

Spectral Graph Theory

Social and Technological Networks

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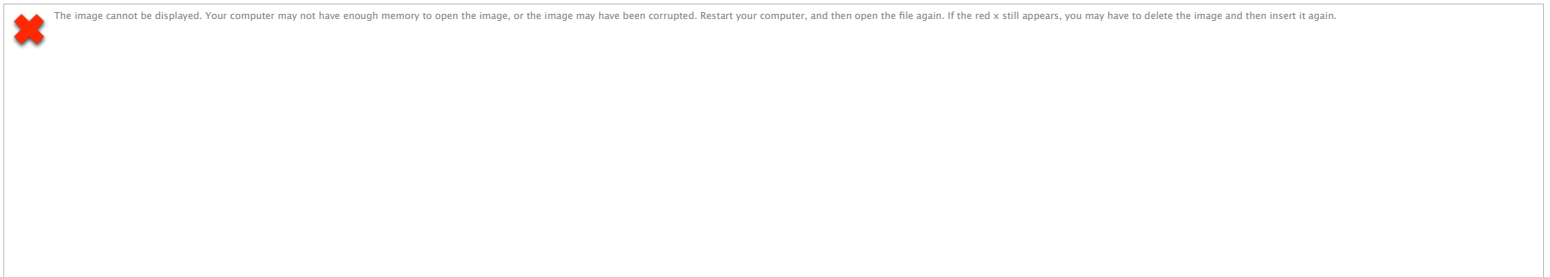
Spectral methods

- Understanding a graph using eigen values and eigen vectors of the matrix
- We saw:
- Ranks of web pages: components of 1st eigen vector of suitable matrix
- Pagerank or HITS are algorithms designed to compute the eigen vector
- Today: other ways spectral methods help in network analysis

Laplacian



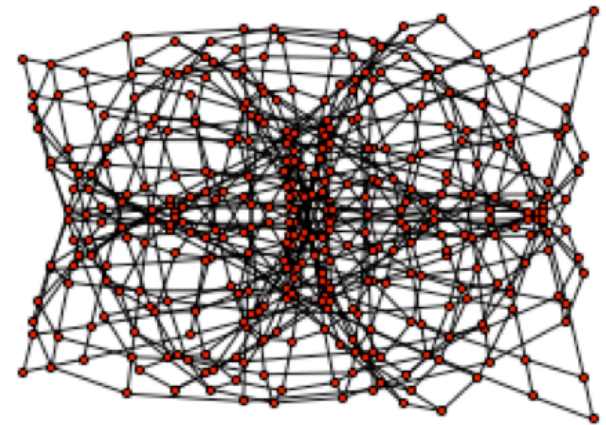
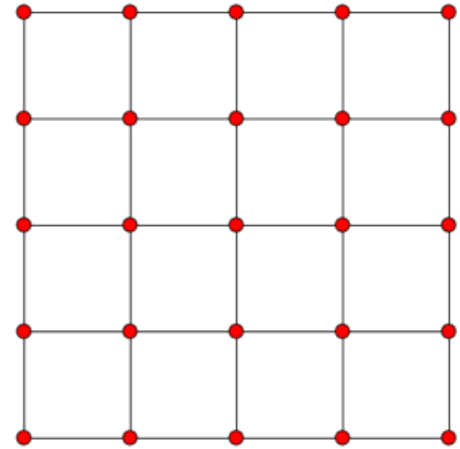
- $L = D - A$ [D is the diagonal matrix of degrees]



- An eigen vector has one value for each node
- We are interested in properties of these values

Application 1: Drawing a graph

- Problem: Computer does not know what a graph is supposed to look like
- A graph is a jumble of edges
- Consider a grid graph:
- We want it drawn *nice*

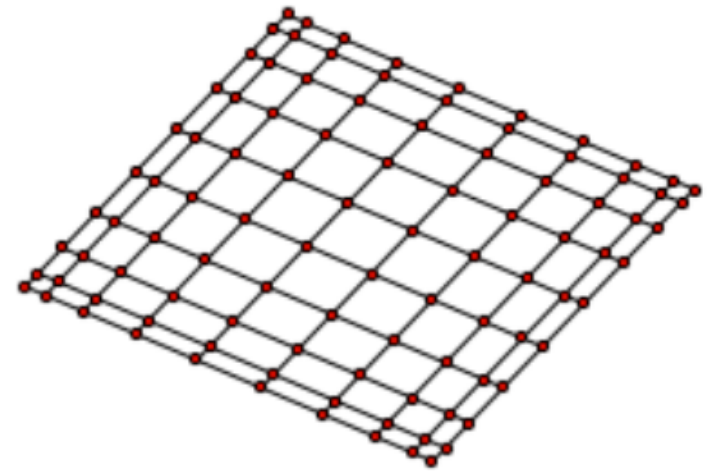


Graph embedding

- Find positions for vertices of a graph in low dimension (compared to n)
- Common objective: Preserve some properties of the graph e.g. approximate distances between vertices
 - Useful in visualization
 - Finding approximate distances
- Using eigen vectors
 - One eigen vector gives x values of nodes
 - Other gives y -values of nodes ... etc

Draw with $v[1]$ and $v[2]$

- Suppose $v[0], v[1], v[2] \dots$
are eigen vectors
 - Sorted by increasing eigen values
- Plot graph using $X=v[1]$,
 $Y=v[2]$
- Produces the grid



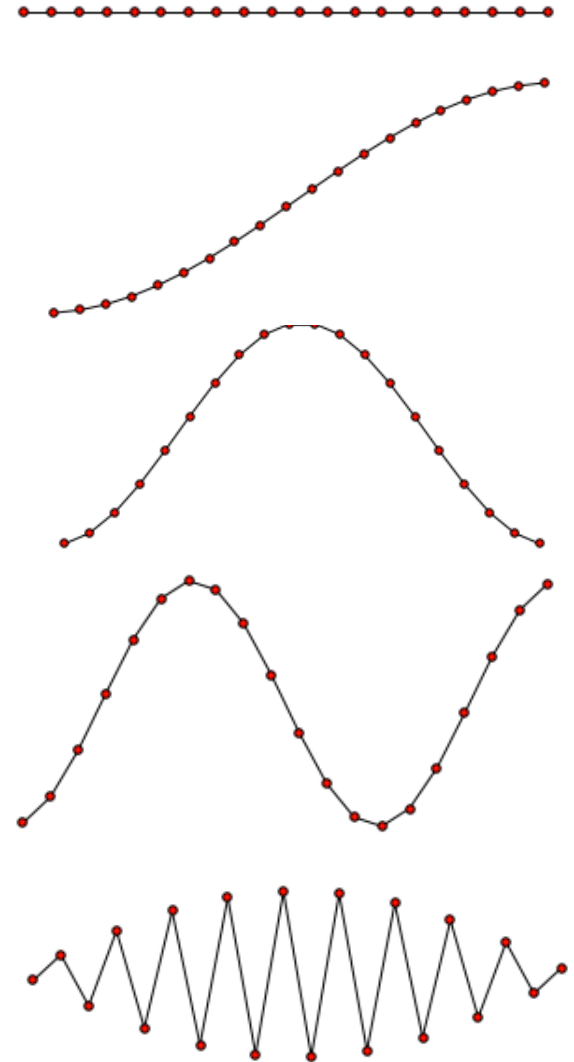
Intuitions: the 1-D case



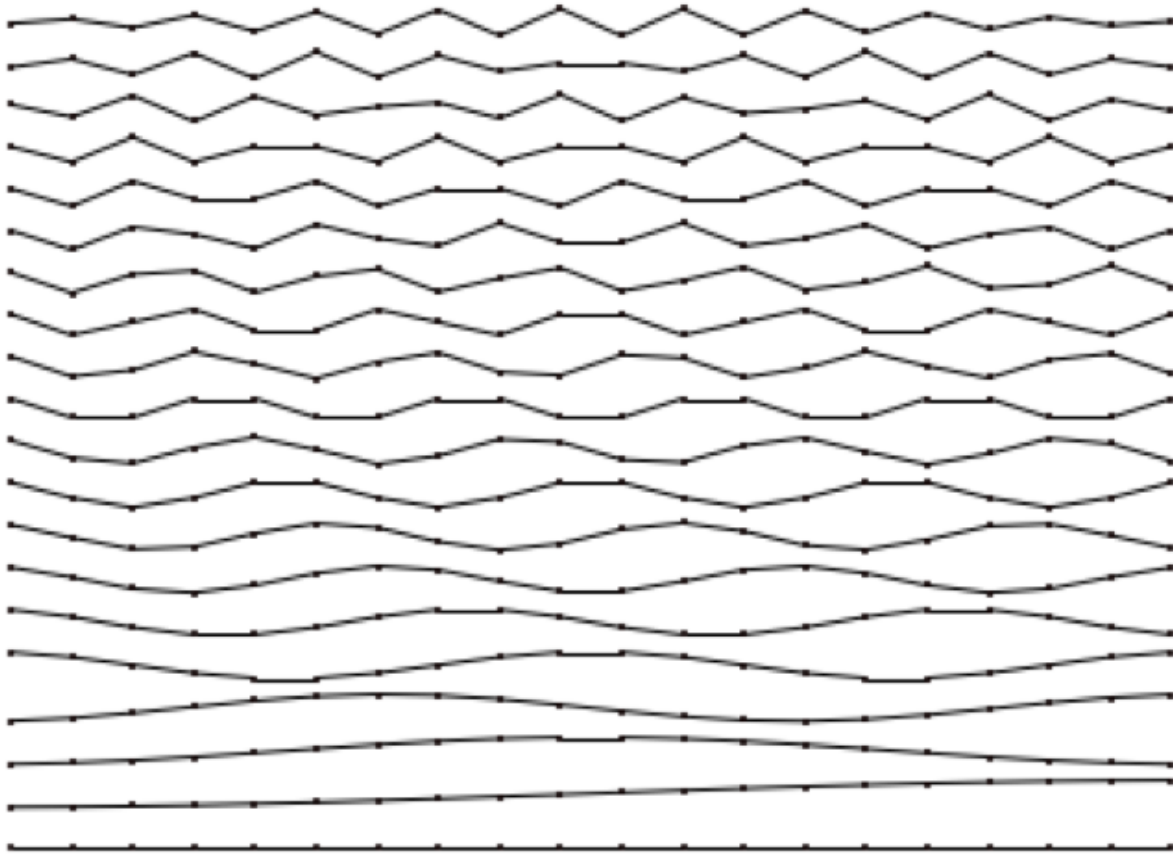
- Suppose we take the j th eigen vector of a chain
- What would that look like?
- We are going to plot the chain along x-axis
- The y axis will have the value of the node in the j th eigen vector
- We want to see how these rise and fall

Observations

- $j = 0$
- $j = 1$
- $j = 2$
- $j = 3$
- $j = 19$

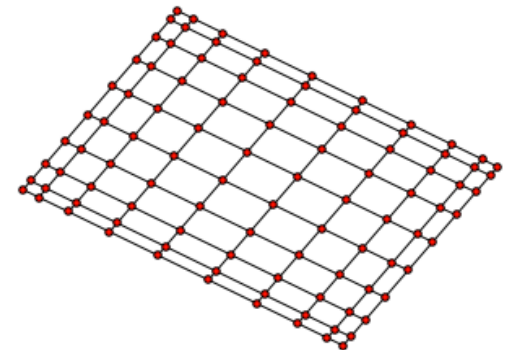
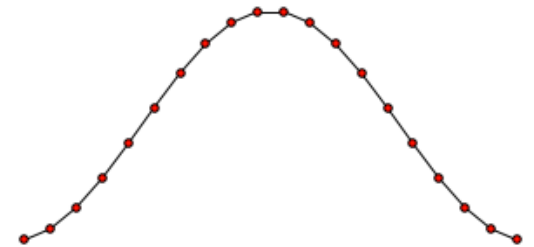
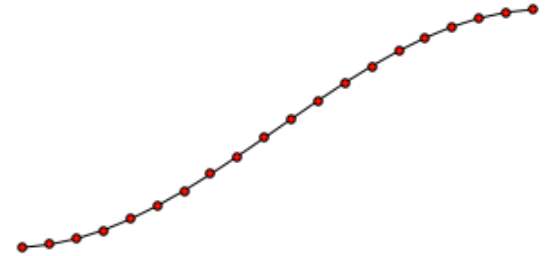
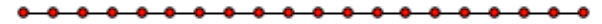


For All j



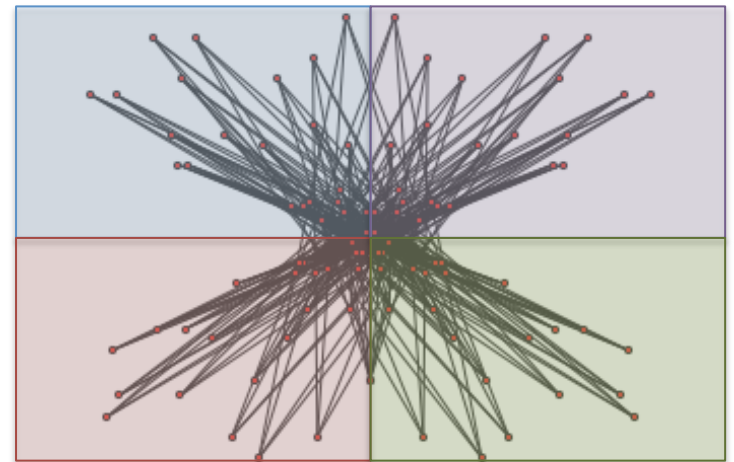
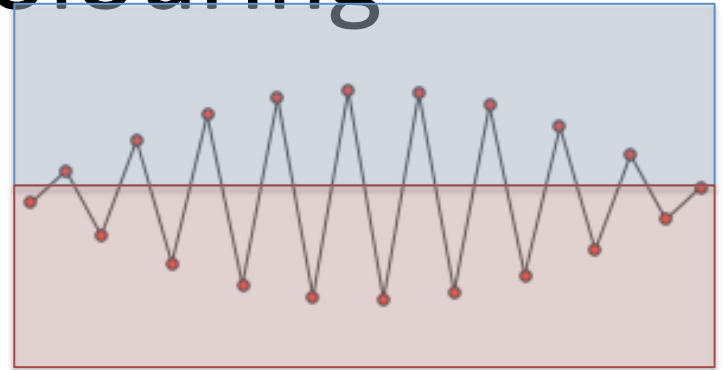
Observations

- In Dim 1 grid:
 - $v[1]$ is monotone
 - $v[2]$ is not monotone
- In dim 2 grid:
 - both $v[1]$ and $v[2]$ are monotone in suitable directions
- For low values of j :
 - Nearby nodes have similar values
 - Useful for embedding



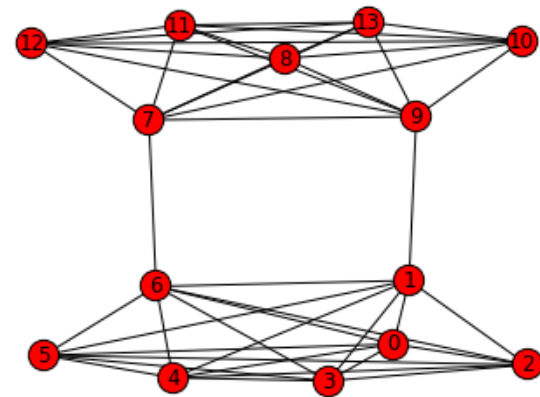
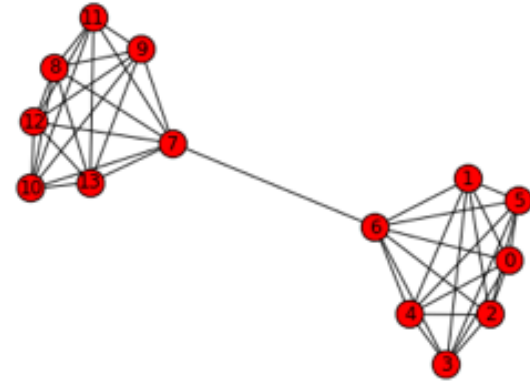
Application 2: Colouring

- Colouring: Assign colours to vertices, such that neighboring vertices do not have same colour
 - E.g. Assignment of radio channels to wireless nodes. Good colouring reduces interference
- Idea: High eigen vectors give *dissimilar* values to nearby nodes
- Use for colouring!



Application 3: Cuts/segmentation/ clustering

- Find the smallest 'cut'
- A small set of edges whose removal disconnects the graph
- Clustering, community detection...



Clustering/community detection

- $v[1]$ tends to stretch the narrow connections: discriminates different communities



Clustering: community detection

- More communities
- Need higher dimensions
- Warning: it does not always work so cleanly
- In this case, the data is very symmetric

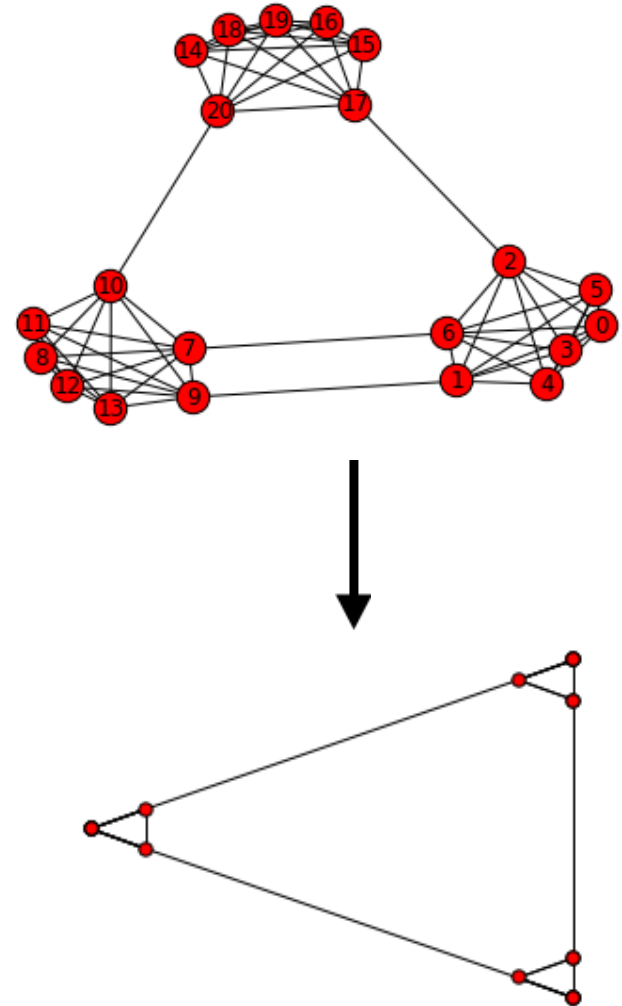
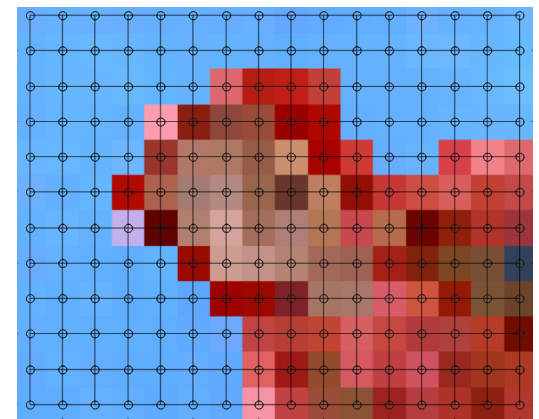


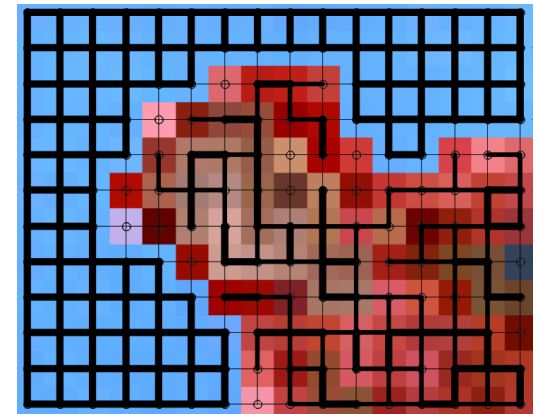
Image segmentation

Shi & malik '00



$v[1]$

$$weight(i, j) \approx e^{-(px_i - px_j)^2}$$



Laplacian matrix

- Imagine a small and different quantity of heat at each node (say, in a metal mesh)
- we write a function u : $u(i) = \text{heat at } i$
- This heat will spread through the mesh/graph
- Question: how much heat will each node have after a small amount of time?
- “heat” can be representative of the probability of a random walk being there

Heat diffusion

- Suppose nodes i and j are neighbors
 - How much heat will flow from i to j ?

Heat diffusion

- Suppose nodes i and j are neighbors
- How much heat will flow from i to j ?
- Proportional to the gradient:
 - $u(i) - u(j)$
 - this is signed: negative means heat flows into i

Heat diffusion

- If i has neighbors j_1, j_2, \dots
- Then heat flowing out of i is:
 $u(i) - u(j_1) + u(i) - u(j_2) + u(i) - u(j_3) + \dots$
 $\text{degree}(i) * u(i) - u(j_1) - u(j_2) - u(j_3) - \dots$
- Hence $L = D - A$



$$\begin{bmatrix} 1 & -1 & 0 & 0 \\ -1 & 2 & -1 & 0 \\ 0 & -1 & 2 & -1 \\ 0 & 0 & -1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} - \begin{bmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

The heat equation

$$\frac{\partial u}{\partial t} = L(u)$$

- The net heat flow out of nodes in a time step
- The change in heat distribution in a small time step
 - The rate of change of heat distribution

The smooth heat equation

- The smooth Laplacian:

$$\Delta f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2}.$$

- The smooth heat equation:

$$\Delta f = \frac{\partial f}{\partial t}$$

Heat flow

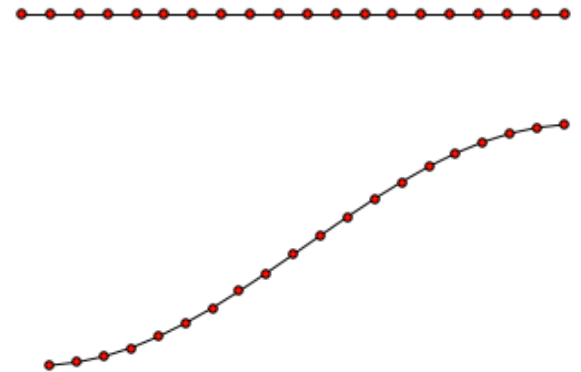
- Will eventually converge of $v[0]$: the zeroth eigen vector, with eigen value $\lambda_0 = 0$
- $v[0]$ is a constant: no more flow!

$v[0] = \text{const}$



Laplacian

- Changed implied by L on any input vector can be represented by sum of action of its eigen vectors (we saw this last time for MM^T)
- $v[0]$ is the slowest component of the change
 - With multiplier $\lambda_0=0$
- $v[1]$ is slowest non-zero component
 - with multiplier λ_1



Spectral gap

- $\lambda_1 - \lambda_0$
- Determines the overall speed of change
- If the slowest component $v[1]$ changes fast
 - Then overall the values must be changing fast
 - Fast diffusion
- If the slowest component is slow
 - Convergence will be slow
- Examples:
 - Expanders have large spectral gaps
 - Grids and dumbbells have small gaps $\sim 1/n$

Application 4: isomorphism testing

- Eigen values different implies graphs are different
- Though not necessarily the other way

Spectral methods

- Wide applicability inside and outside networks
- Related to many fundamental concepts
 - PCA
 - SVD
- Random walks, diffusion, heat equation...
- Results are good many times, but not always
- Relatively hard to give provable properties
- Inefficient: eig. computation costly on large matrix
- (Somewhat) efficient methods exist for more restricted problems
 - e.g. when we want only a few smallest/largest eigen vectors