

# Formal Verification

## Lecture 6: How LTL Model Checking Works

(Potted Version)

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# Recap

- ▶ Previously:
  - ▶ Model Checking CTL formulas
- ▶ This time:
  - ▶ Model Checking LTL
  - ▶ Language-theoretic viewpoint
  - ▶ From LTL formulas to automata (examples)

# LTL Semantics recap

## Definition (Transition System, with $S_0$ explicit)

A transition system  $\mathcal{M} = \langle S, S_0, \rightarrow, L \rangle$  consists of:

$S$	a finite set of states
$S_0 \subseteq S$	a set of initial states
$\rightarrow \subseteq S \times S$	transition relation
$L : S \rightarrow \mathcal{P}(Atom)$	a labelling function

such that  $\forall s_1 \in S. \exists s_2 \in S. s_1 \rightarrow s_2$

## Definition (Path)

A path  $\pi$  in a transition system  $\mathcal{M} = \langle S, S_0, \rightarrow, L \rangle$  is an infinite sequence of states  $s_0, s_1, \dots$  such that  $s_0 \in S_0$  and  $\forall i \geq 0. s_i \rightarrow s_{i+1}$ .

Paths are written as:  $\pi = s_0 \rightarrow s_1 \rightarrow s_2 \rightarrow \dots$

# The LTL Model Checking Problem

LTL model checking seeks to answer the question (with starting state  $s$  omitted):

Does  $\mathcal{M} \models \phi$  hold?

or, equivalently:

Does  $\forall \pi \in \text{Paths}(\mathcal{M}). \pi \models^0 \phi$  hold?

where (recall)  $\pi \models^i \phi$  means “path at position  $i$  satisfies formula  $\phi$ ”.

- ▶ The universal quantification is over the *infinite* set of paths and each path is infinitely long
- ▶ How can we check infinitely many paths?
- ▶ CTL: use a fixed point characterisation of the sets of *states*
- ▶ LTL: sets of *paths*; a path is a sequences of symbols ...  
... so use a *language-theoretic* approach.

## The language accepted by a transition system

Fix a transition system  $\mathcal{M} = \langle S, S_0, \rightarrow, L \rangle$

Let us consider the set of states  $S$  as an *alphabet*  $\Sigma$ .

Each infinite path  $\pi$  is then a word in the set  $\Sigma^\omega$ .

The set of all paths of  $\mathcal{M}$  is the **language**  $\mathcal{L}(\mathcal{M})$  **accepted by**  $\mathcal{M}$ .

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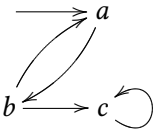
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Example:

$\mathcal{M}$	$\mathcal{L}(\mathcal{M})$
	$\{ abcccc\dots,$ $ ababcccccc\dots,$ $ abababcccccc\dots,$ $ ababababcccccc\dots,$ $ \dots,$ $ ababababababab\dots \}$

## Language of an LTL formula

Let  $\phi$  be an LTL formula, and  $S$  be the set of states of a model with the same set of atomic propositions as  $\phi$ .

Define the language  $\mathcal{L}(\phi)$  of  $\phi$  as:

$$\mathcal{L}(\phi) = \{\pi \in S^\omega \mid \pi \models^0 \phi\}$$

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Alternate definitions of the language of a transition system and of a formula use  $\mathcal{P}(Atom)$  as the alphabet instead of the set of states  $S$  (see H&R).

If the state has a boolean component for each element of  $Atom$ , then the definitions are equivalent.



## Language-theoretic presentation of validity

Recall: LTL model checking seeks to answer the question:

Does  $\mathcal{M} \models \phi$  hold?

or, equivalently:

Does  $\forall \pi \in \text{Paths}(\mathcal{M}). \pi \models^0 \phi$  hold?

Using the presentation of transitions systems and formulas as **languages**, this can now be phrased as:

$$\mathcal{L}(\mathcal{M}) \subseteq \mathcal{L}(\phi)$$

or, equivalently:

$$\mathcal{L}(\mathcal{M}) \cap \overline{\mathcal{L}(\phi)} = \emptyset$$

where  $\overline{X}$  means  $S^\omega - X$ .

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A (non-deterministic) Büchi automaton  $\langle S, \Sigma, \rightarrow, S_0, A \rangle$  consists of:

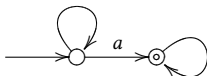
$S$	a finite set of states
$\Sigma$	an alphabet
$\rightarrow \subseteq S \times \Sigma \times S$	transition relation
$S_0 \subseteq S$	set of initial states
$A \subseteq S$	set of accepting states

An infinite word is **accepted** by a Büchi automaton iff there is a run of the automaton on which some **accepting state is visited infinitely often**.

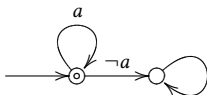
## Example Büchi automata

Here,  $\neg a$  means “any symbol that isn’t  $a$ ”. States marked with  $\odot$  are accepting.

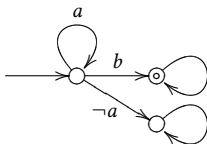
**F**  $a$ :



**G**  $a$ :



$a$  **U**  $b$ :



(Can also do them without the error paths.)

For the general construction for any formula  $\phi$ , see H&R, Section 3.6.3.

## LTL Model Checking Idea

We reformulated the LTL model checking problem to:

$$\mathcal{L}(\mathcal{M}) \cap \overline{\mathcal{L}(\phi)} = \emptyset$$

Now:

1. Observe that  $\overline{\mathcal{L}(\phi)} = \mathcal{L}(\neg\phi)$
2. Let  $A_\phi$  be a Büchi automaton such that  $\mathcal{L}(\phi) = \mathcal{L}(A_\phi)$ .
3. For a suitable notion of *composition*  $\mathcal{M} \otimes A$  of a transition system  $\mathcal{M}$  and a Büchi automaton  $A$ , we have that

$$\mathcal{L}(\mathcal{M} \otimes A) = \mathcal{L}(\mathcal{M}) \cap \mathcal{L}(A)$$

4. So, to check  $\mathcal{M} \models \phi$ , instead check

$$\mathcal{L}(\mathcal{M} \otimes A_{\neg\phi}) = \emptyset$$

5. Use *Fair CTL model checking* to check this last property. See H&R.

## Example: Model Checking LTL formula $G p$

1. Construct an automaton  $A_{\neg G p} = A_{F \neg p}$  for  $F \neg p$ , which takes as input infinite paths of states of a model  $\mathcal{M}$  and accepts just those paths that satisfy  $F \neg p$ .
2. Compose  $A_{F \neg p}$  and  $\mathcal{M}$  and ask whether the language of the composition is empty.
3. If the language is empty, then we know that  $G p$  is satisfied by  $\mathcal{M}$ . If not and we exhibit an accepting path, then that path is a counter-example to  $G p$ : it both is a path in  $\mathcal{M}$  and it satisfies  $A_{F \neg p} = A_{\neg G p}$ .

The next few slides examine this within the context of NuSMV.

## Emulating Büchi automata in NuSMV

Here is a transition system and LTL formula *emulating* a Büchi automaton  $A_F \neg p$  for checking  $F \neg p$ :

```
-- A 2 state automaton for  $F \neg p$ .
```

```
MODULE formula(sys)
```

```
VAR
```

```
  st : { 0, 1 };
```

```
ASSIGN
```

```
  init(st) := 0;
```

```
  next(st) := case
```

```
    -- loop in state 0 if p is always true
```

```
    st = 0 & sys.p : 0;
```

```
    -- If ever p is false, transition to state 1
```

```
    st = 0 & !sys.p : 1;
```

```
    -- then loop forever more in state 1
```

```
    st = 1          : 1;
```

```
  esac;
```

```
-- Accepting states: {1} as st = 1 occurs infinitely often
```

```
-- LTL expression of acceptance condition:
```

```
-- Specification is true just when there are no accepting paths
```

```
LTLSPEC ! G F st = 1;
```



## Composing Büchi automaton and transition system

This composition checks LTL property  $G p$  of the model:

```
-- A model M with 2 alternative definitions of a state property p
MODULE model
  VAR
    st : 0..2;
  ASSIGN
    init(st) := 0;
    next(st) := case
      st = 0 : {1,2};
      st = 1 : 1;
      st = 2 : 2;
    esac;
  DEFINE
    p := st = 0 | st = 1;
    -- p := TRUE

MODULE main
  VAR
    m : model;
    f : formula(m);
```

# Model Checking Results 1

With this definition in the model:

```
p := st = 0 | st = 1;
```

we get:

```
-- specification !( G ( F st = 1)) IN f is false
-- as demonstrated by the following execution sequence
Trace Type: Counterexample
-> State: 1.1 <-
  m.st = 0
  f.st = 0
  m.p = TRUE
-> State: 1.2 <-
  m.st = 2
  m.p = FALSE
-- Loop starts here
-> State: 1.3 <-
  f.st = 1
-- Loop starts here
-> State: 1.4 <-
-> State: 1.5 <-
```

The acceptance condition for a run in this composition is just the acceptance condition for a run of the formula automaton.

## Model Checking Results 2

With this definition in the model:

```
p := TRUE;
```

we get:

```
-- specification !( G ( F st = 1)) IN f is true
```

# Summary

- ▶ LTL Model Checking (H&R 3.6.2, 3.6.3)
  - ▶ Transition systems and formulas as languages
  - ▶ Formulas as Büchi automata
  - ▶ Simulating Büchi automata in NuSMV
- ▶ Next time: Binary Decision Diagrams

*[BDDs are] one of the only really fundamental data structures that came out in the last twenty-five years.*

— Donald Knuth “Fun with Binary Decision Diagrams”