Scalar Optimisation Part 2

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Scalar Optimisation

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Course Structure

- L1 Introduction and Recap
- 4-5 lectures on classical optimisation
 - 2 lectures on scalar optimisation
 - Last lecture on redundant expressions
 - Today look at dataflow framework and SSA
- 4-5 lectures on high level approaches
- 4-5 lectures on adaptive compilation

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Dataflow analysis for redundant expressions: calculate available DEExpr(b) - subexpressions not overwritten in this block b (local) NOTKILLED(b) - subexpressions that are not killed (local) $AVAIL(b) = \bigcap_{p \in pred(b)} (DEExpr(p) \cup (AVAIL(p) \cap NOTKILLED(p)))$

- DEExpr(b) and NOTKILLED(b) can be calculated locally for each basic block b
- Initialise $AVAIL(b) = \emptyset$
- Find for each block in turn calculate AVAIL(b) based on predecessors
- Keep repeating the procedure till results stabilise.





3 informatics



Node	A	В	С	D	E	F	G
pred	-	A	A	С	С	D,E	B,F
DEExpr	a+b	c+d	a+b	b+18	a+17	a+b	a+b
			c+d	a+b	c+d	c+d	c+d
				e+f	e+f	e+f	
Kill				e+f	e+f		

Calculate Avail(b) for each Basic Block b starting at block A $AVAIL(A) = \emptyset$

 $\begin{aligned} AVAIL(B) &= (DEExpr(A) \cup (AVAIL(A) \cap NOTKILLED(A))) \\ &= \{a+b\} \cup (\emptyset \cap U) = \{a+b\} \end{aligned}$

 $\begin{aligned} AVAIL(G) &= (DEExpr(B) \cup (AVAIL(B) \cap NOTKILLED(B))) \\ & \bigcap (DEExpr(F) \cup (AVAIL(F) \cap NOTKILLED(F))) \end{aligned}$



Find available expressions

Post order

Node	A	В	C	D	E	F	G
Avail1	Ø	a+b	a+b	a+b,c+d	a+b,c+d	e+f	c+d
Avail2						a+b,c+d,e+f	a+b,c+d

Reverse Post order: Finds fixed point on first iteration

Node	A	В	C	D	E	F	G
Avail1	Ø	a+b	a+b	a+b,c+d	a+b,c+d	a+b,c+d,e+f	a+b,c+d

Traversal order affects number of iterations to solve equations.

Will solution always terminate?

How many iterations? What class of problems?



Another example: Dataflow analysis for live variables

- A variable v is live at a point p if there is a path from p to a use of v along which v is not redefined.
- Useful to eliminate stores of variables no longer needed useless store elimination
- Useful for detecting uninitialised variables
- Essential for global register allocation
- Determines whether a variable MAY be read after this BB and is therefore a candidate to be put in a register

Equations for live vars

$$\begin{split} LiveOut(b) &= \bigcup_{p \in succ(b)} (UEVar(p) \cup (LiveOut(p) \cap NotKilledVar(p))) \\ UEVar(p) \text{ upwardly exposed variables used in p before redefinition} \\ NotKilledVar(p) \text{ var not defined in this block p} \end{split}$$

- Similar to AVAIL
- Depends on successors not predecessors backward vs forward
- AVAIL is an all paths problem (\cap) LiveOut any path (\cup)
- Can also be solved using iterative algorithm. (How long/terminate?)

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Example of LiveOut



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Solution:

	B0	B1	B2	B3	B4	B5	B6	B7
UEVar	-	-	-	-	-	-	-	a,b,c,d,i
NVarKill	a,b,c,d,y,z	b,d,i,y,z	a,i,y,z	b,c,i,y,z	a,b,c,i,y,z	a,b,d,i,y,z	a,c,d,i,y,z	a,b,c,d

Reverse Post order

Iter	B0	B1	B2	B3	B4	B5	B6	B7
0	-	-	-	-	-	-	-	-
1	-	-	a,b,c,d,i	-	-	-	a,b,c,d,i	_
2	-	a,i	a,b,c,d,i	-	a,c,d,i	a,c,d,i	a,b,c,d,i	i
3	i	a,i	a,b,c,d,i	a,c,d,i	a,c,d,i	a,c,d,i	a,b,c,d,i	i
4	i	a,c,i	a,b,c,d,i	a,c,d,i	a,c,d,i	a,c,d,i	a,b,c,d,i	i
5	i	a,c,i	a,b,c,d,i	a,c,d,i	a,c,d,i	a,c,d,i	a,b,c,d,i	i

5 iterations to fixed point. Is this the quickest solution?

Solution 2

Post order

Iter	B0	B1	B2	B3	B4	B5	B6	B7
0	-	-	-	-	-	-	-	-
1	i	a,c,i	a,b,c,d,i	a,c,d,i	a,c,d,i	a,c,d,i	a,b,c,d,i	_
2	i	a,c,i	a,b,c,d,i	a,c,d,i	a,c,d,i	a,c,d,i	a,b,c,d,i	i
3	i	a,c,i	a,b,c,d,i	a,c,d,i	a,c,d,i	a,c,d,i	a,b,c,d,i	i

- What is the best order?
- Question: why does all this work?

10 informatics

Semi-lattice

A set L and a meet operator \land such that $\forall a, b, c \in L$

1. $a \wedge a = a$

2. $a \wedge b = b \wedge a$

3. $a \wedge (b \wedge c) = (a \wedge b) \wedge c$

 \land imposes an order $a \ge b \rightarrow a \land b = b$

Contains a bottom element \bot , $\bot \land a = \bot$, $a \ge \bot$

Models an ordered finite set of facts

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Semi-lattice

- Choose a semi-lattice to represent the facts
- Attach a meaning to each $a \in L$. Each a distinct set of facts
- For each node (basic block) n in the CFG, associate a function $f_n: L \mapsto L$.
- It models the behaviour of the code belonging to \boldsymbol{n}
- Avail: Semilatice is $(2^E, \wedge)$, E the set of all expressions, \wedge is \cap .

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Round Robin algorithm

```
for i = 1 to N
  Avail(b[i]) = 0
change =true
while (change)
  change =false
  for i = 0 to N
    temp = intersect[i] (Def(x) union (Avail x union Nkill(x)))
    if avail(b[i]) != temp
      change = true
      avail(b[i]) =temp
```

Standard algorithm to solve dataflow. There are faster ones.

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Iterative data flow

- If f is monotone and the semi-lattice bounded then the round robin algorithm terminates and finds a least fixed point
- Given certain technical constraints on f, there is a unique fixed point and **order** of evaluation does not matter
- Pick an order that converges quickly
- A lot of theory about this. Given certain conditions then a round-robin postorder alg will finish in d(G) + 3 passes where d(G) is the loop connectedness
- Most dataflow fits this. Means runs in linear time. Muchnick for more details for more in depth explanation.



Other dataflow analysis

- Reaching definitions : Find all places where a variable was defined and not killed subsequently
- Very Busy Expressions: An expression is evaluated on all paths leaving a block
 used for code hoisting
- Constant Propagation. Shows that a variable v has the same value at point p regardless of control-flow. Allows specialisation.
- Uses a very small lattice and terminates quickly. Easy to express using SSA form



SSA form

- Most advanced analysis needs to track def and uses of vars rather than basic block summary
- Variables can have multiple definitions and uses
- Need to keep track of which def flows to which use over all possible control-flow paths
- SSA gives a unique name to each definition
- Need ϕ nodes to handle merging of control-flow
- Can be constructed in O(n) time. Increasingly standard form.



Example SSA B0_ i = 1 B1 a1= Ø (a0,a4) a2= a3 = b = B2 B3 d = c = d= B4 d= B5 c =b = B6 $\begin{array}{c} a4 = (a2,a3) \\ y = a4 + b \end{array}$ i = i+1

Algorithms using SSA

- Many dataflow algorithms are considerably simplified using SSA
- Value numbering. Each value has a unique name allowing value numbering on complex control-flow
- $Constants(n) = \bigwedge_{p \in pred(n)} F_p(Constants(p))$
- Small lattice $\top > \{-maxint ... + maxint\} > \bot$
- Meet operator: $\top \land x = x, \bot \land x = \bot, c_i \land c_j = c_i if c_i = c_j else \bot$
- F_p depends on the operations in block. Optimistic algorithm

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Algorithms using SSA: Constant propagation

Model F_p

x = y if Constants(p) = $\{(x, c_1), (y, c_2), ..\}$ then Constants(p) = Constants(p) - $(x, c_1) \cup (x, c_2)$

• eg update old value of x (c1) with the new value in y (c2)

 $x = y \text{ op } z \text{ if Constants}(p) = \{(x, c_1), (y, c_2), (z, c_3)..\}$ then Constants(p) = Constants(p) - $(x, c_1) \cup (x, c_2opc_3)$

• eg update old value of x (c1) with the new value after (c2 op c3)

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Limits and Extensions

- Dataflow assumes that all paths in the CFG are taken hence conservative approximations
- Guarded SSA attempts to overcome this by having additional meet nodes γ,η and μ to carry conditional information around
- Arrays considered monolithic objects A[1] = ..., =A[2] considered a def-use
- Array based SSA models access patterns can be generalised using presburger formula
- Inter-procedural challenging. Pointers destroy analysis! Large research effort in points-to analysis.



Summary

- Levels of optimisations
- Examined dataflow as a generic optimisation framework
- Round robin algorithm and lattices
- Using SSA as a framework for optimisation
- Limits of dataflow -other techniques?
- Next lecture code generation.