

Volume Illumination

Visualisation – Lecture 11

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Previously : Volume Rendering

- Image Order Volume Rendering
 - ray casting / intensity transfer function / opacity transfer function
- Artifacts caused by the sampling method, step size etc.





Shear-warp Algorithm

- An efficient method to traverse the volume data [Lacroute '94]
- Assumes a orthographic camera model
 - projection perpendicular to image plane



Ray casting with templates



The rays are parallel:

- Each ray forms an identical path of voxels through the grid
- Path known as a *template*
- Save computation

Note : some voxels are missed - problem : artefacts will be produced.





- Perform warping to get samples back into 2D image grid correctly
 - amount of warp required dependant on viewing angle to volume



Shear-warp factorisation

- Instead of traversing along rays, visit voxels in a plane
 - regardless of camera viewing angle
- Use front-to-back ordering
 - support early termination (last lecture)
- Perform final warp on the image due to the shear process
- Improve efficiency using run-length encoding of voxels
 - Skipping the transparent voxels



Transform to sheared space



- Rays are cast from the base plane voxels at the same place.
- They intersect voxels on subsequent planes in the same location.
- Only one set of interpolation weights needs to be computed for all the voxels in a plane.

- volume is sheared so that rays remain perpendicular to base plane
 - lead to efficient ray computation





Rotation of camera with shear-warp





Final stage of shear-warp

- Final stage of re-sampling (warp) required
 - transform resulting image from sheared space to regular Cartesian space (image plane).



View of Volume





Top down view







Warping the images





Light Propagation in Volumes

- Lighting in volume
 - only transmission and emission considered (until now)
 - can also:
 - reflect light
 - scatter light into different directions



Global Illumination of Volumes



For every voxel ray intersects, need to consider:

- Light absorbed.
- Light emitted.
- Light scattered out of the ray.
- Light scattered into the ray.



Global Illumination of Volumes





For every voxel ray intersects, need to consider:

• Light absorbed.

- Light emitted.
- Light scattered out of the ray.
- Light scattered into the ray.

Normally ignore scattering in volumetric illumination !

Why ? : computational cost



Example: single scatter



Irwin 95.

• Light scattered to produce atmospheric haze effect



Example : multiple scattering



• Light scattered multiple times to produce simulation of a cloud



Example : sub-surface scattering



Very large statue

Medium sized

Small statue.

• Varying how light is scattered inside a surface affects perception

- hence useful in visualisation
- why? prior visual experience, perception of distance?



Volume Illumination - ?

- Scattering is too costly so we usually do not take them into account when doing volume rendering
- But we still can add slight shadows to the volume by illuminating them



Volume Illumination

- Why do we want to illuminate volumes?
- illumination helps us to better understand 3D structure
 - displays visual cues to surface orientation
 - highlight significant
 gradients within
 volume



What are we illuminating ?

- embedded (iso-) surface
- sharp gradients in opacity







Shading an Embedded isosurface

- classify volume with a step function
- use regular specular / diffuse surface shading
- Remember for lighting equations of lecture 2 require
 - illumination direction
 - camera model (position)
 - surface orientation
 - need to calculate and store surface normal



Estimating the surface normal from distance map

- Use distance map to the iso-surface value
- 1. Determine the threshold value
- 2. Determine the surface voxels based on the threshold
- **3.** Compute the normal vectors based on centred difference method

For example, if we sample the centre of the voxels,



$$\begin{split} \delta z_{x} &= \frac{1}{2} (z(x+1, y) - z(x-1, y)) \\ \delta z_{y} &= \frac{1}{2} (z(x, y+1) - z(x, y-1)) \\ N &= (\frac{-\delta z_{x}}{\delta z_{x}^{2} + \delta z_{y}^{2} + 1}, \frac{-\delta z_{y}}{\delta z_{x}^{2} + \delta z_{y}^{2} + 1}, \frac{1}{\delta z_{x}^{2} + \delta z_{y}^{2} + 1}) \end{split}$$



Result : illuminated iso-surface



Shaded embedded iso-surface.

• Surface normals recovered from depth map of surface



Normals are sensitive to step size



Step size through the volume / over the depth map



Artefacts with larger step sizes under standard lighting model



Illuminating Opacity (Scalar) Gradient

- Illuminate "scalar gradient" instead of iso-surface
 - requirement : estimate and store gradient at every voxel



Shaded opacity gradient (shades changes in opacity)



Estimating Opacity Gradient

- Use 3D centred difference operator
 - $\nabla I = (I_x, I_y, I_z) = (\frac{\delta}{\delta x}I, \frac{\delta}{\delta y}I, \frac{\delta}{\delta z}I)$ $\frac{\delta}{\delta x}I = \frac{I(x+1, y, z) I(x-1, y, z)}{2}$



- We can extract the normal vectors of the region where the scalar values are changing significantly, i.e. boundary of tissues
- Evaluate at each voxel and interpolate





Illumination : storing normal vectors

- Visualisation is **interactive**
 - compute normal vectors for surface/gradient once
 - store normal
 - perform interactive shading calculations
- Storage :
 - 256³ data set of 1-byte scalars ~16Mb
 - normal vector (stored as floating point(4-byte)) ~ 200Mb!
 - Solution : quantise direction & magnitude as small number of bits



Illumination : storing normal vectors

 Quantize vector direction into one of N directions on a sub-divided sphere

Subdivide an octahedron into a sphere.

Number the vertices.

Encode the direction according the nearest vertex that the vector passes through.

For infinite light sources, only need to calculate the shading values once and store these in a table.





Summary

- Shear-Warping
- Light scattering
- Volume illumination