Overview

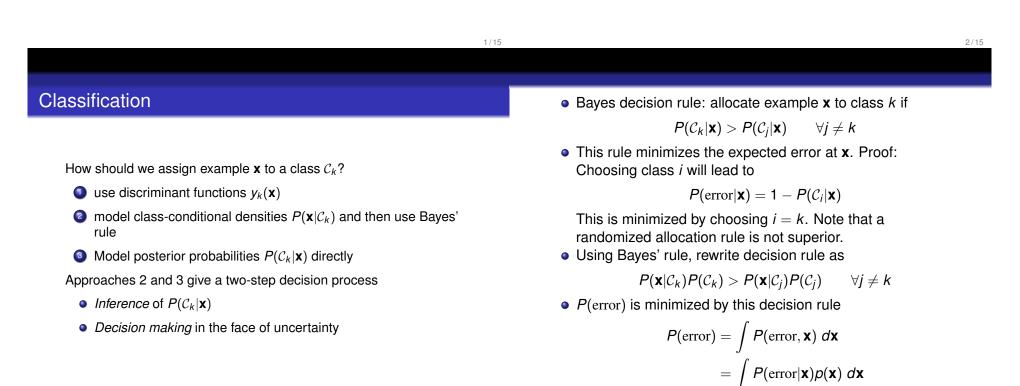
Decision Theory

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- Classification and Bayes decision rule
- Sampling vs diagnostic paradigm
- Classification with Gaussians
- Loss, Utility and Risk
- Reject option
- Reading: Bishop §1.5



Model $P(\mathcal{C}_k | \mathbf{x})$ or $P(\mathbf{x} | \mathcal{C}_k)$? • Diagnostic paradigm (discriminative): Model $P(C_k|\mathbf{x})$ directly

- Sampling paradigm (generative): Model $P(\mathbf{x}|\mathcal{C}_k)$ and $P(\mathcal{C}_k)$
- Pros/cons of diagnostic paradigm:
 - O Modelling $P(\mathcal{C}_k | \mathbf{x})$ can be simpler than modelling class-conditional densities.
 - \odot Less sensitive to modelling assumptions as what we need, $P(\mathcal{C}_k | \mathbf{x})$ is modelled directly
 - $(\mathbf{\dot{s}})$ Marginal density $p(\mathbf{x})$ is needed to handle outliers and missing values
 - \odot Use of unclassified observations difficult in diagnostic paradigm
 - (\mathbf{R}) Dealing with missing inputs is difficult

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class-conditional density 1.2 0.8 0.6 0.4 2.5 0.5 1.5 3.5 1 3 x posterior probability 0.8 0.6 0.4 0.2 0.5 1.5 2 2.5 3.5

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Classification with Gaussians

- Check if
- $\frac{P(\mathcal{C}_1|\mathbf{x})}{P(\mathcal{C}_2|\mathbf{x})} = \frac{p(\mathbf{x}|\mathcal{C}_1)P(\mathcal{C}_1)}{p(\mathbf{x}|\mathcal{C}_2)P(\mathcal{C}_2)} \ge 1$

or if

$$\Delta(\mathbf{x}) = \log \frac{p(\mathbf{x}|\mathcal{C}_1)P(\mathcal{C}_1)}{p(\mathbf{x}|\mathcal{C}_2)P(\mathcal{C}_2)} \gtrless 0$$

• For Gaussian class-conditional densities and $\Sigma_1 = \Sigma_2$ we obtain

$$(\mu_{1} - \mu_{2})^{T} \Sigma^{-1} \mathbf{x} + \frac{1}{2} (\mu_{2}^{T} \Sigma^{-1} \mu_{2} - \mu_{1}^{T} \Sigma^{-1} \mu_{1}) + \ln \frac{P(C_{1})}{P(C_{2})} \ge 0$$

This is a *linear* classifier

• For $\Sigma_1 \neq \Sigma_2$, boundaries are hyperquadrics

Errors resulting from an inaccurate model of the posterior

probabilities accurate modelling is a challenging problem

Errors resulting from an incorrect decision rule

Errors in classification arise from

Errors due to class overlap

these are unavoidable

use the correct rule!

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Loss and Risk

- Actions *a*₁,..., *a*_A might be taken. Given **x**, which one should be taken?
- *L_{ji}* is the loss incurred if action *a_i* is taken when the state of nature is *C_j*
- The expected loss (or risk) of taking action *a_i* given **x** is

$$R(a_i|\mathbf{x}) = \sum_j L_{ji} P(\mathcal{C}_j|\mathbf{x})$$

• Choose action k if

$$\sum_{j} L_{jk} \mathcal{P}(\mathcal{C}_{j} | \mathbf{x}) < \sum_{j} L_{ji} \mathcal{P}(\mathcal{C}_{j} | \mathbf{x}) \qquad \forall i \neq k$$

- Let $a(\mathbf{x}) = \operatorname{argmin}_i R(a_i | \mathbf{x})$
- Overall risk R

$$R = \int R(a(\mathbf{x})|\mathbf{x})p(\mathbf{x}) \ d\mathbf{x}$$

Example loss function

- Patients are classified to classes C_1 = healthy, C_2 = tumour.
- Actions are a_1 = discharge the patient, a_2 = operate
- Assume $L_{11} = L_{22} = 0$, $L_{12} = 1$ and $L_{21} = 10$, i.e. it is 10 times worse to discharge the patient when they have a tumour than to operate when they do not

$$\begin{aligned} R(a_1|\mathbf{x}) &= L_{11}P(\mathcal{C}_1|\mathbf{x}) + L_{21}P(\mathcal{C}_2|\mathbf{x}) = L_{21}P(\mathcal{C}_2|\mathbf{x}) \\ R(a_2|\mathbf{x}) &= L_{12}P(\mathcal{C}_1|\mathbf{x}) + L_{22}P(\mathcal{C}_2|\mathbf{x}) = L_{12}P(\mathcal{C}_1|\mathbf{x}) \end{aligned}$$

• Choose action a_1 when $R(a_1 | \mathbf{x}) < R(a_2 | \mathbf{x})$, i.e. when

$$L_{21}P(\mathcal{C}_2|\mathbf{x}) < L_{12}P(\mathcal{C}_1|\mathbf{x})$$

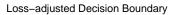
or

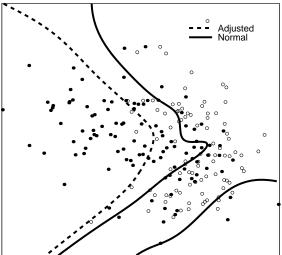
$$\frac{P(\mathcal{C}_1|\mathbf{x})}{P(\mathcal{C}_2|\mathbf{x})} > \frac{L_{21}}{L_{12}} = 10$$

 If L₂₁ = L₁₂ = 1 then threshold is 1; in our case we require stronger evidence in favour of C₁ = healthy in order to discharge the patient

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- In credit risk assignment, losses are monetary
- Note that rescaling loss matrix does not change the decision
- Minimum classification error is obtained by

$$L_{jj} = 1 - \delta_{jj}$$

Utility and Loss

Reject option

- Basically same thing with opposite sign. Maximize expected utility, minimize expected loss.
- See Russell and Norvig ch 16 for a discussion of fundamentals of utility theory, and utility of money [not examinable]
- Russell and Norvig ch 17 discuss sequential decision problems. Involves utilities, uncertainty and sensing; generalizes problems of planning and search. See RL course.

$$P(\operatorname{error}|\mathbf{x}) = 1 - \max_{j} P(\mathcal{C}_{j}|\mathbf{x})$$

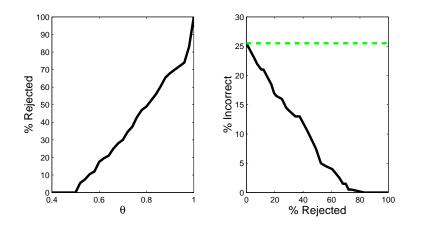
- If we can reject some examples, reject those that are most confusable, i.e. where P(error|x) is highest
- Choose a threshold θ and reject if

$$\max_{j} P(\mathcal{C}_{j} | \mathbf{x}) < \theta$$

• Gives rise to error-reject curves as θ is varied from 0 to 1

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Error-reject curve



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