

Knowledge Engineering

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Lecture 13 – Distributed Rational Decision-Making
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Where are we?

Last time ...

- ▶ Agent interaction & communication
- ▶ Speech act theory
- ▶ Interaction Protocols
- ▶ But how should agents behave in interaction situations?

Today ...

- ▶ Distributed Rational Decision-Making

Basic Considerations

- ▶ In entirely cooperative systems, we can impose constraints on agent behaviour to achieve global system objective
- ▶ In open systems, this is impossible!
 - ▶ We do not own all the agents in the system
 - ▶ We don't know anything about their internal design
 - ▶ Ultimately, they might be malicious
- ▶ But there is (some) hope . . .
if we assume agents to be rational
- ▶ In this case, they can be considered “selfish”, rather than “malevolent” or “randomly behaving”
- ▶ Question: How can we design interaction mechanisms that achieve some global objective *despite* agents being selfish?

Decision Theory

- ▶ A theory of (single-agent) rational decision making
- ▶ Based on a set of alternatives, what is the optimal decision an agent may make?
- ▶ Informally speaking, this depends on how desirable an alternative see and how likely we think it is
 - ▶ decision theory = utility theory + probability theory
- ▶ Let $O = \{o_1, \dots, o_n\}$ a set of possible outcomes (e.g. possible “runs” of the system until final states are reached)
- ▶ A **preference ordering** $\succ_i \subseteq O \times O$ for agent i is an antisymmetric, transitive relation on O , i.e.
 - ▶ $o \succ_i o' \Rightarrow o' \not\succeq_i o$
 - ▶ $o \succ_i o' \wedge o' \succ_i o'' \Rightarrow o \succ_i o''$
- ▶ Such an ordering can be used to express strict preferences of an agent over O (write \succeq_i if also reflexive, i.e. $o \succeq_i o$)

Decision Theory

- ▶ Preferences are often expressed through a **utility function**
 $u_i : O \Rightarrow \mathbb{R} :$

$$u_i(o) > u_i(o') \Leftrightarrow o \succ o', \quad u_i(o) \geq u_i(o') \Leftrightarrow o \succeq o'$$

- ▶ Principle of **expected utility maximisation**:

$$a^* = \arg \max_{a \in A} \sum_{o \in O} P(o|a)u(o)$$

where $a \in A$ are the actions/decisions an agent may take

- ▶ Generally accepted criterion, but also problems:
 - ▶ Incomplete information (wrt outcomes, probabilities, preferences)
 - ▶ Risk aversion attitude (value of additional utility depending on current “wealth”, e.g. money)
 - ▶ Quantification problem (optimal=maximising average utility?, comparability of different utility values)

Game Theory

- ▶ Application of decision-theoretic principles to interaction among several agents
- ▶ Basic model: agents perform simultaneous actions (potentially over several stages), the actual outcome depends on the combination of action chosen by all agents
- ▶ **Normal-form games**: final result reached in single step (in contrast to **extensive-form games**)
 - ▶ Agents $\{1, \dots, n\}$, S_i =set of (pure) **strategies** for agent i ,
 $S = \times_{i=1}^n S_i$ space of **joint strategies**
 - ▶ Utility functions $u_i : S \rightarrow \mathbb{R}$ map joint strategies to utilities
 - ▶ A probability distribution $\sigma_i : S_i \rightarrow [0, 1]$ is called a **mixed strategy** of agent i (can be extended to joint strategies)
- ▶ Game theory is concerned with the study of this kind of games (in particular developing solution concepts for games)

Dominance and Best Response Strategies

- ▶ Two simple and very common criteria for rational decision making in games
- ▶ Strategy $s \in S_i$ is said to **dominate** $s' \in S_i$ iff

$$\forall s_{-i} \in S_{-i} \quad u_i(s, s_{-i}) \geq u_i(s', s_{-i})$$

($s_{-i} = (s_1, \dots, s_{i-1}, s_{i+1}, \dots, s_n)$), same abbrev. used for S)

- ▶ Dominated strategies can be safely deleted from the set of strategies, a rational agent will never play them
- ▶ Some games are solvable in **dominant strategy equilibrium**, i.e. all agents have a single (pure/mixed) strategy that dominates all other strategies

Dominance and Best Response Strategies

- ▶ Strategy $s \in S_i$ is a **best response** to strategies $s_{-i} \in S_{-i}$ iff

$$\forall s' \in S_i, s' \neq s \quad u_i(s, s_{-i}) \geq u_i(s', s_{-i})$$

- ▶ Weaker notion, only considers optimal reaction to a *specific* behaviour of other agents
- ▶ Unlike dominant strategies, best-response strategies (trivially) always exist
- ▶ Strict versions of the above relations require that “>” holds’ for at least one s'
- ▶ Replace s_i/s_{-i} above by σ_i/σ_{-i} and you can extend the definitions for dominant/best-response strategies to mixed strategies

Nash Equilibrium

- ▶ Nash (1951) defined the most famous equilibrium concept for normal-form games
- ▶ A joint strategy $s \in S$ is said to be in (pure-strategy) **Nash equilibrium** (NE), iff

$$\forall i \in \{1, \dots, n\} \forall s'_i \in S_i \quad u_i(s_i, s_{-i}) \geq u_i(s'_i, s_{-i})$$

- ▶ Intuitively, this means that no agent has an incentive to deviate from this strategy combination
- ▶ Very appealing notion, because it can be shown that a (mixed-strategy) NE always exists
- ▶ But also some problems:
 - ▶ Not always unique, how to agree on one of them?
 - ▶ Proof of existence does not provide method to actually find it
 - ▶ Many games do not have pure-strategy NE

Example

Two men are collectively charged with a crime and held in separate cells, with no way of meeting or communicating. They are told that:

- ▶ if one confesses and the other does not, the confessor will be freed, and the other will be jailed for three years;
- ▶ if both confess, then each will be jailed for two years.

Both prisoners know that if neither confesses, then they will each be jailed for one year.

Example

The Prisoner's Dilemma: Nash equilibrium is not Pareto efficient
 (or: no one will dare to cooperate although mutual cooperation is preferred over mutual defection)

	2	C	D
1			
C		(3,3)	(0,5)
D		(5,0)	(1,1)

Problem: $DC \succ CC \succ DD \succ CD$ (from first player's point of view) and $u(CC) > \frac{u(DC)+u(CD)}{2}$

The Evolution of Cooperation?

- ▶ Typical **non-zero sum game**: there is a potential for cooperation but how should it emerge among self-interested agents?
- ▶ This situation occurs in many real life cases:
 - ▶ Nuclear arms race
 - ▶ Tragedy of the commons
 - ▶ “Free rider” problems
- ▶ In (infinitely) iterated case, cooperation is the rational choice in the PD (but “backward induction” problem)
- ▶ Axelrod’s tournament (1984): Iterated Prisoner’s Dilemma with lots of strategies (how to play against different opponents?)
- ▶ TIT FOR TAT strategy (don’t be envious, be nice, retaliate appropriately, don’t hold grudges) very successful

Example

The Coordination Game: No temptation to defect, buy two equilibria (hard to know which one will be chosen by other party)

	2	A	B
1			
A		(1,1)	(-1,-1)
B		(-1,-1)	(1,1)

Game Theory & Multiagent Systems

- ▶ Game theory = foundation for **mechanism design**
- ▶ Design of negotiation protocols for automated negotiation (i.e. coordination in the presence of a conflict of interest)
- ▶ Find protocols that satisfy certain properties
- ▶ *Individual Rationality*: for all agents, the negotiated solution should offer at least as much utility as not participating in the protocol
 - ▶ Necessary precondition for any viable protocol
- ▶ *Social Welfare*: the sum of all agents' utilities under some solution
 - ▶ Somewhat arbitrary, inter-agent utilities might not be comparable
- ▶ *Pareto Efficiency*
 - ▶ No agent could be better off than in current solution without at least one other agent being worse off

Criteria for Negotiation Protocols

- ▶ Stability: motivation for agents to behave in the desired manner
 - ▶ Dominant strategy equilibrium: very stable but does not always exist
 - ▶ Nash equilibrium
 - ▶ Pure Nash equilibria do not exist in all games
 - ▶ There might be more than one. How to pick the right one?
 - ▶ Sometimes not Pareto efficient
 - ▶ Not stable against deviation of a group of agents in coordinated manner
 - ▶ Doesn't necessarily hold in later stages of a sequential game
 - ▶ Computational efficiency
 - ▶ Distribution, communication efficiency

Revelation Principle

- ▶ An example of the kind thing that can be proven using game theory
- ▶ Let $\Theta = \{\theta_1, \dots, \theta_n\}$ “types” of agents i that totally determine their preferences, $f : \Theta \rightarrow O$ a **social choice** function that calculates social outcome given agent types
- ▶ Problem: agents might not reveal their types truthfully
- ▶ A protocol **implements** f if the protocol has an equilibrium (dominant strategy/Nash) whose outcome is the same as that of f if agents revealed types truthfully
- ▶ **Revelation principle:**

Suppose protocol p implements f in Nash/DS equilibrium. Then f is implementable in Nash/DS equilibrium via a single-step protocol where agents reveal their entire types truthfully.

Revelation Principle

- ▶ Proof idea:
 - ▶ add additional step to p in which agents' potentially insincere strategies are computed automatically
 - ▶ simulate original protocol after this step
 - ▶ motivation for agents to reveal their true type in single step (protocol lies optimally on agents' behalf)
- ▶ Significance: enables us to restrict search for desirable protocol to ones where truthful revelation occurs in one step
- ▶ However, only existence result
 - ▶ What if there are other equilibria?
 - ▶ What if "lying" step is hard to compute?
 - ▶ What if agents don't play equilibrium strategies?

Electronic Auctions

- ▶ Auctions = preference-based method for allocating goods
- ▶ Most common types of auctions:
 - ▶ English (first-price open-cry)
 - ▶ Dutch (reverse)
 - ▶ First-price sealed bid
 - ▶ Vickrey auction (second-price sealed bid)
- ▶ Additional variations depending on following characteristics:
 - ▶ private-value vs. public-value (also: correlated value)
 - ▶ risk-neutral, risk-seeking, risk-averse bidders/auctioneer
- ▶ Some interesting issues/problems:
 - ▶ Lying bidders
 - ▶ Lying auctioneer
 - ▶ Bidder collusion
 - ▶ Incentive for speculation

The English Auction (EA)

- ▶ Each bidder raises freely his bid (in public), auction ends if no bidder is willing to raise his bid anymore
- ▶ Bidding process public → in correlated auctions, it can be worthwhile to counter-speculate
- ▶ In correlated auctions, often auctioneer increases price at constant/appropriate rate, also use of reservation prices
- ▶ Dominant strategy in private-value EA: bid a small amount above one's own valuation

The English Auction (EA)

- ▶ Advantages:
 - ▶ Truthful bidding is individually rational & stable
 - ▶ No lying auctioneer
- ▶ Disadvantages:
 - ▶ Can take long to terminate in correlated/common value auctions
 - ▶ Information is given away by bidding in public
 - ▶ Use of shills (in correlated-value EA) and “minimum price bids” possible
 - ▶ Bidder collusion self-enforcing (once agreement has been reached, it is safe to participate in a coalition) and identification of partners easily possible

Dutch/First-Price Sealed Bid Auctions

- ▶ Dutch (descending) auction: seller continuously lowers prices until one of the bidders accepts the price
- ▶ First-price sealed bid: bidders submit bids so that only auctioneer can see them, highest bid wins (only one round of bidding)
- ▶ DA/FPSB strategically equivalent (no information given away during auction, highest bid wins)
- ▶ Advantages:
 - ▶ Efficient in terms of real time (especially Dutch)
 - ▶ No information is given away during auction
 - ▶ Bidder collusion not self-enforcing, and bidders have to identify each other

Dutch/First-Price Sealed Bid Auctions

- ▶ Disadvantages:
 - ▶ No dominant strategy, individually optimal strategy depends on assumptions about others' valuations
 - ▶ Ideally bid less than own valuation but just enough to win
 - ▶ Incentive to counter-speculate
 - ➔ no incentive to bid truthfully
 - ▶ This might incur loss of computational resources in the system
 - ▶ Lying auctioneer

The Vickrey Auction (VA)

- ▶ Second-price sealed bid: Highest bidder wins, but pays price of second-highest bid
- ▶ Advantages:
 - ▶ Truthful bidding is dominant strategy
 - ▶ No incentive for counter-speculation
 - ▶ Computational efficiency
- ▶ Disadvantages:
 - ▶ Bidder collusion self-enforcing
 - ▶ Lying auctioneer
- ▶ Unfortunately, VA is not very popular in real life
- ▶ But very successful in computational multiagent systems

Further Issues

- ▶ Pareto efficiency: all protocols allocate auction item to the bidder who values it most (in isolated private value/common value auctions)
 - ▶ But this result requires risk-neutrality if there is some uncertainty about own valuations
- ▶ Revenue equivalence in terms of expected revenue among all protocols if valuations independent, bidders risk-neutral and auction is private value
- ▶ **Winner's curse** in correlated/common value auctions
 - ▶ If I win, I always know I won't get to re-sell at the same price, because others value the goods less!

Further Issues

- ▶ Some properties of protocols change
 - ▶ if there is uncertainty about own valuations
 - ▶ if one can pay to obtain information about others' valuations
 - ▶ if we are looking at sequential (multiple) auctions
- ▶ Undesirable private information revelation
 - ▶ Example: truthful bidding in EA/VA may lead sub-contractors to re-negotiate rates after finding out that price was lower than they thought
- ▶ In terms of communication, auctions are not a very expressive method of negotiation!
 - ▶ Solely concerned with determining a selling price for some item

Other Methods

- ▶ Voting: determining an optimal “social choice” given individual preferences
- ▶ Bargaining: different set of possible agreements (“deals”), but conflict of interest regarding these
- ▶ Market Equilibrium Mechanisms: how to derive optimal production and consumption plans in a market
- ▶ Contract Nets: determining optimal task allocations among a set of agents
- ▶ Coalition Formation: how to find the best coalition structure in an agent society (if different coalitions can ensure different payoffs) and how to reward coalition participants

Critique

While game-theoretic/decision-theoretic approaches are currently very popular, there is also some criticism:

- ▶ How far can we get in terms of cooperation while assuming purely self-interested agents?
 - ▶ Good for economic interactions but how about other social processes?
 - ▶ In a sense, these approaches assume “worst case” of possible agent behaviour and disregard higher (more fragile) levels of cooperation
- ▶ Although mathematically rigorous,
 - ▶ ... the proofs only work under simplifying assumptions
 - ▶ ... often don't consider irrational behaviour
 - ▶ ... can only deal with a “utilitised” world
- ▶ Relationship to goal-directed, rational reasoning (e.g. BDI) and to deductive reasoning complex and not entirely clear

Summary

- ▶ Discussed rational decision-making mechanisms in societies of self-interested agents
- ▶ Idea of “mechanism design”: design protocols that ensure global properties despite agents’ self-interest under certain rationality assumptions
- ▶ Discussed foundations and fundamental problems of decision theory and game theory
- ▶ Looked at auctions as a particular method for automated negotiation
- ▶ Next time: **Semantic Web** (probably)