

Knowledge Engineering

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Lecture 7 – Model-Based Reasoning
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Where are we?

Last time ...

- ▶ we discussed further issues in ontologies
 - ▶ Semantic networks
 - ▶ Description logics
 - ▶ Reasoning with default information

Today ...

- ▶ Model-Based Reasoning Systems

Model-Based Reasoning

- ▶ So far, discussion focussed on general KR&R principles
- ▶ But what is their practical use?
- ▶ Discuss Model-Based Reasoning (MBR) as a “case study” in designing practical reasoning systems
- ▶ Basic idea: use a model of the system as a “simulation” of it to conduct reasoning about its behaviour
- ▶ Describe system in terms of its components and the interactions between them

Model-Based Reasoning

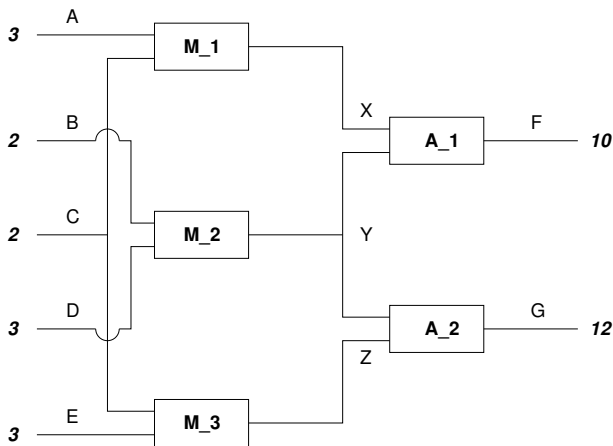
- ▶ Can be used in two ways:
 1. diagnosis (detection of faults)
 2. prediction of behaviour (for design & configuration)
- ▶ Here: Restriction to diagnostic tasks
- ▶ Interaction between predicted behaviour and actual observations ➡ identify system components that failed
- ▶ Particular challenge: identifying multiple simultaneous faults

General Diagnostic Engine

- ▶ General Diagnostic Engine (GDE): a MBR engine intended to locate and isolate multiple simultaneous faults
- ▶ Assumptions:
 - ▶ Faults are in components, not in interconnections (unless these are defined as components)
 - ▶ Device representation is faithful
 - ▶ Faults are not intermittent
- ▶ Will look at extended example rather than precise algorithm

Example

Circuit of adders A_i and multipliers M_j , inputs $A-E$ and outputs F, G



Minimal Candidates

- ▶ Basic problem: F should be 12 but is 10
- ▶ Treat input/output values (e.g. $A = 3$) as facts and statements like “ M_1 is working” (written as M_1) as assumptions
- ▶ Can generate further facts under assumptions give:
 1. $X = 6\{M_1\}$
 2. $Y = 6\{M_2\}$
 3. $Z = 6\{M_3\}$
 4. $Z = 6\{M_2, A_2\}$ (from 2. and $G = 12$)
 5. $X = 4\{M_2, A_1\}$ (from 2. and $F = 10$)
 6. $Y = 4\{M_1, A_1\}$ (from 1. and $F = 10$)
 7. $Z = 8\{M_1, A_1, A_2\}$ (from 6. and $G = 12$)

Minimal Candidates

- ▶ Contradiction btw. 1. and 5. ➔ not all of M_1 , M_2 and A_1 are working (same conflict caused by 6.)
- ▶ Conflict btw. 7. and 3. ➔ not all of M_1 , A_1 , A_2 , M_3 are working
- ▶ At least one of $\{M_1, M_2, A_1\}$ and at least one of $\{M_1, M_3, A_1, A_2\}$ are faulty
- ▶ Set of **minimal candidates**: $\{A_1\}$, $\{M_1\}$, $\{A_2, M_2\}$, $\{M_2, M_3\}$ (minimal sets of components that would explain both assertions)
- ➔ Attention should focus on A_1 and M_1 ➔ measure X (measurement becomes a new fact and process continues)

Candidate Discrimination

- ▶ Problem with above procedure: generates too many possible faults
- ▶ How to identify best measurements to distinguish between candidates?
- ▶ Recall that new predictions are stored as statements $x = v\{e_1, \dots, e_m\}$ where v is the value of x warranted by the minimal set of environments $\{e_1, \dots, e_m\}$
- ▶ Any measurement that contradicts a predicted value is a conflict for the supporting environments
- ▶ In previous example: $X = 4$ vs. $X = 6$ resulted in one of $\{A_1\}$, $\{M_1\}$, $\{A_2, M_2\}$, $\{M_2, M_3\}$ being faulty

Candidate Discrimination

- ▶ Cases after measurement:
 - ▶ $X = 4$, conflict with $\{M_1\}$ → $\{M_1\}$ becomes new minimal candidate
 - ▶ $X = 6$, conflict with $\{A_1, M_2\}$ and $\{A_1, A_2, M_3\}$ → new candidates $\{A_1\}$, $\{M_2, M_3\}$ and $\{A_2, M_2\}$
 - ▶ $X \neq 4$ and $X \neq 6$, conflict with $\{A_1, M_2\}$, $\{A_1, A_2, M_3\}$ and $\{M_1\}$ → minimal candidates $\{A_1, M_1\}$, $\{M_1, M_2, M_3\}$, $\{A_2, M_1, M_2\}$
- ▶ In this simple example, X was identified because more probable singletons $\{M_1\}$ and $\{A_1\}$ are differentiable with its measurement

Candidate Discrimination

- ▶ In general case: hypothesize over all possible measurements (complex)
- ▶ Idea: Choose variable with minimal entropy $\sum_i -p_i \log p_i$ where p_i is probability that i -th remaining candidate is culprit
- ▶ Assume that all components fail independently with equal probability (strong assumption!)
- ▶ Consider only candidates with minimum number of elements = N
- ▶ Let c_{ik} number of candidates that predict value v_{ik} for variable x_i
- ▶ Choose x_i that minimises $\sum_k c_{ik} \log c_{ik}$
- ▶ Iteratively perform one-step lookahead for $N = 1, N = 2, \dots$, etc.

Example

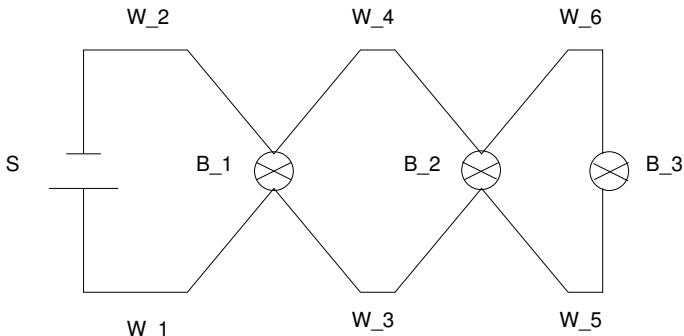
- ▶ In our example, two single-component candidates: $\{M_1\}$, $\{A_1\}$ ($N = 1$)
- ▶ Possible measurements:
 - ▶ $X = 4 \Rightarrow M_1$ faulty (since it predicts $X = 6$), A_1 not (it is part of environments $\{A_1, M_2\}$ and $\{A_1, A_2, M_3\}$)
 - ▶ $X = 6 \Rightarrow A_1$ faulty
 - ▶ $Y = 6$ or $Z = 6 \Rightarrow A_1$ or A_2 faulty
 - ▶ Things like $Y = 4$ are ruled out in present consideration (its supporting environment would be $\{A_1, M_1\}$ (same for $Z = 8$))
- ▶ One component that predicts either value for X , two for the only possibly value for Y and Z
- ▶ Entropies $X : 1 \log 1 + 1 \log 1 = 0$, $Y/Z : 2 \log 2 = 1.4$

Introducing Fault Models

- ▶ GDE based on idea of “component is faulty if retraction of its correctness assumption is consistent with observations”
- ▶ But no knowledge of how components might fail
- ▶ Consider following example: If some bulbs in an electrical circuit are not lit, GDE would also consider that lit bulbs are faulty since they operate without power and battery is empty
- ▶ Logically consistent but counter-intuitive
- ▶ Solution: include explicit **fault models** such that if each of the known possible faults contradicts observations the component can't be faulty

Example

Observations: B_3 is lit while B_1 and B_2 are off



Minimal candidates: $\{B_1, B_2\}$, $\{S, B_3\}$, $\{S, W_5\}$, $\{W_2, W_5\}$
 etc. (22 total)

Fault Models

- ▶ Only $\{B_1, B_2\}$ reasonable, otherwise wires would have to produce voltage or bulb lit without voltage
- ▶ But GDE would require further measurements . . .
- ▶ Use following fault models
 - ▶ Bulb broken
 - ▶ Wire broken
 - ▶ Battery empty
- ▶ First one rules out all candidates in which B_3 occurs
- ▶ Since previous candidates were minimal, delete those with deleted elements
- ▶ B_3 is lit, so there is current → eliminate all candidates with faulty battery or wires

Summary

- ▶ Model-based reasoning
- ▶ General Diagnostic Engine
- ▶ Candidate Discrimination
- ▶ Fault Models
- ▶ Next time: **Reasoning with Uncertainty**