

Inf2b - Learning

Lecture 9: Classification with Gaussians

Hiroshi Shimodaira

(Credit: Iain Murray and Steve Renals)

Centre for Speech Technology Research (CSTR)
School of Informatics
University of Edinburgh

<http://www.inf.ed.ac.uk/teaching/courses/inf2b/>
<https://piazza.com/ed.ac.uk/spring2020/infr08028>

Office hours: Wednesdays at 14:00-15:00 in IF-3.04

Jan-Mar 2020

Today's Schedule

Classification with Gaussians

- 1 The multidimensional Gaussian distribution (recap.)
- 2 Practical topics on covariance matrix
- 3 Bayes theorem and probability densities
- 4 1-dimensional Gaussian classifier
- 5 Multivariate Gaussian classifier
- 6 Evaluation of classifier performance

The multidimensional Gaussian distribution

- The D -dimensional vector $\mathbf{x} = (x_1, \dots, x_D)^T$ is multivariate Gaussian if it has a probability density function of the following form:

$$p(\mathbf{x} | \boldsymbol{\mu}, \boldsymbol{\Sigma}) = \frac{1}{(2\pi)^{D/2} |\boldsymbol{\Sigma}|^{1/2}} \exp \left(-\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu}) \right).$$

The pdf is parameterised by the mean vector $\boldsymbol{\mu}$ and the covariance matrix $\boldsymbol{\Sigma}$.

- The 1-dimensional Gaussian is a special case of this pdf
- The argument to the exponential $\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu})$ is referred to as a *quadratic form*, and it is always *non-negative*.

Covariance matrix

Covariance matrix (with ML estimation):

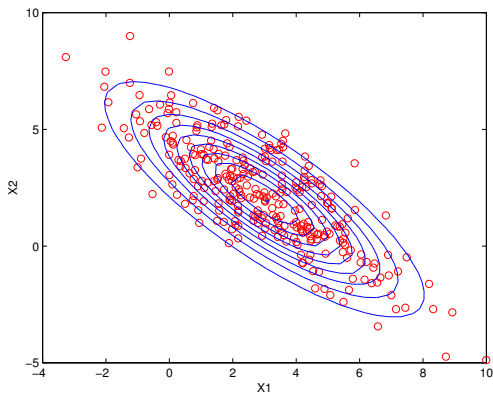
$$\Sigma = \begin{pmatrix} \sigma_{11} & \cdots & \sigma_{1D} \\ \vdots & \ddots & \vdots \\ \sigma_{D1} & \cdots & \sigma_{DD} \end{pmatrix} = \frac{1}{N} \sum_{n=1}^N (\mathbf{x}_n - \boldsymbol{\mu})(\mathbf{x}_n - \boldsymbol{\mu})^T$$

where $\mathbf{x}_n = (x_{n1}, \dots, x_{nD})^T$

$\boldsymbol{\mu} = (\mu_1, \dots, \mu_D)^T$

- Symmetric : $\Sigma^T = \Sigma$, and $(\Sigma^{-1})^T = \Sigma^{-1}$
- Semi-positive definite: $\mathbf{x}^T \Sigma \mathbf{x} \geq 0$, and $\mathbf{x}^T \Sigma^{-1} \mathbf{x} \geq 0$
- cf: sample covariance matrix, which uses $\frac{1}{N-1}$.

Maximum likelihood fit to a Gaussian



Tips on calculating covariance matrices

MATLAB is optimised for matrix/vector operations

$$\begin{aligned}\Sigma_{(D \times D)} &= \frac{1}{N} \sum_{n=1}^N (\mathbf{x}_n - \boldsymbol{\mu})_{(D \times 1)} (\mathbf{x}_n - \boldsymbol{\mu})_{(1 \times D)}^T \\ &= \frac{1}{N} (\mathbf{x}_1 - \boldsymbol{\mu}, \dots, \mathbf{x}_N - \boldsymbol{\mu})_{(D \times N)} \begin{pmatrix} \mathbf{x}_1^T - \boldsymbol{\mu}^T \\ \vdots \\ \mathbf{x}_N^T - \boldsymbol{\mu}^T \end{pmatrix}_{(N \times D)} \\ &= \frac{1}{N} (\mathbf{X} - \mathbf{M}_N)_{(D \times N)}^T (\mathbf{X} - \mathbf{M}_N)_{(N \times D)}\end{aligned}$$

$$\mathbf{X}_{(N \times D)} = \begin{bmatrix} \mathbf{x}_1^T \\ \vdots \\ \mathbf{x}_N^T \end{bmatrix} = \begin{bmatrix} x_{11}, \dots, x_{1D} \\ \vdots \\ x_{N1}, \dots, x_{ND} \end{bmatrix}, \quad \mathbf{M}_N_{(N \times D)} = \begin{bmatrix} \boldsymbol{\mu} \\ \vdots \\ \boldsymbol{\mu} \end{bmatrix} = \begin{bmatrix} \mu_1, \dots, \mu_D \\ \vdots \\ \mu_1, \dots, \mu_D \end{bmatrix}$$

$$\mathbf{M}_{(1 \times D)} = \boldsymbol{\mu}^T = [\mu_1, \dots, \mu_D], \quad = \frac{1}{N} \mathbf{1}_{NN} \mathbf{X}$$

Properties of covariance matrix

$$\begin{aligned}\Sigma &= V D V^T \\ &= \begin{pmatrix} v_{11} & \cdots & v_{1D} \\ \vdots & \ddots & \vdots \\ v_{D1} & \cdots & v_{DD} \end{pmatrix} \begin{pmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_D \end{pmatrix} \begin{pmatrix} v_{11} & \cdots & v_{1D} \\ \vdots & \ddots & \vdots \\ v_{D1} & \cdots & v_{DD} \end{pmatrix}^T \\ &= (\mathbf{v}_1, \dots, \mathbf{v}_D) \text{Diag}(\lambda_1, \dots, \lambda_D) (\mathbf{v}_1, \dots, \mathbf{v}_D)^T\end{aligned}$$

- \mathbf{v}_i : eigen vector, λ_i : eigen value

$$\Sigma \mathbf{v}_i = \lambda_i \mathbf{v}_i$$

- $\lambda_i \geq 0$, $\|\mathbf{v}_i\| = 1$
- $|\Sigma| = \prod_{i=1}^D \lambda_i$
- $\sum_{i=1}^D \sigma_{ii} = \sum_{i=1}^D \lambda_i$

Properties of covariance matrix

- $\text{rank}(\Sigma)$
 - the number of linearly independent columns (or rows)
 - the number of bases (i.e. the dimension of the column space)

$$\text{rank}(\Sigma) = D \rightarrow \forall_i : \lambda_i > 0$$

$$\forall_{i \neq j} : \mathbf{v}_i \perp \mathbf{v}_j$$

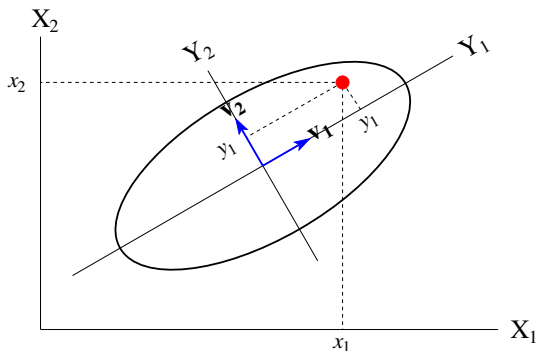
$$|\Sigma| > 0$$

$$\text{rank}(\Sigma) < D \rightarrow \exists_i : \lambda_i = 0$$

$$\exists_{(i,j)} : \rho(x_i, x_j) = 1$$

$$|\Sigma| = 0$$

Geometry of covariance matrix



Sort eigen values: $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_D$

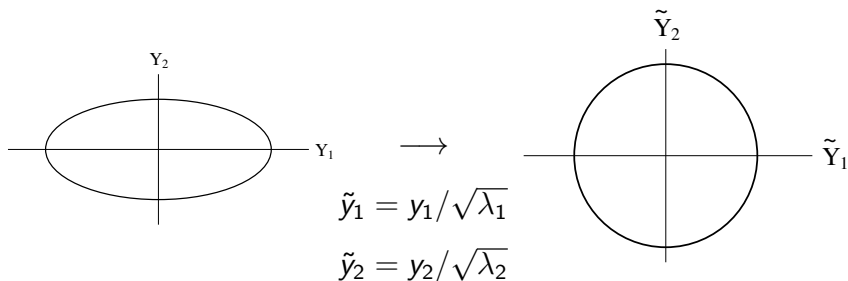
\mathbf{v}_1 : eigen vector of λ_1

\mathbf{v}_2 : eigen vector of λ_2

$$y_1 = \mathbf{v}_1^T \mathbf{x}, \quad \text{Var}(y_1) = \lambda_1$$

$$y_2 = \mathbf{v}_2^T \mathbf{x}, \quad \text{Var}(y_2) = \lambda_2$$

Geometry of covariance matrix



$$(\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu}) = (\tilde{\mathbf{y}} - \tilde{\mathbf{u}})^T (\tilde{\mathbf{y}} - \tilde{\mathbf{u}}) = \|\tilde{\mathbf{y}} - \tilde{\mathbf{u}}\|^2 \quad (\dagger)$$

$$\begin{aligned} \text{where } \tilde{\mathbf{u}} &= \left(\frac{\mathbf{v}_1}{\sqrt{\lambda_1}}, \frac{\mathbf{v}_2}{\sqrt{\lambda_2}} \right)^T \boldsymbol{\mu} \\ &= \left(\frac{\mathbf{v}_1^T \boldsymbol{\mu}}{\sqrt{\lambda_1}}, \frac{\mathbf{v}_2^T \boldsymbol{\mu}}{\sqrt{\lambda_2}} \right)^T \end{aligned}$$

Problems with the estimation of covariance matrix

- $|\Sigma| \rightarrow 0$ when
 - N is not large enough (when compared with D)
NB: $|\Sigma| = 0$ for $N \leq D$
 - There is high dependence (correlation) among variables (e.g. $\rho(x_i, x_j) \approx 1$)
- Σ^{-1} becomes unstable when $|\Sigma|$ is small.
- Solutions?
 - Share Σ among classes (\Rightarrow linear discriminant functions)
 - Assume independence among variables \Rightarrow a diagonal covariance matrix rather than a 'full' covariance matrix.
 - Reduce the dimensionality by transforming the data into a low-dimensional vector space (e.g. PCA).
 - Another regularisation:
 - Add a small positive number to the diagonal elements
$$\Sigma \leftarrow \Sigma + \epsilon I$$

Shared covariance matrix among classes

- How to estimate the shared covariance:

$$\Sigma_k = \Sigma \text{ for all } k = 1, \dots, K$$

$$\begin{aligned}\Sigma &= \frac{1}{K} \sum_{k=1}^K \Sigma_k \\ &= \frac{1}{K} \sum_{k=1}^K \frac{1}{N_k} \sum_{n=1}^{N_k} (\mathbf{x}_n^{(k)} - \boldsymbol{\mu}^{(k)})(\mathbf{x}_n^{(k)} - \boldsymbol{\mu}^{(k)})^T\end{aligned}$$

- Why is the following not good?

$$\begin{aligned}\Sigma &= \frac{1}{N} \sum_{n=1}^N (\mathbf{x}_n - \boldsymbol{\mu})(\mathbf{x}_n - \boldsymbol{\mu})^T \\ &= \frac{1}{K} \sum_{k=1}^K \frac{1}{N_k} \sum_{n=1}^N (\mathbf{x}_n^{(k)} - \boldsymbol{\mu})(\mathbf{x}_n^{(k)} - \boldsymbol{\mu})^T\end{aligned}$$

Covariance matrix when naive Bayes is assumed

$$\Sigma = \begin{pmatrix} \sigma_{11} & & 0 \\ & \ddots & \\ 0 & & \sigma_{DD} \end{pmatrix}, \quad \sigma_{ij} = 0 \text{ for } i \neq j$$

$$\begin{aligned} p(\mathbf{x} | \boldsymbol{\mu}, \Sigma) &= \frac{1}{(2\pi)^{D/2} |\Sigma|^{1/2}} \exp\left(-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^T \Sigma^{-1}(\mathbf{x} - \boldsymbol{\mu})\right) \\ &= p(x_1 | \mu_1, \sigma_{11}) \cdots p(x_D | \mu_D, \sigma_{DD}) \\ &= \prod_{i=1}^D \left\{ \frac{1}{\sqrt{2\pi\sigma_{ii}}} \exp\left(\frac{-(x_i - \mu_i)^2}{2\sigma_{ii}}\right) \right\} \end{aligned}$$

Bayes theorem and probability densities

- Rules for probability densities are similar to those for probabilities:

$$p(x, y) = p(x|y) p(y)$$

$$p(x) = \int p(x, y) dy$$

- We may mix probabilities of discrete variables and probability densities of continuous variables:

$$p(x, Z) = p(x|Z) P(Z)$$

- Bayes' theorem for continuous data x and class C :

$$P(C|x) = \frac{p(x|C) P(C)}{p(x)}$$

$$P(C|x) \propto p(x|C) P(C)$$

Bayes theorem and univariate Gaussians

- If $p(x|C)$ is Gaussian with mean μ and variance σ^2 :

$$\begin{aligned}P(C|x) &\propto p(x|C) P(C) = N(x; \mu, \sigma^2) P(C) \\ &\propto \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(\frac{-(x - \mu)^2}{2\sigma^2}\right) P(C)\end{aligned}$$

- The log likelihood $LL(x|C)$ is:

$$\begin{aligned}LL(x|\mu, \sigma^2) &= \ln p(x|\mu, \sigma^2) \\ &= \frac{1}{2} \left(-\ln(2\pi) - \ln \sigma^2 - \frac{(x - \mu)^2}{\sigma^2} \right)\end{aligned}$$

- The log posterior probability $\ln P(C|x)$ is:

$$\begin{aligned}\ln P(C|x) &\propto LL(x|C) + \ln P(C) \\ &\propto \frac{1}{2} \left(-\ln(2\pi) - \ln \sigma^2 - \frac{(x - \mu)^2}{\sigma^2} \right) + \ln P(C)\end{aligned}$$

Log probability ratio (log odds)

For a classification problem of two classes: C_1 and C_2 ,

$$\begin{aligned}\ln \frac{P(C_1|x)}{P(C_2|x)} &= \ln P(C_1|x) - \ln P(C_2|x) \\ &= -\frac{1}{2} \left(\frac{(x - \mu_1)^2}{\sigma_1^2} - \frac{(x - \mu_2)^2}{\sigma_2^2} + \ln \sigma_1^2 - \ln \sigma_2^2 \right) \\ &\quad + \ln P(C_1) - \ln P(C_2)\end{aligned}$$

$$\ln P(C_1|x) - \ln P(C_2|x) > 0 \Rightarrow C_1$$

$$\ln P(C_1|x) - \ln P(C_2|x) < 0 \Rightarrow C_2$$

Example: 1-dimensional Gaussian classifier

- Two classes, S and T , with some observations:

Class S		10	8	10	10	11	11
Class T		12	9	15	10	13	13

- Assume that each class may be modelled by a Gaussian. The estimated mean and variance of each pdf with the maximum likelihood (ML) estimation are given as follows:

$$\begin{aligned}\mu(S) &= 10 & \sigma^2(S) &= 1 \\ \mu(T) &= 12 & \sigma^2(T) &= 4\end{aligned}$$

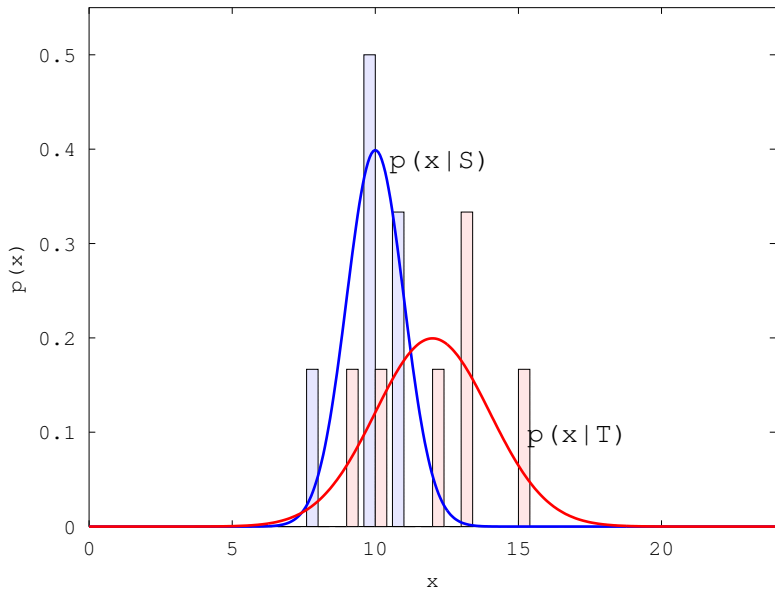
- The following unlabelled data points are available:

$$x_1 = 10, \quad x_2 = 11, \quad x_3 = 6$$

To which class should each of the data points be assigned?

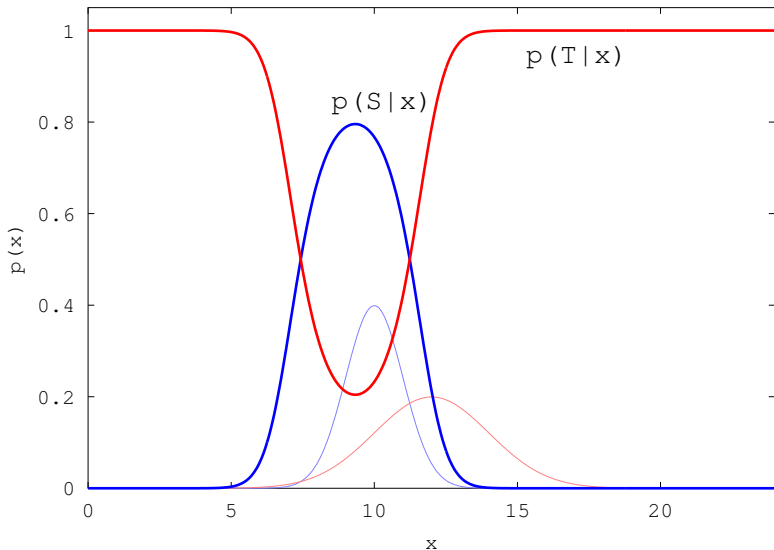
Assume the two classes have equal prior probabilities.

Gaussian pdfs for S and T vs histograms



Posterior probabilities

$$P(S) = 0.5, \quad P(T) = 0.5$$



Example: 1-dimensional Gaussian classifier (cont.)

- Take the log odds (posterior probability ratios):

$$\ln \frac{P(S|X=x)}{P(T|X=x)} = -\frac{1}{2} \left(\frac{(x - \mu_S)^2}{\sigma_S^2} - \frac{(x - \mu_T)^2}{\sigma_T^2} + \ln \sigma_S^2 - \ln \sigma_T^2 \right) + \ln P(S) - \ln P(T)$$

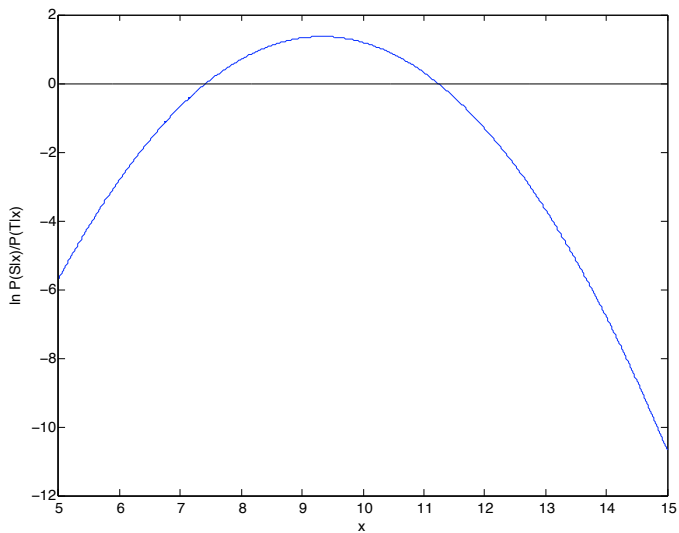
- In the example the priors are equal, so:

$$\begin{aligned} \ln \frac{P(S|X=x)}{P(T|X=x)} &= -\frac{1}{2} \left(\frac{(x - \mu_S)^2}{\sigma_S^2} - \frac{(x - \mu_T)^2}{\sigma_T^2} + \ln \sigma_S^2 - \ln \sigma_T^2 \right) \\ &= -\frac{1}{2} \left((x - 10)^2 - \frac{(x - 12)^2}{4} - \ln 4 \right) \end{aligned}$$

- If log odds are less than 0 assign to T , otherwise assign to S .

Log odds

Test samples: $x_1 = 10$, $x_2 = 11$, $x_3 = 6$



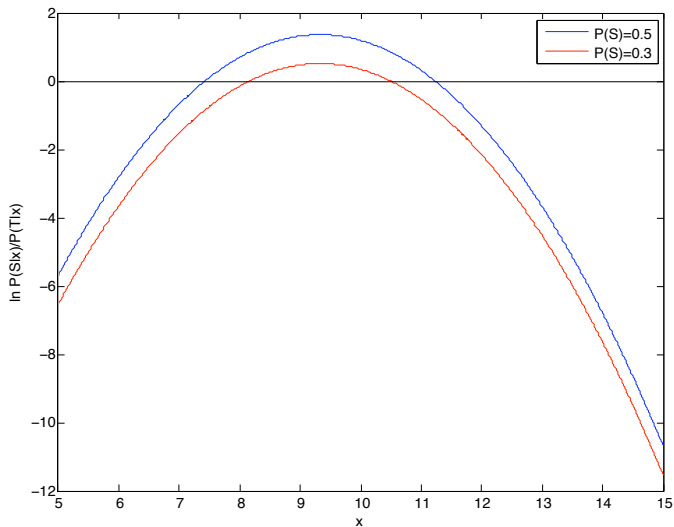
Example: unequal priors

- Now, assume $P(S) = 0.3$, $P(T) = 0.7$. Including this prior information, to which class should each of the above test data points, x_1, x_2, x_3 , be assigned?
- Again compute the log odds:

$$\begin{aligned}\ln \frac{P(S|X=x)}{P(T|X=x)} &= -\frac{1}{2} \left(\frac{(x - \mu_S)^2}{\sigma_S^2} - \frac{(x - \mu_T)^2}{\sigma_T^2} + \ln \sigma_S^2 - \ln \sigma_T^2 \right) \\ &\quad + \ln P(S) - \ln P(T) \\ &= -\frac{1}{2} \left((x - 10)^2 - \frac{(x - 12)^2}{4} - \ln 4 \right) + \ln P(S) - \ln P(T) \\ &= -\frac{1}{2} \left((x - 10)^2 - \frac{(x - 12)^2}{4} - \ln 4 \right) + \ln(3/7)\end{aligned}$$

Log odds

Test samples: $x_1 = 10$, $x_2 = 11$, $x_3 = 6$



Multivariate Gaussian classifier

- Multivariate Gaussian (in D dimensions):

$$p(\mathbf{x} | \boldsymbol{\mu}, \boldsymbol{\Sigma}) = \frac{1}{(2\pi)^{D/2} |\boldsymbol{\Sigma}|^{1/2}} \exp \left(-\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu}) \right)$$

- Log likelihood:

$$LL(\mathbf{x} | \boldsymbol{\mu}, \boldsymbol{\Sigma}) = -\frac{D}{2} \ln(2\pi) - \frac{1}{2} \ln |\boldsymbol{\Sigma}| - \frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu})$$

- Posterior probability: $p(C | \mathbf{x}) \propto p(\mathbf{x} | \boldsymbol{\mu}, \boldsymbol{\Sigma}) P(C)$

- Log posterior probability:

$$\ln P(C | \mathbf{x}) \propto -\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu}) - \frac{1}{2} \ln |\boldsymbol{\Sigma}| + \ln P(C) + \text{const.}$$

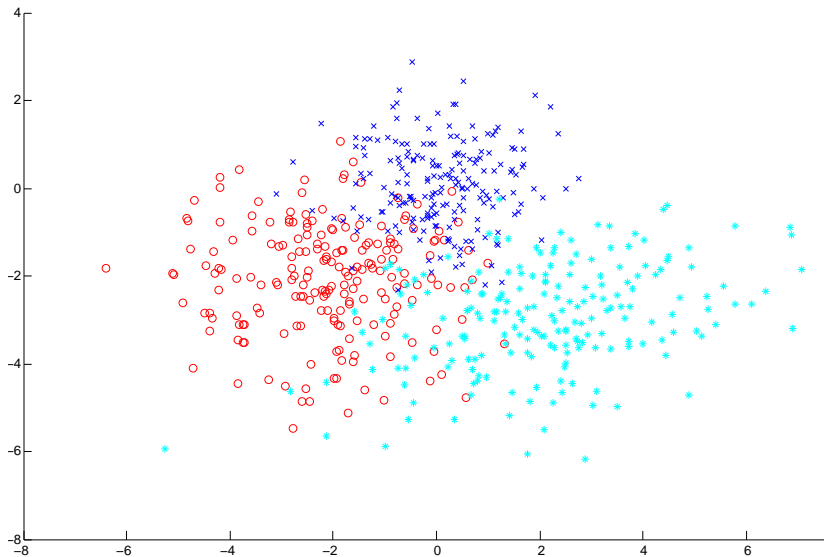
- Try Q4 of Tutorial 4

Example

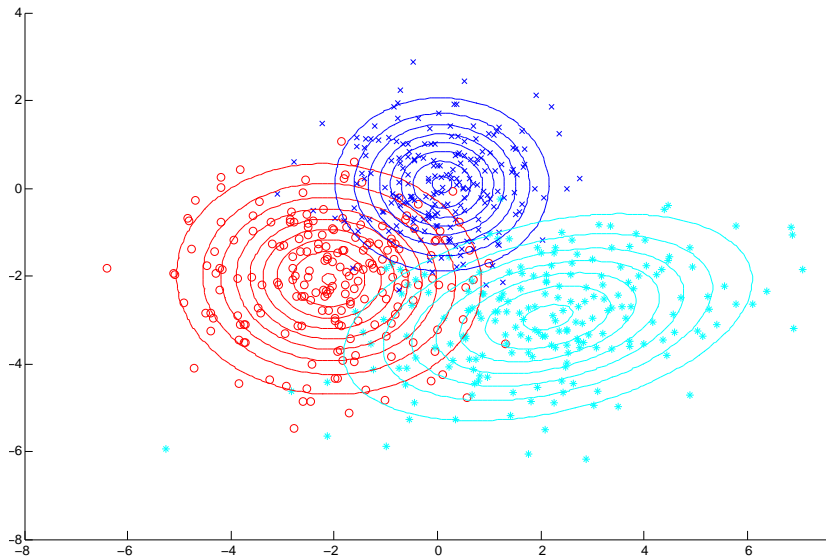
- 2-dimensional data from three classes (A, B, C).
- The classes have equal prior probabilities.
- 200 points in each class
- Load into Matlab ($n \times 2$ matrices, each row is a data point) and display using a scatter plot:

```
xa = load('trainA.dat');  
xb = load('trainB.dat');  
xc = load('trainC.dat');  
hold on;  
scatter(xa(:, 1), xa(:,2), 'r', 'o');  
scatter(xb(:, 1), xb(:,2), 'b', 'x');  
scatter(xc(:, 1), xc(:,2), 'c', '*');
```

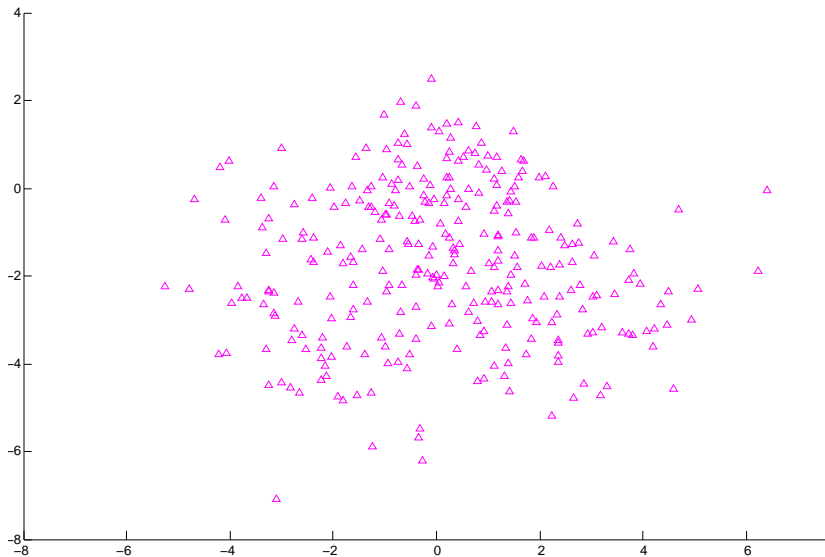
Training data



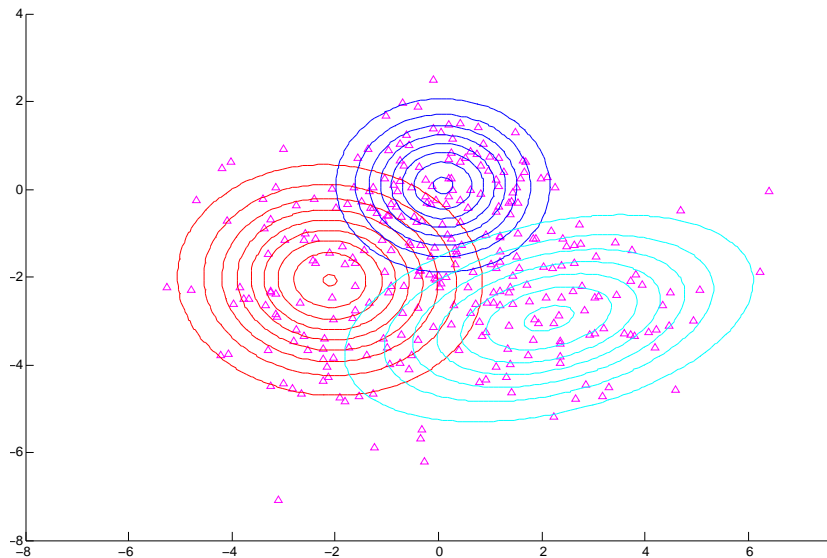
Gaussians estimated from training data



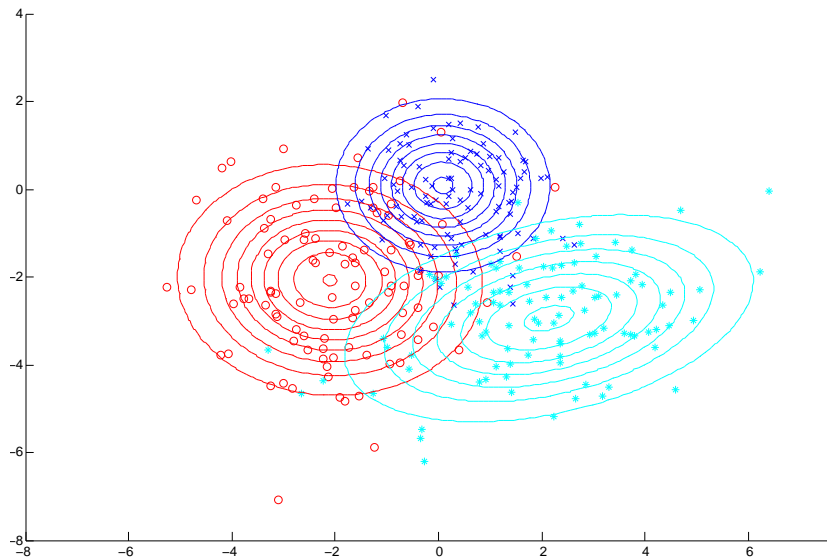
Testing data



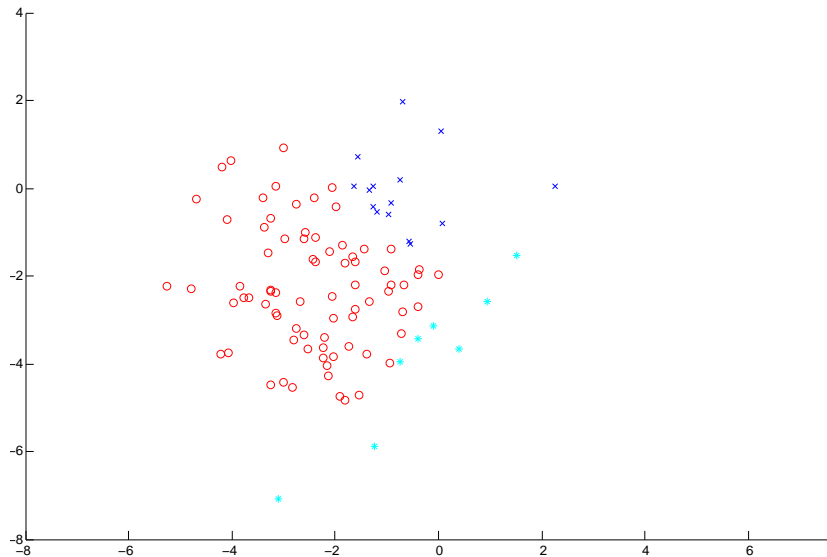
Testing data — with estimated class distributions



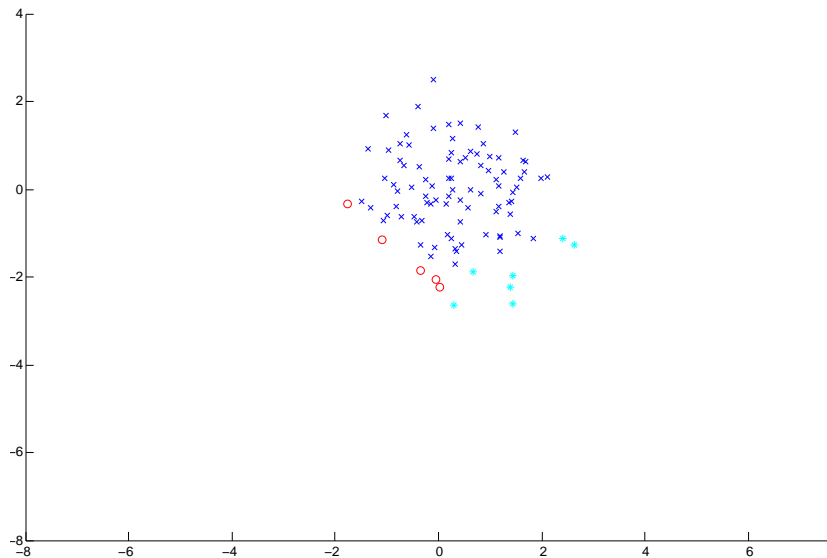
Testing data — with true class indicated



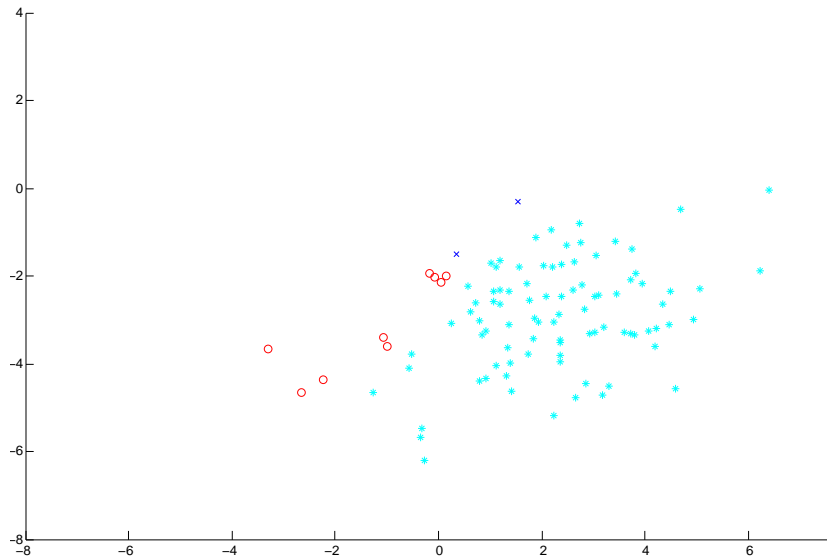
Classifying test data from class A



Classifying test data from class B



Classifying test data from class C



Result

- Analyse the result by percent correct, and in more detail with a **confusion matrix**
 - Columns of a confusion matrix correspond to the predicted classes (classifier outputs)
 - Rows correspond to the actual (true) class labels
 - Element (r, c) is the number of patterns from true class r that were classified as class c
 - Total number of correctly classified patterns is obtained by summing the numbers on the leading diagonal
- Confusion matrix in this case

Test Data		Predicted class		
		A	B	C
Actual class	A	77	15	8
	B	5	88	7
	C	9	2	89

- Overall proportion of test patterns correctly classified is $(77 + 88 + 89)/300 = 254/300 = 0.85$

Performance measures

- Accuracy (correct classification rate) = $1 - \text{error rate}$
- Confusion matrix
- Precision, Recall
- F-measure (F1 score)

$$F_1 = 2 \frac{\text{Precision} \times \text{Recall}}{\text{Precision} + \text{Recall}}$$

- Receiver operating characteristic (ROC)

NB: measures shown in grey are non-examinable

Example: Classifying spoken vowels

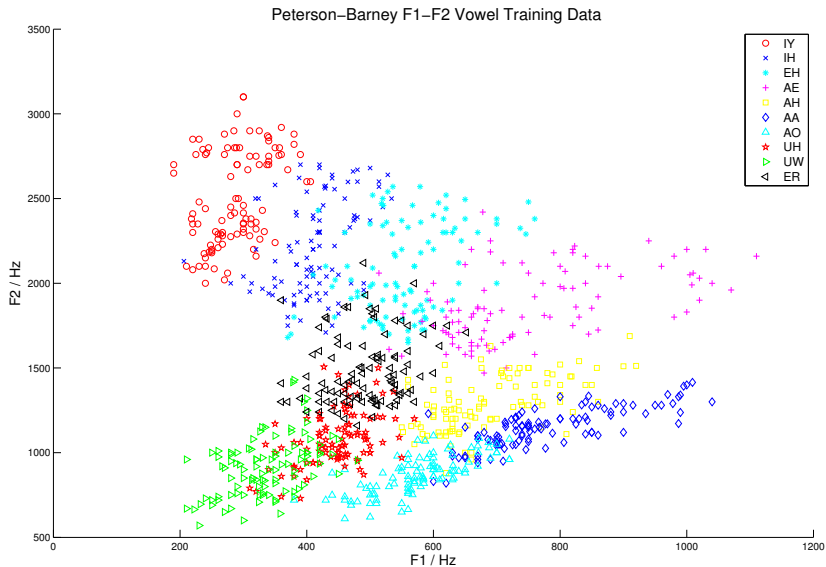
- 10 Spoken vowels in American English
- Vowels can be characterised by formant frequencies — resonances of vocal tract
 - there are usually three or four identifiable formants
 - first two formants written as F1 and F2
- Peterson-Barney data — recordings of spoken vowels by American men, women, and children
 - two examples of each vowel per person
 - for this example, data split into training and test sets
 - children's data not used in this example
 - different speakers in training and test sets
- (see <http://en.wikipedia.org/wiki/Vowel> for more)
- Classify the data using a Gaussian classifier
- Assume equal priors

The data

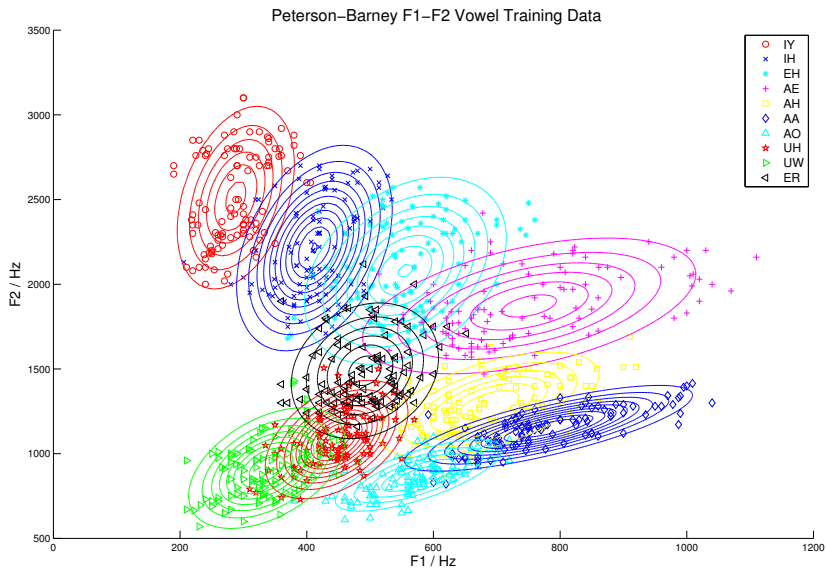
Ten steady-state vowels, frequencies of F1 and F2 at their centre:

- IY — “bee”
- IH — “big”
- EH — “red”
- AE — “at”
- AH — “honey”
- AA — “heart”
- AO — “frost”
- UH — “could”
- UW — “you”
- ER — “bird”

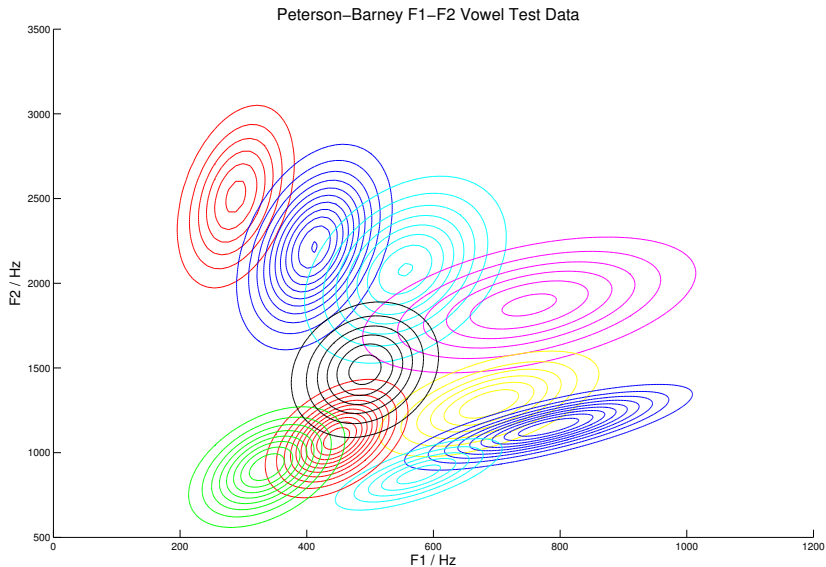
Vowel data — 10 classes



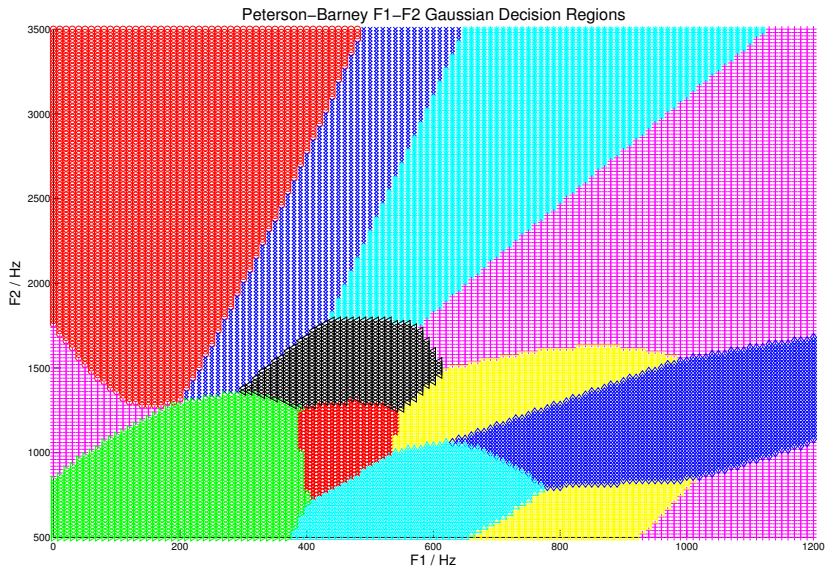
Data and Gaussians for each class



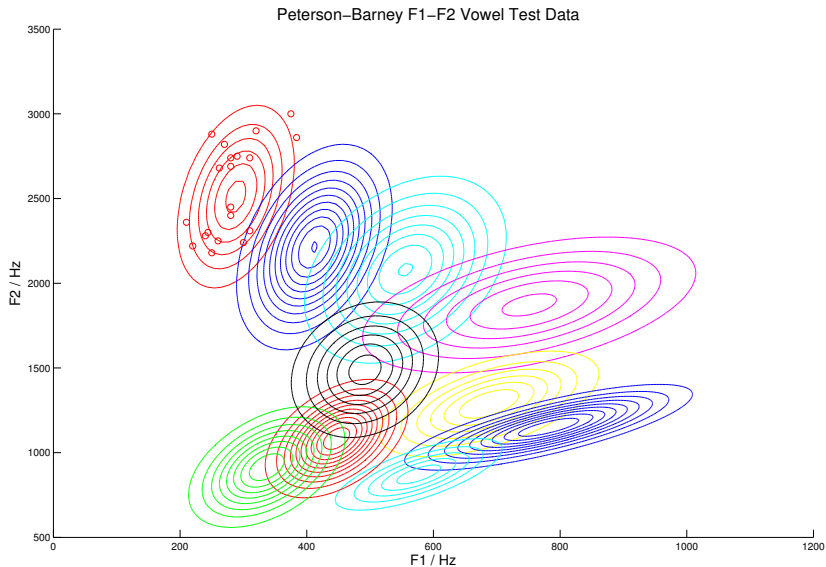
Gaussians for each class



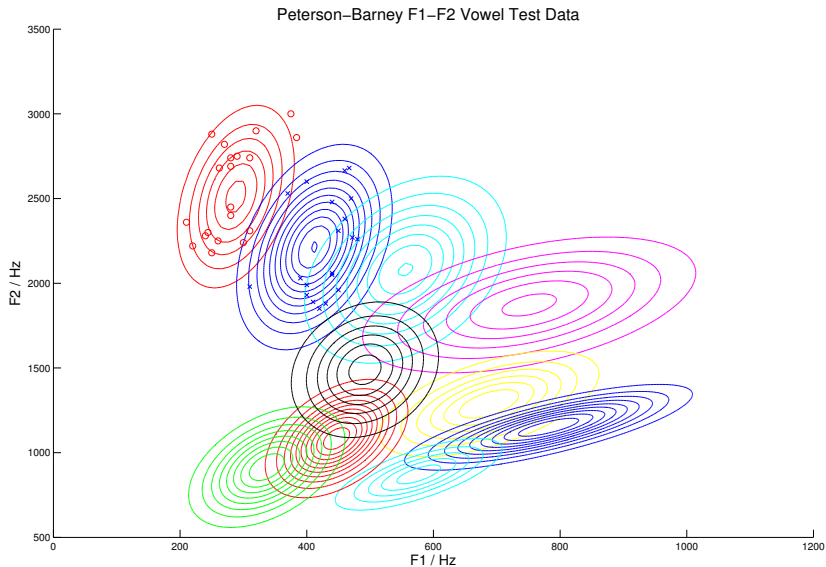
Decision Regions



Test data for class 1 (IY)



Test data for class 2 (IY)



Confusion matrix

	Predicted class										
	IY	IH	EH	AE	AH	AA	AO	UH	UW	ER	% corr.
IY	20	0	0	0	0	0	0	0	0	0	100
IH	0	20	0	0	0	0	0	0	0	0	100
EH	0	0	15	1	0	0	0	0	0	4	75
AE	0	0	3	16	1	0	0	0	0	0	80
AH	0	0	0	0	18	2	0	0	0	0	90
AA	0	0	0	0	2	17	1	0	0	0	85
AO	0	0	0	0	0	4	16	0	0	0	80
UH	0	0	0	0	2	0	0	18	0	0	90
UW	0	0	0	0	0	0	0	5	15	0	75
ER	0	0	0	0	0	0	0	2	0	18	90

Total: 86.5% correct

Exercise

- 1 Consider estimating a covariance matrix Σ from a data set. Discuss what we could say about the data for the following situations:
 - Σ is almost diagonal (i.e. $\sigma_{ij} \approx 0$ for $i \neq j$).
 - $|\Sigma| \approx 0$.
- 2 Give examples of data for each situation above.
- 3 Discuss the minimum number of training samples required to have a covariance matrix that is invertible, i.e. $|\Sigma| \neq 0$. (Hint: think $D = 1$ first, and $D = 2$, and so on.)

Summary

- Covariance matrix
- Using Bayes' theorem with pdfs
- Log probability ratio (log odds)
- The Gaussian classifier: 1-dimensional and multi-dimensional
- Classification examples
- Evaluation measures. Confusion matrix

Familiarise yourself with vector/matrix operations, using pens and papers! (as well as computers)