

# Compiler Optimisation

## Dataflow Analysis

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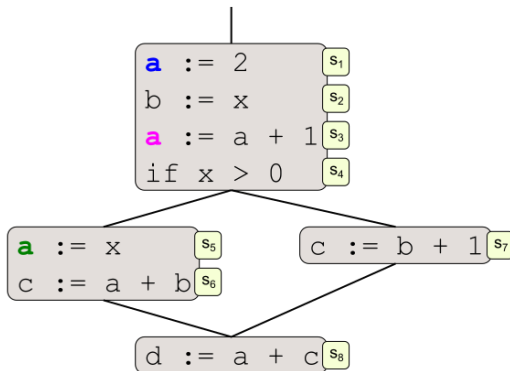
2019

# Introduction

- Optimisations often split into
  - **Analysis:** Calculate some values at points in program
  - **Transformation:** Improve the program where analysis allows
- Data flow analyses are common class of analyses
- Data pushed around control flow graph simulating effect of statements
- This lecture introduces:
  - Reaching definitions analysis in detail
  - Algorithms to compute data flow

# Reaching definitions

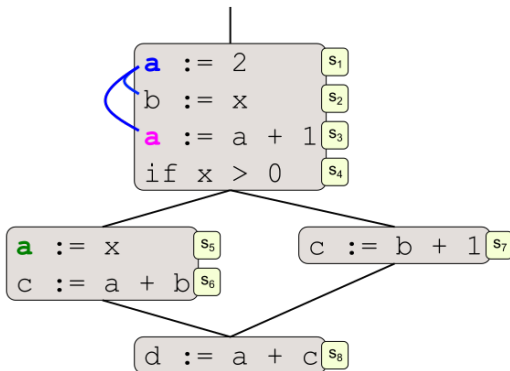
Definition of variable  $x$  at program point  $d$  **reaches** point  $u$  if  
 $\exists$  control-flow path  $p$  from  $d$  to  $u$  such that  
no definition of  $x$  appears on that path



Where do definitions of  $a$  reach?

# Reaching definitions

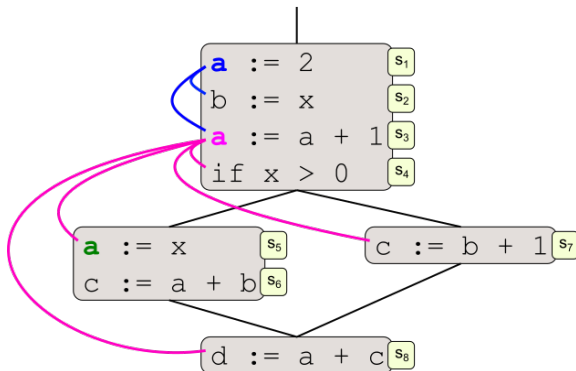
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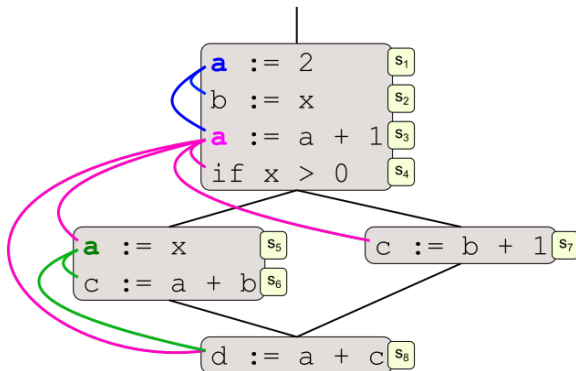
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# Reaching definitions

## Local analysis

Local analysis works only on a single basic block.

Computation by simulation or abstract interpretation<sup>1</sup>

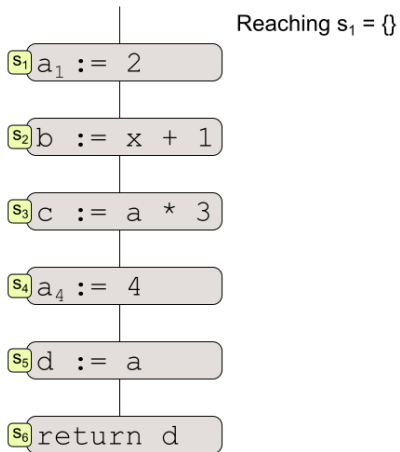
- Maintain a set of current reaching definitions
- At the start node, there are no definitions
- Go through all the statements from start to end
- If assignment statement  $x_i := \dots$ 
  - First,  $\forall j$  remove  $x_j$
  - Then, add  $x_i$  to the set
- Otherwise set unchanged

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<sup>1</sup>Execute only bits we care about, namely where definitions reach

# Reaching definitions

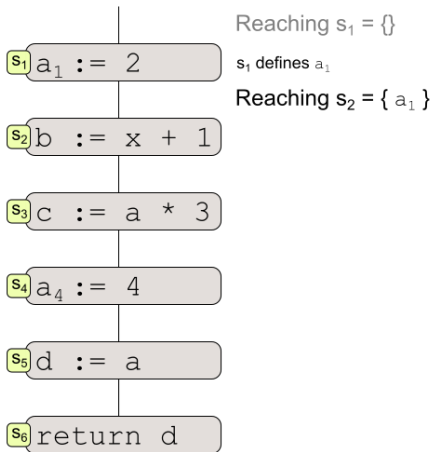
## Local analysis





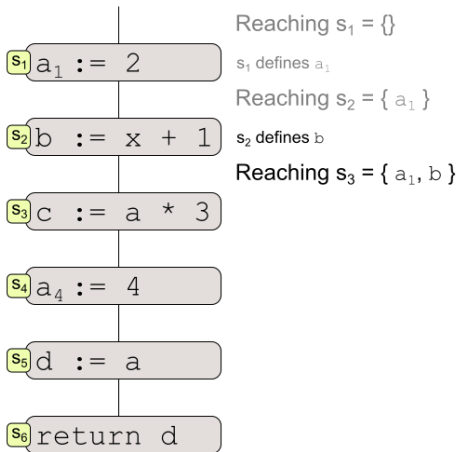
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## Local analysis



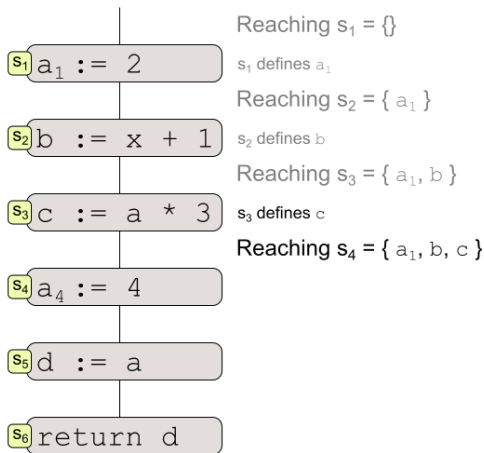
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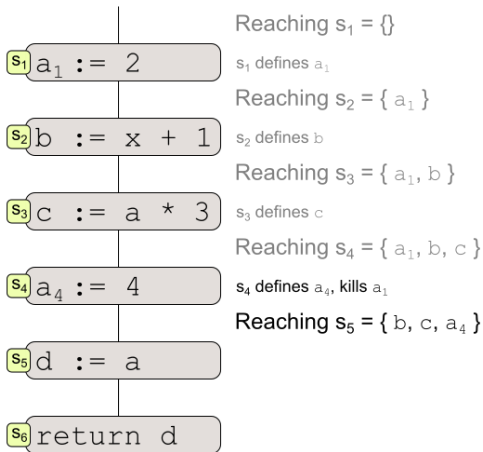
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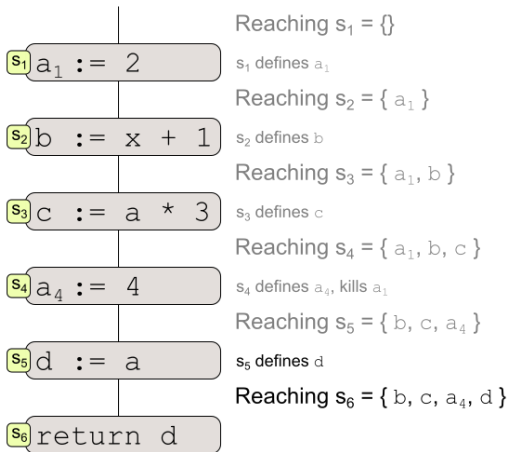
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## Local analysis



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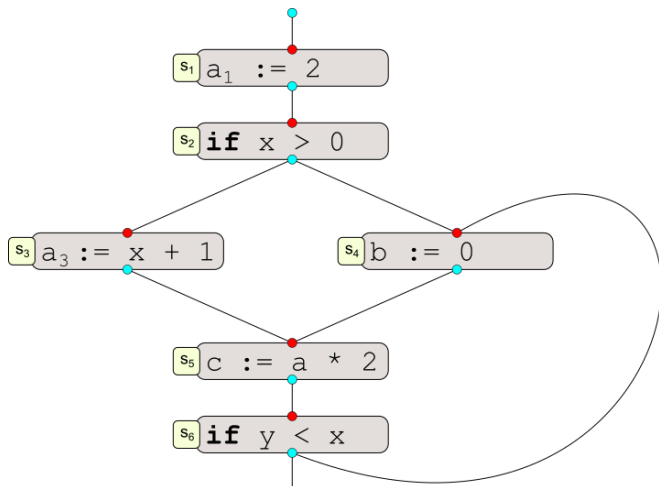
## Global analysis

- Control flow complicates matters
- Consider reaching definitions:
  - Entering a statement - the *In* program point for the statement
  - Leaving a statement - the *Out* program point for the statement
- Root is a special start node
- We will try the previous approach on this and see where it fails

# Reaching definitions

## Global analysis

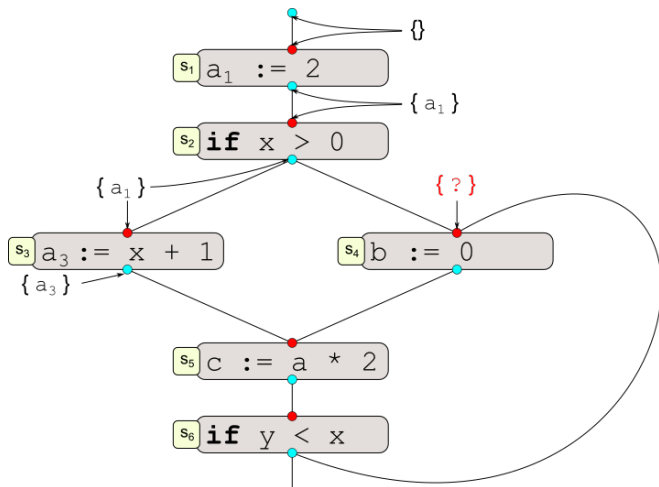
Control flow example; try the previous approach



# Reaching definitions

## Global analysis

$s_4$  has 2 predecessors; and don't know  $Out(s_6)$

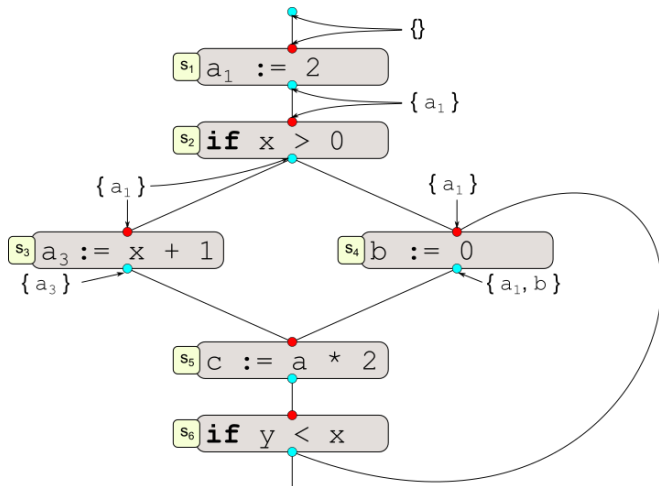




# Reaching definitions

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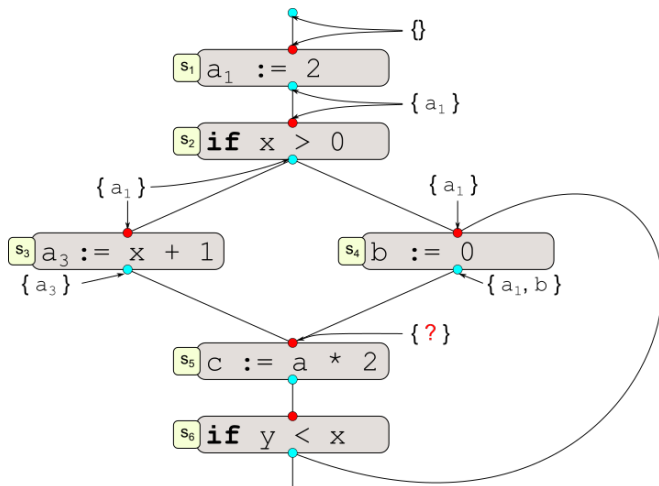
But, we know at least that  $a_1$  reaches  $s_4$



# Reaching definitions

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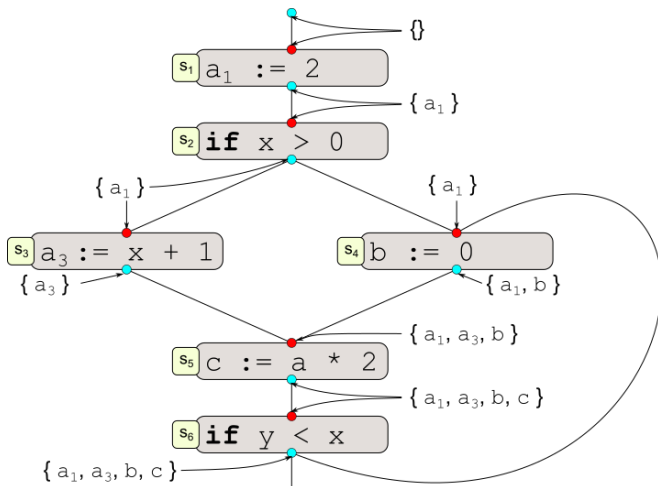
$s_5$  has 2 predecessors



# Reaching definitions

## Global analysis

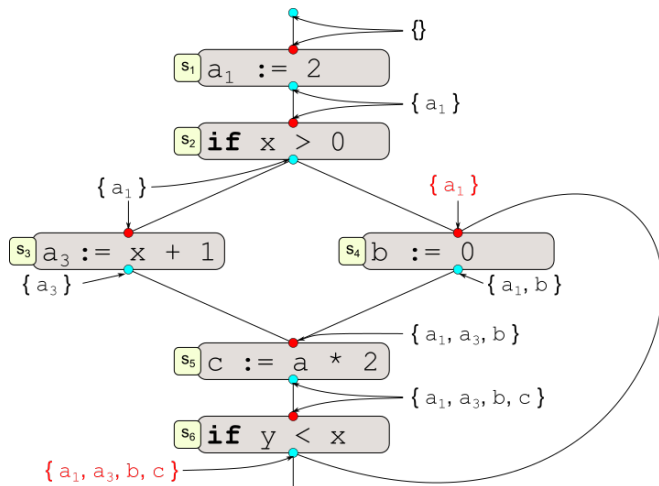
All incoming definitions reach; do union



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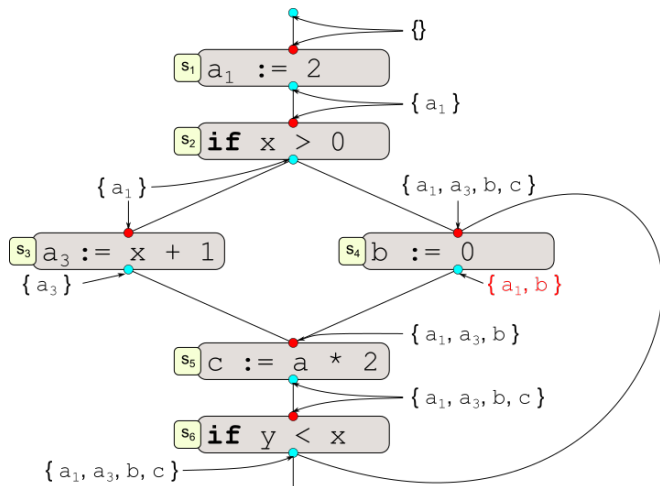
Inconsistency now we know more about  $Out(s_6)$



# Reaching definitions

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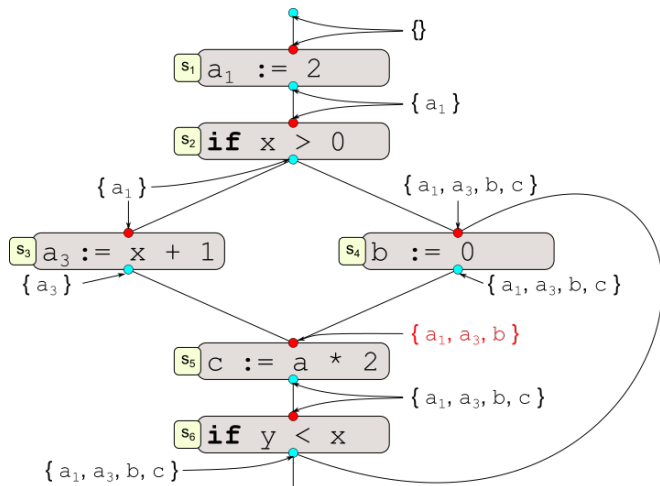
All incoming definitions reach; do union; inconsistency



# Reaching definitions

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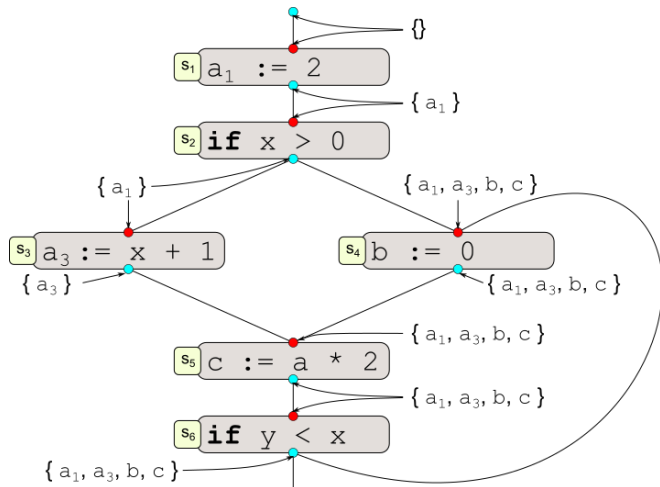
### Inconsistency



# Reaching definitions

## Global analysis

### Consistent state



# Reaching definitions

## Dataflow equations

Let us formalise our intuition



# Reaching definitions

## Dataflow equations

Let us formalise our intuition

- To simulate a statement,  $s$ , compute  $Out(s)$  from  $In(s)$   
If assignment to  $x$ , delete all definitions of  $x$ , add new definition

$$Out(s : d_i := ...) = (In(s) - \{d_j; \forall j\}) \cup \{d_i\}$$

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- Multiple edges must merge to compute  $In(s)$  from  $Pred(s)$   
All incoming definitions reach

$$In(s) = \bigcup_{\forall p \in Pred(s)} Out(p)$$

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- If we don't know, start with empty  
 $Init(s) = \emptyset$

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- Note that often  $Out(s)$  is written

$$Out(s : d_i := ...) = (In(s) - Kill(s)) \cup Gen(s)$$

The  $Gen$  and  $Kill$  sets can often be precomputed

Also, EaC combines  $In$  and  $Out$  to use only one equation

# Reaching definitions

## Observations

- Analysis defines properties at points with *recurrence relations*
- Assumes a control flow graph
- Start with a conservative approximation
- Refine the approximations
- Stop when consistent (no further change)
- Information flows *forward* from a statement to its successors

# Ingredients of dataflow analysis

- **Direction** - forward or backward

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<sup>2</sup>In a later lecture

# Ingredients of dataflow analysis

- **Direction** - forward or backward
- **Transfer function** - computes statement effect
  - e.g.  $Out(s) = Gen(s) \cup (In(s) - Kill(s))$

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- **Meet operator** - merges values from multiple incoming edges
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  - Should be most conservative value
  - Start node often a special case; e.g. encoding function parameters

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- **Value set** - the bits information being passed around
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- **Initial values**
  - Should be most conservative value
  - Start node often a special case; e.g. encoding function parameters
- Some properties of the above to ensure termination<sup>2</sup>

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<sup>2</sup>In a later lecture

# Algorithms

## Round-robin iterative algorithm

```
for each node3, n, do  
    Initialise n  
while values changing do  
    for each node do  
        Apply meet and transfer function
```

There are many, many data flow algorithms that fit

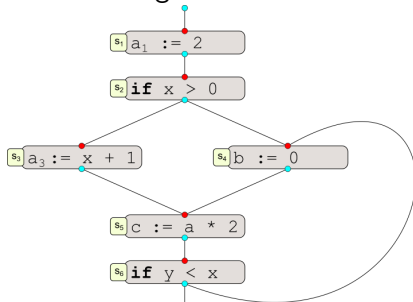
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<sup>3</sup>Note, node not statement. Include special start node

# Algorithms

## Round-robin iterative algorithm

Reaching definitions control flow example - Calculate RD sets?



$$In(s) = \bigcup_{\forall p \in Pred(s)} Out(p)$$

$$Out(s : d_i := \dots) = (In(s) - \{d_j; \forall j\}) \cup d_i$$

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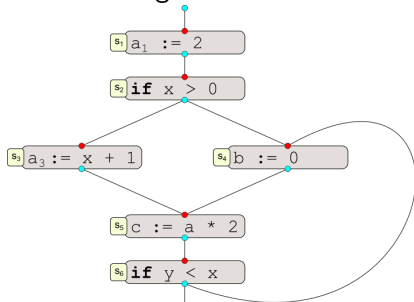
Node	s1	s2	s3	s4	s5	s6
RD <sup>4</sup>	∅	∅	∅	∅	∅	∅

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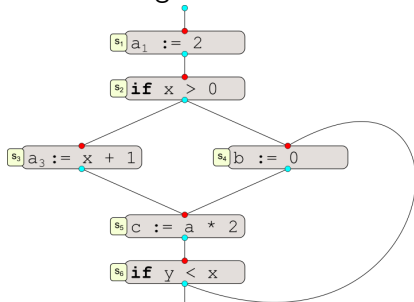
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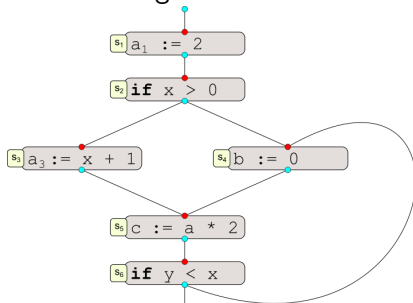
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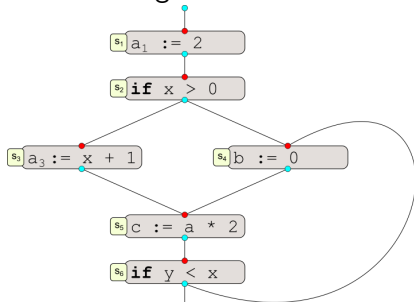
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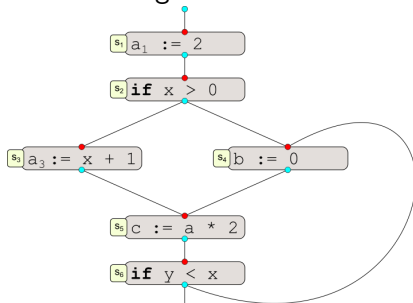
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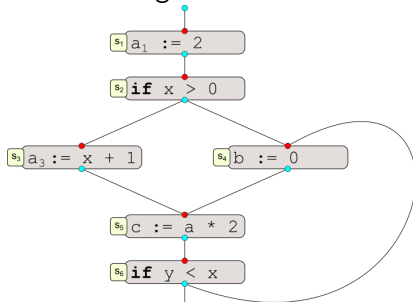
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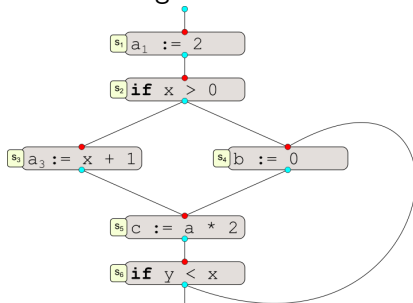
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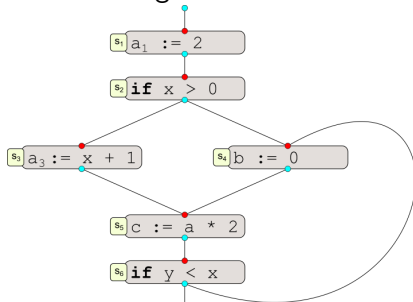
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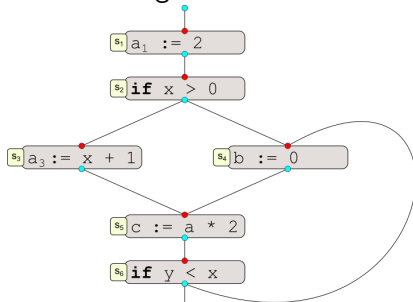
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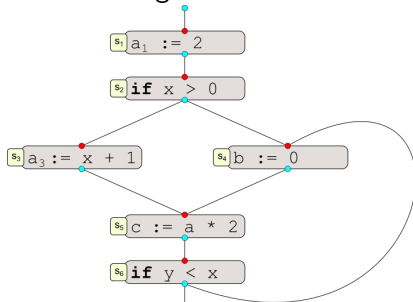
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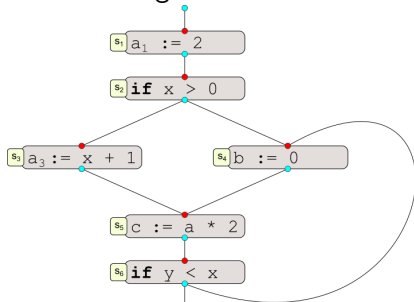
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	$\emptyset$	a1	a1	a1	a1, a3, b	a1, a3, b, c
	$\emptyset$	a1	a1	a1, a3, b, c	a1, a3, b, c	

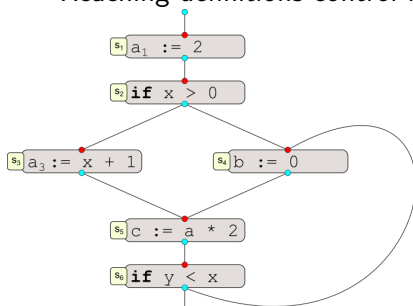
<sup>4</sup>For brevity, *In* and *Out* are combined



# Algorithms

## Round-robin iterative algorithm

Reaching definitions control flow example - Calculate RD sets?



$$In(s) = \bigcup_{\forall p \in Pred(s)} Out(p)$$

$$Out(s : d_i := \dots) = (In(s) - \{d_j; \forall j\}) \cup d_i$$

$$RD(s) = \bigcup_{\forall p: d_i = \dots \in Pred(s)} (RD(p) - \{d_j; \forall j\}) \cup \{d_i\}$$

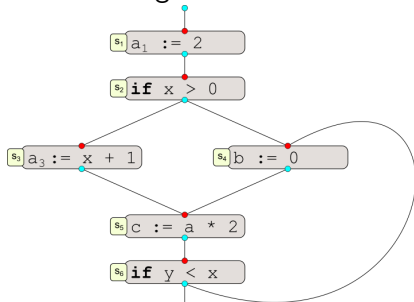
Node	s1	s2	s3	s4	s5	s6
RD <sup>4</sup>	$\emptyset$	$\emptyset$	$\emptyset$	$\emptyset$	$\emptyset$	$\emptyset$
	$\emptyset$	a1	a1	a1	a1, a3, b	a1, a3, b, c
	$\emptyset$	a1	a1	a1, a3, b, c	a1, a3, b, c	a1, a3, b, c

<sup>4</sup>For brevity, *In* and *Out* are combined

# Algorithms

## Round-robin iterative algorithm

Reaching definitions control flow example - Calculate RD sets?



$$In(s) = \bigcup_{\forall p \in Pred(s)} Out(p)$$

$$Out(s : d_i := ...) = (In(s) - \{d_j; \forall j\}) \cup d_i$$

↓

$$RD(s) = \bigcup_{\forall p: d_i := \dots \in Pred(s)} (RD(p) - \{d_j; \forall j\}) \cup \{d_i\}$$

Node	s <sub>1</sub>	s <sub>2</sub>	s <sub>3</sub>	s <sub>4</sub>	s <sub>5</sub>	s <sub>6</sub>
RD <sup>4</sup>	∅	∅	∅	∅	∅	∅
	∅	a <sub>1</sub>	a <sub>1</sub>	a <sub>1</sub>	a <sub>1</sub> , a <sub>3</sub> , b	a <sub>1</sub> , a <sub>3</sub> , b, c
	∅	a <sub>1</sub>	a <sub>1</sub>	a <sub>1</sub> , a <sub>3</sub> , b, c	a <sub>1</sub> , a <sub>3</sub> , b, c	a <sub>1</sub> , a <sub>3</sub> , b, c
	∅	a <sub>1</sub>	a <sub>1</sub>	a <sub>1</sub> , a <sub>3</sub> , b, c	a <sub>1</sub> , a <sub>3</sub> , b, c	a <sub>1</sub> , a <sub>3</sub> , b, c

<sup>4</sup>For brevity, *In* and *Out* are combined

# Algorithms

## Termination

Does round robin for reaching definitions always terminate?

# Algorithms

## Termination


Does round robin for reaching definitions always terminate?

**Yes**

- Each step of the iteration can only grow a set or leave unchanged
- Finite number of elements in each set, so finite number of times can change
- Each iteration either has a change or stops
- Must terminate

# Algorithms

## Speeding up

- Round-robin algorithm is slow, may require many passes through nodes
- Can speed up by considering basic blocks (e.g. compute Gen and Kill for whole block)
- Only nodes which have inputs changed need to be processed - use work list
- Reducible graphs can be handled more efficiently (see  EaC p.527)

# Algorithms

## Order matters

May reduce number of iterations by changing evaluation order<sup>5</sup>

- Backward analysis - evaluate node after successors

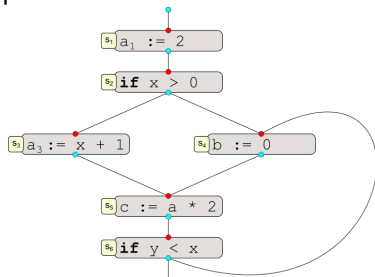
Use **postorder**

- Forward analysis - evaluate node before successors

Use **reverse postorder**

Orders for reaching definitions example

Post(1)	$s_4 s_6 s_5 s_3 s_2 s_1$
Post(2)	$s_6 s_5 s_4 s_3 s_2 s_1$
Rev(1)	$s_1 s_2 s_3 s_5 s_6 s_4$
Rev(2)	$s_1 s_2 s_3 s_4 s_5 s_6$



<sup>5</sup>A lot of theory about this. Given certain conditions then a round-robin postorder alg will finish in  $d(G) + 3$  passes where  $d(G)$  is the loop connectedness. Muchnick for more details

# Algorithms

## Limitations

Data flow analyses have some limitations:

- Static analysis may be very conservative
- True CFG generally undecidable
  - (e.g. condition may be constant but unprovable)
- Pointers introduce aliases
  - E.g. `*x = 10`; Does `x` point to another variable, `y` or `z`? That would give a definition of `y` or `z`. May not know at compile time which
  - Precise alias analysis not solved
- Array access
  - Generally cannot tell which indices are used
- Function calls may not be reasoned across
  - If inter-procedural, virtual calls and function pointer expand sets of functions

# Algorithms

## Path sensitive dataflow

- Some IRs/analyses force different information along edges
  - Range analysis: compute possible ranges of integers; must know which edge out of `if`
  - Java exception: change the stack contents
- Each edge has a label - (e.g. `THEN`, `ELSE`, `EXCEPTION`)
- Transfer function includes label as argument



# Summary

- Reaching definitions
- Data flow algorithms