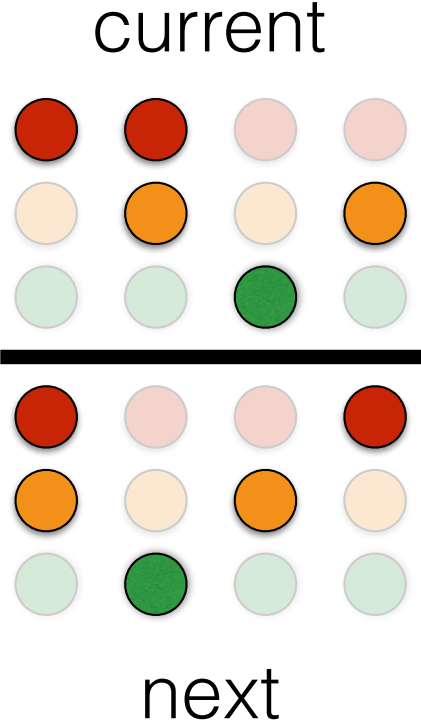
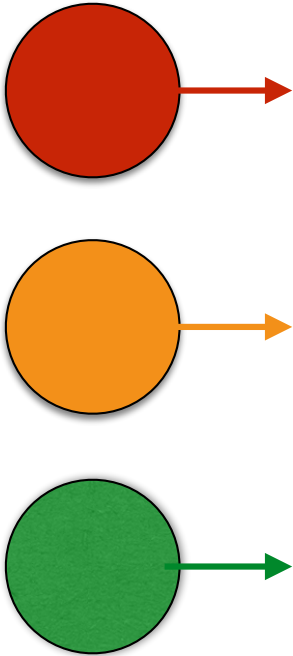






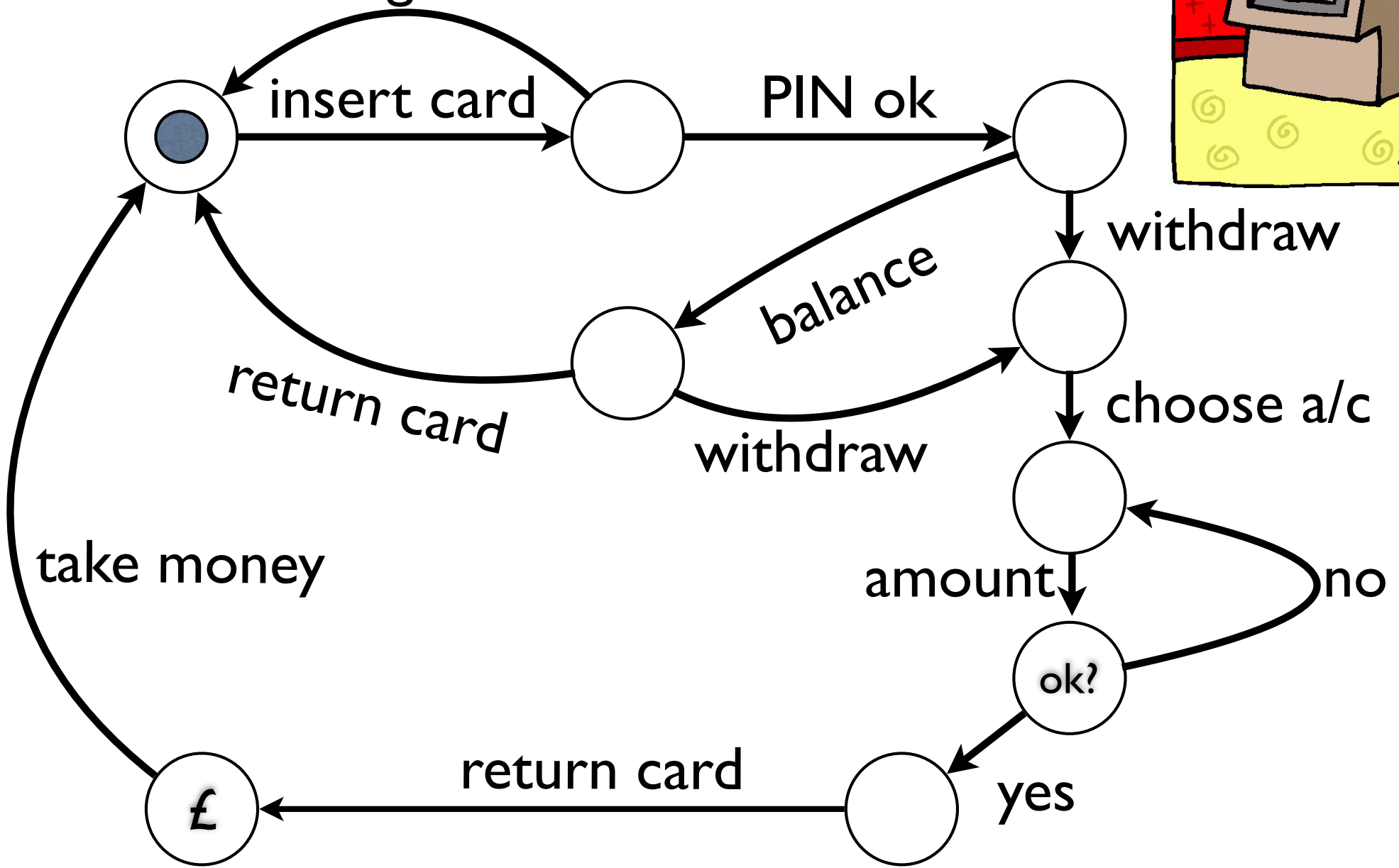


# Exercise 1.2



$$\begin{aligned} R' &= R \text{ xor } A \\ A' &= G \text{ or } (R \text{ and not } A) \\ G' &= R \text{ and } A \end{aligned}$$

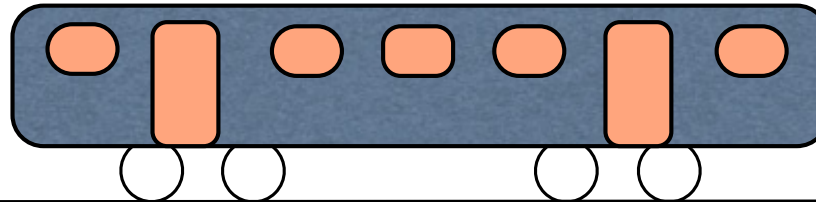
# ATM





# Counting trains

A

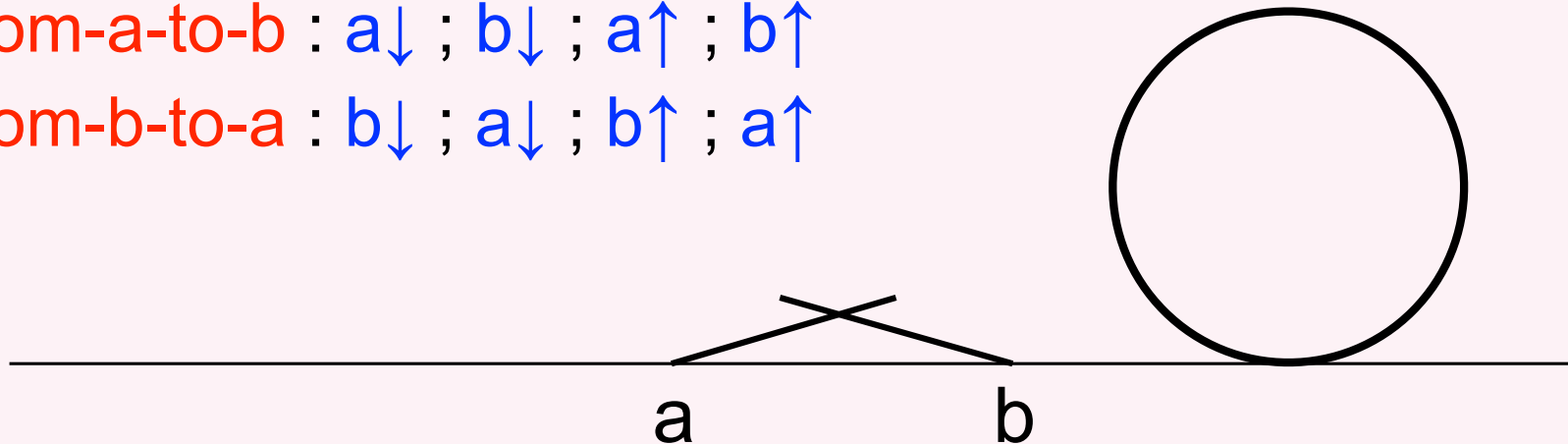


B

axle sensor (detects passing wheels)

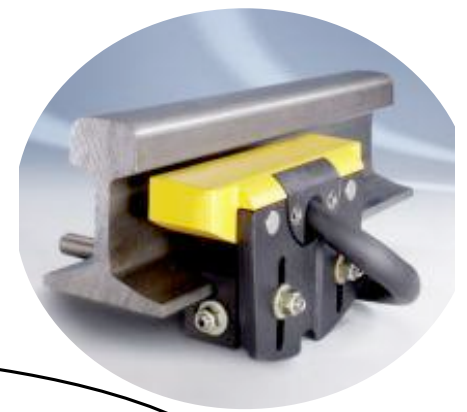
from-a-to-b :  $a \downarrow$  ;  $b \downarrow$  ;  $a \uparrow$  ;  $b \uparrow$

from-b-to-a :  $b \downarrow$  ;  $a \downarrow$  ;  $b \uparrow$  ;  $a \uparrow$

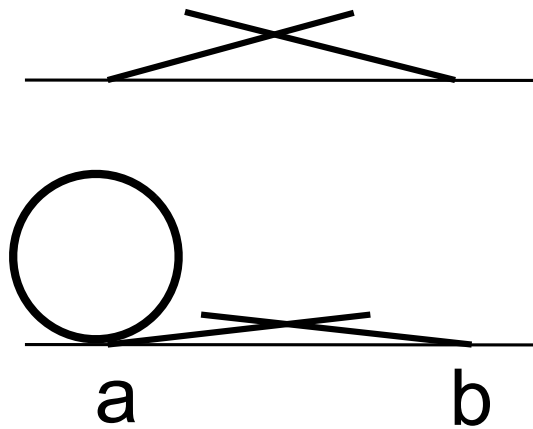




# Finite-state machines



axle sensor

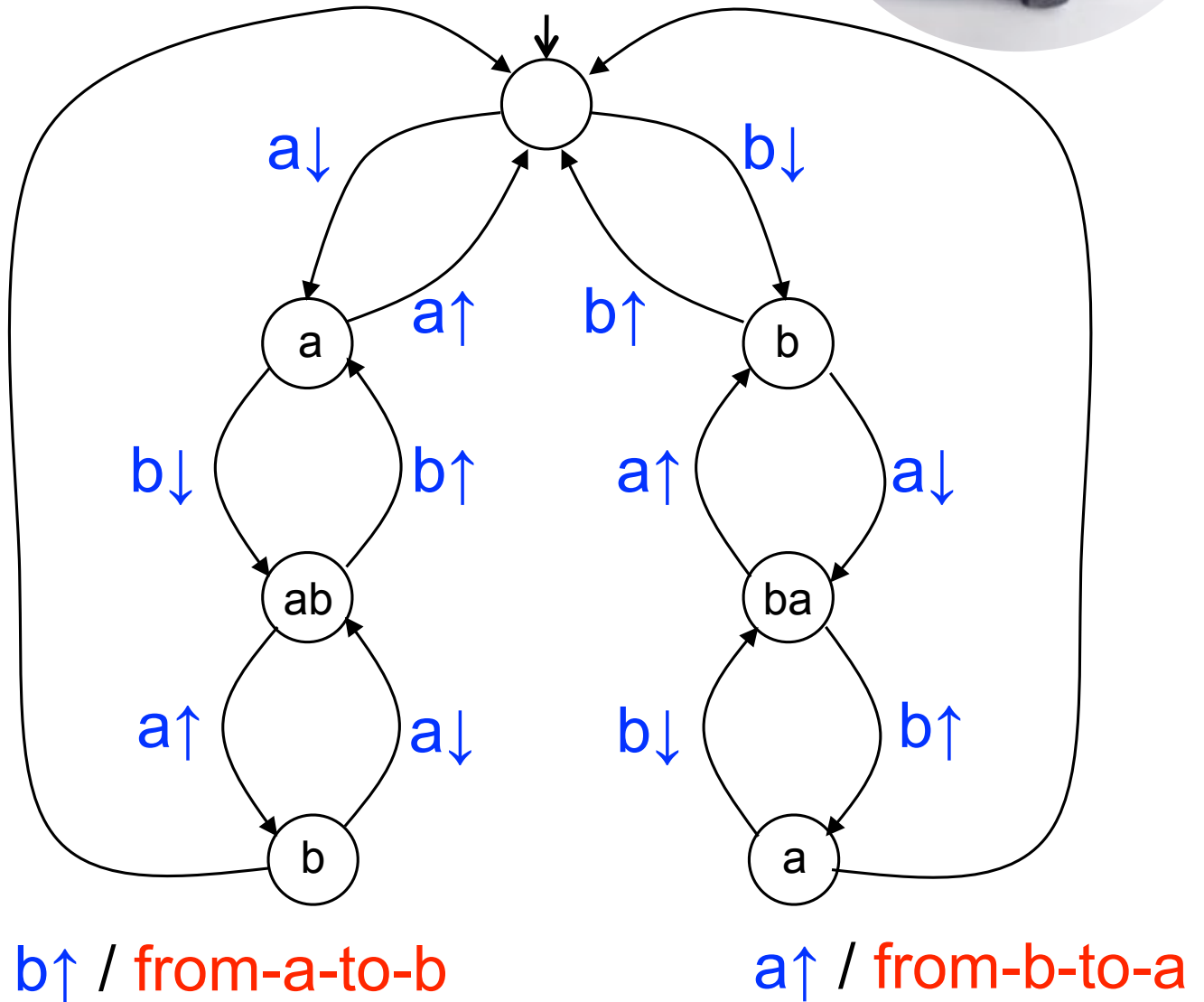


inputs :

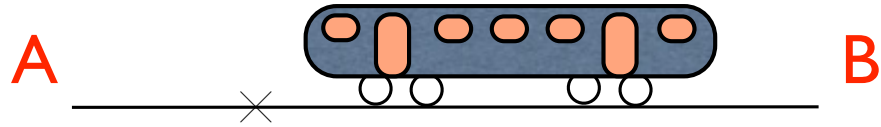
$a\uparrow$ ,  $a\downarrow$ ,  $b\uparrow$ ,  $b\downarrow$

outputs :

from-a-to-b,  
from-b-to-a



# Hierarchical FSMs



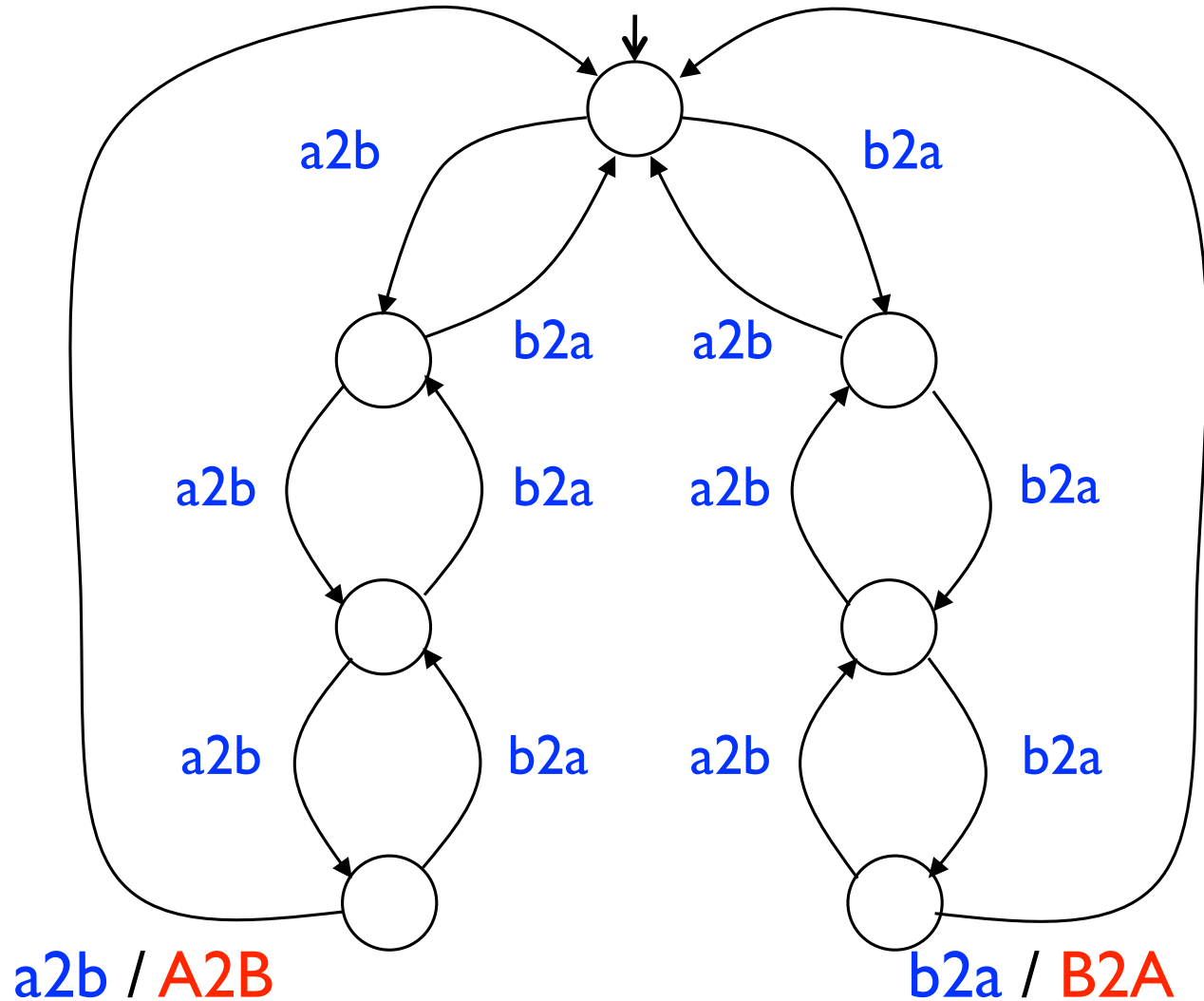
carriage counter

inputs :

a2b, b2a

outputs :

A2B, B2A



a2b = from-a-to-b

# Application Fields



## Industry

- real-time control, vending machines, cash dispensers, etc.

## Electronic circuits

- data path / control path
- memory / cache handling
- protocols, USB, etc.



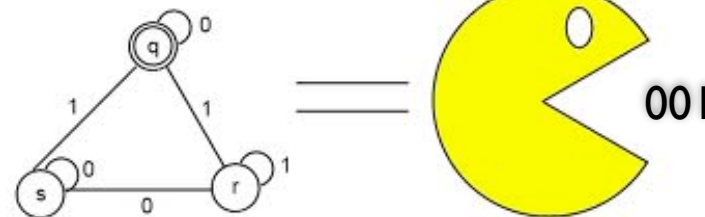
## Communication protocols

- initiation and maintenance of communication links
- error detection and handling, packet retransmission



## Language analysis

- natural languages
- programming languages
- search engines



# A Decimal Number

