Bayesian Kegression Previously: fit functions f(x) is a single guess of what the output will be. For classification we fitted P(y 1 x) by max likelihood. For regression we can also write down a probabilistic model eg wTX $p(y|X) = N(y; f(x; w), \sigma^2)$ For now vasiance OT On? assume the same for each "noise" example.

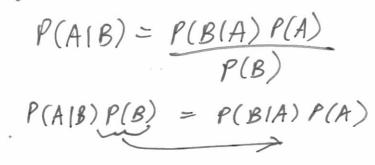
Maximum Likelihood

Minimize negative log-likelihood

 $-\log p(\mathbf{y}|\mathbf{X}, \mathbf{w}) = -\sum \log p(\mathbf{y}^{(n)}|\mathbf{x}^{(n)}, \mathbf{w})$ Eu(n) 3 $= \frac{1}{25^2} \sum_{n=1}^{\infty} \left[\left(y^{(n)} - f(x^{(n)}; w) \right)^2 + \sum_{n=1}^{\infty} \log(2\pi\sigma^2) \right]$ $= \frac{1}{2\sigma^{2}} \sum_{n} \left[(y^{(n)} - f(x^{(n)}; y^{(n)})^{2} + \frac{N}{2} \log(2\pi\sigma^{2}) \right]$ That is Minimize sum of squares.

We are uncertain about the model given data standard doviation of noise \neq_{χ} We use probability distributions to express beliefs about parameters For example: The "posterior distribution" = P(Data (w) P(w) p(w | Data) P(Data) Ey, X3 ~ P(Data (w) P(w) "Prior beliefs"

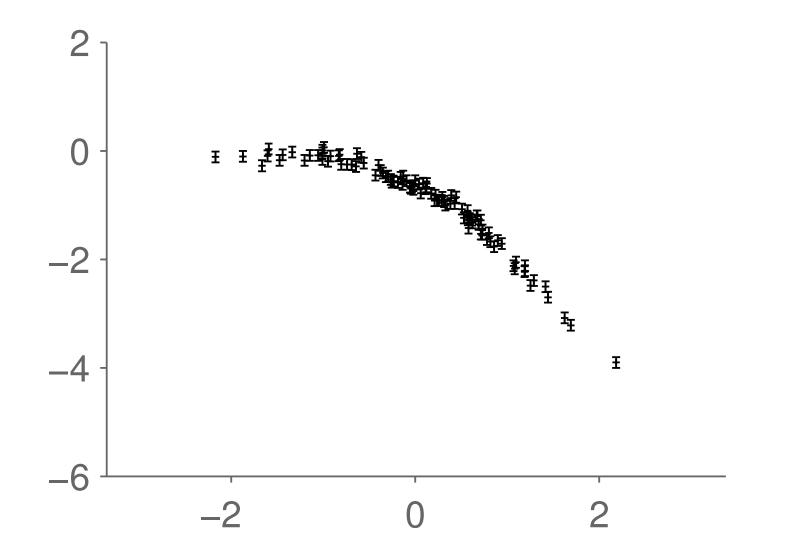
Bayes' Rule



Prior distribution $P(\underline{w}) = N(\underline{w}', 0, \sigma_{\text{prior}}^2)$ y "X weight space W, x + W2 Boyes Rule updates using p(wID the data Wz τ Ø

Computing the Posterior For linear regression Ey, X3 $p(\underline{w}|D) \propto p(\underline{w})p(D|\underline{w})$ ~ N(w; O, opnor) N(y, Iw, o2I) f(X,W) at each ipat. Is Gaussian: e- some quadratic in w We find linear & quadratic coeff's of $\stackrel{w}{\rightarrow}$ \implies mean & covariance.

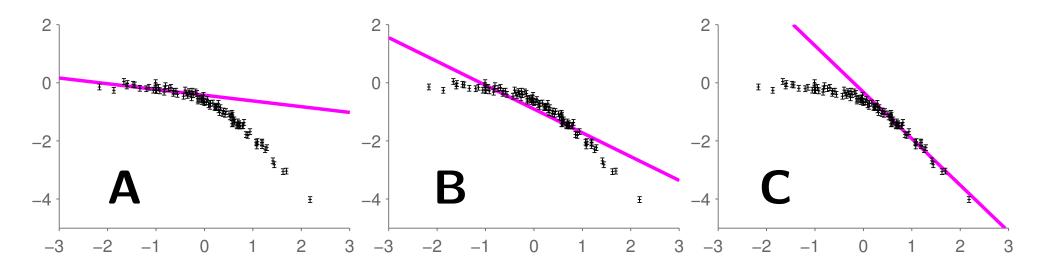
Model mismatch



What will Bayesian linear regression do?

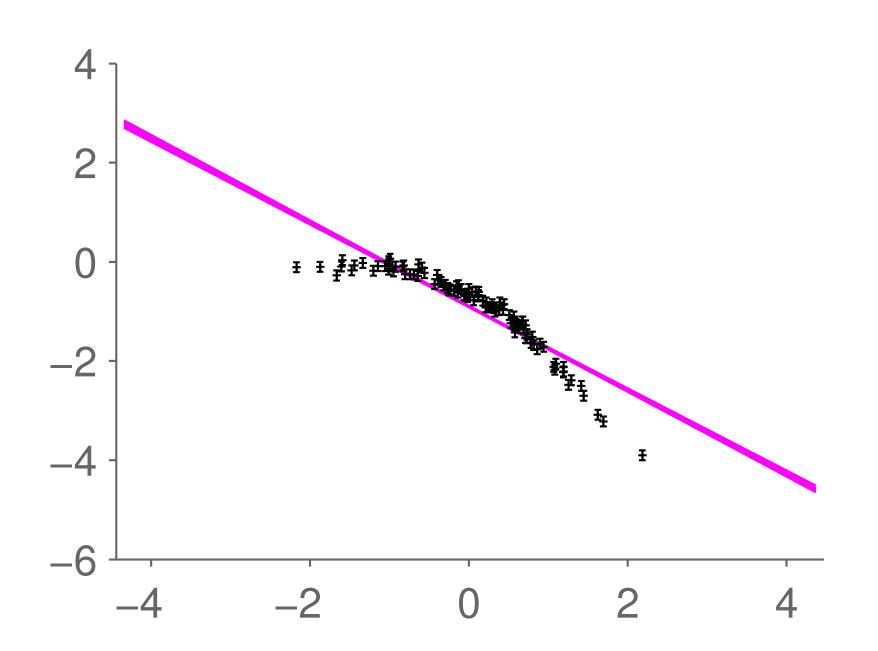
Quiz

Given a (wrong) linear assumption, which explanations are typical of the posterior distribution?



- **D** All of the above
- **E** None of the above
- **Z** Not sure

'Underfitting'



Posterior very certain despite blatant misfit. Peaked around least bad option.