1. Discriminant functions (recap)
2. Decision boundary of linear discriminants (recap)
3. Discriminative training of linear discriminants (Perceptron)
4. Structures and decision boundaries of Perceptron
5. LSE Training of linear discriminants
6. Appendix - calculus, gradient descent, linear regression
Discriminant functions (recap)

\[ y_k(x) = \ln \left( P(x|C)P(C_k) \right) \]

\[ = -\frac{1}{2} (x - \mu_k)^T \Sigma_k^{-1} (x - \mu_k) - \frac{1}{2} \ln |\Sigma_k| + \ln P(C_k) \]

\[ = -\frac{1}{2} x^T \Sigma_k^{-1} x + \mu_k^T \Sigma_k^{-1} x - \frac{1}{2} \mu_k^T \Sigma_k^{-1} \mu_k - \frac{1}{2} \ln |\Sigma_k| + \ln P(C_k) \]
Linear discriminants for a 2-class problem

$y_1(x) = w_1^T x + w_{10}$
$y_2(x) = w_2^T x + w_{20}$

Combined discriminant function:

$$y(x) = y_1(x) - y_2(x) = (w_1 - w_2)^T x + (w_{10} - w_{20})$$
$$= w^T x + w_0$$

Decision:

$$C = \begin{cases} 
1, & \text{if } y(x) \geq 0, \\
2, & \text{if } y(x) < 0
\end{cases}$$
Decision boundary of linear discriminants

Decision boundary:

\[ y(x) = \mathbf{w}^T \mathbf{x} + w_0 = 0 \]

<table>
<thead>
<tr>
<th>Dimension</th>
<th>Decision boundary</th>
</tr>
</thead>
<tbody>
<tr>
<td>2</td>
<td>line ( w_1 x_1 + w_2 x_2 + w_0 = 0 )</td>
</tr>
<tr>
<td>3</td>
<td>plane ( w_1 x_1 + w_2 x_2 + w_3 x_3 + w_0 = 0 )</td>
</tr>
<tr>
<td>( D )</td>
<td>hyperplane ( (\sum_{i=1}^{D} w_i x_i) + w_0 = 0 )</td>
</tr>
</tbody>
</table>

NB: \( \mathbf{w} \) is a normal vector to the hyperplane
$y(x) = w_1x_1 + w_2x_2 + w_0 = 0$ (if $w_2 
eq 0$)

$(x_2 = -\frac{w_1}{w_2}x_1 - \frac{w_0}{w_2})$,
Decision boundary of linear discriminant (3D)

\[ y(x) = w_1 x_1 + w_2 x_2 + w_3 x_3 + w_0 = 0 \]
Approach to linear discriminant functions

Generative models : \( p(x|C_k) \)

Discriminant function based on Bayes decision rule

\[
y_k(x) = \ln p(x|C_k) + \ln P(C_k)
\]

\[
\downarrow \quad \text{Gaussian pdf (model)}
\]

\[
y_k(x) = -\frac{1}{2}(x - \mu_k)^T \Sigma_k^{-1}(x - \mu_k) - \frac{1}{2} \ln |\Sigma_k| + \ln P(C_k)
\]

\[
\downarrow \quad \text{Equal covariance assumption}
\]

\[
y_k(x) = w^T x + w_0
\]

\[
\uparrow \quad \text{Why not estimating the decision boundary or } P(C_k|x) \text{ directly?}
\]

Discriminative training / models

(Logistic regression, Perceptron / Neural network, SVM)
A discriminant for a two-class problem:

\[ y(x) = y_1(x) - y_2(x) = (w_1 - w_2)^T x + (w_{10} - w_{20}) = w^T x + w_0 \]
Perceptron error correction algorithm

\[ a(\dot{x}) = \mathbf{w}^T \mathbf{x} + w_0 = \dot{\mathbf{w}}^T \dot{x} \]

where \( \dot{\mathbf{w}} = (w_0, \mathbf{w}^T)^T \), \( \dot{x} = (1, \mathbf{x}^T)^T \)

Let’s just use \( \mathbf{w} \) and \( \mathbf{x} \) to denote \( \dot{\mathbf{w}} \) and \( \dot{x} \) from now on!

\[ y(x) = g( a(x) ) = g( \mathbf{w}^T \mathbf{x} ) \]

where \( g(a) = \begin{cases} 
1, & \text{if } a \geq 0, \\
0, & \text{if } a < 0 
\end{cases} \)

\( g(a) \): activation / transfer function

Training set: \( \mathcal{D} = \{ (\mathbf{x}_1, t_1), \ldots, (\mathbf{x}_N, t_N) \} \)

where \( t_i \in \{0, 1\} \): target value

Modify \( \mathbf{w} \) if \( \mathbf{x}_i \) was misclassified

\[ \mathbf{w}^{(\text{new})} \leftarrow \mathbf{w} + \eta (t_i - y(\mathbf{x}_i)) \mathbf{x}_i \]  \[ 0 < \eta < 1 \]

learning rate

NB:

\[ (\mathbf{w}^{(\text{new})})^T \mathbf{x}_i = \mathbf{w}^T \mathbf{x}_i + \eta (t_i - y(\mathbf{x}_i)) \| \mathbf{x}_i \|^2 \]
Geometry of Perceptron’s error correction

\[ y(x_i) = g(w^T x_i) \]
\[ w^{\text{(new)}} \leftarrow w + \eta (t_i - y(x_i)) x_i \quad (0 < \eta < 1) \]

<table>
<thead>
<tr>
<th>( t_i - y(x_i) )</th>
<th>( y(x_i) )</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0</td>
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<tr>
<td>1</td>
<td>1</td>
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</table>

\[ w^T x = \| w \| \| x \| \cos \theta \]
Geometry of Perceptron’s error correction (cont.)

\[ y(x_i) = g(w^T x_i) \]
\[ w^{(\text{new})} \leftarrow w + \eta (t_i - y(x_i)) x_i \quad (0 < \eta < 1) \]

<table>
<thead>
<tr>
<th>( t_i - y(x_i) )</th>
<th>( y(x_i) )</th>
</tr>
</thead>
<tbody>
<tr>
<td>( t_i )</td>
<td>( 0 )</td>
</tr>
</tbody>
</table>

\[ w^T x = \|w\| \|x\| \cos \theta \]
Geometry of Perceptron’s error correction (cont.)

\[ y(x_i) = g(w^T x_i) \]

\[ w^{(\text{new})} \leftarrow w + \eta (t_i - y(x_i)) x_i \quad (0 < \eta < 1) \]

\[
\begin{array}{c|cc}
 t_i - y(x_i) & y(x_i) \\
 \hline
 0 & 0 & 1 \\
 1 & 1 & 0
\end{array}
\]

\[ w^T x = \|w\| \|x\| \cos \theta \]
The Perceptron learning algorithm

Incremental (online) Perceptron algorithm:

\[
\text{for } i = 1, \ldots, N \quad \text{\begin{align*}
\mathbf{w} &\leftarrow \mathbf{w} + \eta (t_i - y(x_i)) \mathbf{x}_i \\
\end{align*}}
\]

Batch Perceptron algorithm:

\[
\begin{align*}
\mathbf{v}_{sum} &= 0 \\
\text{for } i = 1, \ldots, N \quad \text{\begin{align*}
\mathbf{v}_{sum} &\leftarrow \mathbf{v}_{sum} + (t_i - y(x_i)) \mathbf{x}_i \\
\mathbf{w} &\leftarrow \mathbf{w} + \eta \mathbf{v}_{sum}
\end{align*}}
\]

What about convergence?

The Perceptron learning algorithm terminates if training samples are \textit{linearly separable}.
Linearly separable vs linearly non-separable

(a-1) Linearly separable

(a-2) Linearly non-separable

(b)
Background of Perceptron

(a) function unit

1940s  Warren McCulloch and Walter Pitts : 'threshold logic'
       Donald Hebb : 'Hebbian learning'
1957  Frank Rosenblatt : 'Perceptron'

Character recognition by Perceptron
Perceptron structures and decision boundaries

\[ y(x) = g(a(x)) = g(w^T x) \]

\[ w = (w_0, w_1, \ldots, w_D)^T \]
\[ x = (1, x_1, \ldots, x_D)^T \]

where \( g(a) = \begin{cases} 1, & \text{if } a \geq 0, \\ 0, & \text{if } a < 0 \end{cases} \)

NB: A one node/neuron constructs a decision boundary, which splits the input space into two regions

\[ x_2 \geq x_1 - 1 \]
\[ a(x) = 1 - x_1 + x_2 = w_0 + w_1 x_1 + w_2 x_2 \]
\[ w_0 = 1, w_1 = -1, w_2 = 1 \]
Perceptron as a logical function

<table>
<thead>
<tr>
<th>NOT</th>
<th>OR</th>
<th>NAND</th>
<th>XOR</th>
</tr>
</thead>
<tbody>
<tr>
<td>$x_1$</td>
<td>$y$</td>
<td>$x_1$</td>
<td>$x_2$</td>
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<tr>
<td>0</td>
<td>1</td>
<td>0</td>
<td>0</td>
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<tr>
<td>1</td>
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<td>0</td>
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Question: find the weights for each function
Perceptron structures and decision boundaries (cont.)

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Perceptron structures and decision boundaries (cont.)

\[ \sum \]

\[
\begin{align*}
\sum \\
\sum \\
\sum
\end{align*}
\]

[Diagram of Perceptron structure with nodes and decision boundaries]
Perceptron structures and decision boundaries (cont.)

![Diagram of Perceptron structures and decision boundaries](image)
Perceptron structures and decision boundaries (cont.)
Problems with the Perceptron learning algorithm

- No training algorithms for multi-layer Perceptron
- Non-convergence for linearly non-separable data
- Weights $\mathbf{w}$ are adjusted for misclassified data only (correctly classified data are not considered at all)

$\Rightarrow$

- Consider not only mis-classification (on train data), but also the optimality of decision boundary
  - Least squares error training
  - Large margin classifiers (e.g. SVM)
Training with least squares

- Squared error function:
  \[ E(w) = \frac{1}{2} \sum_{n=1}^{N} (w^T x_n - t_n)^2 \]

- Optimisation problem:
  \[ \min_{w} E(w) \]

- One way to solve this is to apply gradient descent (steepest descent):
  \[ w \leftarrow w - \eta \nabla_w E(w) \]
  where \( \eta \) : step size (a small positive const.)
  \[ \nabla_w E(w) = \left( \frac{\partial E}{\partial w_0}, \ldots, \frac{\partial E}{\partial w_D} \right)^T \]
Training with least squares (cont.)

\[
\frac{\partial E}{\partial w_i} = \frac{\partial}{\partial w_i} \frac{1}{2} \sum_{n=1}^{N} (w^T x_n - t_n)^2
\]

\[
= \sum_{n=1}^{N} (w^T x_n - t_n) \frac{\partial}{\partial w_i} w^T x_n
\]

\[
= \sum_{n=1}^{N} (w^T x_n - t_n) x_{ni}
\]

- Trainable in linearly non-separable case
- Not robust (sensitive) against erroneous data (outliers) far away from the boundary
- More or less a linear discriminant
Appendix – derivatives

Derivatives of functions of one variable
\[
\frac{df}{dx} = f'(x) = \lim_{\epsilon \to 0} \frac{f(x + \epsilon) - f(x)}{\epsilon}
\]
e.g., \( f(x) = 4x^3 \), \( f'(x) = 12x^2 \)

Partial derivatives of functions of more than one variable
\[
\frac{\partial f}{\partial x} = \lim_{\epsilon \to 0} \frac{f(x + \epsilon, y) - f(x, y)}{\epsilon}
\]
e.g., \( f(x, y) = y^3x^2 \), \( \frac{\partial f}{\partial x} = 2y^3x \)
# Derivative Rules

<table>
<thead>
<tr>
<th>Function</th>
<th>Derivative</th>
</tr>
</thead>
<tbody>
<tr>
<td>Constant</td>
<td>c</td>
</tr>
<tr>
<td>x</td>
<td>1</td>
</tr>
<tr>
<td>Power</td>
<td>( x^n )</td>
</tr>
<tr>
<td>( \frac{1}{x} )</td>
<td>( -\frac{1}{x^2} )</td>
</tr>
<tr>
<td>( \sqrt{x} )</td>
<td>( \frac{1}{2}x^{-\frac{1}{2}} )</td>
</tr>
<tr>
<td>Exponential</td>
<td>( e^x )</td>
</tr>
<tr>
<td>Logarithms</td>
<td>( \ln(x) )</td>
</tr>
<tr>
<td>Sum rule</td>
<td>( f(x) + g(x) )</td>
</tr>
<tr>
<td>Product rule</td>
<td>( f(x)g(x) )</td>
</tr>
<tr>
<td>Reciprocal rule</td>
<td>( \frac{1}{f(x)} )</td>
</tr>
<tr>
<td>( \frac{f(x)}{g(x)} )</td>
<td>( \frac{f'(x)g(x) - f(x)g'(x)}{g^2(x)} )</td>
</tr>
<tr>
<td>Chain rule</td>
<td>( f(g(x)) )</td>
</tr>
<tr>
<td>( z = f(y), y = g(x) )</td>
<td>( \frac{dz}{dx} = \frac{dz}{dy} \frac{dy}{dx} )</td>
</tr>
</tbody>
</table>
Vectors of derivatives

Consider $f(x)$, where $x = (x_1, \ldots, x_D)^T$

**Notation:** all partial derivatives put in a vector:

$$\nabla_x f(x) = \left( \frac{\partial f}{\partial x_1}, \frac{\partial f}{\partial x_2}, \ldots, \frac{\partial f}{\partial x_D} \right)^T$$

**Example:** $f(x) = x_1^3 x_2^2$

$$\nabla_x f(x) = \begin{pmatrix} 3x_1^2 x_2^2 \\ 2x_1^3 x_2 \end{pmatrix}$$

**Fact:** $f(x)$ changes most quickly in direction $\nabla_x f(x)$
Gradient descent (steepest descent)

- First order optimisation algorithm using $\nabla_x f(x)$

- Optimisation problem: $\min_x f(x)$

- Useful when analytic solutions (closed forms) are not available or difficult to find

Algorithm

1. Set an initial value $x_0$ and set $t = 0$
2. If $\|\nabla_x f(x_t)\| \simeq 0$, then stop. Otherwise, do the following.
   3. $x_{t+1} = x_t - \eta \nabla_x f(x_t)$ for $\eta > 0$
   4. $t = t + 1$, and go to step 2.

- Problem: stops at a local minimum (difficult to find a global maximum).
Linear regression (one variable) least squares line fitting

- Training set: \( D = \{(x_n, t_n)\}_{n=1}^{N} \)
- Linear regression: \( \hat{t}_n = ax_n + b \)
- Objective function: \( E = \sum_{n=1}^{N} (t_i - (ax_i + b))^2 \)
- Optimisation problem: \( \min_{a,b} E \)
- Partial derivatives:

\[
\frac{\partial E}{\partial a} = 2 \sum_{n=1}^{N} ((t_i - (ax_i + b)) (-x_i)) \\
= 2a \sum_{n=1}^{N} x_i^2 + 2b \sum_{n=1}^{N} x_i - 2 \sum_{n=1}^{N} t_ix_i
\]

\[
\frac{\partial E}{\partial b} = -2 \sum_{n=1}^{N} ((t_i - (ax_i + b)) \\
= 2a \sum_{n=1}^{N} x_i + 2b \sum_{n=1}^{N} 1 - 2 \sum_{n=1}^{N} t_i
\]
Letting $\frac{\partial E}{\partial a} = 0$ and $\frac{\partial E}{\partial b} = 0$

\[
\begin{pmatrix}
\sum_{n=1}^{N} x_i^2 & \sum_{n=1}^{N} x_i \\
\sum_{n=1}^{N} x_i & \sum_{n=1}^{N} 1
\end{pmatrix}
\begin{pmatrix}
a \\
b
\end{pmatrix}
= 
\begin{pmatrix}
\sum_{n=1}^{N} t_i x_i \\
\sum_{n=1}^{N} t_i
\end{pmatrix}
\]
Training set:
\[ \mathcal{D} = \{(x_n, t_n)\}_{n=1}^N \], where
\[ x_n = (1, x_1, \ldots, x_D)^T \]
Linear regression:
\[ \hat{t}_n = w^T x_n \]
Objective function:
\[ E = \sum_{n=1}^N (t_n - w^T x_n)^2 \]
Optimisation problem:
\[ \min_{a,b} E \]
Linear regression (multiple variables) \((cont.)\)

- \(E = \sum_{n=1}^{N} (t_n - \mathbf{w}^T \mathbf{x}_n)^2\)

- Partial derivatives: \(\frac{\partial E}{\partial w_i} = -2 \sum_{n=1}^{N} (t_n - \mathbf{w}^T \mathbf{x}_n) x_{ni}\)

- Vector/matrix representation \((NE)\):

\[
X = \begin{bmatrix}
\mathbf{x}_1^T \\
\vdots \\
\mathbf{x}_N^T
\end{bmatrix} = \begin{bmatrix}
x_{10}, \ldots, x_{1d} \\
\vdots \\
x_{N0}, \ldots, x_{Nd}
\end{bmatrix}, \quad T = \begin{bmatrix}
t_1 \\
\vdots \\
t_N
\end{bmatrix}
\]

\(E = (T - X \mathbf{w})^T (T - X \mathbf{w})\)

\(\frac{\partial E}{\partial \mathbf{w}} = -2X^T (T - X \mathbf{w})\)

Letting \(\frac{\partial E}{\partial \mathbf{w}} = 0\) \(\Rightarrow X^T (T - X \mathbf{w}) = 0\)

\(X^T X \mathbf{W} = X^T T\)

\(\mathbf{W} = (X^T X)^{-1} X^T T\) \hspace{1cm} \cdots \text{analytic solution if the inverse exists}\)
Training discriminant functions directly (discriminative training)

Perceptron training algorithm
- Perceptron error correction algorithm
- Least squares error + gradient descent algorithm

Linearly separable vs linearly non-separable

Perceptron structures and decision boundaries

See Notes 11 for a Perceptron with multiple output nodes