Introduction to Theoretical Computer Science

Lecture 13: The Polynomial Hierarchy, Alternation and PSPACE

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The Class CoNP

trick Question

Is the class NP closed under complement?

We don't know.

Question

Why can't we just flip the answer, like we do for P?

Nondeterministic machines accept if just one path accepts. To flip the answer of an NRM, we'd have to accept an answer if all paths reject. This is no longer an (angelic) NRM.

Question

What is **NP** \cap **CoNP**? is it **P**? (we don't know)

Polynomial Hierarchy

Alternation and **PSPACE**

What we have now



Sigmas

We shall introduce notation to describe polynomial problems.

Sigma

The set $\Sigma_1^{\mathbf{P}}$ describes all problems that can be phrased as $\{y \mid \exists^{\mathbf{P}} x \in \mathbb{N}. R(x, y)\}$, where *R* is a **P**-decidable predicate and $\exists^{\mathbf{P}} x \dots$ indicates that *x* is of size polynomial in the size of *y*.

- If a problem $Q \in \Sigma_1^{\mathsf{P}}$ then Q is in **NP**. Why? (we can "guess" an x and polynomially test R(x, y))
- If a problem Q is in **NP** then $P \in \Sigma_1^{\mathbf{P}}$. Why?

Certificates

We can say that x is a *certificate* showing which "guesses" can made by our NRM giving an accepting run.

So, $\mathbf{NP} = \Sigma_1^{\mathbf{P}}$.



Pi

The set $\Pi_1^{\mathbf{P}}$ describes all problems that can be phrased as $\{y \mid \forall^{\mathbf{P}}x \in \mathbb{N}. R(x, y)\}$, where *R* is a **P**-decidable predicate and $\forall^{\mathbf{P}}x \dots$ indicates that *x* is of size polynomial in the size of *y*.

$$\overline{E_1^{\mathbf{P}}} = \overline{\{x \mid \exists^{\mathbf{P}}y. R(x, y)\}} \\ = \{x \mid \neg \exists^{\mathbf{P}}y. R(x, y)\} \\ = \{x \mid \forall^{\mathbf{P}}y. \neg R(x, y)\} \\ = \Pi_1^{\mathbf{P}}$$

As $\Sigma_1^{\mathbf{P}}$ is **NP**, $\Pi_1^{\mathbf{P}}$ is **CoNP**.



For reasons that are unknown to me, some books have:

Delta The set $\Delta_1^{\mathbf{P}}$ describes the intersection of $\Sigma_1^{\mathbf{P}}$ and $\Pi_1^{\mathbf{P}}$.

While others have

Delta

The set Δ_1^P describes the set P

From our characterisations of $\Sigma_1^{\mathbf{P}}$ and $\Pi_1^{\mathbf{P}}$, we have that $\Delta_1^{\mathbf{P}} \supseteq \mathbf{P}$, but we don't know if these definitions are equal.

Relabeling



Moving Higher

Definitions

• $\Sigma_2^{\mathbf{P}}$ is all problems of form $\{x \mid \exists^{\mathbf{P}} y. \forall^{\mathbf{P}} z. R(x, y, z)\}$. • $\Pi_2^{\mathbf{P}}$ is all problems of form $\{x \mid \forall^{\mathbf{P}} y. \exists^{\mathbf{P}} z. R(x, y, z)\}$. • $\Delta_2^{\mathbf{P}} = \Sigma_2^{\mathbf{P}} \cap \Pi_2^{\mathbf{P}}$

Note that $\Sigma_1^{\mathbf{P}}, \Pi_1^{\mathbf{P}}, \Delta_1^{\mathbf{P}}$ are all $\subseteq \Delta_2^{\mathbf{P}}$ (and therefore $\subseteq \Sigma_2^{\mathbf{P}}$ and $\subseteq \Pi_2^{\mathbf{P}}$). Why? (our R can simply "ignore" one of the parameters) Polynomial Hierarchy

Alternation and **PSPACE**

The Polynomial Hierarchy



An equivalent characterisation

We can define in terms of oracles:
Δ₂^P is all problems that are decidable in polynomial time by some deterministic TM/RM with an O(1) oracle for some complete problem in Σ₁^P, i.e. it is P with an O(1) oracle for NP.

- Σ₂^P allows the TM/RM to be nondeterministic, i.e. it is NP with an O(1) oracle for NP.
- Π₂^P is CoNP with an oracle for NP.

Building up

In general, for any n > 1:

- $\Delta_n^{\mathbf{P}}$ is all problems that are decidable by some deterministic, polynomially bounded TM/RM with an $\mathcal{O}(1)$ oracle for some problem $\in \Sigma_{n-1}^{\mathbf{P}}$.
- Σ_n^{P} are all problems that are decidable by some nondeterministic, polynomially bounded TM/RM with an $\mathcal{O}(1)$ oracle for some problem $\in \Sigma_{n-1}^{\mathsf{P}}$.
- $\Pi_n^{\mathbf{P}}$ are all problems decidable by some *co-nondeterministic*, polynomially bounded TM/RM with an $\mathcal{O}(1)$ oracle for some problem $\in \Sigma_{n-1}^{\mathbf{P}}$.

Co-nondeterminism

Could also be called *demonic* nondeterminism. Like our normal (angelic) nondeterminism but only accepts if *all* paths accept.

Alternation

Alternation

Equivalently $\Sigma_n^{\mathbf{P}}$ are all problems that can be phrased as some alternation of (**P**-bounded) quantifiers, starting with $\exists^{\mathbf{P}}$:

$$\{w \mid \exists^{\mathsf{P}} x_1. \forall^{\mathsf{P}} x_2. \exists^{\mathsf{P}} x_3. \forall^{\mathsf{P}} x_4. \ldots x_n. R(w, x_1, \ldots, x_n)\}$$

$\Pi_n^{\mathbf{P}}$ starts instead with $\forall^{\mathbf{P}}$:

$$\{w \mid \forall^{\mathsf{P}} x_1. \exists^{\mathsf{P}} x_2. \forall^{\mathsf{P}} x_3. \exists^{\mathsf{P}} x_4. \ldots x_n. R(w, x_1, \ldots, x_n)\}$$

Alternating Machines

Alternating Machines combine the acceptance modes of both angelic and demonic nondeterministic machines.

Alternating Register Machines

Consider NRMs where instead of just a MAYBE instruction we have a MAYBE $^\forall$ instruction and a MAYBE $^\exists$ instruction.

- MAYBE³ is a nondeterministic choice where we accept if one branch accepts.
- MAYBE[∀] is a nondeterministic choice where we accept only when both branches accept.

Alternating Turing Machines are defined by labelling states with either \forall or \exists .

Alternating Machines and the Polynomial Hierarchy

- The class ∑_n^P could equivalently be defined as the class of problems decided in polynomial time by an alternating machine that initially uses ∃-nondeterminism, and every path in the machine swaps quantifiers (i.e. to ∀ or back to ∃) at most n − 1 times.
- **I** $\Pi_n^{\mathbf{P}}$ is the same, except that we start with \forall instead.

The class **AP**

AP is the class of all problems decidable by an alternating machine in polynomial time, without any restriction on swapping quantifiers.

AP is known to be equal to **PSPACE** (more on this in a moment)

A Fragile House of Cards

Warning

The polynomial hierarchy could collapse at any point. (i.e. all of the classes in the PH could be equal)

We don't know that $P \neq PSPACE$, and the entire polynomial hierarchy is contained inside AP which = PSPACE.

Wait, what's **PSPACE**?

An RM/TM is f(n)-space-bounded if it may use only f(inputsize) space. For TMs, space means cells on tape; for RMs, number of bits in registers. **PSPACE** is the class of problems solvable by polynomially-space-bounded machines.

The following are obvious (**Exercise**: why?): **PSPACE** \supseteq **P**? **PSPACE** \supseteq **NP**? **PSPACE** \subseteq **EXPTIME**?

Conclusions

This concludes our study of complexity theory. Next week, we start on a new (or rather, very old) model of computation that is the foundation for modern studies of programming languages and their semantics, the λ -calculus.