INFI-CG 2016 Lecture 21	
Vision: computational	
aspects	
Richard Shillcock	
1 /30	
Today's goals	
To explore some of the computational aspects of mapping from the visual world to the brain.	

Today's readings
Hirsch, H.V., & Spinelli, D. N. (1971). Modification of the distribution of receptive field orientation in cats by selective visual exposure during development. <i>Experimental Brain Research</i> , <i>12</i> (5), 509-527.
Hubel, D. H., & Wiesel, T. N. (1963). Receptive fields of cells in striate cortex of very young, visually inexperienced kittens. <i>Journal of Neurophysiology</i> , 26(6), 994-1002.

3 /20



Magno- a	and parvocellular pathways
	layers 1 and 2 - magnocellular layers 3-6 - parvocellular layers 2, 3 and 5 - ipsilateral eye layers 1, 4 and 6 - contralateral eye
lateral geniculate nucleus (LGN)	5 /30





Topographic mapping

Stained VI in the mouse, showing the areas that were activated by the visual stimulus. (Note also the cortical magnification of the fovea.)

Systematicity: Penfield's homunculus



Visual topographic mapping



The higher visual areas become increasingly attuned to bigger receptive fields, with bilateral inputs (see, e.g., Tootell et al., 1998), and less clear retinotopic mapping.

Does the brain ever throw away information?



Systematicity

8 /30

Systematicity is pervasive in the brain, most clearly nearer the sensorium. It is a way of importing relationships and larger-scale representation into the brain "for free".



Ecological realism vs abstract stimuli	· · · · · · · · · · · · · · · · · · ·
Pond-like backgrounds versus white backgrounds (Lettvin, Maturana, McCulloch, and Pitts).	
There's never a "null" context.	
The risk of researching a technique; the assumptions become incorporated into the science in an invisible way.	
11/30	





detector".	
Each is interested in an aspect of the environr	nent.
Contrast detectors (light/dark in a small area).	
Convexity detectors (small, dark and moving).	
Changing contrast detectors (moving edges).	
Dimming detectors (dimming from edge or cen	tre of
the visual field)	
Dark detectors (overall light intensity)	
	14/30

	The frog's visual world	
Moving	B M	
Stationary	C	
	15/30	

Convexity detection	
$\left(\frac{1}{2} \right)$	
16/30	

The frog's visual world

Perception, 1981, volume 10, pages 421-422

The frog ganglion cell: not a feature detector and not a monkey cortical cell

Donald C Hood

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There are two fundamental misconceptions about frog ganglion cells that have been perpetuated in most recent textbooks. A large number of texts written for courses on perception, S and P, and physiological psychology use the forg gangion cell as an example, par excellence, of a feature detector. Many go further and compare the processing doen in the forg retrains with that carried out in the cat and monky cortex. The truth is, the properties of the frog's ganglion cells have *neure* fitted the generally accepted definitions of a feature detector, Further interposetties have recently been shown to be similar to those of other vertebrate ganglion cells. As generally used the term frequency detector is call that its most sensitive

Looking further into amphibian vision

"Together, our results indicate that the salamander retina uses a population code in which every point in visual space is represented by multiple neurons with subtly different visual sensitivities" Segev et al. (2006).

We see a history of progress through reinterpretation. New analyses subsume earlier ones and introduce new concepts.

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Vision	25	obi	lect	recos	Inition
	au				5



features. 19/30



The task becomes one of looking for objects.



Recognition as parsing	
Is something like syntax going on? – Combining invariances in a rule-governed way.	
22/30	

				Marr's	s a	approach
ls it corr from the	ect re'	to try and ?	1"s	start simple	e a	nd work up
		Viewer centred			715	Object centred
Input Image		Primal Sketch		2 1/2-D Sketch		3-D Model Representation
Perceived intensities	-	Zero crossings, blobs,edges, bars, ends, virtual lines, groups, curves boundaries.		Local surface orientation and discontinuities in depth and in surface orientation	->	3-D models hierarchically organised in terms of surface and volumetric primitives
		<u> </u>	,		,	23/30





Edges versus surfaces Biederman & Ju (1988)	
Naming and verification tasks showed no difference between photographs and cartoons. 25/30	
The importance of edges Hochberg & Brooks (1962)	
A 19-month old boy had previously only learned to name toys and other objects.	
He was given line drawings of known objects.	
There was no evidence of learning being required.	
26/30	

Is simplicity really the answer?



Complexity an	nd situatedness
movement parallax	
binocularity	
	0
light source	28/30

Challenges

Understand the relationship between objects, activity and whole scenes.

Decide how much we wish to base artificial systems on human cognition.

Appreciate the relationship between "clever" syntax-like solutions and "dumb" brute-force solutions.

(Never be satisfied with one-or-the-other binary choices.)

29/30

References

Marr, D. (1982). Vision. Freeman and Company. New York.

Biederman, I. (1987). Recognition-by-components: a theory of human image understanding. Psychological Review, 94(2), 115-147.

Biederman, I., & Ju, G. (1988). Surface versus edge-based determinants of visual recognition. Cognitive Psychology, 20(1), 38-64.

Hochberg, J., & Brooks, V. (1962). Pictorial recognition as an unlearned ability: A study of one child's performance. the american *Journal of Psychology*, 75(4), 624-628.

Lowe, D. G. (1987). Three-dimensional object recognition from single twodimensional images. Artificial Intelligence, 31 (3), 355-395.

Segev, R., Puchalla, J., & Berry, M. J. (2006). Functional organization of ganglion cells in the salamander retina. *Journal of Neurophysiology*, 95(4), 2277-2292.

Lettvin, J.Y., Maturana, H. R., McCulloch, W. S., & Pitts, W. H. (1959). What the frog's eye tells the frog's brain. Proceedings of the IRE, 47(11), 1940-1951.