

Modelling tools for Bio-PEPA

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Bio-PEPA



Properties

- Formal
- High-level
- Concise
- Readable
- Static analysis
- Multiple analysis vectors

Ciocchetta, F., and J. Hillston.

Bio-PEPA: A framework for the modelling and analysis of biological systems.

Theoretical Computer Science.

Volume 410, Issues 33-34, 21 August 2009, Pages 3065–3084.

Concurrent Systems Biology: To Nadia Busi (1968–2007)











Outline



- The Bio-PEPA language
 Bio-PEPA Software Tools
 Analysis based on ODEs
 Analysis based on CTMCs
 Examples: Two Genetic Networks

 The Network With Protein Degradation (M₁)
 The Network Without Protein Degradation (M₂)
- 6 Larger examples



Outline



The Bio-PEPA language Bio-PEPA Software Tools Analysis based on ODEs Analysis based on CTMCs Examples: Two Genetic Networks The Network With Protein Degradation (M₁) The Network Without Protein Degradation (M₂) Larger examples



Enzyme-Substrate example



 Consider the simple Enzyme-Substrate reaction involving an enzyme E, a substrate S, a compound E:S and a product P.

$$E + S \underset{k_{-1}}{\stackrel{k_1}{\rightleftharpoons}} E:S \xrightarrow{k_2} E + P$$



Formulation in Bio-PEPA



The kinetic functions

<i>r</i> ₁	$k_1 imes E imes S$
<i>r</i> ₋₁	$k_{-1} imes E:S$
<i>r</i> ₂	$k_2 imes E:S$

The Bio-PEPA model

Ε	$r_1\downarrow$	+	r_{-1} \uparrow	+	$r_2 \uparrow$
S	$r_1\downarrow$	+	$r_{-1}\uparrow$		
E:S	$r_1 \uparrow$	+	$r_{-1}\downarrow$	+	$r_2\downarrow$



The differential equations



The Bio-PEPA model

E	$r_1\downarrow$	+	r_{-1} \uparrow	+	$r_2 \uparrow$
S	$r_1\downarrow$	+	$r_{-1}\uparrow$		
E:S	$r_1 \uparrow$	+	$r_{-1}\downarrow$	+	$r_2\downarrow$

The differential equations

dE/dt	$-r_{1}$	+	<i>r</i> _1	+	<i>r</i> ₂
dS/dt	$-r_1$	+	<i>r</i> _1		
dE:S/dt	<i>r</i> ₁	—	<i>r</i> _1	—	<i>r</i> ₂
dP/dt					<i>r</i> ₂



The Jacobian



The differential equations

dE/dt	$-k_1 \times E \times S + k_{-1} \times E:S + k_2 \times E:S$
dS/dt	$-k_1 \times E \times S + k_{-1} \times E:S$
dE:S/dt	$k_1 \times E \times S - k_{-1} \times E:S - k_2 \times E:S$
dP/dt	$k_2 imes E:S$

The Jacobian

	E	S	E:S	Р
E	∂f _E /∂E	$\partial f_E / \partial S$	$\partial f_E / \partial E:S$	$\partial f_E / \partial P$
S	$\partial f_S / \partial E$	$\partial f_S / \partial S$	$\partial f_{S}/\partial E:S$	$\partial f_{\mathcal{S}}/\partial P$
E:S	∂f _{ES} /∂E	$\partial f_{ES}/\partial S$	$\partial f_{ES}/\partial E:S$	$\partial f_{ES}/\partial P$
Р	$\partial f_P / \partial E$	$\partial f_P / \partial S$	$\partial f_P / \partial E:S$	$\partial f_P / \partial P$



The Jacobian



The differential equations

dE/dt	$-k_1 \times E \times S + k_{-1} \times E:S + k_2 \times E:S$
dS/dt	$-k_1 \times E \times S + k_{-1} \times E:S$
dE:S/dt	$k_1 \times E \times S - k_{-1} \times E:S - k_2 \times E:S$
dP/dt	$k_2 imes E:S$

The Jacobian

	E	5	E:S	Р
E	$-k_1 imes S$	$-k_1 imes E$	$k_{-1} + k_2$	
S	$-k_1 imes S$	$-k_1 imes E$	k_{-1}	
E:S	$k_1 imes S$	$k_1 imes E$	$-k_{-1} - k_2$	
Р			k ₂	



Using the Jacobian



 ODE solvers generally use *finite differences* to approximate the Jacobian matrix if it is not supplied, but an implementation of the analytically derived Jacobian can improve the speed, accuracy and reliability of the program.



Using the Jacobian



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- The Jacobian (and Hessian and higher derivatives) are computed automatically from the differential equations using *symbolic differentiation*.



Using the Jacobian



- ODE solvers generally use *finite differences* to approximate the Jacobian matrix if it is not supplied, but an implementation of the analytically derived Jacobian can improve the speed, accuracy and reliability of the program.
- The Jacobian (and Hessian and higher derivatives) are computed automatically from the differential equations using *symbolic differentiation*.
- Programs that compute *bifurcations* will use the Hessian and higher derivatives.



Outline



The Bio-PEPA language Bio-PEPA Software Tools Analysis based on ODEs Analysis based on CTMCs Examples: Two Genetic Networks The Network With Protein Degradation (M₁) The Network Without Protein Degradation (M₂) Larger examples







- 1. Facilitate running several different types of quantitative analysis on a single Bio-PEPA model.
- 2. Facilitate combining the results of several runs of one particular type of analysis of a Bio-PEPA model.
- 3. Require as little explicit programming as possible from users.
- 4. Allow users to choose the parameters of interest for closer investigation.
- 5. Build on other mature simulators and numerical libraries where possible to avoid re-implementing existing functionality.
- 6. Users should be involved in deciding which features are important through suggesting enhancements to current versions.



Bio-PEPA Analysis





Bio-PEPA Eclipse Plug-in



- A complete environment for working with Bio-PEPA models.
- Eclipse front-end and a separate back-end library.

editor for the Bio-PEPA language User problems view			parser for the Bio-PEPA language
			static analysis
outline view for the reaction-centric view		Core	ISBJava time series analysis (ODE, SSA)
graphing support via common plugin	1		export facility (SBML; PRISM)
	editor for the Bio-PEPA language problems view outline view for the reaction-centric view graphing support via common plugin	editor for the Bio-PEPA language problems view outline view for the reaction-centric view graphing support via common plugin	editor for the Bio-PEPA language problems view outline view for the reaction-centric view graphing support via common plugin



Availability



 The Bio-PEPA tools are freely available for download from www.biopepa.org. Adam Duguid, Stephen Gilmore, Maria Luisa Guerriero, Jane Hillston and Laurence Loewe.

Design and Development of Software Tools for Bio-PEPA.

Winter Simulation Conference.

Austin, Texas. December 2009.



Software demo: Bio-PEPA Eclipse Plug-in



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Outline







Differential equation analysis



Several different differential equation solvers exist.

- SUNDIALS ODE integrators in C
- Matlab numerical computing platform
- MatCont Matlab toolbox for continuation analysis
- AUTO C and Fortran package for numerical continuation

Different formats and languages for problem description.







- VFGEN is a vector field file generator for differential equation solvers and other computational tools.
- VFGEN lets you define your vector field once (using XML), and export the vector field in several formats.
- VFGEN uses a C++ symbolic algebra library (GiNaC) to generate Jacobians and higher derivatives automatically.







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Warren Weckesser.

VFGEN: A Code Generation Tool.

Journal of Numerical Analysis, Industrial and Applied Mathematics, Volume 3(1-2):151–165, 2008.



VFgen representation of the Enzyme-Substrate model



```
<?xml version="1.0"?>
<VectorField Name="mm001">
<Parameter Name="k1." Description="k1" Latex="k.1" DefaultValue="1"/>
<Parameter Name="km1." Description="km1" Latex="k_{-1}" DefaultValue="0.1"/>
<Parameter Name="k2_" Description="k2" Latex="k_2" DefaultValue="0.01"/>
<Expression Name="r1-" Description="r1" Latex="r-1" Formula=" k1- * E- * S- "/>
<Expression Name="rm1_" Description="rm1" Latex="r_{-1}" Formula=" km1_* E_colon_S_"/>
<Expression Name="r2" Description="r2" Latex="r_2" Formula=" k2_* E_colon_S_"/>
<StateVariable Name="E_" Description="E" Latex="E" DefaultInitialCondition="100"
   Formula=" - r1_{-} + rm1_{-} + r2_{-}"/>
<StateVariable Name="S_" Description="S" Latex="S" DefaultInitialCondition="100"
   Formula=" - r1_{-} + rm1_{-}"/>
<StateVariable Name="E_colon_S_" Description="E:S" Latex="\hbox{\textit{E:S}}"
   DefaultInitialCondition="0" Formula="r1_ - rm1_ - r2_"/>
<StateVariable Name="P_" Description="P" Latex="P" DefaultInitialCondition="0"
   Formula="r2_"/>
</VectorField>
```



Analysing Bio-PEPA models with Matlab





¥	Figu			2	-		3
<u>E</u> il <u>E</u>	d <u>V</u> ie	Ins∈	Toc	<u>D</u> eski	<u>W</u> ind	<u>H</u> el	э
	E(0)			100	0		
	S(0)			100	0		
	E:S(0)		0			
	P(0)			0			
	k1			1			
	km1			0.1			
	k2			0.0	1		
Stop Time			500	0			
🔲 Separate Axes			es				
G							



Analysing Bio-PEPA models with Matlab





✓ Figu	re 2 📃 🗖 🦻
<u>F</u> il <u>E</u> d <u>V</u> ie Inse <u>I</u>	oc <u>D</u> eskt <u>W</u> ind <u>H</u> el 🤋
E(0)	100
S(0)	100
E:S(0)	0
P(0)	0
k1	1
km1	0.1
k2	0.01
Stop Time	500
Separate Axes	
Go	



Bifurcation analysis and continuation analysis



- We have some support for more general analysis of ODE models generated from Bio-PEPA descriptions.
- We can now perform bifurcation analysis and continuation analysis on Bio-PEPA models.
 - Useful for studying systems which oscillate.
- Can compute *phase response curves*.



Phase response curve





A. Dhooge, W. Govaerts, Yu.A. Kuznetsov, W. Mestrom, A.M. Riet and B. Sautois MATCONT and CL_MATCONT: Continuation toolboxes in Matlab December 2006.



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Enzyme-Substrate example



• Consider again the simple Enzyme-Substrate reaction involving an enzyme *E*, a substrate *S*, a compound *E*:*S* and a product *P*.

$$E + S \underset{k_{-1}}{\stackrel{k_1}{\rightleftharpoons}} E:S \xrightarrow{k_2} E + P$$

- Suppose that we could initiate this system with only 5 molecules of *E*, 5 molecules of *S*, no compound and no product.
- With only 4 species and 3 reaction channels the system has a small reachable state-space.



Discrete state-space of the Enzyme-Substrate example







Markov chain of the Enzyme-Substrate example







Probability distribution



- If we know the initial molecule counts and the values of the rate constants k₁ = 1.0, k₋₁ = 20.0 and k₂ = 0.05 we can compute the probability of being in each state of the state-space at all future time points.
- At time t = 0 we have Pr(5, 5, 0, 0) = 1.



Transient probability, t = 0







Transient probability, t = 0.001 **CSBE**

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Transient probability, t = 0.01 **CSBE**

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CSBE

















































































































Transient probability, t = 100 **COBE**







Transient probability, t = 110 **COBE**





Transient probability, t = 120 **Constant Constant Constant**





Transient probability, t = 130 **COBE**







Transient probability, t = 140 **Constant Constant Constant**





Transient probability, t = 150 **Coste Coste Cos**





Transient probability, t = 160 **COSBE**





Transient probability, t = 170 **COBE**





Transient probability, t = 180 **COSBE**





Transient probability, t = 190 **Constant Constant Constant**





Transient probability, t = 200 **CONTRE** FOR SYSTEMS BIOLOGY AT EDINBURGH





Transient probability, t = 210 **COBE**





Transient probability, t = 220 **CSBE**





Transient probability, t = 230 **CSBE**





Transient probability, t = 240 **CSBE**





Transient probability, t = 250 **CSBE**





Transient probability, t = 260 **CSBE**






Transient probability, t = 270 **CSBE**





Transient probability, t = 280 **COSBE**





Transient probability, t = 290 **Constant Constant Constant**





Transient probability, t = 300 **CSBE**





Transient probability, t = 310 **COBE**





Transient probability, t = 320 **CSBE**





Transient probability, t = 330 **COBE**





Transient probability, t = 340 **Constant Constant Constant**





Transient probability, t = 350 **CSBE**





Transient probability, t = 360 **CSBE**







Transient probability, t = 370 **CSBE**





Transient probability, t = 380 **CSBE**







Transient probability, t = 390 **CSBE**







Transient probability, t = 400 **Constant Constant Constant**





Transient probability, t = 410 **Constant Constant Constant**







0.000000

 $\frac{25k_1}{k_2}$

Transient probability, t = 420 **Constant Constant Constant**





Transient probability, t = 430 **CONTRE** FOR SYSTEMS BIOLOGY AT EDINBURGH





Transient probability, t = 440 **Constant Constant Constant**





Transient probability, t = 450 **COSBE**





Transient probability, t = 460 **COSBE**



 $2k_{-1}$

3k₂

 $4k_1$

 $2k_2$

 $5k_1$

+(0.010919

 k_2

★(0.943692)



 $5k_{-}$

0.000000

 $4k_{-1}$

 $5k_2$

 $2k_1$

0.000000

 $3k_{-1}$

4k2 (0.000000)

 $)3k_1$

Transient probability, t = 470 **CSBE**





Transient probability, t = 480 **CONTRE** FOR SYSTEMS BIOLOGY AT EDINBURGH





Transient probability, t = 490 **Constant Constant Constant**





Transient probability, t = 500 **COBE**







Transient probability, t = 510 **CSBE**





Transient probability, t = 520 **COSBE**





Transient probability, t = 530 **CSBE**







Transient probability, t = 540 **CONTRE** FOR SYSTEMS BIOLOGY AT EDINBURGH





Transient probability, t = 550 **COSBE**





Transient probability, t = 560 **CSBE**







Transient probability, t = 570 **CSBE**





Transient probability, t = 580 **COSBE**





Transient probability, t = 590 **COSBE**





Transient probability, t = 600 **CSBE**





Adding synthesis to the Enzyme-Substrate model



• If we consider an extension of the model with an additional reaction r_0 which synthesises the compound *E*:*S* as shown below with the synthesis occurring at a constant rate $r_0 = k_0$ then this additional reaction channel changes the analysis of the model dramatically.

$$E:S | r_0 \uparrow + r_1 \uparrow + r_{-1} \downarrow + r_2 \downarrow$$



Change to the model state space



The state which was previously a deadlock state now admits an r₀ reaction which leads it to a previously unreachable state, (5,0,1,5). The reactions r₋₁, r₁ and r₂ can occur in states reachable from that.








Each of these states, and every other state, now allows an r₀ reaction, taking them to previously unreachable states each of which allows r₀ and reactions r₋₁, r₁ and r₂ subsequent to that.



Adding synthesis



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Adding synthesis



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- The effect of introducing this single synthesis reaction is that we now cannot find any upper bound N such that the molecular species counts are guaranteed to lie in the bounded integer range 0 to N.
- If we are unable to bound the reachable state-space then we cannot in general analyse our model by probabilistic model-checking.





1. The generation of the derivation graph of the underlying state-space does not take into account the numerical values assigned to the rate constants, and the propensity functions which depend on those. This means that the derivation graph may include many states which the system is almost sure not to reach within a particular time bound.





2. Most chemical systems involve several widely varying time scales, so such systems are nearly always stiff. A consequence of this is that the first passage time to many states is likely to be long and truncation of the state-space using a time-bounded reachability metric is likely to be productive.





3. Many of the logical formulae which we wish to check involve reaching within a fixed time bound model states which satisfy a given predicate.





4. Stochastic simulation methods such as Gillespie's Direct Method generate exact stochastic simulations of trajectories from the initial state to states reachable within a given time bound.



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- The Network With Protein Degradation (\mathcal{M}_1)
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Examples: Two Genetic Networks



- In order to illustrate our approach we consider two models. These represent, under different assumptions, a general genetic network with a negative feedback. An example of this kind of network is the control circuit for the λ repressor protein Cl of λ-phage in *E.Coli*.
- We have four biochemical entities that interact with each other through six reactions. The biochemical entities are the DNA (D), the mRNA (M), a protein in monomeric form (P) and a protein in dimeric form (P2).







The network is unbounded



- The network is structurally unbounded, since both transcription and translation lead to the creation of new molecules.
- However, the two degradation reactions and the transcription inhibition by means of the dimeric protein have a regulatory effect on the protein synthesis and therefore, under some conditions, all the species reach a finite average value.



The network with protein degradation (\mathcal{M}_1)



We perform 1000 independent stochastic simulation runs using Gillespie's Direct Method. The number of runs is large enough to take into account the variability of the system, but still making the total simulation time reasonable. We used T = 20000 s as a simulation stop time: by that time the system has reached a stable state.



The network with protein degradation (\mathcal{M}_1)



We can estimate the upper bounds for the amounts of each species as the maximum values obtained in any run at any time instant, and we can use these values in the PRISM model.

$$Max_M = 5;$$
 $Max_P = 33;$ $Max_{P2} = 18$



Simulation averages and model-checking for \mathcal{M}_1







Estimating the error introduced by truncation



As another form of validation of the derived bounds, we have calculated the probabilities of reaching them at different time instants:

•
$$\mathcal{P}_{=?}[true \ \mathbf{U}^{\leq T} \ M = 5],$$

•
$$\mathcal{P}_{=?}[true \ \mathrm{U}^{\leq T} \ P = 33]$$
, and

•
$$\mathcal{P}_{=?}[true \ U^{\leq T} \ P2 = 18].$$

• The results provide a means of estimating the error which might have been introduced by bounding the system.



Estimating the error introduced by truncation







The network without protein degradation (\mathcal{M}_2)





Estimating the error introduced by truncation







Determining the probability that P2 > P







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$gp130/JAK/STAT\ pathway$

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Co-transcriptional cleavage





rRNA transcription

Reaction graph

Bio-PEPA model

Federica Ciocchetta, Jane Hillston, Martin Kos and David Tollervey Modelling co-transcriptional cleavage in the synthesis of yeast pre-rRNA. *Theoretical Computer Science* Volume 408, Issue 1, 17 November 2008, Pages 41-54.



Acknowledgements



- Adam Duguid is supported by the EPSRC Doctoral Training Grant EP/P501407/1.
- Allan Clark, Vashti Galpin and Stephen Gilmore are supported by the EPSRC grant EP/E031439/1 "Stochastic Process Algebra for Biochemical Signalling Pathway Analysis".
- Jane Hillston is supported by the Engineering and Physical Sciences Research Council (EPSRC) Advanced Research Fellowship and research grant EP/C543696/1 "Process Algebra Approaches to Collective Dynamics".
- Maria Luisa Guerriero and Laurence Loewe are supported by the Centre for Systems Biology at Edinburgh. The Centre for Systems Biology at Edinburgh is a Centre for Integrative Systems Biology (CISB) funded by BBSRC and EPSRC, reference BB/D019621/1.

