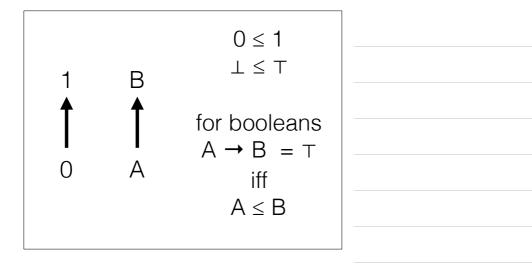
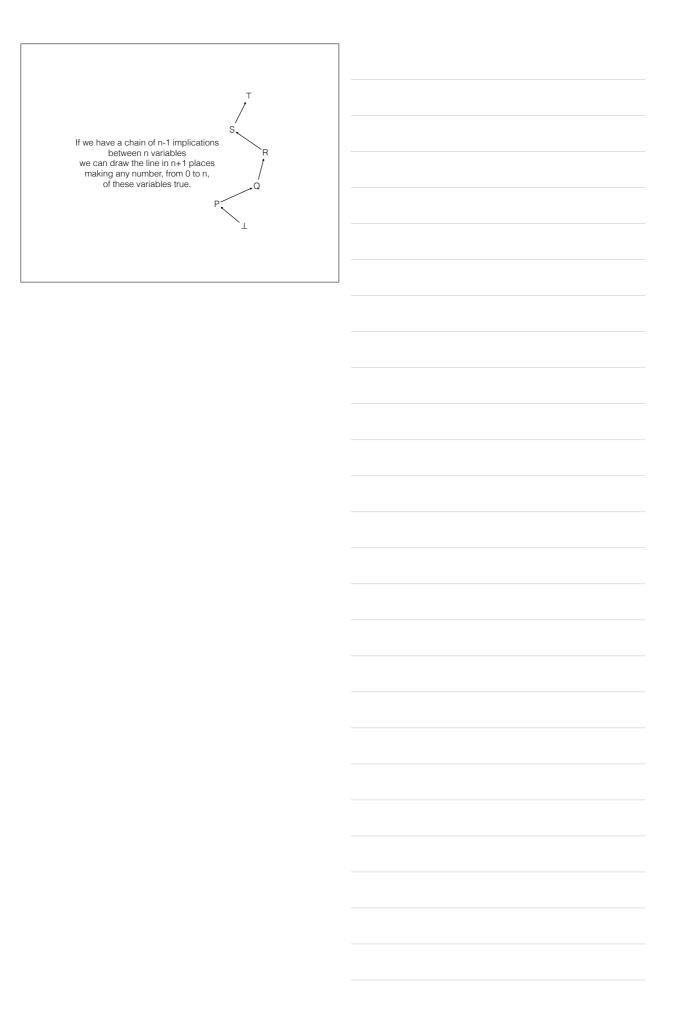
Informatics 1

SATisfaction revision

Michael Fourman

1



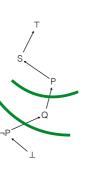


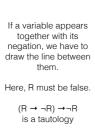
If some of the variables are negated we can do the same (but making the negated variables false when they fall above the line and true when they fall below)	

If a variable appears together with its negation, we have to draw the line between them.

Here, P must be true.

 $(\neg P \rightarrow P) \rightarrow P$ is a tautology

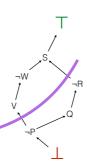




ars S S S S S S S S S S S S S S S S S S S	

The same trick works if our implications form a partial order. But we have more options since we can draw a wavy line.

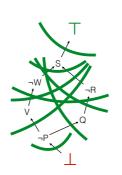
The **arrow rule** says that, whenever our line cuts an arrow, then the head must be on the side of true and the tail on the side of false.



The same trick works if our implications form a partial order. But we have more options since we can draw a wavy line.

Not all of the valid truth assignments are represented in this diagram.

How many are missing?



Clausal Form

Clausal form is a set of sets of literals $\Big\{ \ \{\neg A,C\}, \, \{\neg B,D\}, \, \{\neg E,B\}, \, \{\neg E,A\}, \, \{A,E\}, \, \{E,B\}, \{\neg B, \neg C, \, \neg D\} \, \Big\}$

A (partial) truth assignment makes a clause true iff it makes at least one of its literals true (so it can never make the empty clause {} true)

A (partial) truth assignment makes a clausal form true iff it makes all of its clauses true (so the empty clausal form $\{\}$ is always true).

9

2-SAT

A clausal form with at most two literals per clause.

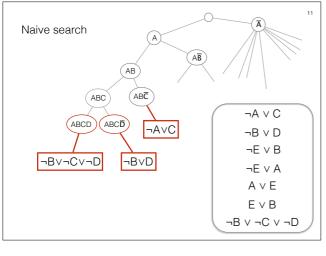
Corresponds to a conjunction of implications.

We can draw the directed graph and count the satisfying valuations.

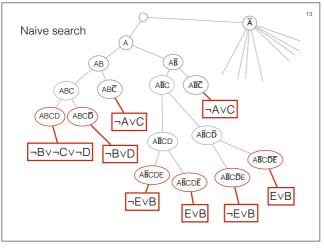
When 3 or more are involved, satisfaction gets complicated.

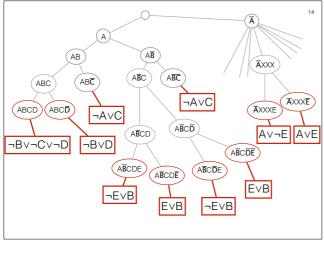
In general, we must search for satisfaction.

I	
l	
l	
l	
l	
l	
l	
l	
l	
l	
l	
l	
l	
l	
l	
l	
l	
l	
l	
l	
l	
J	



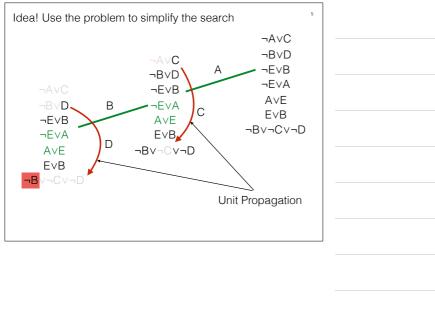
Naive search	
function Naive(V, Φ) if $V \models \neg \Phi$ then return false; if $V \models \Phi$ then return true; otherwise,	
choose an A mentioned in Φ but not mentioned in V return Naive(V^A, Φ)	
 Naive(V^¬A, Φ)	
(call Naive(Ø, Φ))	





١	
J	

Davis Putnam Logemann Loveland (DPLL)	
function Naive(V, Φ) if $V \models \neg \Phi$ then return false; if $V \models \Phi$ then return true;	
if V, C ⊨ X, where X is literal and clause C ∈ Φ return Naive(V^X, Φ)	
otherwise, choose an A mentioned in Φ but not mentioned in V	
return Naive(V^A, Φ) Naive(V^¬A, Φ)	
(call Naive(Ø, Φ))	



Davis Putnam Logemann Loveland (DPLL) implementation - add V to Φ	
unit propagation function DPLL(Φ) if Φ is a consistent set of literals then return true; if Φ contains an empty clause	
then return false; for every unit clause I in Φ Φ ← unit-propagate(I, Φ); I ← choose-literal(Φ);	
return DPLL(Φ υ {I}) or DPLL(Φ υ {not(I)});	

Clausal form is a set of sets of literals

$$\mathbf{X} = \left\{ X_0, X_1, \dots, X_{n-1} \right\}$$

Resolution rule for clauses

$$\frac{\textbf{X}}{(\textbf{X} \cup \textbf{Y}) \setminus \{ \neg A, A \}} \quad \text{where } \neg A \in \textbf{X}, \, A \in \textbf{Y}$$

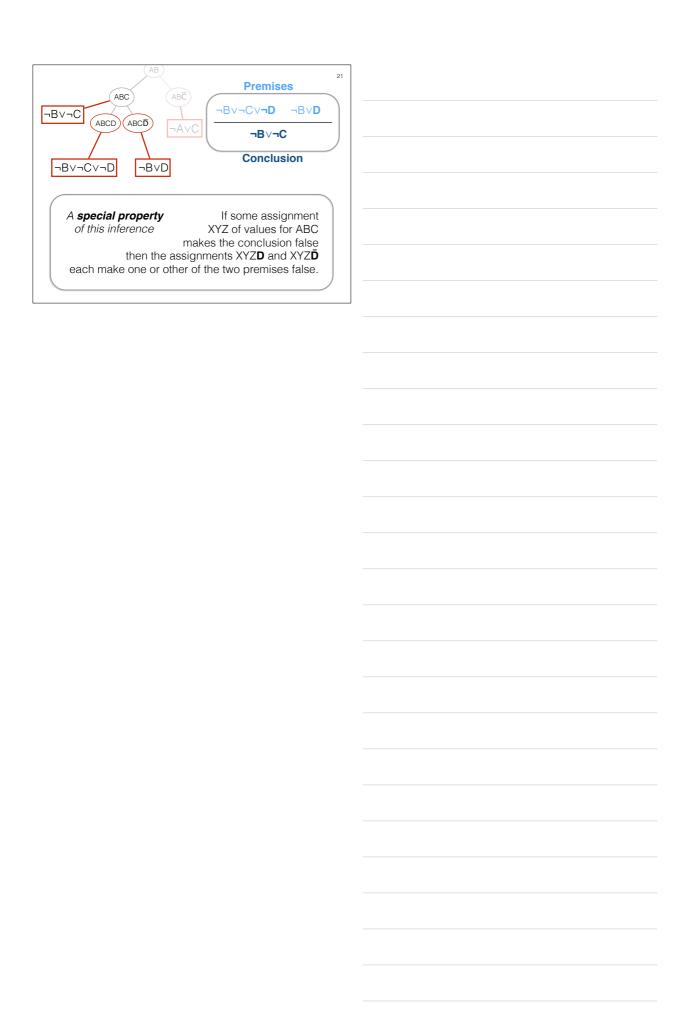
If either \boldsymbol{X} or \boldsymbol{Y} is a singleton then this is just unit propagation.

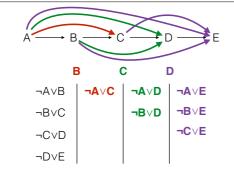
So, resolution is a generalisation of unit propagation. Search is no longer needed

18









We keep adding clauses obtained by resolution.

Davis Putnam - choose a variable then add all instances.

Different orders for resolution will give the same results.

Davis Putnam	
Take a collection $\mathcal C$ of clauses.	
For each propositional letter, A For each pair $(X, Y) \mid X \in C \land Y \in C \land A \in X \land \neg A \in Y$ if $R(X, Y, A) = \{\}$ return UNSAT if $R(X, Y, A)$ is consistent $C := C \cup \{R(X, Y)\}$ return SAT	
Where $R(X, Y, A) = X \cup Y \setminus \{A, \neg A\}$	
Heuristic: start with variables that occur seldom.	