

Interaction Design Case Study - 2

Tweeting Bottles and other stories

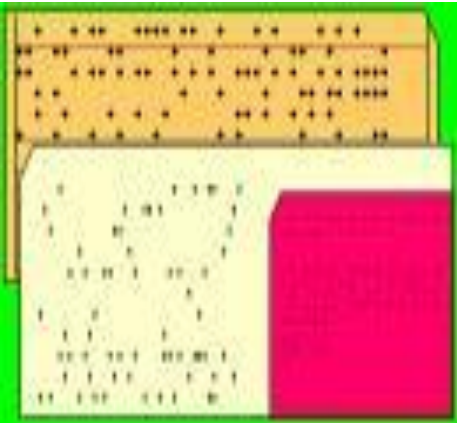
Literal and Stylised Representations

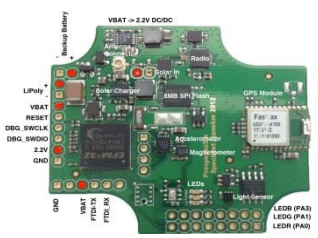
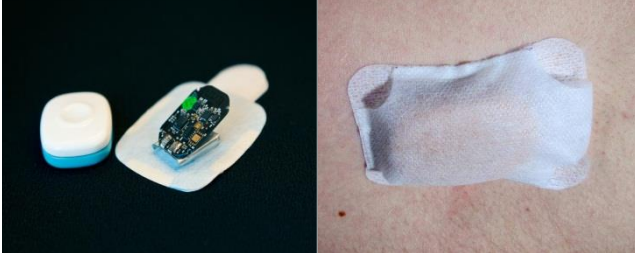
- Focal and Peripheral attention
- Detailed and Abstracted representations
- Intended audience: technical / non-technical

Outcomes of Case Study - 2

- Primary site of interaction: Virtual or Physical world
- Nature of Interaction: explicit or oblivious to the user
- Personal v/s Social v/s Public

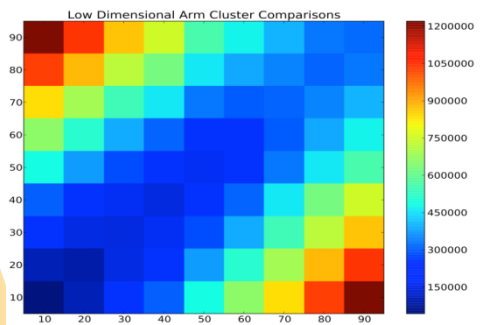
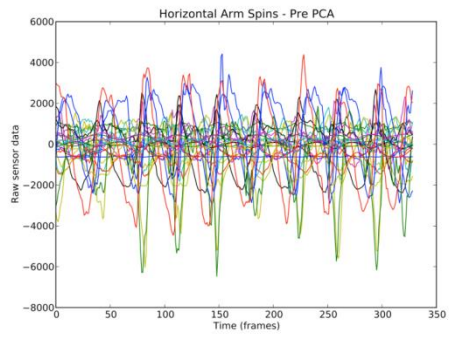
I/O devices



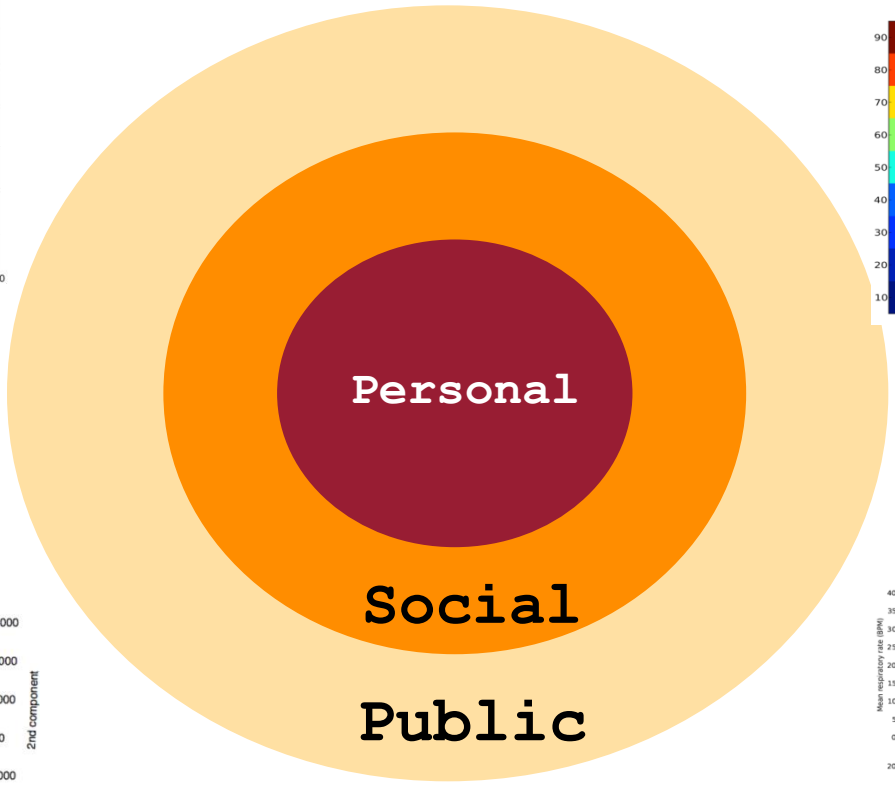


Integration of Computation, Communication and Control to provide time-bounded decisions and actions

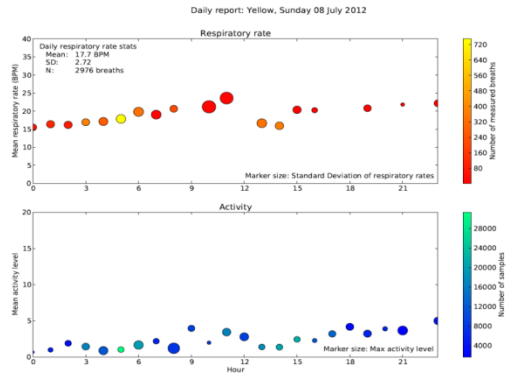
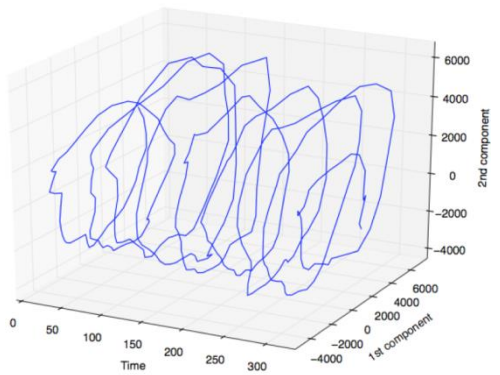
Sense – Learn -- Act



Computation



“Intelligence”



Communication

Speckled Computing



Tweeting Bottles

- Category : Consumer
- Requirements: Recognise predefined actions such as pouring, squeezing and shaking when using consumer products
- Users: Consumer behaviour analysts; Enhance user experience
- Sensors: 3-D Accelerometer
- Actuators: None
- Data Analysis: Clustering techniques to identify pouring, shaking and squeezing.
- Wireless protocol: 2.4GHz Bluetooth 4.0 radio

Sensing Daily Rituals

How do consumers use FMCG products?

Current methods

- Interviews
- Diaries
- Questionnaires

Advantages

- Low-tech

Disadvantages

- Error-prone, Inaccurate, Intrusive, Overhead, Unreliable (noisy data)
- Time-consuming - what's in it for the consumer?





Tweeting bottles

Sensors recognise usage of FMCG products

No change in consumer behaviour

- Customer oblivious to data collection
- Data transmitted automatically to server

Data Analytics extracts actionable information

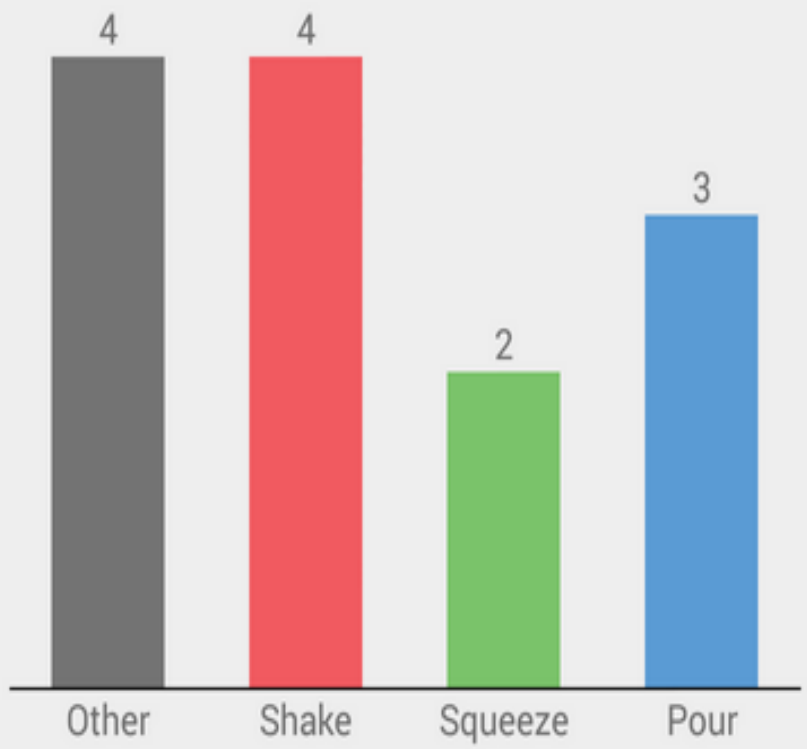
- Times and Frequency of usage
- Usage patterns (diurnal, monthly, annual)

Make informed Business and Design decisions

CONNECTED
NanoSpeck2
CF:04:D4:B5:93:8F

Daily Rituals 1

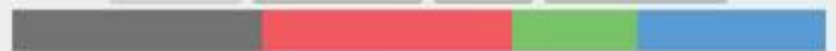
No. Events:13



Daily Rituals

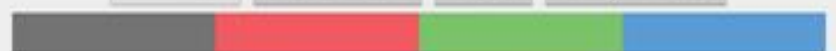
Device 1 CONNECTED 2015 08 31 11:56:30

Connect Disconnect Reset Daily Rituals



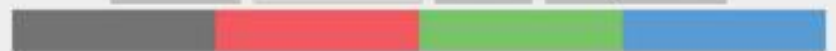
Device 2 CONNECTED 2015 08 31 11:56:30

Connect Disconnect Reset Daily Rituals



Device 3 DISCONNECTED

Connect Disconnect Reset Daily Rituals



Events

- Pouring
- Squeezing
- Shaking

Phone App

- Recognises events
- Timestamp
- Transmits to server

Back Graph

CONNECTED
NanoSpeck2
CF:04:D4:B5:93:8F

Event No: 1 Action Type: Other
2015 08 27 15:01:45

Event No: 2 Action Type: Pour
2015 08 27 15:01:57

Event No: 3 Action Type: Shake
2015 08 27 15:36:17

Event No: 4 Action Type: Shake
2015 08 27 16:18:48

Event No: 5 Action Type: Other
2015 08 27 17:32:21

Event No: 6 Action Type: Other
2015 08 27 17:34:17

Event No: 7 Action Type: Squeeze
2015 08 31 10:36:07

Event No: 8 Action Type: Pour
2015 08 31 10:36:24

Event No: 9 Action Type: Shake
2015 08 31 10:36:35

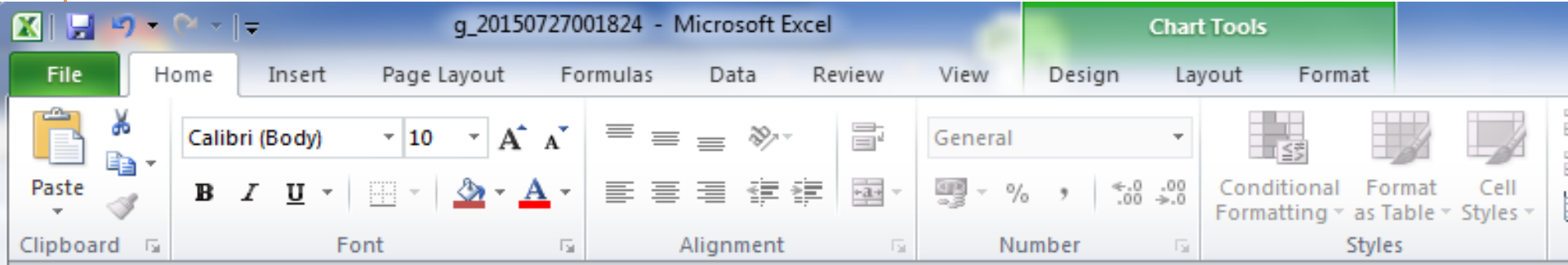
Event No: 10 Action Type: Pour
2015 08 31 10:39:47

Event No: 11 Action Type: Other
2015 08 31 11:41:43

Event No: 12 Action Type: Shake
2015 08 31 11:43:28

Event No: 13 Action Type: Squeeze
2015 08 31 11:49:27

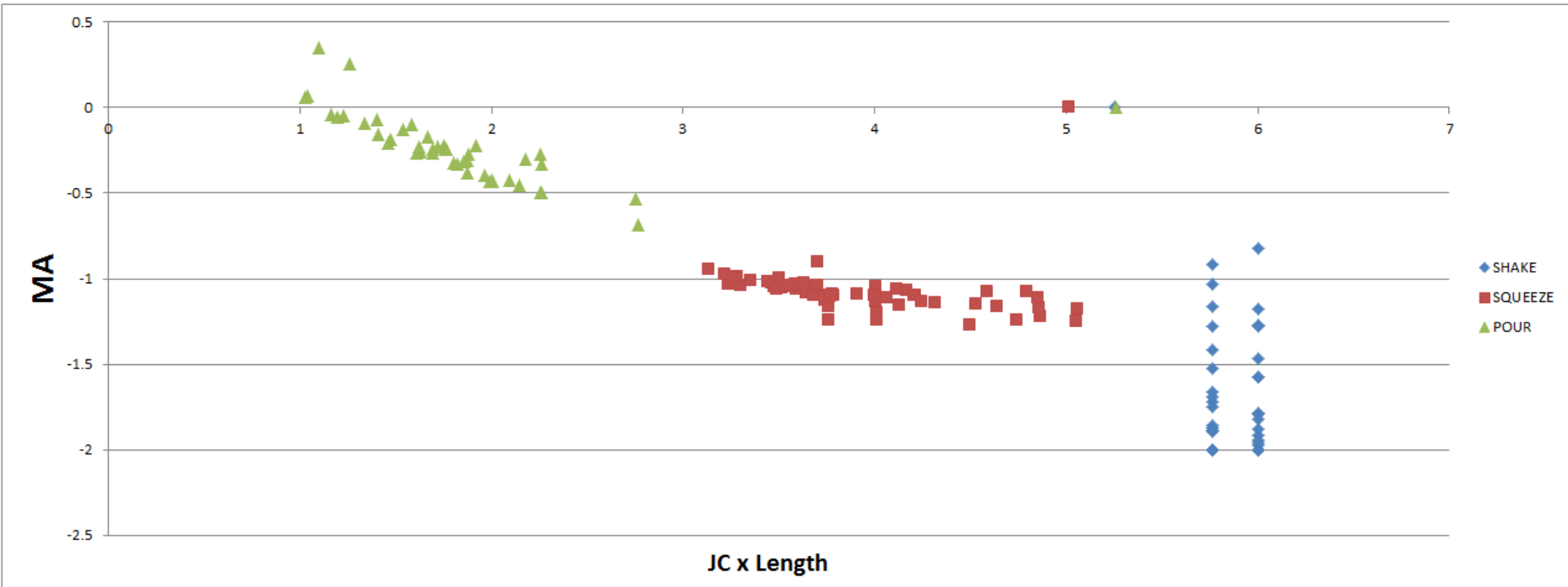




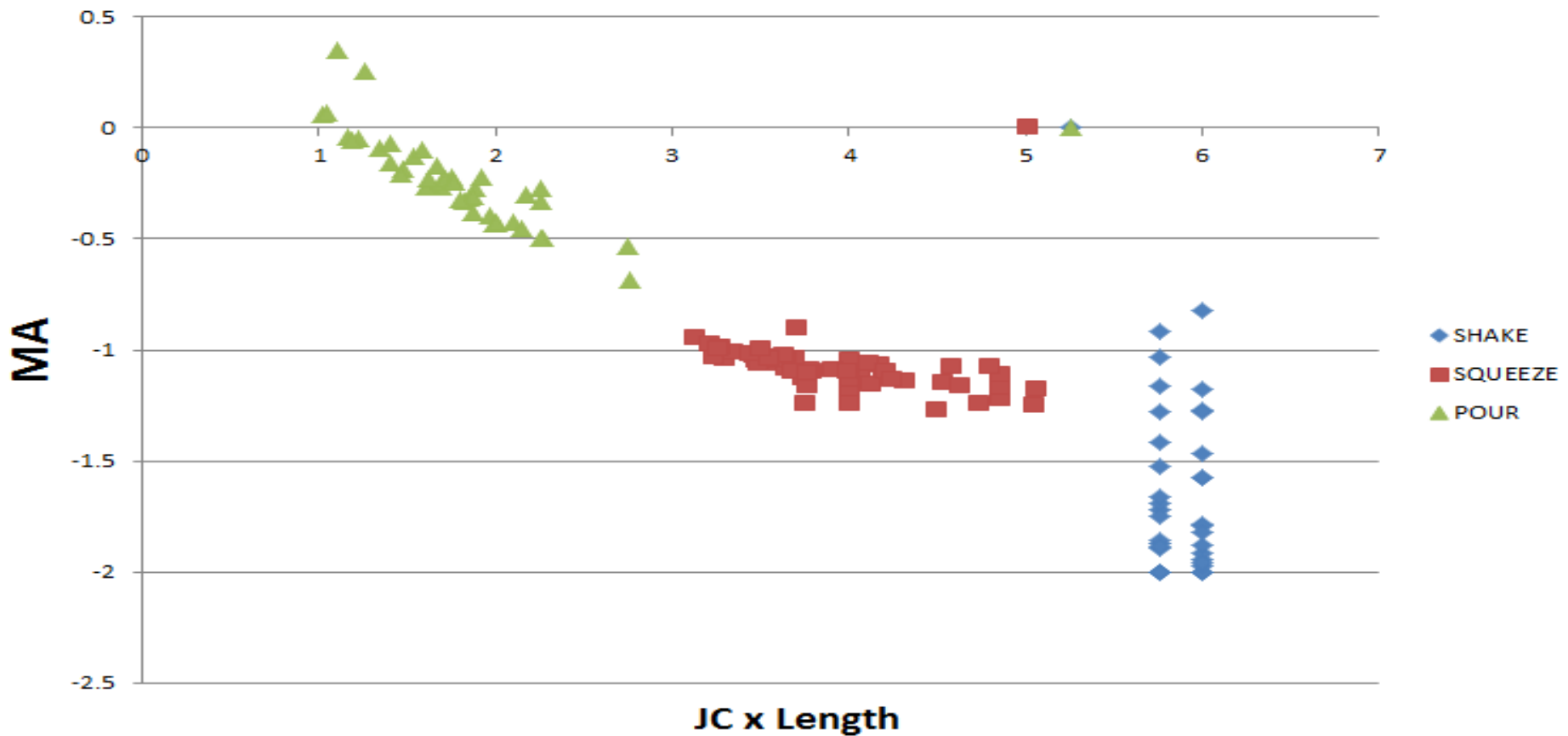
	A	B	C	D	E	F	G	H	I	J	K
1	name	time_stamp	accelz	ActionNur	ActionLen	ActionTyp	JC	MA	TV	JL	RG
2	SHAKE	20150724150851.csv									
3	RespeckLF	2.01507E+13	1.001221	1	50	0	0.119995	-2	1.527656	5.999756	3.999756
4	RespeckLF	2.01507E+13	1.002441	2	75	0	0.079997	-1.57623	0.965653	5.999755	3.999756
5	RespeckLF	2.01507E+13	1.001221	3	25	0	0.23999	-2	2.594624	5.999757	3.999756
6	RespeckLF	2.01507E+13	1.001221	4	50	0	0.119995	-2	1.44894	5.999757	3.999756
7	RespeckLF	2.01507E+13	1.002197	5	50	0	0.119995	-2	1.452802	5.999757	3.999756
8	RespeckLF	2.01507E+13	1.000488	6	50	0	0.119995	-1.17782	0.832689	5.999755	3.361182

- MA = min. avg. (avg. of 10 min. z-axis acclerometer values)
- JC = jerk count
- Length = number of z-axis accelerometer values in the window

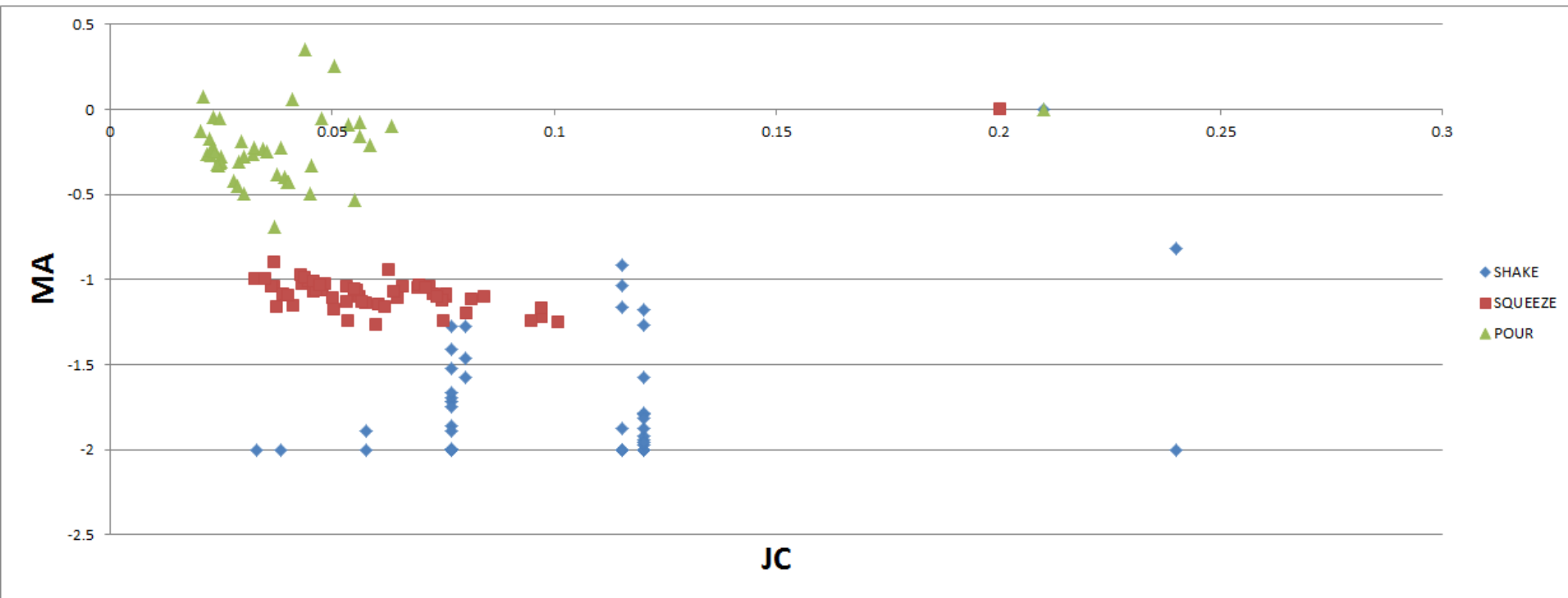
Clustering three actions - 1



Clustering three actions - 2



Clustering three actions - 4



Golf Swing

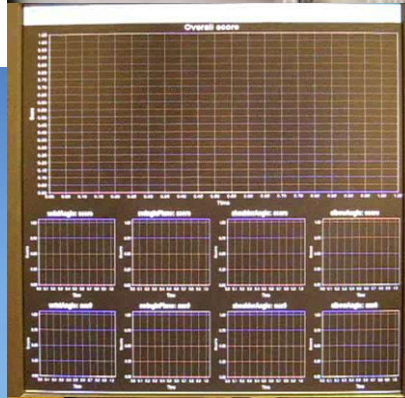
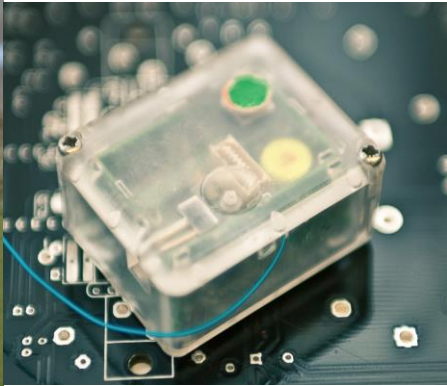


Arvind, D.K., Bates, C.A., 2008 "The Speckled Golfer", In 3rd Int. Conf. on Body Area Networks, March 13 - 17, 2008, Tempe AZ, USA, IEEE Press.

Analysis of golf swing

- on the golf course, and not in the studio
- Accurate, infrastructure-less, portable, strap-on
- Real-time feedback either sonic or visual (on a PDA)
- Fully wireless, and full body (if required)
- Score the “goodness” of a swing based on existing body of research on the biomechanics of golf swing
- Estimate the “distance” of a swing from the personal best

Golf Swing Statistics from any place



Analysis of Motor Control Skills



- Swing of the club
- Impact of the clubhead with the ball
- Flight of the ball towards the target

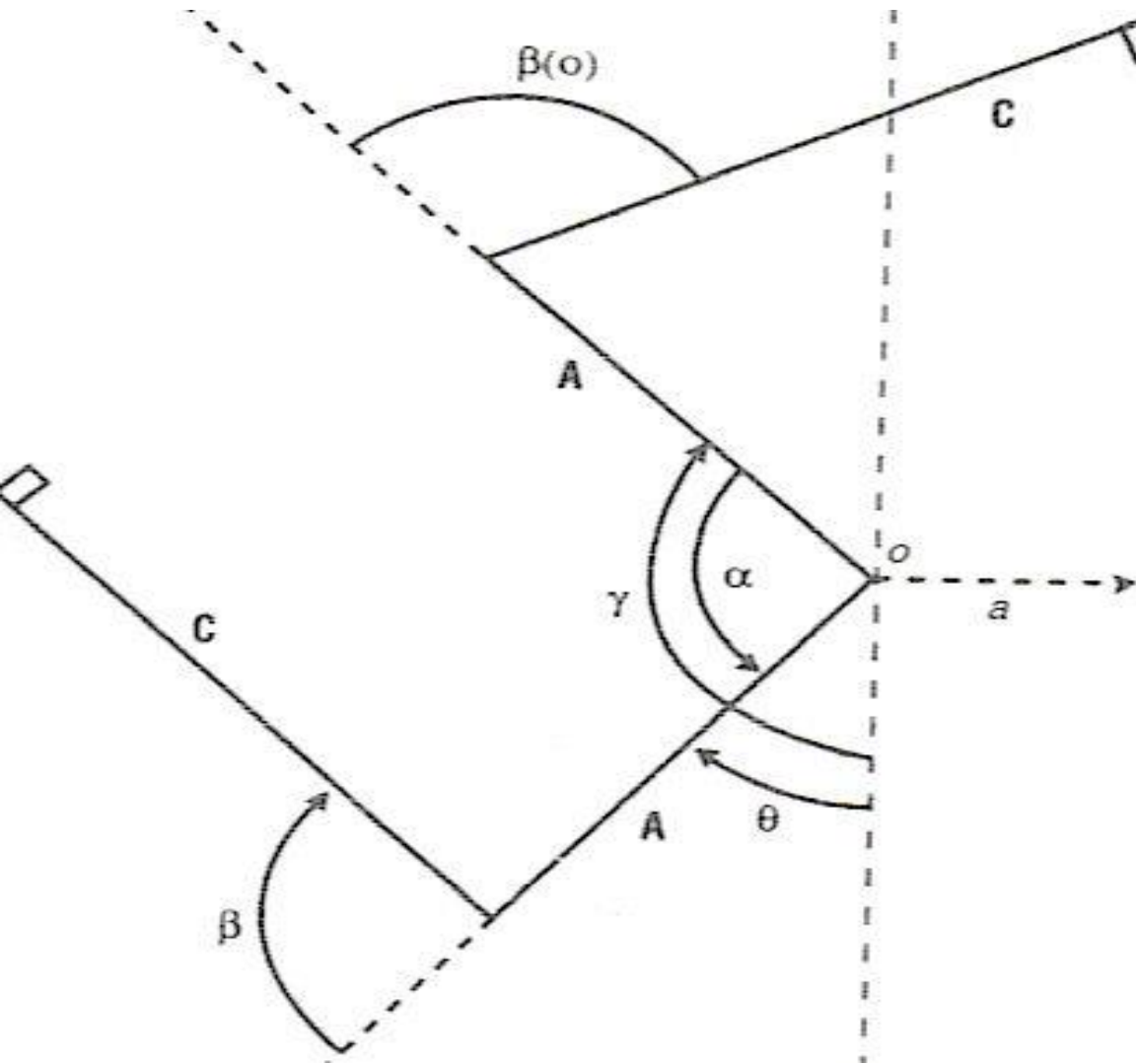
Swing of the Club

- Modelled as a double pendulum
 - Arms of the golfer act as one pendulum connected to the club
 - Club acts as another pendulum
- Equation of motion for a double pendulum using Newton's Laws

Model of the Swing

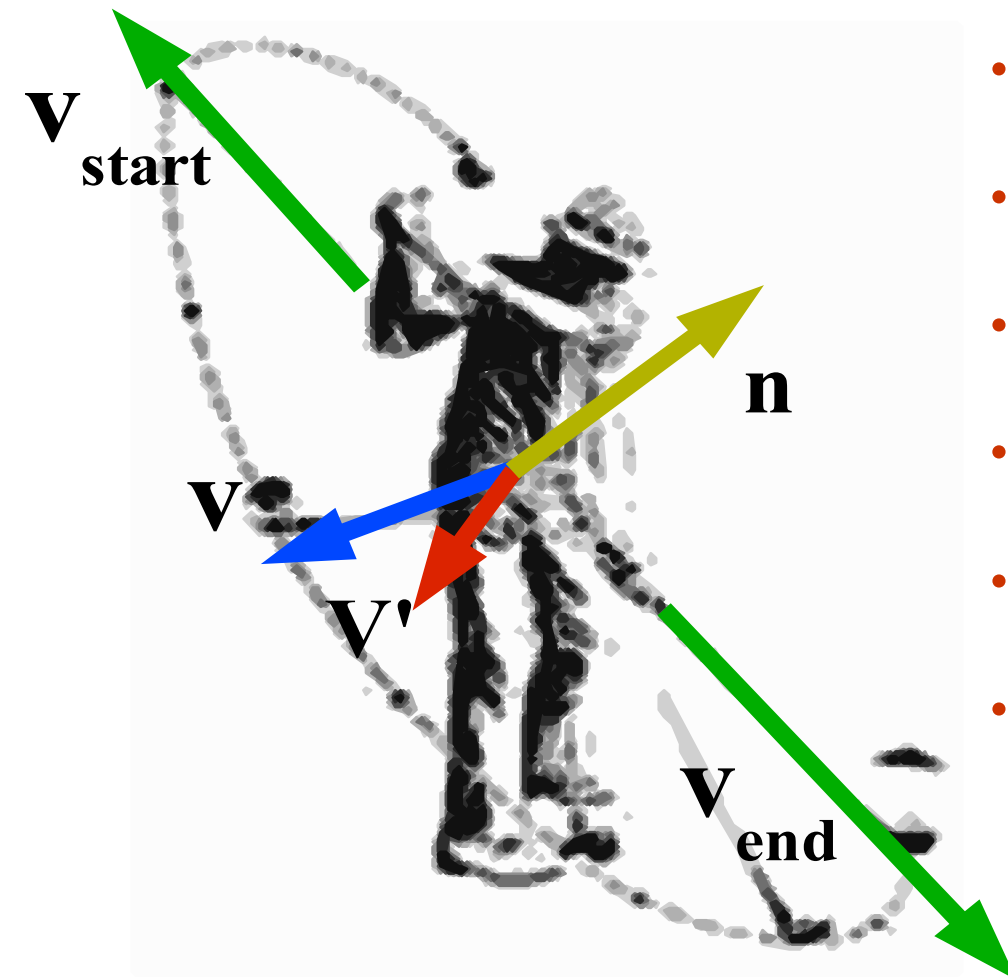
- Arms of the golfer swing about an axis that moves during the downswing
- Club swings about a moving axis near the wrists of the golfer
- Two rigid rods – Arm (A) and the Club (C)
- Rod A: point halfway b/w shoulder to wrist

Biomechanics of the Swing



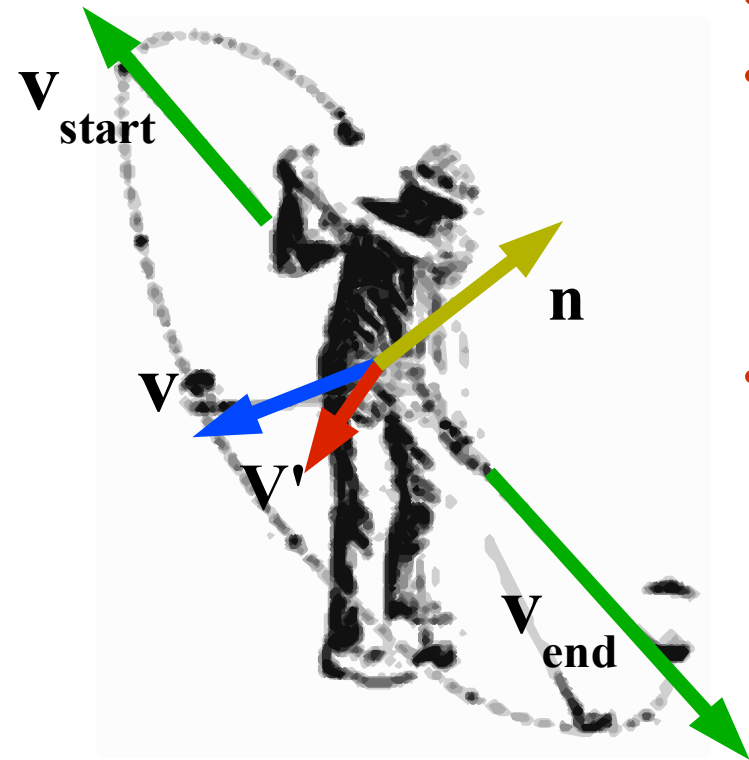
- a : hor. accl. at O
- *Gamma*: angle of rod A with the downward dir. at the start of the downswing
- *Beta*: wrist-cock angle
- *Theta*: downward angle of rod A
- *Alpha*: downward swing angle
- *Alpha dot*: angular vel. of rod A
- *Alpha double dot*: angular accl. of rod A

“Swinging in the Plane” Rule



- **vstart** – vector pointing down the shaft at the start of swing
- **vend** – shaft vector at the end of the swing
- **n** = **vstart** x **vend** and is normal to the swing plane
- **v'** – general shaft vector during the swing which does not lie in the plane
- **v** – correct shaft vector which does lie in the plane defined by **n**
- α - angle between **v'** and **n**, where $\cos(\alpha) = \mathbf{v}' \cdot \mathbf{n} / |\mathbf{v}'||\mathbf{n}|$

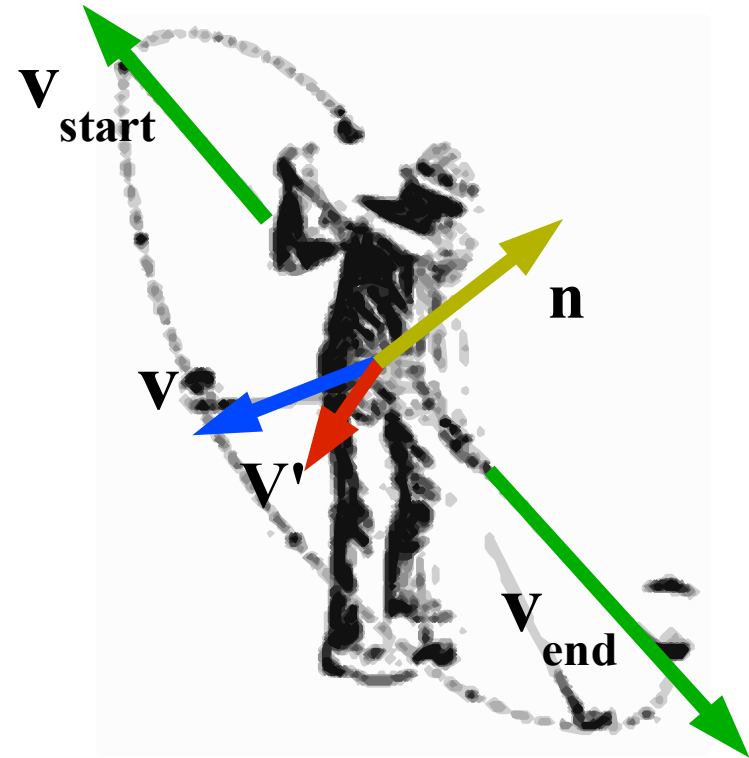
“Swinging in the Plane” Rule



- $\cos(\alpha) = \mathbf{v}' \cdot \mathbf{n} / |\mathbf{v}'| |\mathbf{n}|$, α - angle between \mathbf{v}' and \mathbf{n}
- \mathbf{v}' is obtained by taking the local down-shaft vector in the club sensor's co-ordinate system and rotating it by the current orientation of the device, to give a vector that points down the shaft in the world co-ordinate system
- $\mathbf{v}_{world} = \mathbf{q}^* \times \mathbf{v}_{local} \times \mathbf{q}$
 \mathbf{q} – quaternion specifying orientation of the device; \mathbf{q}^* is the conjugate; “ \mathbf{v}_{world} ”, vector pointing down the shaft in the world co-ordinate system, and \mathbf{v}_{local} , in the local co-ordinate frame; \times is the quaternion product

The rule returns $1 - \cos(\alpha)$ as a score, which is 1 for a swing perfectly within the plane, and 0 when perpendicular to the swing plane

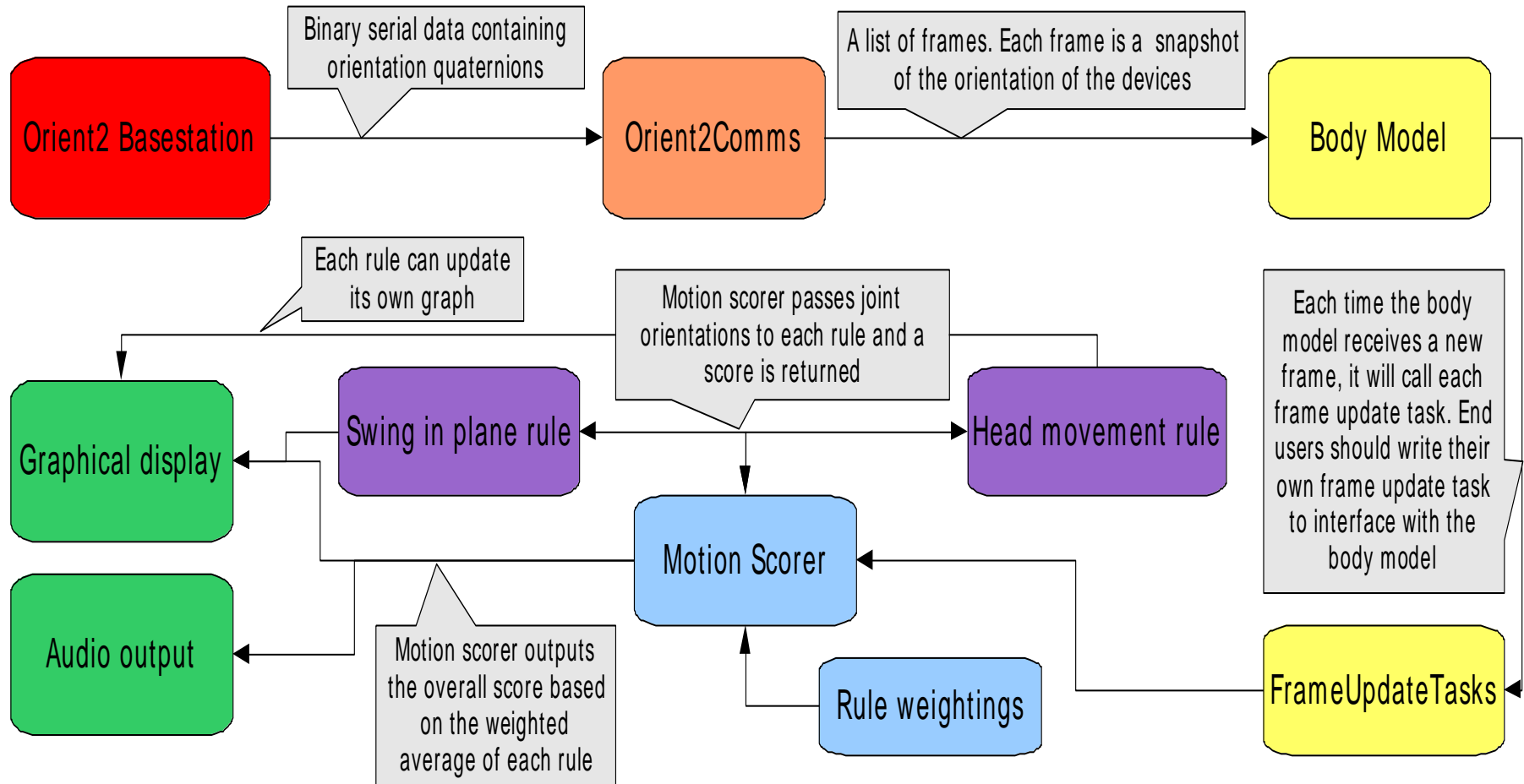
“Head Movement” Rule

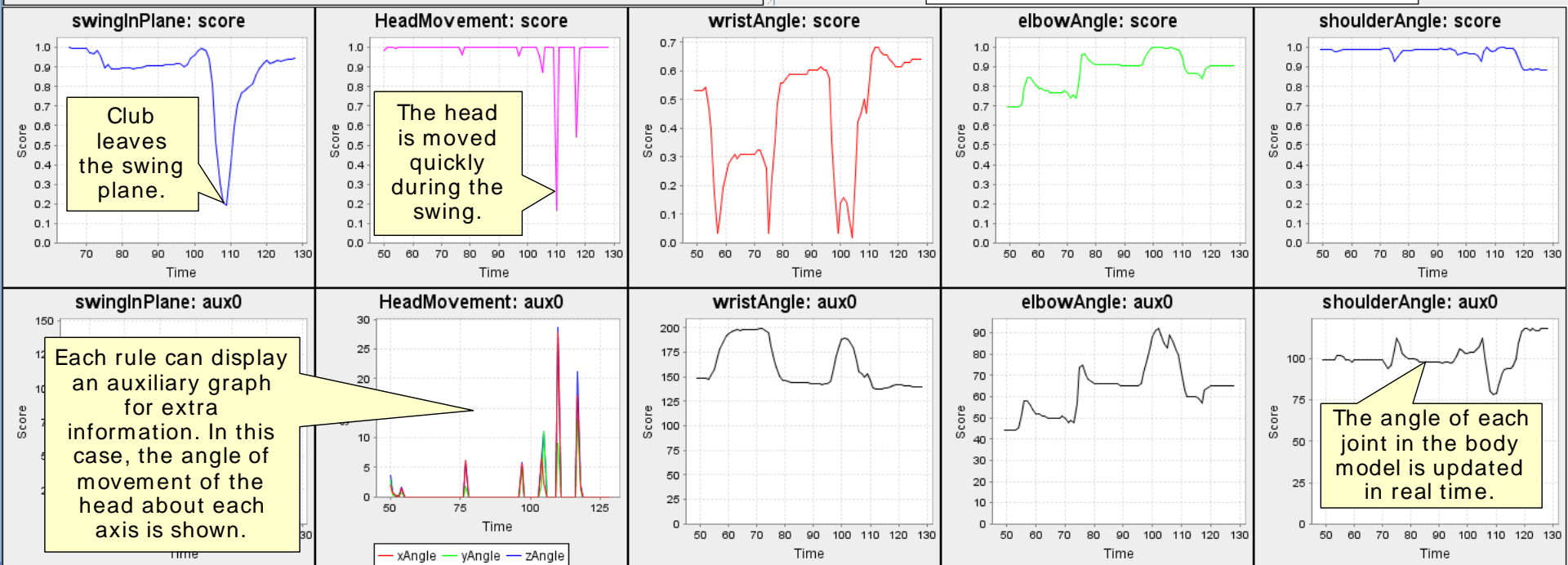
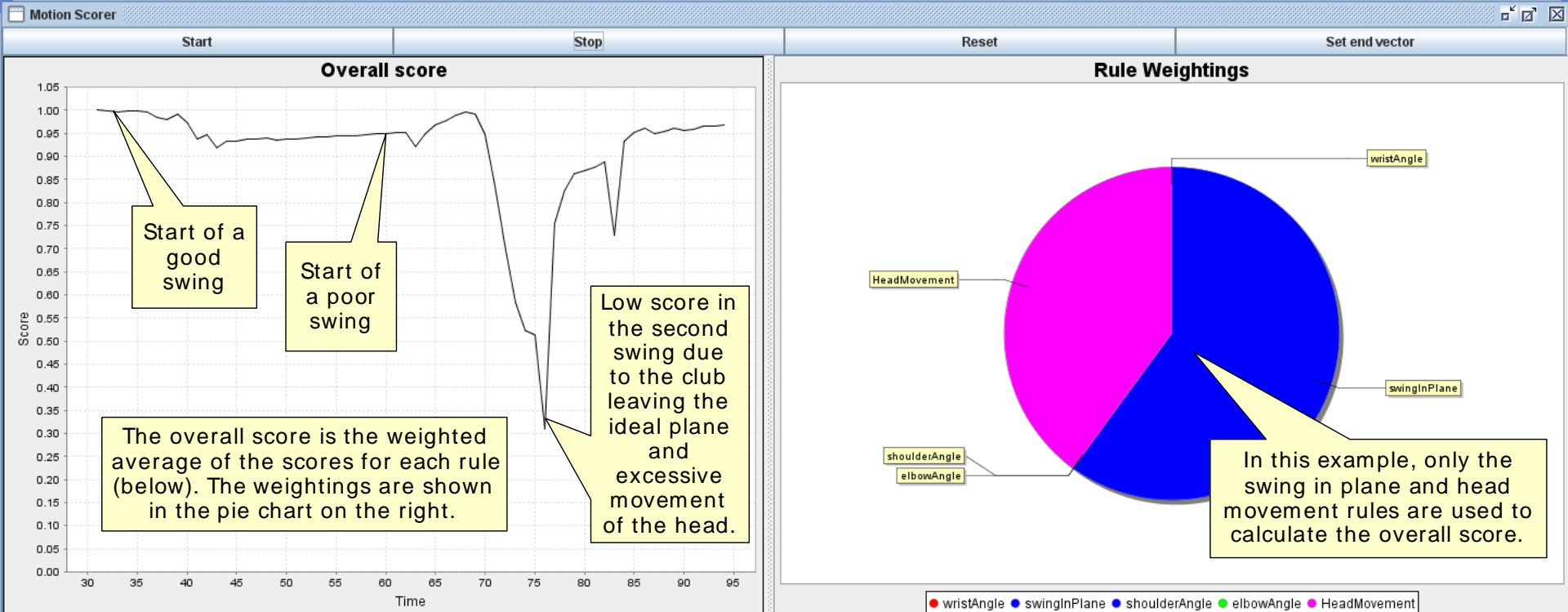


- Change in the orientation of the head about each axis between consecutive snapshots of the golf swing
- **Orient** speck attached to the cap – the root for the body model, and any head movement is recorded relative to the motion of the body
- For each snapshot calculate the world direction vector that points along each axis of the head-mounted device, and compare it to the previous value

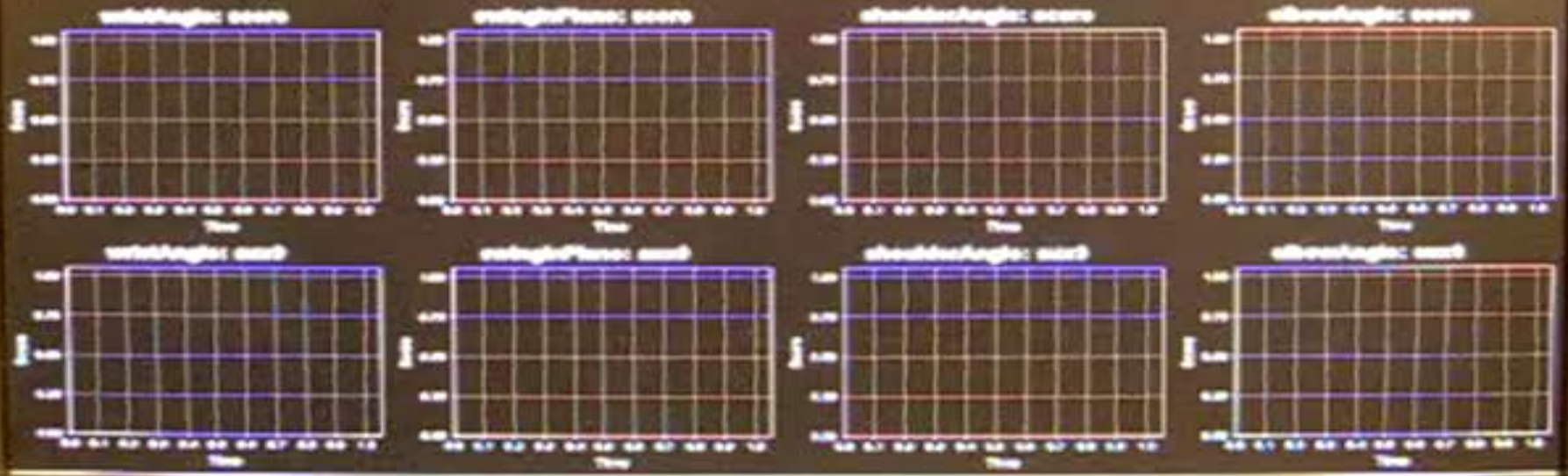
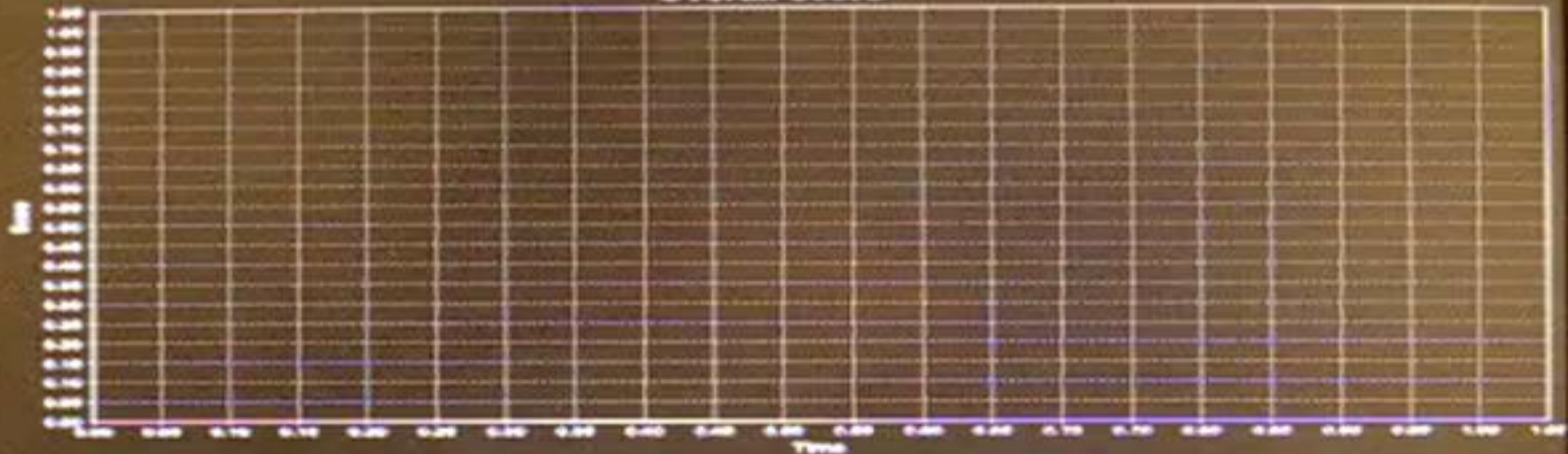
score = $(\text{Abs}(\cos(\delta x)) + \text{Abs}(\cos(\delta y)) + \text{Abs}(\cos(\delta z))) / 3$,
 δx , δy , δz are changes in alignment along the x, y and z axis

Body model on the Mobile





Overall score



Top Row: Distance of swing from ideal plane

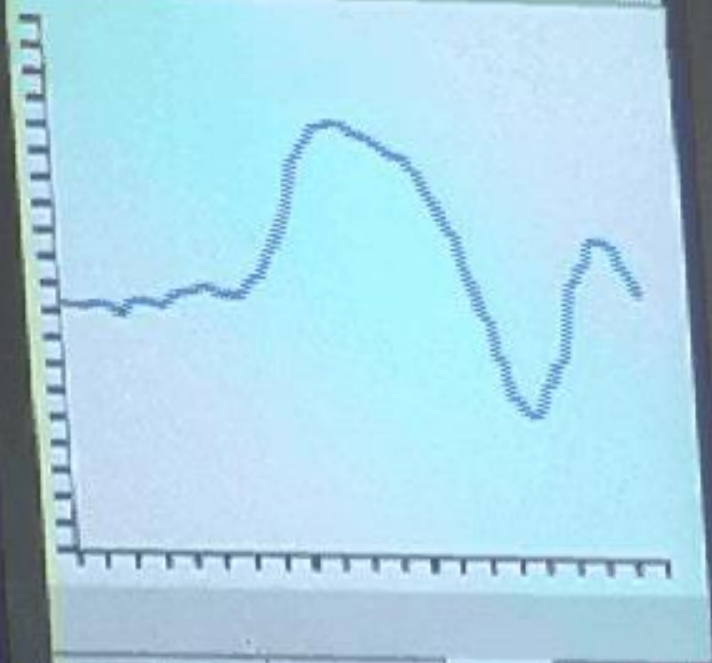
Middle Row: Sine of the angle at the wrist, elbow and shoulder

Bottom Row: Angle away from the plane and the 3 joint angles

MotionViewer

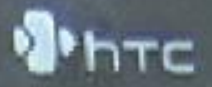
$\theta = \frac{2}{x} \frac{1}{k} x$

Graph X



Joint Mapping Orientation Graph 2D

File





A comparative study of surgical skills assessment in a physical laparoscopy simulator using wireless inertial sensors

R L Evans¹, R W Partridge² and D K Arvind¹

¹School of Informatics, University of Edinburgh

² Royal Hospital for Sick Children, NHS Lothian
Edinburgh, Scotland

In Proc. Wireless Health 2014, Bethesda MA, USA, Nov. 2014,
ACM Press



Overview

- **Laparoscopy Surgery Training**

- Medical expertise combined with manual dexterity in both hands and spatial awareness
- Training on real patients under supervision is expensive and time-consuming
- Surgical Simulators are a safe environment to practise key skills and provide automated measure of performance and feedback on improvements

- **An improved Use-case model**

- Take-home surgical simulator (eosim.com)
- Surgeons practise basic skills in their own time
- Inertial sensors (Orient specks) attached to the instruments provide feedback on performance of standard set of key skills
- Keep track of individual progress and comparison with cohort of trainees

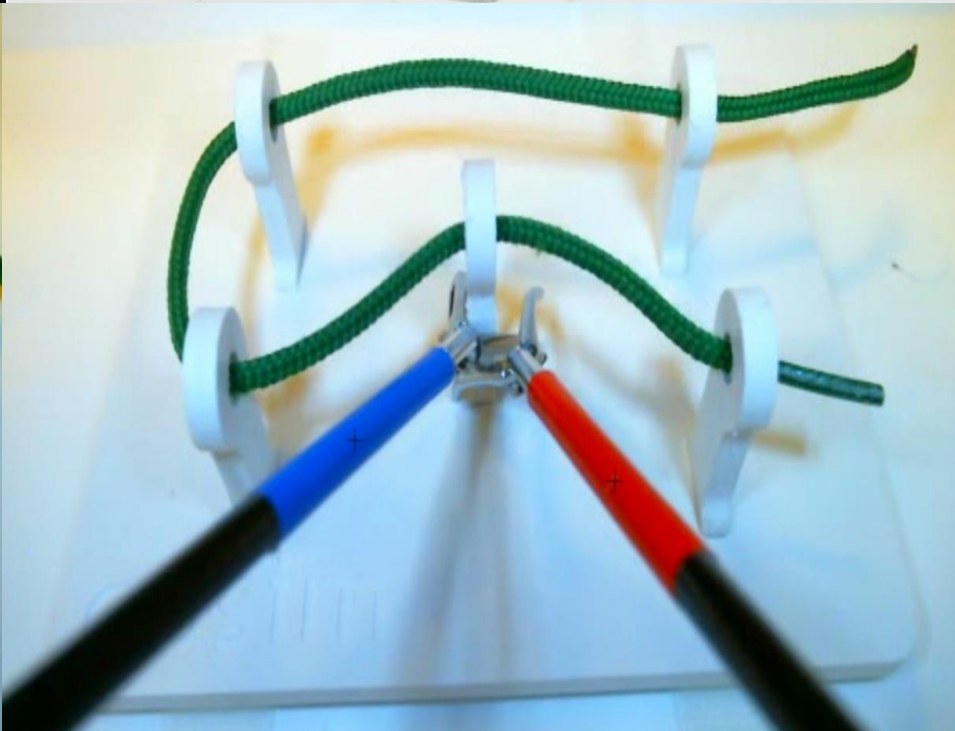
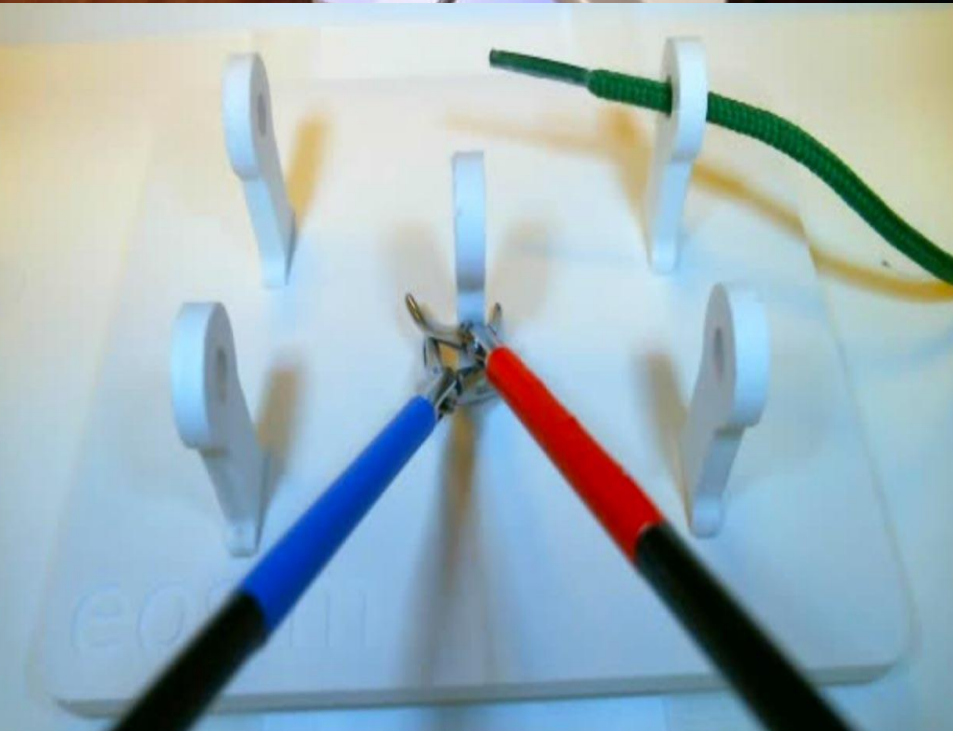
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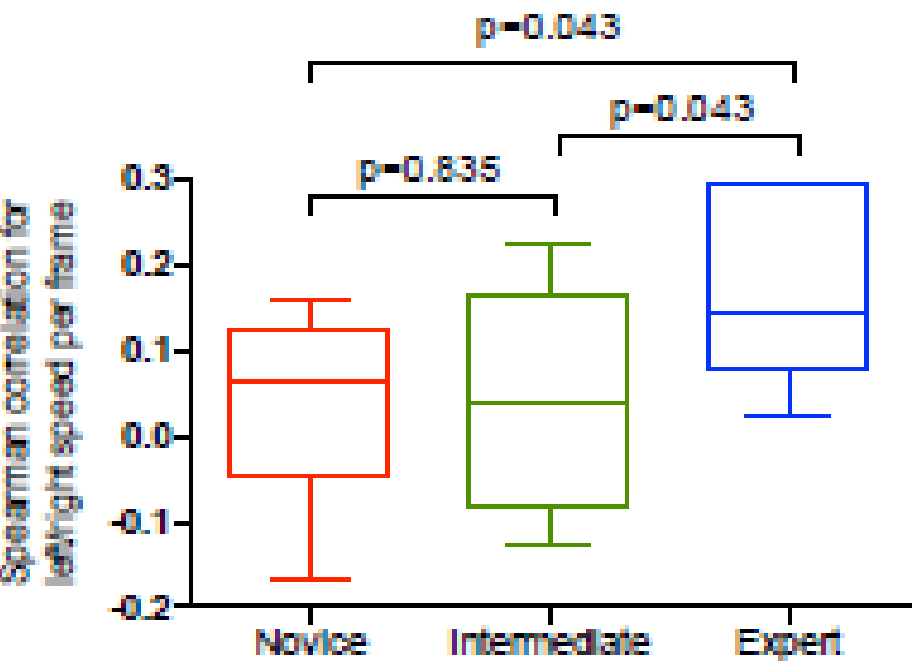
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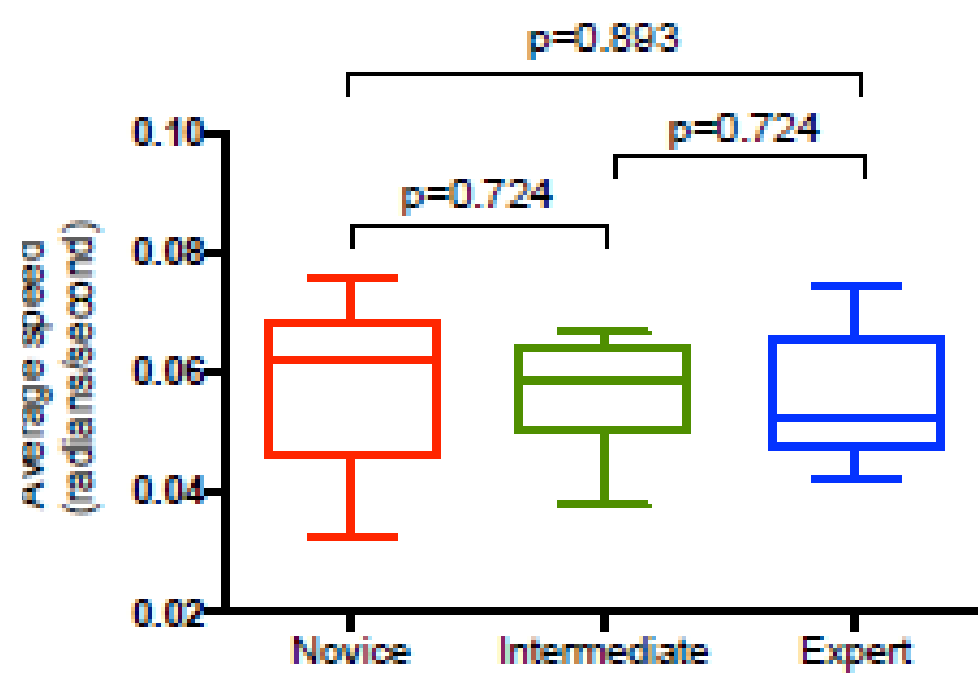
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Ambidexterity.



Average Speed.



Combined outputs from a leave-one-out cross-validation of the linear regression model.

$$\text{score} = -2 + 1000\alpha - 0.02T + 5 \times 10^{-10} \cdot S - 0.4\theta - 1.6A$$

Average Acceleration (α), Total Duration (T), Motion Smoothness (S), Angular Distance (θ), Ambidexterity (A).

