Instruction Scheduling

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Instruction Scheduling



Course Structure

- Introduction and Recap
- Course Work
- Scalar optimisation and dataflow
- L5 Code generation
- L6 Instruction scheduling
- Next register allocation

Overview

- Scheduling to hide latency and exploit ILP
- Dependence graph dependences between instructions + latency
- Local list Scheduling + priorities
- Forward versus backward scheduling
- Software pipelining of loops



Aim

- Order instructions to minimise execution time. Hide latency of instructions such as loads and branches by executing instructions in their shadow
- Exploit instruction level parallelism by making sure there are multiple instructions available to be simultaneously executed
- Two flavours of ILP: Superscalar and vliw. Both require similar analysis but vliw is static scheduled and requires more explicit treatment
- Affected by machine resources number and type of functional unit, number of registers
- Assume register allocation is separately performed later.



Example Superscalar, 1 FU: New Op each cycle iff operands ready

 $w = w^2 x^* y^* z$. Assume global activation pointer in r0

load/stores 3 cycles, mults 2, others 1

1 loadAI r0, $@w \rightarrow r1$ 1 loadAI r0, $@w \rightarrow r1$ 4 add r1,r1 ->r1 $2 \text{ loadAI } r0, @x \rightarrow r2$ 5 loadAI r0, $@x \rightarrow r2$ 3 loadAI r0,@y ->r3 8 mult r1,r2->r1 4 add r1,r1 ->r1 9 loadAI r0,@y ->r2 5 mult r1,r2->r1 12 mult r1,r2 ->r1 6 loadAI r0,@z->r2 13 loadAI r0,@z->r2 7 mult r1,r3 ->r1 16 mult r1,r2 ->r1 9 mult r1,r2 ->r1 18 storeAI r1->r0.@w 11 storeAI r1->r0.@w 21 r1 is free 14 r1 is free Second version - extra register, move loads earlier. Space vs time



List Scheduling

- Build a dependence graph of operations and delays
- Determine schedule to minimise execution time
- NP-complete: difficulty comes with determining which of the many available operands to schedule- need a priority function for tie breaking
- Use a greedy approach list scheduling for local blocks
- Extend to greater scope later.

List Scheduling

```
cycle = 0
ready = leaves of dependence graph G
active = empty
while (ready union active != empty)
if available remove an instruction from ready based on priority
add instruction to active
for each instruction in active
if completed remove from active
for each successor of instruction
```

if successors operand ready then add to ready



Ignore anti-dependences - assume unlimited registers Critical path a b d f h i



Example



1 a loadAI r0,0w -> r1 2 c loadAI r0,0x -> r2 3 e loadAI r0,0y ->r3 4 b add r1,r1 ->r1 5 d mult r1,r2->r1 6 g loadAI r0,0z->r2 7 f mult r1,r3 ->r1 9 h mult r1,r2 ->r1 11 i storeAI r1->r0,0w

List Scheduling here uses critical path as priority. The labelled arcs denote critical path length for each instruction. Choose highest value first.



Priorities

- The longest latency path or critical path is a good priority
- Last use of a value decreases demand for register as moves it nearer def
- Number of descendants encourages scheduler to pursue multiple paths
- Longer latency first others can fit in shadow
- Forward list scheduling does well but sometimes backward does better.

Forward vs Backward: 3 unit VLIW. Does NOT wait for operands

You are responsible for them being available: Fill delays with noops!



Schedule for 3 units - integer, integer and store

Priority to critical path - tie break left to right

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Forward and Backward Scheduling: Blanks = noops

	Int	Int	Stores
1	loadl1	lshift	
2	loadI2	loadI3	
3	loadI4	add1	
4	add2	add3	
5	add4	addl	store1
6	cmp		store2
7			store3
8			store4
9			store5
10			
11			
12			
13	cbr		

	Int	Int	Stores
1	loadl1		
2	addl	lshift	
3	add4	loadI3	
4	add3	loadI2	store5
5	add2	loadl1	store4
6	add1		store3
7			store2
8			store1
9			
10			
11	cmp		
12	cbr		
13			



Loop scheduling

- Loop structures can dominate execution time
- Specialist technique software pipelining
- Calculation of minimum initiation interval
- This corresponds to the critical path of a loop
- Modulo Scheduling take into account resources



Software pipelining

- Scheme aimed at exploiting ILP in loops: Lam 1998. Significant impact on performance on statically scheduled vliw.
- Previous techniques need unrolling of loop to perform well.
- The recurrence or cyclic dependence length is the equivalent to the critical path
- Achieves performance by overlapping different iterations of a loop
- Has same effect as hardware pipelining available in out-of-order superscalar

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Example

```
r_c = 0
r_0a = 0a
r_1 = n*4
r_ub = r1+r_0a
r_ub = r1+r_0a
r_ub = r1+r_0a
r_ub = r1+r_0a
r_ub = r_0a > r_ub \text{ goto exit}
r_c = r_c + r_a
r_0a = r_0a + 4
r_0a <= r_ub \text{ goto Loop}
exit: store(c) = rc
```

If branches take 1 cycle - each iteration takes 4 cycles after scheduling the loop body. $r_0a = performed$ in shadow of load

Iterations can overlapped: Recurrence on r_c shown



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Software pipelining

Fixed Resources



Unbounded Iterations

Each unit is responsible for part of the computation of an iteration. An iteration is pipelined across several units

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Pipeline evaluation: Recurrence on r_c not shown

	Load	Int	Branch
1	$r_a = load(r_@a)$	$r_@a = r_@a + 4$	
2	$r_a = load(r_@a)$	$r_@a = r_@a+4$ $r_c = r_c + r_a$	if r_@a <= r_ub goto loop
	$r_a = load(r_@a)$	$ r_@a = r_@a+4 r_c = r_c + r_a $	if r_@a <= r_ub goto loop
n	$r_a = load(r_@a)$	$r_@a = r_@a+4$ $r_c = r_c + r_a$	if r_@a <= r_ub goto loop
n+1		$r_@a = r_@a+4$ r c = r c + r a	if r_@a <= r_ub goto loop

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Code template



$$r_@a = r_@a+4$$
epilogue
$$r_c = r_c + r_a$$

The schedule must consider function unit type, data dependences and latencies Assume 3 functional units: Load, Int and Branch and vliw processor Generate this code filling in with noops

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Code

	Load Unit	Integer Unit	Branch Unit
	nop	$r_@a = @a$	nop
	nop	r1 = n * 4	nop
	nop	$r_ub = r1 + r_@a$	nop
	$r_a = load(r_@a)$	rc = 0	nop
	nop	$r_@a = r_@a + 4$	if r_@a >r_ub goto exit
Loop:	r_a =load(r_@a)	$r_@a = r_@a + 4$	if r_@a >r_ub goto exit
	nop	$r_c = r_c + r_a$	nop
exit	nop	nop	nop
	nop	$r_c = r_c + r_a$	nop

Respect dependencies and latencies. Inner loop takes just 2 cycles rather than 4 How do we do this automatically?

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Applying software pipelining

- calculate an initiation interval bounded by number of functional units and recurrence distance - smaller ii = smaller loop body =faster
- 2 integer ops, 1 unit, min ii = ²/₁. Recurrences on c delay 1 over 1 iteration so min ii is ¹/₁. Combined min ii =2.
- Try scheduling with min ii using modulo scheduling
- If fails try with increased ii
- put in prologue and epilogue code
- May need to put in register copies etc not considered here

Data Dependence graph and schedule

1: $r_c = 0$ 2: r_@a = @a 3: r1 = n*44: r_ub= r1+r_@a 5: if r_@a >r_ub goto exit 6: loop: $r_a = load(r_@a)$ 7: $r_{c} = r_{c} + r_{a}$ 8: r_@a = r_@a +4 if r_@a <= r_ub goto Loop 9: 10:exit: store(c)=rc



Schedule instructions to units modulo ii. 6 and 8 map into load and integer unit on cycle 0. 9 map into branch on cycle 1. 7 maps into integer on cycle 3 mod 2 = cycle 1.



Current research

- Much research in different software pipelining techniques
- Difficult when there is general control flow in the loop
- Predication in IA64 for example really helps here
- Some recent work in exhaustive scheduling -ie solve the NP-complete problem for basic blocks. Show that it is possible if only used when list scheduling fails
- Despite separation of concerns, code generation and ISA have an impact on scheduling. Cavazos et al PLDI 2004 look at using machine learning to really automate instruction scheduling

Summary

- Dependence graph dependences between instructions + latency
- Local list Scheduling + critical path
- Superblock and trace scheduling greater scope for optimisation
- Specialist technique software pipelining
- Calculation of minimum initiation interval
- Modulo Scheduling take into account resources

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