

Structure and Synthesis of Robot Motion

Motion Synthesis with Strategic Considerations I

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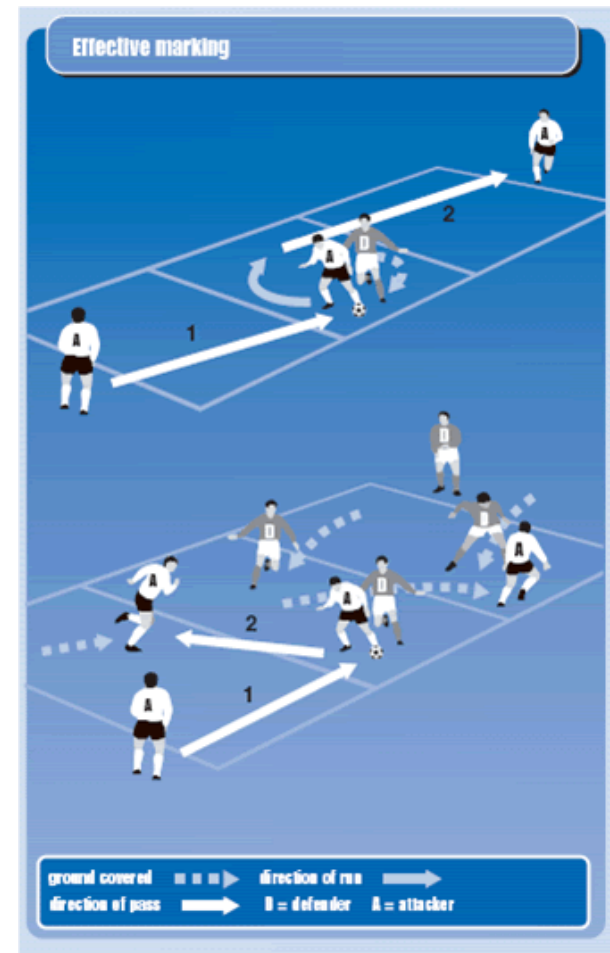
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Acknowledgement

The contents of this lecture are based on a tutorial at AAAI 2008 by Y. Gal and A. Pfeffer

I have used their original slides, with a bit of editorial additions to fit within a lecture.

Question: How will you tell a humanoid robot to mark another player?



Applications of Societal Importance



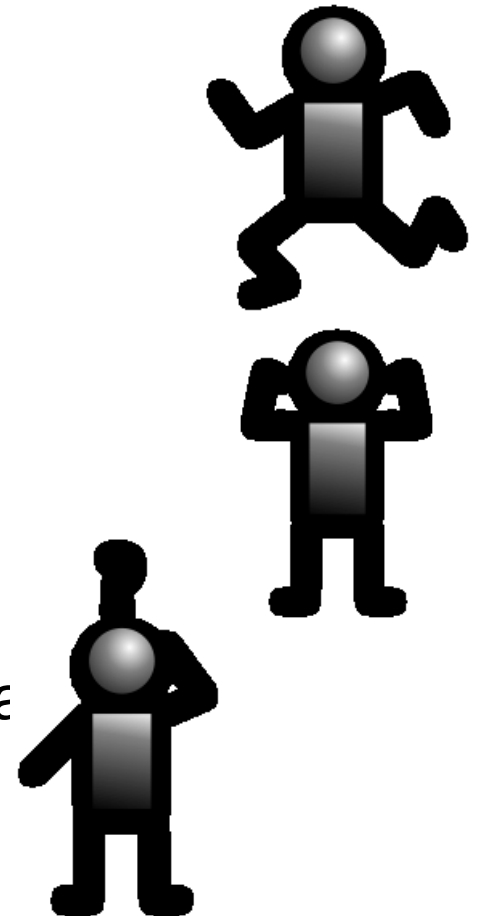
NurseBot



Ubiko, a hospital robot guide
Aizu Central Hospital, Japan

Multi-agent Decision-making

- Two sources of uncertainty
 - the environment
 - other agents
- Multi-agent decision problem, or game, includes
 - strategies
 - outcomes
 - utilities
- A solution concept for a game includes a strategy *profile* for all agents.



What is a game ?

A game includes a set of agents $\mathbf{N} = \{1, \dots, n\}$.
For each agent i , includes a set of strategies \mathbf{S}_i .

Joint strategy profile (s_1, \dots, s_n) determines outcome of game,
where $s_i \in \mathbf{S}_i$.

Payoff function, $u_i : \mathbf{S}_1, \dots, \mathbf{S}_n \rightarrow R$
represents utility for i given (s_1, \dots, s_n)

Let $\mathbf{S}_{-i} = \mathbf{S}_1 \times, \dots, \times \mathbf{S}_{i-1} \times \mathbf{S}_{i+1} \times, \dots, \times \mathbf{S}_n$ be
the joint set of strategies for all players other than i .

Normal Form Representation: The Prisoners' Dilemma

		Bob	
		<i>C</i>	<i>D</i>
Alice	<i>C</i>	$(-1, -1)$ → $(-5, 0)$	
	<i>D</i>	$(0, -5)$ → $(-3, -3)$	

- Row player is Alice; column player is Bob. Values in cell (C, D) denotes payoff to Alice when playing *C* and to Bob when playing *D*.
- A **dominant** strategy is one which is best for an agent regardless of other agents' actions.
- The dominant strategy for both players in the prisoners' dilemma is to defect (D, D) .

Battle of the Sexes

- Row player is Alice; column player is Bob.
 - Alice prefers watching a football match (*FM*) over going to the ballet (*B*); conversely for Bob.
 - Both players do not like to mis-coordinate.
- Entry (*FM*, *B*) denotes payoff to (Alice, Bob) when Alice goes to *FM* and Bob goes to *B*.

		Bob	
		<i>FM</i>	<i>B</i>
Alice	<i>FM</i>	(2, 1)	(0, 0)
	<i>B</i>	(0, 0)	(1, 2)

Battle of the Sexes

- Dominant strategies do not exist for either Alice or Bob.
 - But given Alice's strategy, Bob can choose a strategy to maximize his utility (and similarly for Alice)

		Bob	
		<i>FM</i>	<i>B</i>
Alice	<i>FM</i>	(2, 1) ←	(0, 0) ↓
	<i>B</i>	(0, 0) ↑	(1, 2) →

Battle of the Sexes

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		Bob	
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Nash Equilibrium

- A strategy profile $\mathbf{s}^* = (s_1, \dots, s_n)$ is a Nash equilibrium if no player has the incentive to deviate from its assigned strategy.
- Formally, for every player i and $s_i \in \mathbf{S}_i$,

$$u_i(s_i^*, \mathbf{s}_{-i}^*) \geq u_i(s_i, \mathbf{s}_{-i}^*)$$

		Bob	
		<i>FM</i>	<i>B</i>
Alice	<i>FM</i>	(2, 1)	(0, 0)
	<i>B</i>	(0, 0)	(1, 2)

Matching Pennies

- Alice and Bob can each turn a penny to “heads” or “tails”. The payoffs depend on whether Alice and Bob coordinate. The game is zero sum.

		Bob	
		<i>H</i>	<i>T</i>
Alice	<i>H</i>	$(1, -1)$	$(-1, 1)$
	<i>T</i>	$(-1, 1)$	$(1, -1)$

Mixed Strategies

For each player i , a mixed strategy profile defines a probability $\sigma_i(s_i)$ for each pure strategy s_i .

Let σ be a mixed strategy profile for all players.

The expected utility for i given σ is

$$u_i(\sigma) = \sum_{\mathbf{s} \in \mathbf{S}} \prod_j \sigma_j(s_j) \cdot u_i(\mathbf{s})$$

Mixed Strategy Equilibrium

σ is a Nash equilibrium if no player has the incentive to deviate from its assigned strategy.

Formally, for every player i and $\sigma_i \in \Delta \mathbf{S}_i$,

$$u_i(\sigma_i^*, \sigma_{-i}^*) \geq u_i(\sigma_i, \sigma_{-i}^*)$$

Theorem (Nash 50) Every finite game has a mixed strategy equilibrium.

Mixed strategy equilibrium for Matching Pennies: Alice and Bob choose heads and tails with probability 0.5.

Sequential Decisions

- Normal form represents situation where agents make simultaneous decisions
- What happens when players make decisions sequentially?
- We need to be able to represent situations in which different agents have different information
- **Extensive form games:** like single agent decision trees, plus information sets

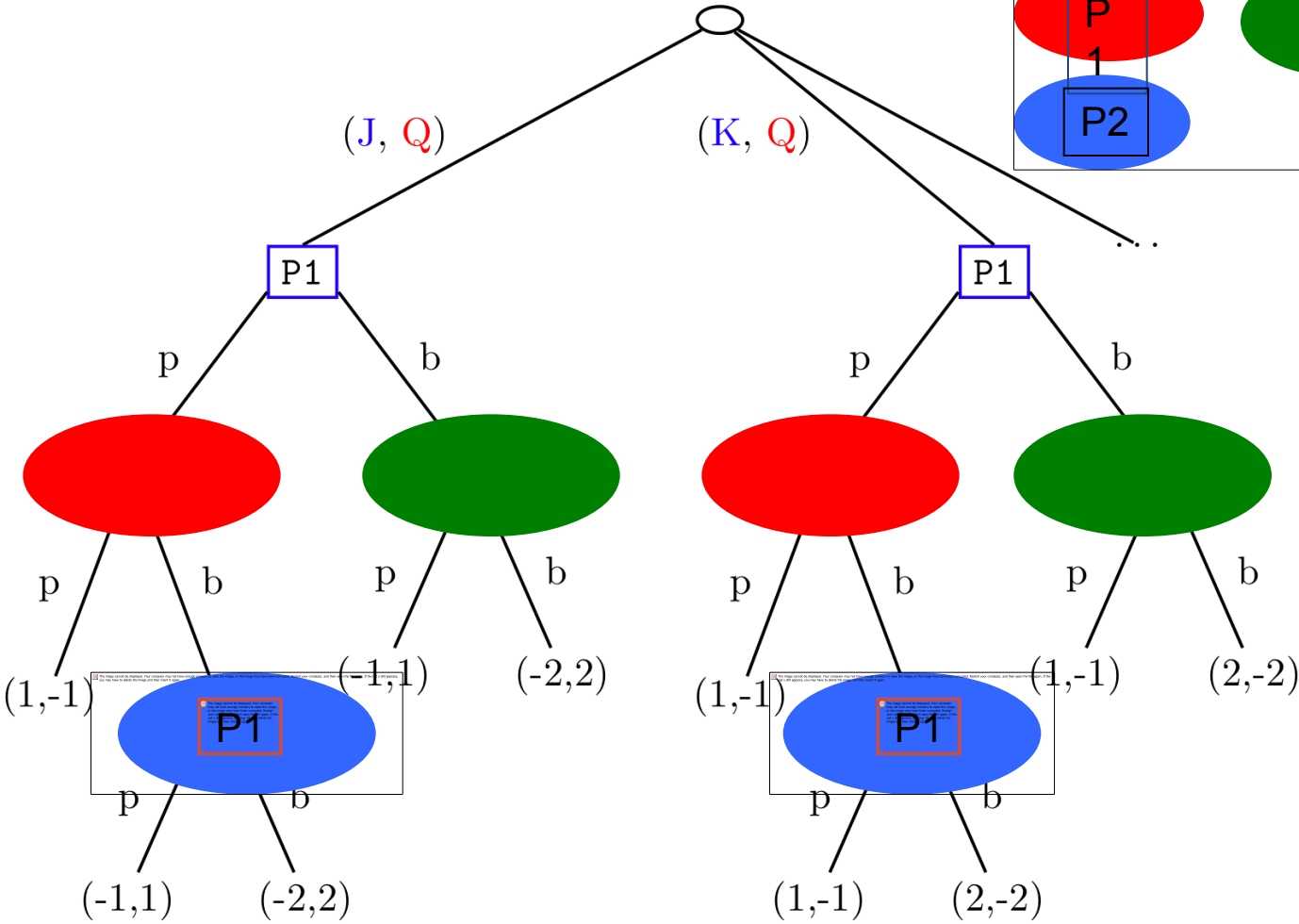
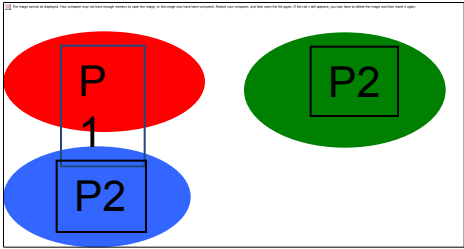
“Constrained” Poker [Kuhn 1950]

- Two players (P1,P2) each given £2
- Three cards in the deck: K, Q, J
- All players put £1 in the pot and pick a card, visible only to themselves.
- P1 bets £1 or passes;
- P2 bets £1 or passes;
- if P1 passes and P2 bets
- P1 can bet its £1 or pass.
- If both players bet (or pass), player with higher card wins £2 (or £1).
- If one player passes and the other bets, the betting player wins £1



Partial Extensive Form Game Tree for Kuhn Poker

Information Sets



Solution Algorithms: Normal Form Game

- Exact solutions:
 - Two player zero-sum games
 - Can be solved by a linear program in polynomial time (in number of strategies)
 - Two player general-sum game
 - Can be solved by a linear complimentary program (exponential worst-case complexity) [Lemke-Howson '64]
- Approximate solutions for multi-player games:
 - Continuation and triangulation methods [Govindan and Wilson '03, McKelvey & McLennan '96]
 - Search [Porter, Nudelman and Shoham '05]
- Off-the-shelf packages
 - Gambit, Game tracer

Solution Algorithms: Extensive Form Games

- Two player perfect information zero-sum game
 - can be solved by minimax search (with alpha-beta pruning)
- Two player perfect information general-sum game
 - Can be solved using backward-induction
- Two player imperfect information general-sum game
 - Can be solved using sequence form algorithm

[Koller, Megiddo, von Stengel '94].