Factor Analysis and Beyond

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Overview

- Principal Components Analysis
- Factor Analysis
- Independent Components Analysis
- Non-linear Factor Analysis
- Reading: Handout on "Factor Analysis and Beyond", Bishop §12.1, 12.2 (but not 12.2.1, 12.2.2, 12.2.3), 12.4 (but not 12.4.2)

Covariance matrix

- Let $\langle \rangle$ denote an average
- Suppose we have a random vector $\mathbf{X} = (X_1, X_2, \dots, X_d)^T$
- $\langle \mathbf{X} \rangle$ denotes the mean of \mathbf{X} , $(\mu_1, \mu_2, \dots \mu_d)^T$
- σ_{ii} = ⟨(X_i − µ_i)²⟩ is the variance of component *i* (gives a measure of the "spread" of component *i*)
- σ_{ij} = ⟨(X_i − µ_i)(X_j − µ_j)⟩ is the covariance between components *i* and *j*



- In *d*-dimensions there are *d* variances and *d*(*d* − 1)/2 covariances which can be arranged into a *covariance matrix* Σ
- The population covariance matrix is denoted Σ, the sample covariance matrix is denoted S

Principal Components Analysis

If you want to use a single number to describe a whole vector drawn from a known distribution, pick the projection of the vector onto the direction of maximum variation (variance)

- Assume $\langle \mathbf{x} \rangle = \mathbf{0}$
- $\blacktriangleright y = \mathbf{W} \cdot \mathbf{X}$
- Choose **w** to maximize $\langle y^2 \rangle$, subject to **w**.**w** = 1
- Solution: w is the eigenvector corresponding to the largest eigenvalue of Σ = ⟨xx^T⟩

- Generalize this to consider projection from *d* dimensions down to *m*
- Σ has eigenvalues $\lambda_1 \geq \lambda_2 \geq \ldots \lambda_d \geq 0$
- The directions to choose are the first *m* eigenvectors of Σ corresponding to λ₁,..., λ_m

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$$\mathbf{w}_i \cdot \mathbf{w}_j = 0$$
 $i \neq j$

 Fraction of total variation explained by using *m* principal components is

$$\frac{\sum_{i=1}^{m} \lambda_i}{\sum_{i=1}^{d} \lambda_i}$$

PCA is basically a rotation of the axes in the data space

Factor Analysis

- A latent variable model; can the observations be explained in terms of a small number of unobserved latent variables ?
- FA is a proper statistical model of the data; it explains covariance between variables rather than variance (cf PCA)
- ► FA has a controversial rôle in social sciences

- visible variables : $\mathbf{x} = (x_1, \dots, x_d)$,
- ► latent variables: $\mathbf{z} = (z_1, \dots, z_m)$, $\mathbf{z} \sim N(0, I_m)$
- ► noise variables: $\mathbf{e} = (e_1, \dots, e_d)$, $\mathbf{e} \sim N(0, \Psi)$, where $\Psi = \text{diag}(\psi_1, \dots, \psi_d)$.

Assume

$$\mathbf{x} = oldsymbol{\mu} + oldsymbol{W} \mathbf{z} + \mathbf{e}$$

then covariance structure of **x** is

$$C = WW^T + \Psi$$

W is called the factor loadings matrix

 $p(\mathbf{x})$ is like a multivariate Gaussian pancake

$$egin{aligned} & p(\mathbf{x}|\mathbf{z}) \sim \mathcal{N}(\mathcal{W}\mathbf{z}+\boldsymbol{\mu},\Psi) \ & p(\mathbf{x}) = \int p(\mathbf{x}|\mathbf{z}) p(\mathbf{z}) d\mathbf{z} \ & p(\mathbf{x}) \sim \mathcal{N}(\boldsymbol{\mu},\mathcal{W}\mathcal{W}^{T}+\Psi) \end{aligned}$$

- ► Rotation of solution: if W is a solution, so is WR where RR^T = I_m as (WR)(WR)^T = WW^T. Causes a problem if we want to interpret factors. Unique solution can be imposed by various conditions, e.g. that W^TΨ⁻¹W is diagonal.
- Is the FA model a simplification of the covariance structure? S has d(d + 1)/2 independent entries. Ψ and W together have d + dm free parameters (and uniqueness condition above can reduce this). FA model makes sense if number of free parameters is less than d(d + 1)/2.

FA example

[from Mardia, Kent & Bibby, table 9.4.1]

Correlation matrix

mechanics	(1	0.553	0.547	0.410	0.389	١
vectors		1	0.610	0.485	0.437	۱
algebra	1		1	0.711	0.665	I
analysis				1	0.607	I
statstics					1)	ļ

► Maximum likelihood FA (impose that W^T Ψ⁻¹ W is diagonal). Require m ≤ 2 otherwise more free parameters than entries in S.

Variable	m = 1 w 1	m = 2 w 1	(not rotated) w ₂	m = 2 ῶ 1	(rotated) ũ 2
1	0.600	0.628	0.372	0.270	0.678
2	0.667	0.696	0.313	0.360	0.673
3	0.917	0.899	-0.050	0.743	0.510
4	0.772	0.779	-0.201	0.740	0.317
5	0.724	0.728	-0.200	0.698	0.286

- 1-factor and first factor of the 2-factor solutions differ (cf PCA)
- problem of interpretation due to rotation of factors

FA for visualization

 $p(\mathbf{z}|\mathbf{x}) \propto p(\mathbf{z})p(\mathbf{x}|\mathbf{z})$

Posterior is a Gaussian. If **z** is low dimensional. Can be used for visualization (as with PCA)



Learning W, Ψ

- Maximum likelihood solution available (Lawley/Jöreskog).
- EM algorithm for ML solution (Rubin and Thayer, 1982)
 - E-step: for each \mathbf{x}_i , infer $p(\mathbf{z}|\mathbf{x}_i)$
 - M-step: do linear regression from z to x to get W
- Choice of *m* difficult (see Bayesian methods later).

Comparing FA and PCA

- Both are linear methods and model second-order structure S
- FA is invariant to changes in scaling on the axes, but not rotation invariant (cf PCA).
- FA models covariance, PCA models variance

Tipping and Bishop (1997), see Bishop §12.2

Let $\Psi = \sigma^2 I$.

- In this case W_{ML} spans the space defined by the first m eigenvectors of S
- ▶ PCA and FA give same results as $\Psi \rightarrow 0$.

Example Application: Handwritten Digits Recognition

Hinton, Dayan and Revow, IEEE Trans Neural Networks 8(1), 1997

- Do digit recognition with class-conditional densities
- ▶ 8×8 images $\Rightarrow 64 \cdot 65/2$ entries in the covariance matrix.
- 10-dimensional latent space used
- Visualization of W matrix. Each hidden unit gives rise to a weight image ...
- In practice use a mixture of FAs!

Useful Texts

on PCA and FA

- B. S. Everitt and G. Dunn "Applied Multivariate Data Analysis" Edward Arnold, 1991.
- C. Chatfield and A. J. Collins "Introduction to Multivariate Analysis", Chapman and Hall, 1980.
- K. V. Mardia, J. T. Kent and J. M. Bibby "Multivariate Analysis", Academic Press, 1979.

Independent Components Analysis

 A non-Gaussian latent variable model, plus linear transformation, e.g.

$$p(\mathbf{z}) \propto \prod_{i=1}^{m} e^{-|z_i|}$$

 $\mathbf{x} = W\mathbf{z} + \boldsymbol{\mu} + \mathbf{e}$

- Rotational symmetry in z-space is now broken
- p(x) is non-Gaussian, go beyond second-order statistics of data for fitting model
- Can be used with $\dim(\mathbf{z}) = \dim(\mathbf{x})$ for blind source separation
- http://www.cnl.salk.edu/~tony/ica.html
- Blind source separation demo: Te-Won Lee





unmixed

mixed

A General View of Latent Variable Models



- Clustering: z is one-on-in-m encoding
- Factor analysis: $\mathbf{z} \sim N(0, I_m)$
- ► ICA: $p(\mathbf{z}) = \prod_i p(z_i)$, and each $p(z_i)$ is non-Gaussian
- Latent Dirichlet Allocation: z ~ Dir(α) (Blei et al, 2003).
 Used especially for "topic modelling" of documents

Non-linear Factor Analysis

$$p(\mathbf{x}) = \int p(\mathbf{x}|\mathbf{z}) p(\mathbf{z}) d\mathbf{z}$$

For PPCA

$$p(\mathbf{x}|\mathbf{z}) \sim N(W\mathbf{z} + \boldsymbol{\mu}, \sigma^2 I)$$

If we make the prediction of the mean a non-linear function of z, we get non-linear factor analysis, with $p(\mathbf{x}|\mathbf{z}) \sim N(\phi(\mathbf{z}), \sigma^2 I)$ and $\phi(\mathbf{z}) = (\phi_1(\mathbf{z}), \phi_2(\mathbf{z}), \dots, \phi_d(\mathbf{z}))^T$. However, there is a problem— we can't do the integral analytically, so we need to approximate it.

$$p(\mathbf{x}) \simeq \frac{1}{K} \sum_{k=1}^{K} p(\mathbf{x} | \mathbf{z}_k)$$

where the samples \mathbf{z}_k are drawn from the density $p(\mathbf{z})$. Note that the approximation to $p(\mathbf{x})$ is a mixture of Gaussians.



- Generative Topographic Mapping (Bishop, Svensen and Williams, 1997/8)
- Do GTM demo

Fitting the Model to Data

- Adjust the parameters of φ and σ² to maximize the log likelihood of the data.
- For a simple form of mapping φ(z) = ∑_i w_iψ_i(z) we can obtain EM updates for the weights {w_i} and the variance σ².
- We are fitting a constrained mixture of Gaussians to the data. The algorithm works quite like Kohonen's self-organizing map (SOM), but is more principled as there is an objective function.

Visualization

 The mean may be a bad summary of the posterior distribution.



Manifold Learning

- A manifold is a topological space that is locally Euclidean
- We are particularly interested in the case of non-linear dimensionality reduction, where a low-dimensional nonlinear manifold is embedded in a high-dimensional space
- As well as GTM, there are other methods for non-linear dimensionality reduction. Some recent methods based on eigendecomposition include:
 - Isomap (Renenbaum et al, 2000)
 - Local linear embedding (Roweis and Saul, 2000)
 - Lapacian eigenmaps (Belkin and Niyogi, 2001)