

Logic Programming

Lecture 2: Unification and proof search

Outline for today

- Quick review
- Equality and unification
- How Prolog searches for answers

Quick review

- Atoms `bart` `'Mr. Burns'`
- Variables `X` `Y` `Z`
- Predicates `p(t1, ..., tn)`
- Terms
- Facts `father(homer, bart).`
- Goals `p(t1, ..., tn), ..., q(t1', ..., tn')`.
- Rules `p(ts) :- q(ts'), ..., r(ts'')`.

Infix operators

- Prolog has built-in *constants* and *infix operators*
- Examples:
 - Equality: `t = u` (or `=(t, u)`)
 - Pairing: `(t, u)` (or `,(t, u)`)
 - Empty list: `[]`
 - List concatenation: `[X|Y]` (or `.(X, Y)`)
- You can also define your own infix operators!

General observations

- Prolog is **untyped**
 - everything is a "term"
- Prolog is **declarative**
 - "predicates" with side effects, such as print, are the exception, not the rule
- Prolog does **not** have explicit control flow constructs (while, do)
 - the search strategy allows us to simulate iteration
 - but this is not usually the best way to program
- Therefore, try to **forget what you already know** from other languages

Terms

- Also have...
 - **Numbers:** 1 2 3 42 -0.12345
 - Additional **constants** and **infix operators**
- More on these later.

Unification (I)

- The equation $t = u$ is a basic goal
 - with a special meaning
- What happens if we ask:
 - ?- $X = c$
 - ?- $f(X, g(Y, Z)) = f(c, g(X, Y))$
 - ?- $f(X, g(Y, f(X))) = f(c, g(X, Y))$
- *And how does it do that?*

Unification (II)

Unification (II)

?- $X = c$.

Unification (II)

?- $X = c$.

$X=c$

yes

Unification (II)

?- $X = c$.

$X=c$

yes

?- $f(X, g(Y, Z)) = f(c, g(X, Y))$.

Unification (II)

?- $X = c$.

$X=c$

yes

?- $f(X, g(Y, Z)) = f(c, g(X, Y))$.

$X=c$

$Y=c$

$Z=c$

yes

Unification (II)

?- $X = c$.

X=c

yes

?- $f(X, g(Y, Z)) = f(c, g(X, Y))$.

X=c

Y=c

Z=c

yes

?- $f(X, g(Y, f(X))) = f(c, g(X, Y))$.

Unification (II)

?- $X = c$.

X=c

yes

?- $f(X, g(Y, Z)) = f(c, g(X, Y))$.

X=c

Y=c

Z=c

yes

?- $f(X, g(Y, f(X))) = f(c, g(X, Y))$.

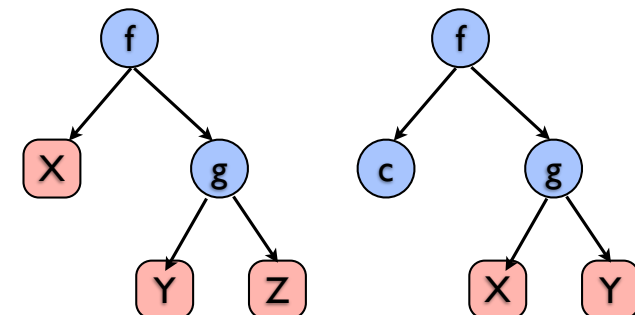
no

Unification (III)

- A *substitution* is a mapping from variables to terms
 - $X_1=t_1, \dots, X_n=t_n$
- Given two terms t and u
 - with free variables $X_1 \dots X_n$
- a *unifier* is a substitution that makes t and u equal

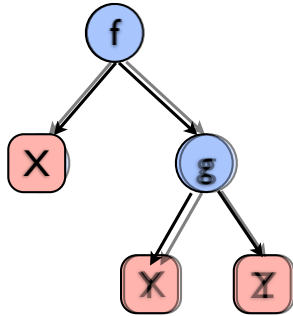
Example (I)

$$f(X, g(Y, Z)) = f(c, g(X, Y))$$



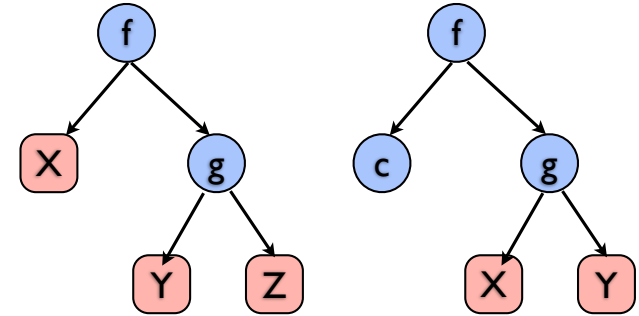
Example (I)

$$f(X, g(Y, Z)) = f(c, g(X, Y))$$



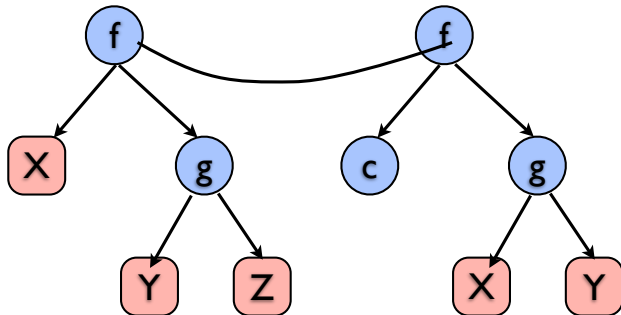
Example (I)

$$f(X, g(Y, Z)) = f(c, g(X, Y))$$



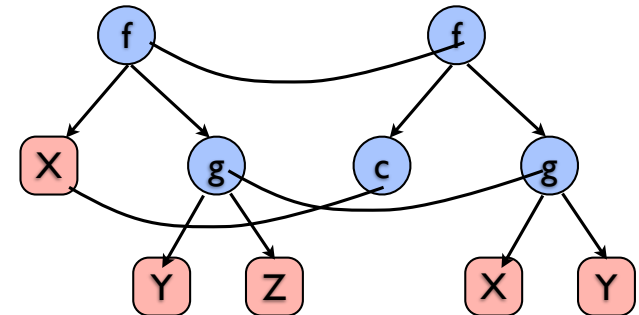
Example (I)

$$f(X, g(Y, Z)) = f(c, g(X, Y))$$



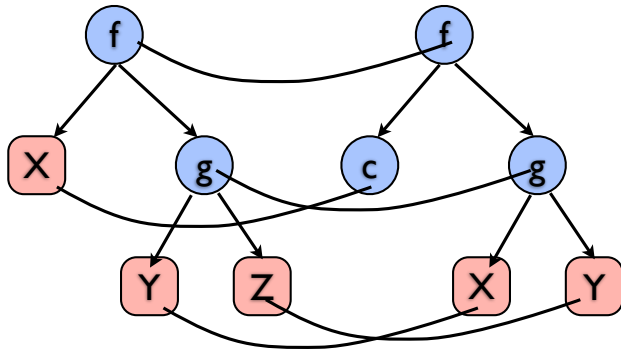
Example (I)

$$f(X, g(Y, Z)) = f(c, g(X, Y))$$



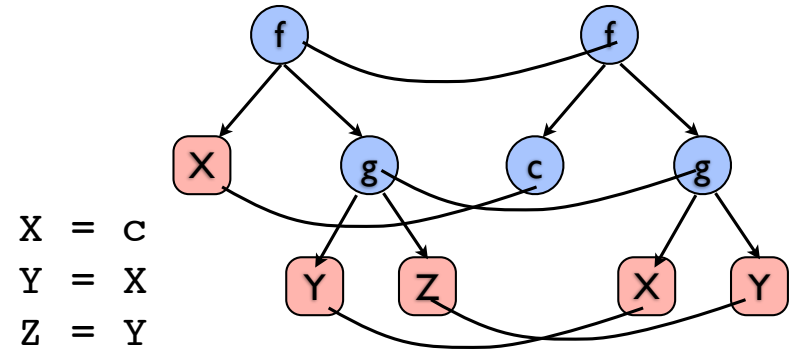
Example (I)

$$f(X, g(Y, Z)) = f(c, g(X, Y))$$



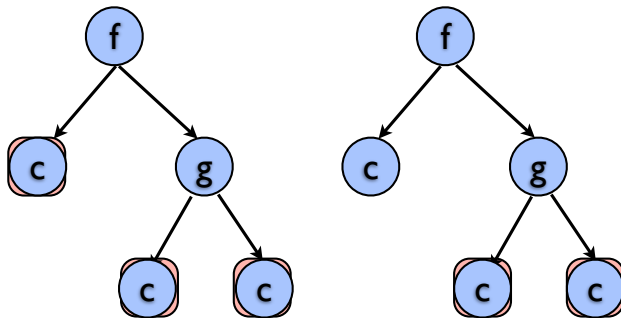
Example (I)

$$f(X, g(Y, Z)) = f(c, g(X, Y))$$



Example (I)

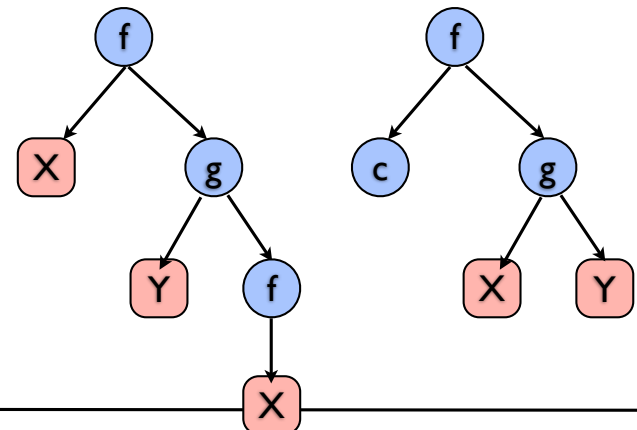
$$f(X, g(Y, Z)) = f(c, g(X, Y))$$



X = c
Y = c
Z = c

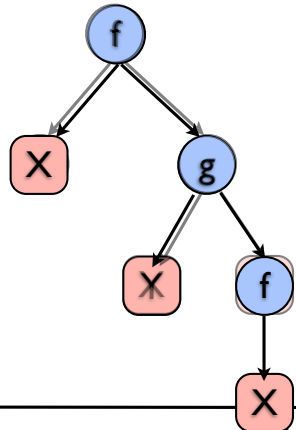
Example (II)

$$f(X, g(Y, f(X))) = f(c, g(X, Y))$$



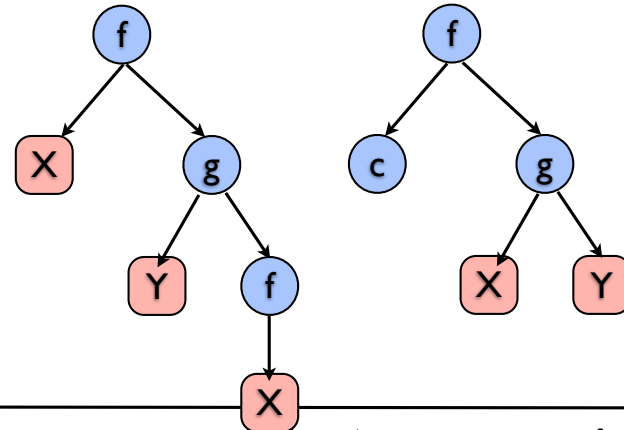
Example (II)

$$f(X, g(Y, f(X))) = f(c, g(X, Y))$$



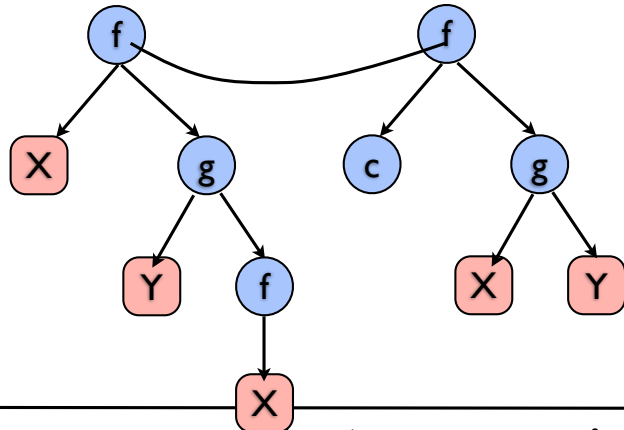
Example (II)

$$f(X, g(Y, f(X))) = f(c, g(X, Y))$$



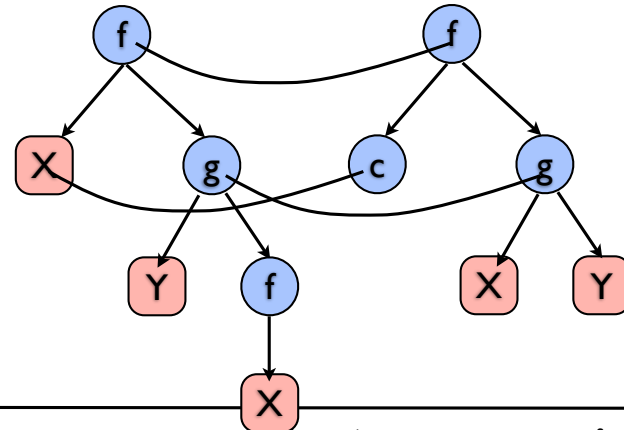
Example (II)

$$f(X, g(Y, f(X))) = f(c, g(X, Y))$$



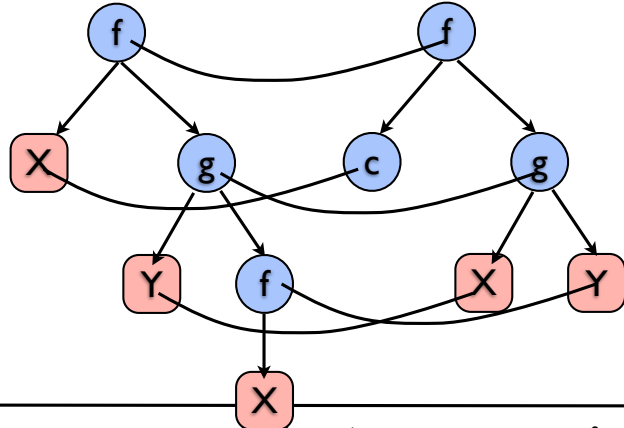
Example (II)

$$f(X, g(Y, f(X))) = f(c, g(X, Y))$$



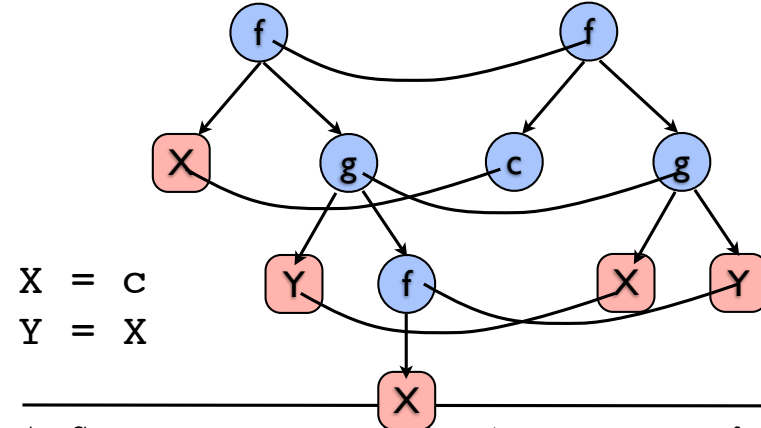
Example (II)

$$f(X, g(Y, f(X))) = f(c, g(X, Y))$$



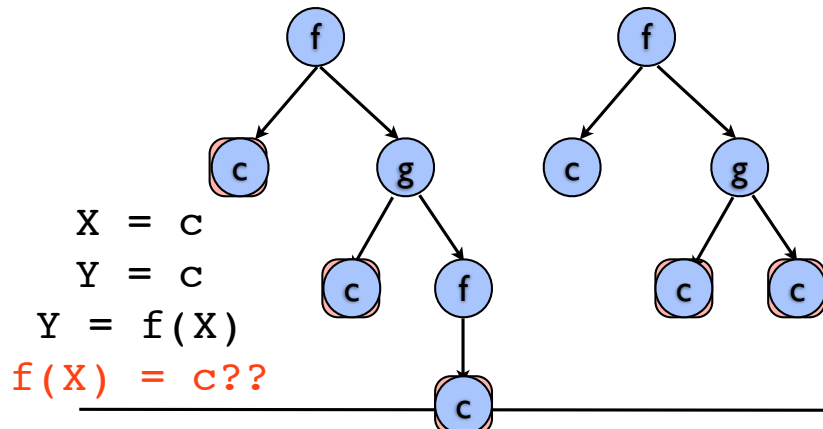
Example (II)

$$f(X, g(Y, f(X))) = f(c, g(X, Y))$$



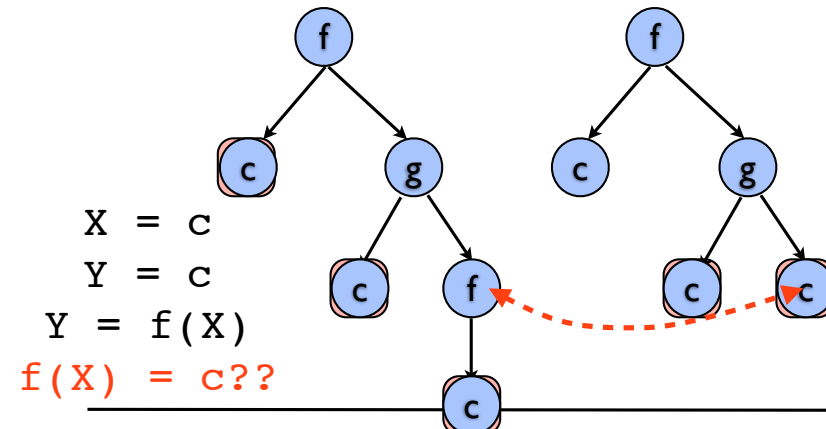
Example (II)

$$f(X, g(Y, f(X))) = f(c, g(X, Y))$$



Example (II)

$$f(X, g(Y, f(X))) = f(c, g(X, Y))$$



Robinson's Algorithm (I)

- Consider a general unification problem

$$t_1 = u_1, t_2 = u_2, \dots, t_n = u_n$$

- Reduce the problem by decomposing each equation into one or more "smaller" equations
- Succeed if we reduce to a "solved form", otherwise fail

Robinson's Algorithm (II)

- Two constants unify if they are equal.

$$c = c, P \rightarrow P$$

$$c = d, P \rightarrow \text{fail.}$$

Robinson's Algorithm (III)

- Two function applications unify if the head symbols are equal, and the corresponding arguments unify.

$$f(t_1, \dots, t_n) = f(u_1, \dots, u_n), P \rightarrow$$

$$t_1 = u_1, \dots, t_n = u_n, P$$

- Must have equal numbers of arguments

$$f(\dots) = g(\dots), P \rightarrow \text{fail}$$

$$f(\dots) = c, P \rightarrow \text{fail.}$$

Robinson's Algorithm (IV)

- Otherwise, a variable X unifies with a term t provided X does not occur in t .

$$X = t, P \rightarrow P[t/X]$$

(**occurs-check**: X must not be in $\text{Vars}(t)$)

- Proceed by substituting t for X in P .

Occurs check

- What happens if we try to unify X with something that *contains* X ?
 $?- X = f(X).$
- Logically, this should **fail**
 - there is no (finite) unifier!
- Most Prolog implementations skip this check for efficiency reasons
 - can use `unify_with_occurs_check/2`

Execution model

- The query is run by trying to find a solution to the goal using the clauses
 - Unification is used to match goals and clauses
 - There may be zero, one, or many solutions
 - Execution may backtrack
- Formal model called **SLD** resolution
 - which you'll see in the theory lectures

Depth-first search (I)

- Idea: To solve atomic goal A ,
 - If B is a **fact** in the program, and $\theta(A) = \theta(B)$, then return answer θ
 - Else, if $B :- G_1, \dots, G_n$ is a **clause** in the program, and θ unifies A with B , then solve $\theta(G_1) \dots \theta(G_n)$
 - Else, give up on this goal.
 - **Backtrack** to last choice point
- Clauses are tried **in declaration order**
- Compound goals are tried **in left-right order**

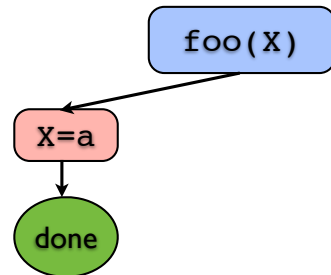
Depth-first search (II)

- Prolog normally tries clauses in order of appearance in program.
- Assume: `foo(a). foo(b). foo(c).`
- Then:
 $?- \text{foo}(X).$

`foo(X)`

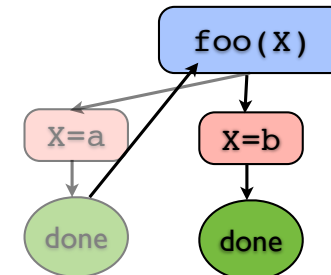
Depth-first search (II)

- Prolog normally searches for clauses in order of appearance in database.
- Assume: foo(a). foo(b). foo(c).
- Then:
?- foo(X).
X = a



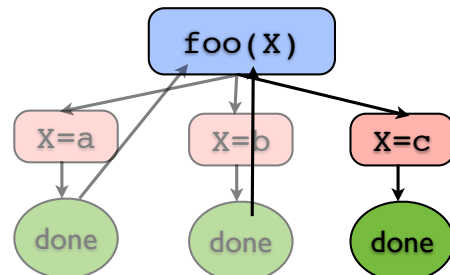
Depth-first search (II)

- Prolog normally searches for clauses in order of appearance in database.
- Assume: foo(a). foo(b). foo(c).
- Then:
?- foo(X).
X = a;
X = b



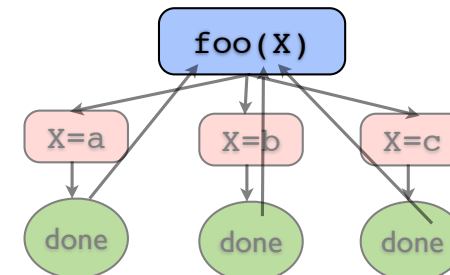
Depth-first search (II)

- Prolog normally searches for clauses in order of appearance in database.
- Assume: foo(a). foo(b). foo(c).
- Then:
?- foo(X).
X = a;
X = b;
X = c



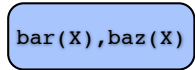
Depth-first search (II)

- Prolog normally searches for clauses in order of appearance in database.
- Assume: foo(a). foo(b). foo(c).
- Then:
?- foo(X).
X = a;
X = b;
X = c;
no



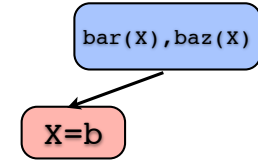
Depth-first search (III)

- Prolog *backtracks* to the last choice point if a subgoal fails.
- Assume: `bar(b). bar(c). baz(c).`
- Then:
?- `bar(X), baz(X).`



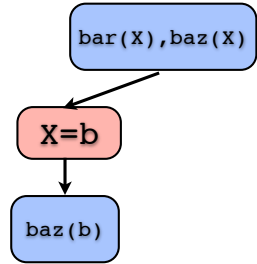
Depth-first search (III)

- Prolog *backtracks* to the last choice point if a subgoal fails.
- Assume: `bar(b). bar(c). baz(c).`
- Then:
?- `bar(X), baz(X).`



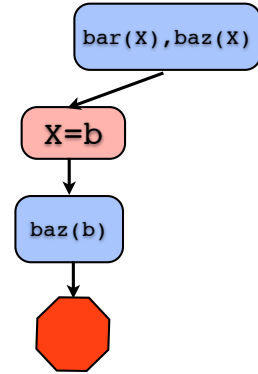
Depth-first search (III)

- Prolog *backtracks* to the last choice point if a subgoal fails.
- Assume: `bar(b). bar(c). baz(c).`
- Then:
?- `bar(X), baz(X).`



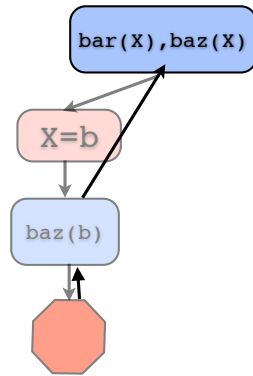
Depth-first search (III)

- Prolog *backtracks* to the last choice point if a subgoal fails.
- Assume: `bar(b). bar(c). baz(c).`
- Then:
?- `bar(X), baz(X).`



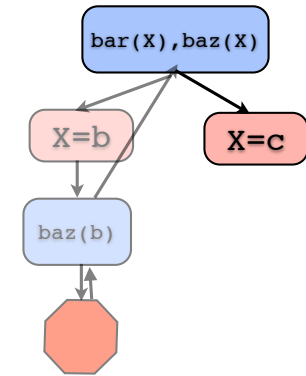
Depth-first search (III)

- Prolog *backtracks* to the last choice point if a subgoal fails.
- Assume: bar(b). bar(c). baz(c).
- Then:
?- bar(X), baz(X).



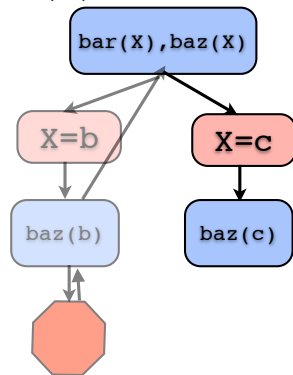
Depth-first search (III)

- Prolog *backtracks* to the last choice point if a subgoal fails.
- Assume: bar(b). bar(c). baz(c).
- Then:
?- bar(X), baz(X).



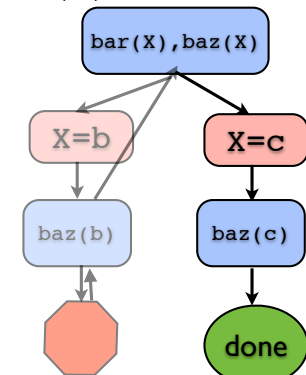
Depth-first search (III)

- Prolog *backtracks* to the last choice point if a subgoal fails.
- Assume: bar(b). bar(c). baz(c).
- Then:
?- bar(X), baz(X).



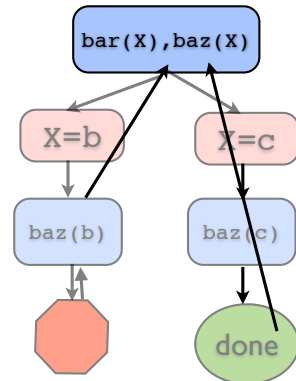
Depth-first search (III)

- Prolog *backtracks* to the last choice point if a subgoal fails.
- Assume: bar(b). bar(c). baz(c).
- Then:
?- bar(X), baz(X).
X = c



Depth-first search (III)

- Prolog *backtracks* to the last choice point if a subgoal fails.
- Assume: `bar(b). bar(c). baz(c).`
- Then:
`?- bar(X), baz(X).`
`X = c;`
`no`



"Generate and test"

- Common Prolog programming idiom:
`find(X) :- generate(X), test(X).`
- where `test(X)` **checks if X is a solution**
- `generate(X)` **searches for solutions**
 - Can use to constrain (infinite) search space
 - Can use different generators to get different search strategies besides depth-first

Limitations of depth-first search

- Recursion needs to be handled carefully to avoid loops
 - Rule order and goal order matter
 - More in next lecture
- Not complete "in practice"
 - legitimate answers may be missed due to loops

Other search strategies

- Breadth-first search / iterative deepening
 - Explore all alternatives, interleaved
 - Price: memory overhead
- Bottom-up (forward chaining)
 - Compute all possible answers derivable from facts & rules
 - Only viable for "Datalog" programs with "flat" data (only constants and variables)
 - Supported by commercial tools for big data (LogicBlox, DLV)

Next time

- Recursion
- Lists, trees, data structures
- Further reading: LPN ch. 2
- Tutorial #1 will be up soon