

Inf2b Learning and Data

Lecture 8: Real-valued distributions and Gaussians

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(Credit: Iain Murray and Steve Renals)

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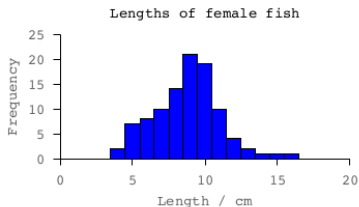
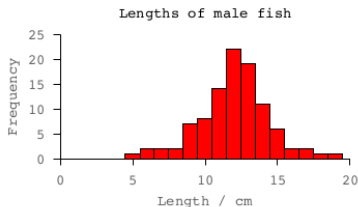
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Today's Schedule

- 1 Continuous random variables
- 2 The Gaussian distribution (one-dimensional)
- 3 The multidimensional Gaussian distribution

Discrete to continuous random variables

Fish example again:

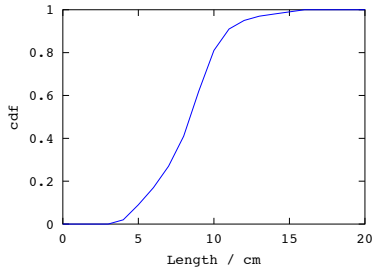
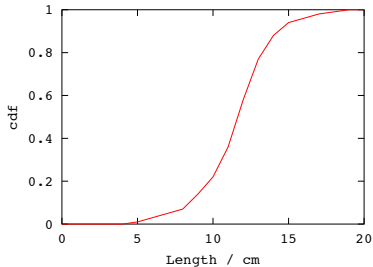
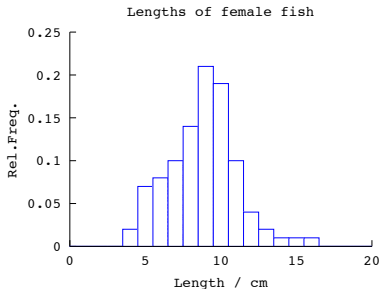
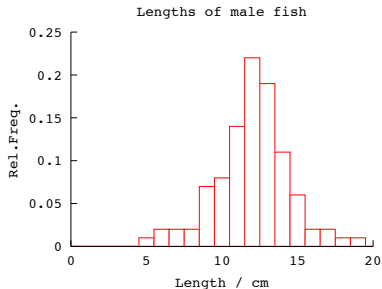


$$c^* = \arg \max_c P(c|x) = \arg \max_c \frac{P(x|c)P(c)}{P(x)} = \arg \max_c P(x|c)P(c)$$

- What if the number of bins $\rightarrow \infty$? (i.e. the width of bin $\rightarrow 0$)
- $P(X = x|C)$ will be almost 0 everywhere!
- We instead consider a **cumulative distribution function (cdf)** with a continuous random variable:

$$F(x) = P(X \leq x)$$

Cumulative distribution functions graphed



Cumulative distribution function properties

Cumulative distribution functions have the following properties:

- 1 $F(-\infty) = 0$;
- 2 $F(\infty) = 1$;
- 3 If $a \leq b$ then $F(a) \leq F(b)$.

To obtain the probability of falling in an interval we can do the following:

$$\begin{aligned}P(a < X \leq b) &= P(X \leq b) - P(X \leq a) \\ &= F(b) - F(a)\end{aligned}$$

Probability density function (pdf)

- The rate of change of the cdf gives us the **probability density function (pdf)**, $p(x)$:

$$p(x) = \frac{d}{dx} F(x) = F'(x)$$

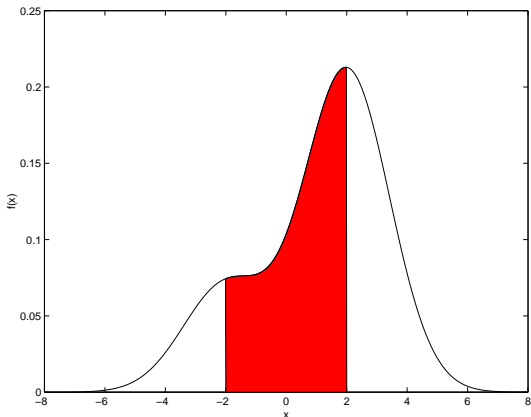
$$F(x) = \int_{-\infty}^x p(x) dx$$

- $p(x)$ is **not** the probability that X has value x . But the pdf is proportional to the probability that X lies in a small interval $[x, x + dx]$.
- Notation: p for pdf, P for probability

The probability that the random variable lies in interval (a, b) is given by:

$$\begin{aligned}P(a < X \leq b) &= F(b) - F(a) \\&= \int_{-\infty}^b p(x) dx - \int_{-\infty}^a p(x) dx \\&= \int_a^b p(x) dx\end{aligned}$$

The probability that the random variable lies in interval (a, b) is the area under the pdf between a and b :



The Gaussian distribution

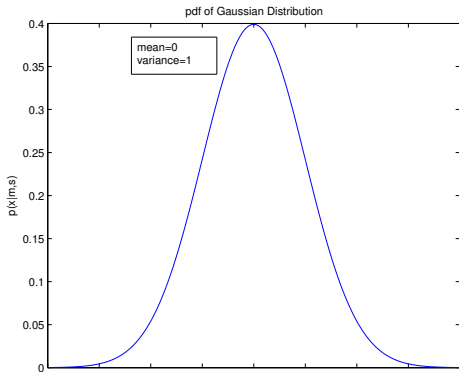
- The **Gaussian** (or **Normal**) distribution is the most common (and easily analysed) continuous distribution
- It is also a reasonable model in many situations (the famous bell curve)
- If a (scalar) variable has a Gaussian distribution, then it has a probability density function with this form:

$$p(x|\mu, \sigma^2) = N(x; \mu, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(\frac{-(x - \mu)^2}{2\sigma^2}\right)$$

- The Gaussian is described by two parameters:
 - the mean μ (location)
 - the variance σ^2 (dispersion)

Plot of Gaussian distribution

- Gaussians have the same shape, with the location controlled by the mean, and the spread controlled by the variance
- One-dimensional Gaussian with zero mean and unit variance
($\mu = 0, \sigma^2 = 1$)



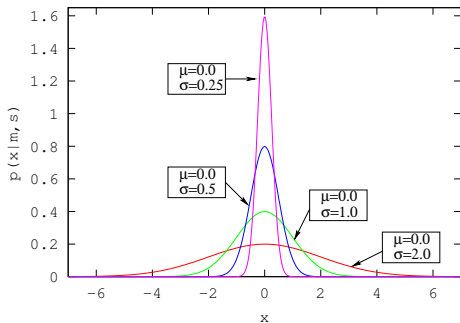
Another plot of a Gaussian



Properties of the Gaussian distribution

$$N(x; \mu, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(x - \mu)^2}{2\sigma^2}\right)$$

pdfs of Gaussian distributions



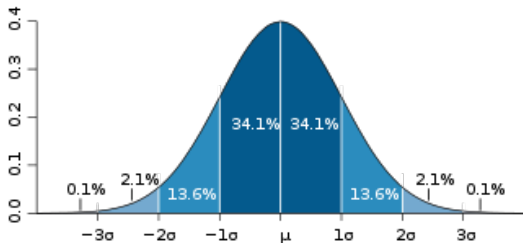
$$\int_{-\infty}^{\infty} N(x; \mu, \sigma^2) dx = 1$$

$$\lim_{\sigma \rightarrow 0} N(x; \mu, \sigma^2) = \delta(x - \mu)$$

(Dirac delta function)

Facts about the Gaussian distribution

- A Gaussian can be used to describe approximately any random variable that tends to cluster around the mean
- Concentration:
 - About 68% of values drawn from a normal distribution are within one SD away from the mean
 - About 95% are within two SDs
 - About 99.7% lie within three SDs of the mean



Central Limit Theorem

- Under certain conditions, the sum of a large number of random variables will have approximately normal distribution.
- Several other distributions are well approximated by the Normal distribution:
 - Binomial $B(n, p)$, when n is large and p is not too close to 1 or 0
 - Poisson $P_o(\lambda)$ when λ is large
 - Other distributions including chi-squared and Students T
- The Wikipedia entry on the Gaussian distribution is good

Parameter estimation

- Estimate mean and variance parameters of a Gaussian from data $x^{(1)}, x^{(2)}, \dots, x^{(n)}$
- Use sample mean and sample variance estimates:

$$\mu = \frac{1}{n} \sum_{i=1}^n x^{(i)} \quad (\text{sample mean})$$

$$\sigma^2 = \frac{1}{n} \sum_{i=1}^n (x^{(i)} - \mu)^2 \quad (\text{sample variance}),$$

Example: Gaussians

A pattern recognition problem has two classes, S and T .
Some observations are available for each class:

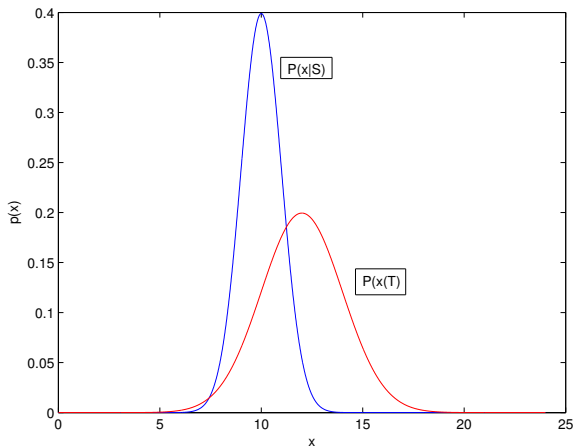
Class S		10	8	10	10	11	11
Class T		12	9	15	10	13	13

The mean and variance of each pdf are estimated by the sample mean and sample variance.

$$\begin{aligned} S : & \text{ mean} = 10; \quad \text{variance} = 1 \\ T : & \text{ mean} = 12; \quad \text{variance} = 4 \end{aligned}$$

Example: pdfs

Sketch the pdf for each class.



Summary of one-dimensional Gaussians

Gaussians

- Continuous random variable: cumulative distribution function (cdf) and probability density function (pdf)
- Gaussian pdf (one dimension):

$$p(x | \mu, \sigma^2) = N(x; \mu, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(\frac{-(x - \mu)^2}{2\sigma^2}\right)$$

- Estimate parameters (mean and variance) using maximum likelihood estimation (See Tutorial 8)

The multidimensional Gaussian distribution

- The d -dimensional vector $\mathbf{x} = (x_1, \dots, x_d)^T$ is multivariate Gaussian if it has a probability density function of the following form:

$$p(\mathbf{x} | \boldsymbol{\mu}, \boldsymbol{\Sigma}) = \frac{1}{(2\pi)^{d/2} |\boldsymbol{\Sigma}|^{1/2}} \exp \left(-\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu}) \right).$$

The pdf is parameterised by the mean vector $\boldsymbol{\mu}$ and the covariance matrix $\boldsymbol{\Sigma}$.

- The 1-dimensional Gaussian is a special case of this pdf
- The argument to the exponential $\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu})$ is referred to as a *quadratic form*.

Covariance matrix

- The mean vector $\boldsymbol{\mu}$ is the expectation of \mathbf{x} :

$$\boldsymbol{\mu} = E[\mathbf{x}]$$

- The covariance matrix $\vec{\Sigma}$ is the expectation of the deviation of \mathbf{x} from the mean:

$$\boldsymbol{\Sigma} = E[(\mathbf{x} - \boldsymbol{\mu})(\mathbf{x} - \boldsymbol{\mu})^T]$$

- $\boldsymbol{\Sigma}$ is a $d \times d$ symmetric matrix:

$$\sigma_{ij} = E[(x_i - \mu_i)(x_j - \mu_j)] = E[(x_j - \mu_j)(x_i - \mu_i)] = \sigma_{ji}.$$

- The sign of the covariance helps to determine the relationship between two components:
 - If x_j is large when x_i is large, then $(x_j - \mu_j)(x_i - \mu_i)$ will tend to be positive;
 - If x_j is small when x_i is large, then $(x_j - \mu_j)(x_i - \mu_i)$ will tend to be negative.

Maximum likelihood estimation (MLE):

$$\boldsymbol{\mu} = E[\mathbf{x}]$$

$$\hat{\boldsymbol{\mu}} = \frac{1}{n} \sum_{i=1}^n \mathbf{x}^{(i)}$$

$$\boldsymbol{\Sigma} = E[(\mathbf{x} - \boldsymbol{\mu})(\mathbf{x} - \boldsymbol{\mu})^T]$$

$$\hat{\boldsymbol{\Sigma}} = \frac{1}{n} \sum_{i=1}^n (\mathbf{x}^{(i)} - \hat{\boldsymbol{\mu}})(\mathbf{x}^{(i)} - \hat{\boldsymbol{\mu}})^T$$

Correlation matrix

The covariance matrix is not scale-independent: Define the **correlation coefficient**:

$$\rho(x_i, x_j) = \rho_{ij} = \frac{\sigma_{ij}}{\sqrt{\sigma_{ii}\sigma_{jj}}}$$

- Scale-independent (ie independent of the measurement units) and location-independent, ie:

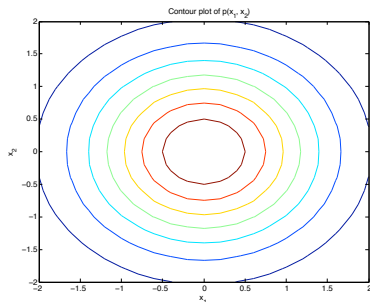
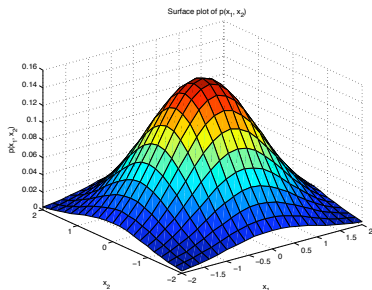
$$\rho(x_i, x_j) = \rho(ax_i + b, cx_j + d)$$

- The correlation coefficient satisfies $-1 \leq \rho \leq 1$, and

$$\rho(x, y) = +1 \quad \text{if } y = ax + b \quad a > 0$$

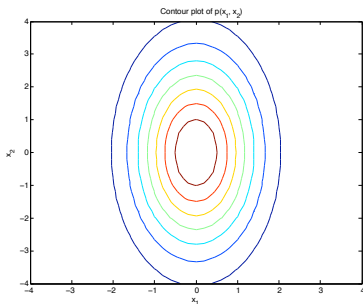
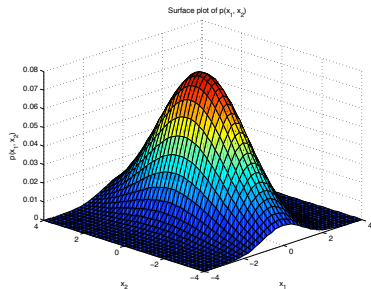
$$\rho(x, y) = -1 \quad \text{if } y = ax + b \quad a < 0$$

Spherical Gaussian



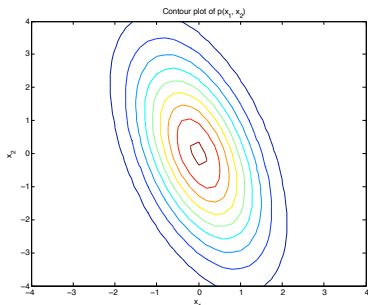
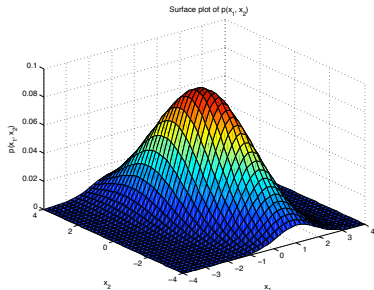
$$\mu = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad \Sigma = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \quad \rho_{12} = 0$$

2-dimensional Gaussian with a diagonal covariance matrix



$$\mu = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad \Sigma = \begin{pmatrix} 1 & 0 \\ 0 & 4 \end{pmatrix} \quad \rho_{12} = 0$$

2-dimensional Gaussian with a full covariance matrix



$$\mu = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad \Sigma = \begin{pmatrix} 1 & -1 \\ -1 & 4 \end{pmatrix} \quad \rho_{12} = -0.5$$

Parameter estimation of multivariate Gaussian distribution can be difficult

Gaussians

- Continuous random variable: cumulative distribution function and probability density function
- Univariate Gaussian pdf:

$$p(x | \mu, \sigma^2) = N(x; \mu, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(\frac{-(x - \mu)^2}{2\sigma^2}\right)$$

- Multivariate Gaussian pdf:

$$p(\mathbf{x} | \boldsymbol{\mu}, \boldsymbol{\Sigma}) = \frac{1}{(2\pi)^{d/2} |\boldsymbol{\Sigma}|^{1/2}} \exp\left(-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1}(\mathbf{x} - \boldsymbol{\mu})\right)$$

- Estimate parameters (mean and covariance matrix) using maximum likelihood estimation