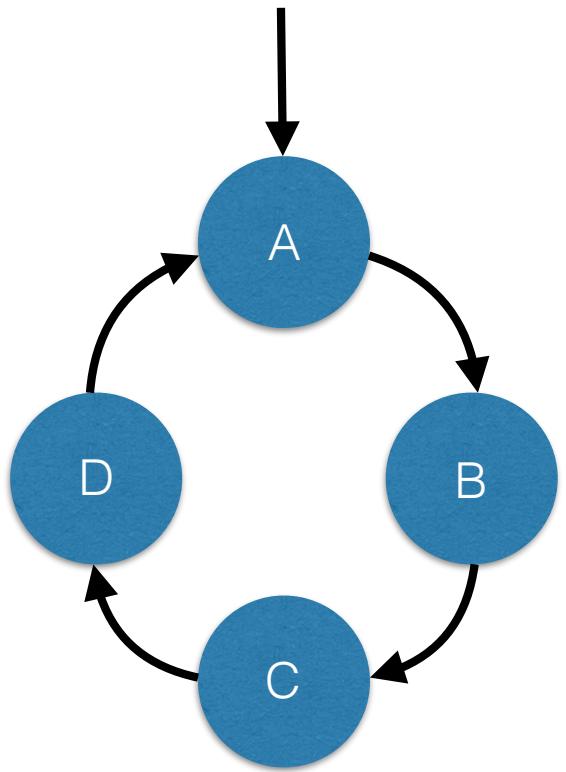


# Finite-State Machines (Automata) lecture 12



- a simple form of computation
- used widely
- one way to find patterns



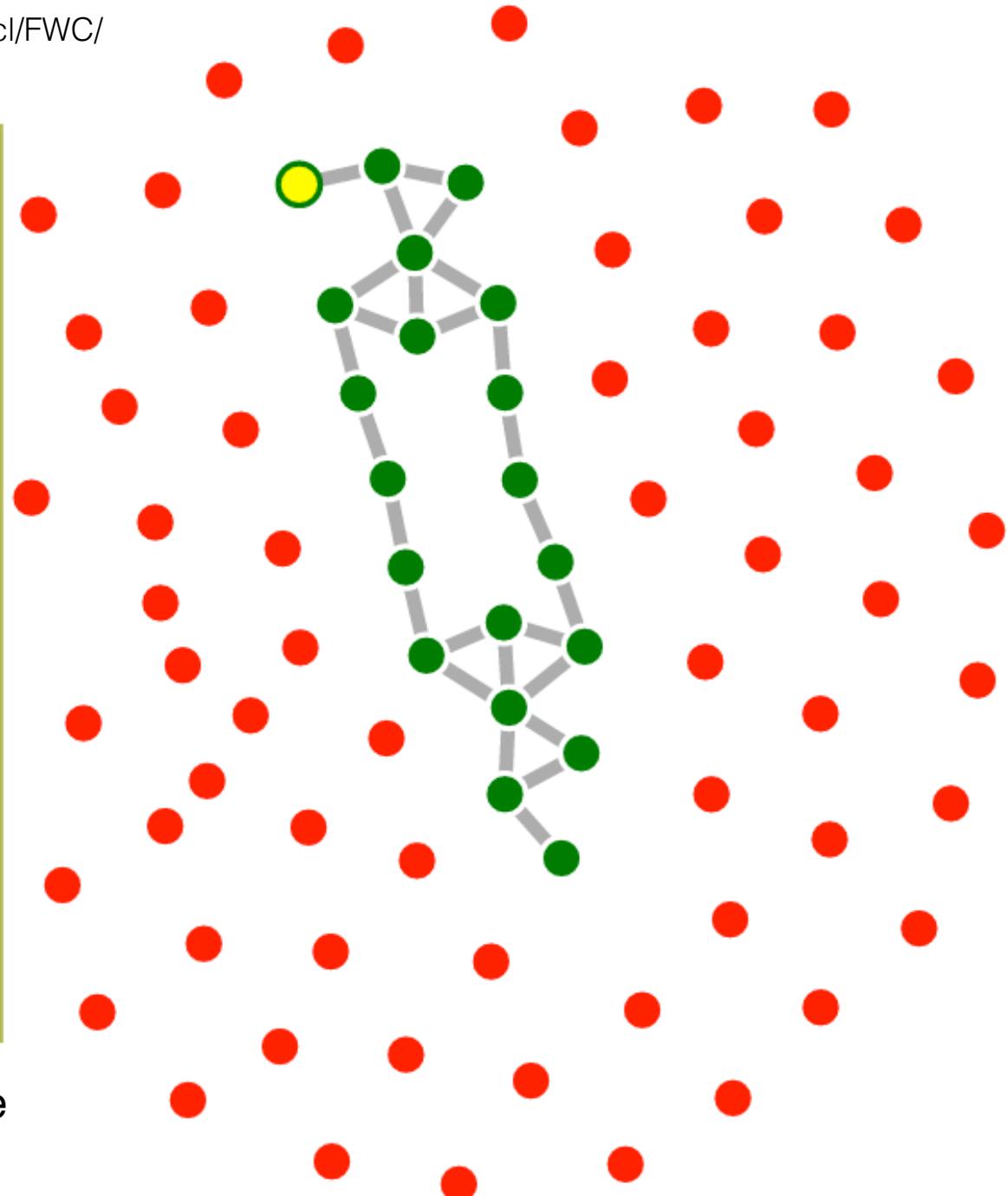
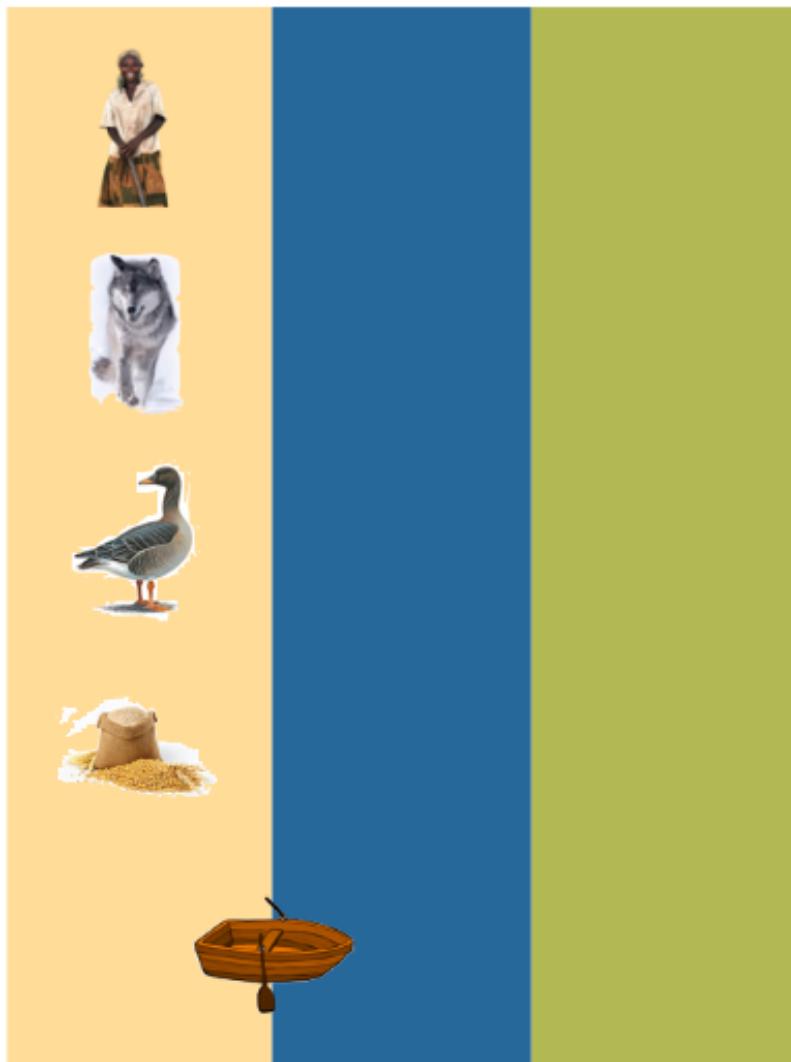
current

---

A B C D

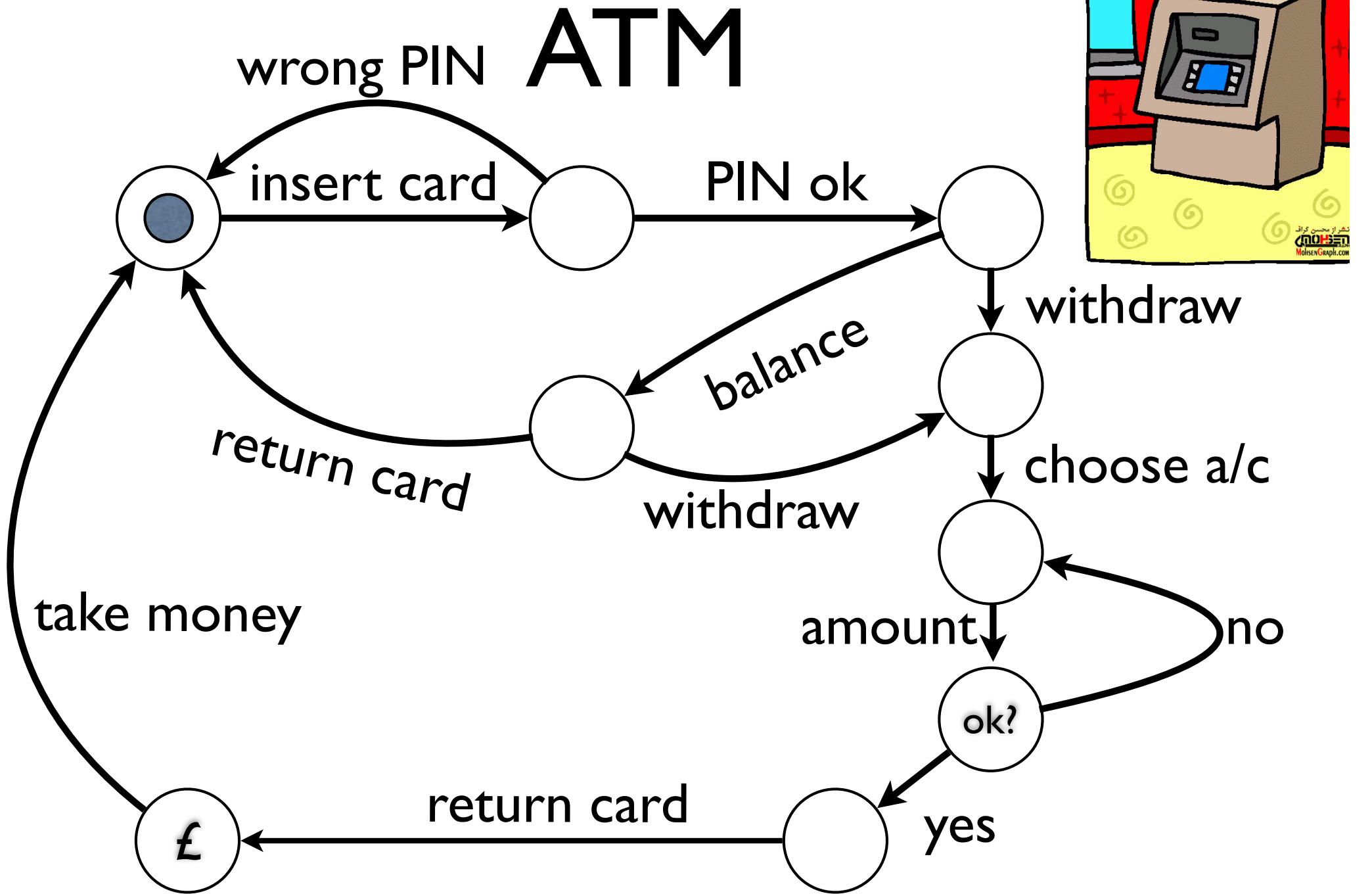
B C D A

next



How can we use logic to specify the transitions?

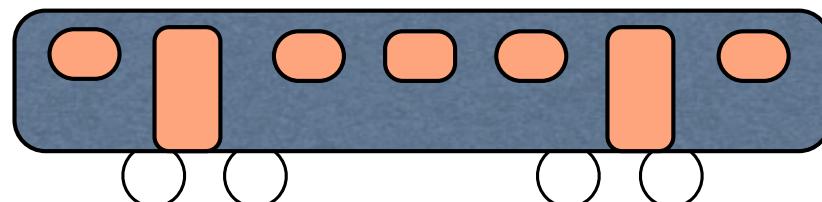
This is a **non-deterministic** system. We define a next state **relation**.





# Counting trains

A

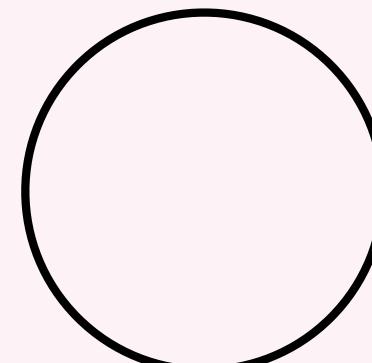


B

axle sensor (detects passing wheels)

from-a-to-b :  $a \downarrow ; b \downarrow ; a \uparrow ; b \uparrow$

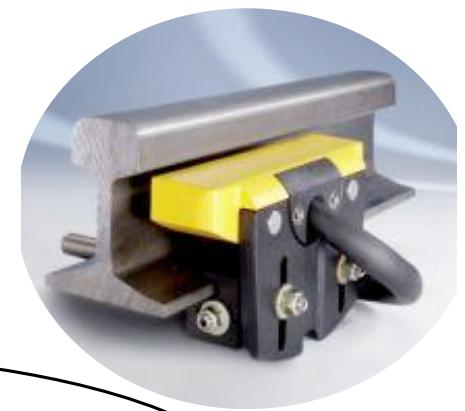
from-b-to-a :  $b \downarrow ; a \downarrow ; b \uparrow ; a \uparrow$



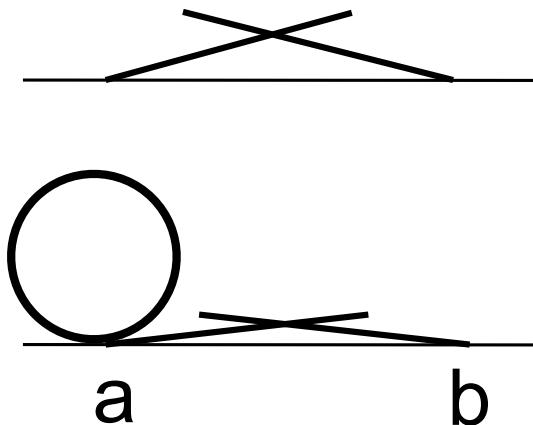
a

b

# Finite-state machines



axle sensor

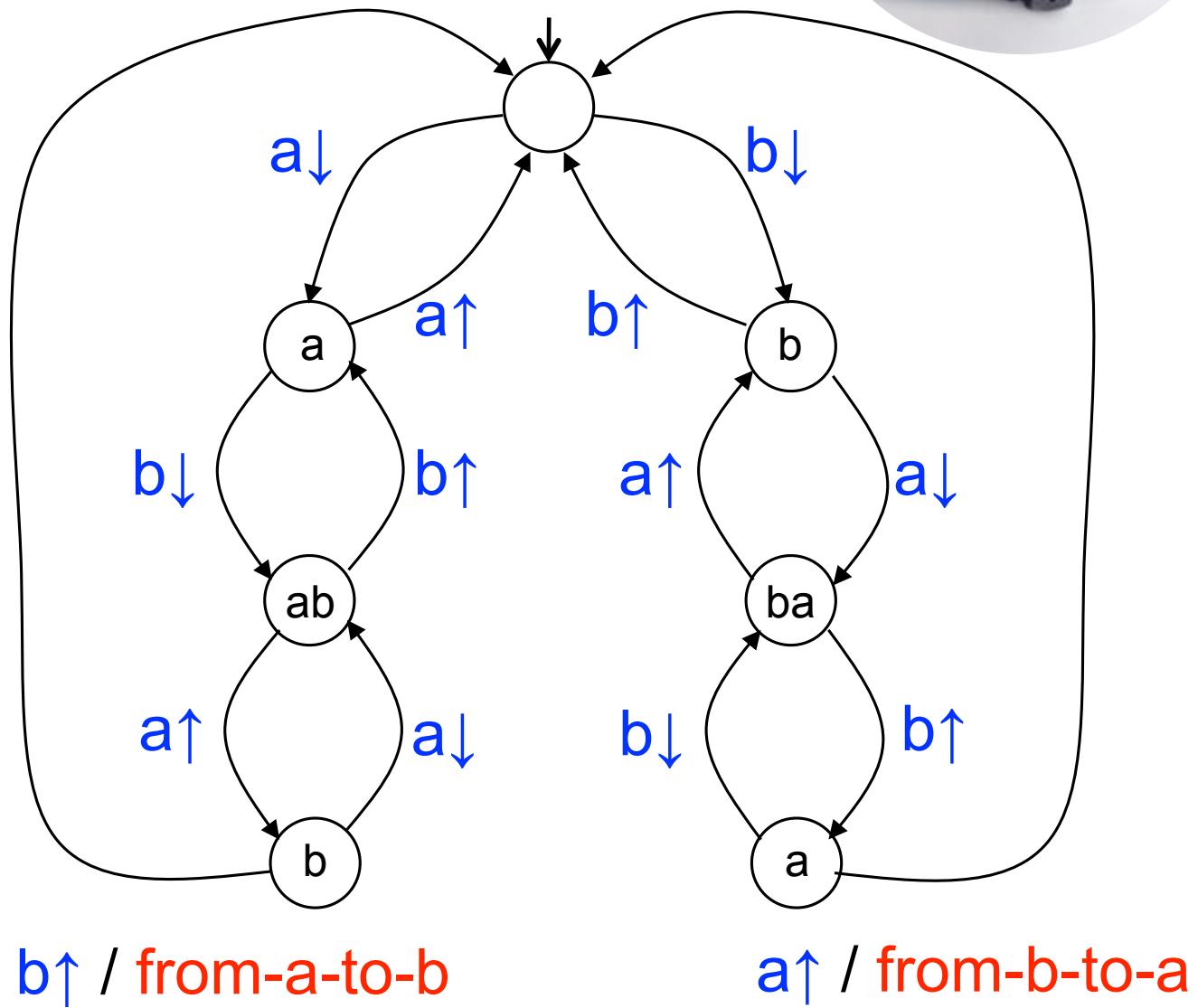


inputs :

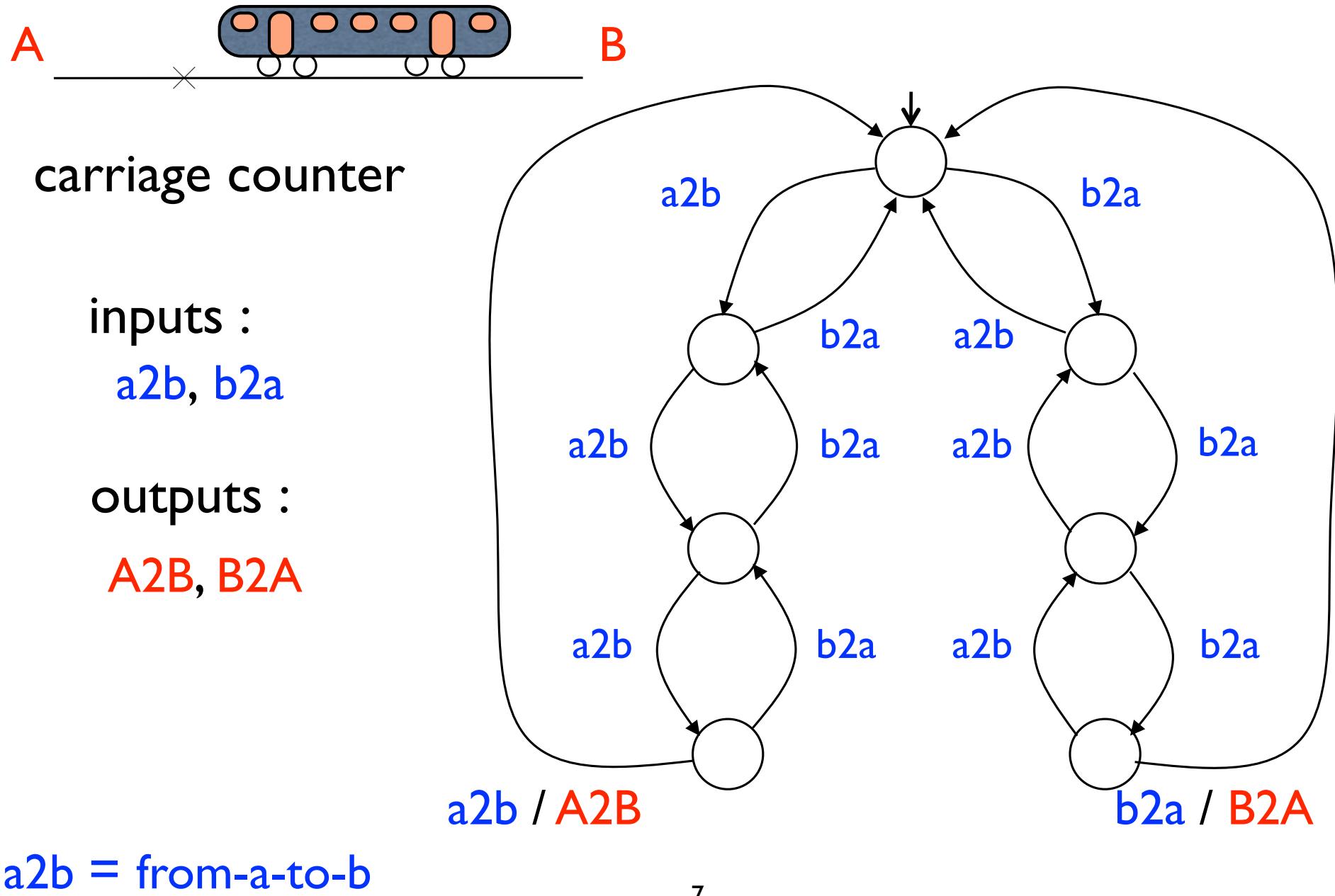
$a\uparrow, a\downarrow, b\uparrow, b\downarrow$

outputs :

from-a-to-b,  
from-b-to-a



# Hierarchical FSMs



# Application Fields



## Industry

- real-time control, vending machines, cash dispensers, etc.

## Electronic circuits

- data path / control path
- memory / cache handling
- protocols, USB, etc.



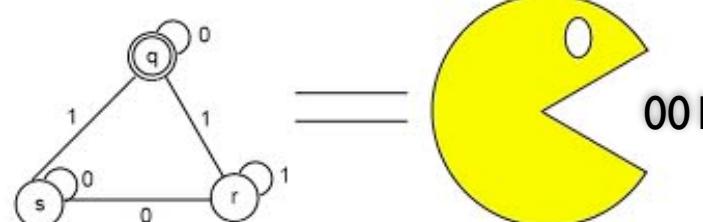
## Communication protocols

- initiation and maintenance of communication links
- error detection and handling, packet retransmission



## Language analysis

- natural languages
- programming languages
- search engines



# A Decimal Number

