Genetic Algorithms and Genetic Programming
Lecture 6
Gillian Hayes
9th October 2007

The Schema Theorem – Reminder

\[ E(m(H, t + 1)) \geq m(H, t) \frac{\hat{u}(H, t)}{f(t)} (1 - p_c \frac{d(H)}{I - 1}) [(1 - p_m)^{o(H)}] \]

Highest when
- \( \hat{u}(H, t) \) is large – fit
- \( d(H) \) is small – short
- \( o(H) \) is small – small number of defined bits

Identifies building blocks of a good solution.

Lecture 6: The Building Block Hypothesis

- The Building Block Hypothesis
- Experimental evidence for the BBH
- The Royal Road functions
- Disruption and Hitchhiking
- GAs versus Hill-climbing
- The “killer instinct”
- Local search

The Building Block Hypothesis 1

Schema Theorem: short, low-order, above average schemata receive exponentially increasing trials in subsequent generations of a genetic algorithm. During crossover, these “building blocks” become exchanged and combined. So the Schema Theorem identifies the building blocks of a good solution although it only addresses the disruptive effects of crossover (and the constructive effects of crossover are supposed to be a large part of why GAs work). How do we address these constructive effects?

Building Block Hypothesis: a genetic algorithm seeks optimal performance through the juxtaposition of short, low-order, high-performance schemata, called the building blocks.
The Building Block Hypothesis 2

BBH: crossover combines short, low-order schemata into increasingly fit candidate solutions. Requires:

- short, low-order, high-fitness schemata
- “stepping stone” solutions which combine $H_i$ and $H_j$ to create even higher fitness schemata

The Building Block Hypothesis

The Building Block Hypothesis is a hypothesis – so we can do an experiment to test it.

Experiment: use a problem which contains explicit building blocks and observe the population. Do the building blocks combine to give good solutions in the way the BBH predicts?

Mitchell, Forrest, Holland set up such a problem, using Royal Road functions.

Details: Mitchell, Chapter 4, pp127–133

The Royal Road Function(s) 1

Define fitness in terms of particular schemata: substrings that, if present in population, ought to be combinable into the optimal solution. They should lay out a “Royal Road” to the global optimum.

The first RR function $R_1$ is defined using a list of schemata $s_i$. Each $s_i$ has a fitness coefficient $c_i$. The fitness $R_1(x)$ of some bit string $x$ is given by:

$$R_1(x) = \sum_i c_i \delta_i(x), \quad \delta_i(x) = \begin{cases} 1 & \text{if } x \in s_i \\ 0 & \text{otherwise} \end{cases}$$

Simple example using 16 bits. Suppose:

- $s_1 = 1111 * * * * * * * * * * *$
- $s_2 = * * * 1111 * * * * * * * * *$
- $s_3 = * * * * * * * 1111 * * * * *$
- $s_4 = * * * * * * * * * * * * * 1111$

and suppose $c_1 = c_2 = c_3 = c_4 = 4$ and $s_{\text{opt}} = 1111111111111111$

Then $R_1(\text{opt}) = 16$

Take the string 1111010010011111. It samples/matches $s_1$ and $s_4$.

So $\delta_1(x) = \delta_4(x) = 1$ and $\delta_2(x) = \delta_3(x) = 0$.

And $R_1(1111010010011111) = 8$. 
The Royal Road Function(s) 2

Several Royal Road functions defined in terms of different combinations of schemata, with building blocks at different levels, e.g. 4 contiguous 1s, 8 contiguous 1s, 16 contiguous 1s, etc.

Try to evolve the string with all 1s and compare performance of GA against a number of hill-climbing schemes:

- Steepest-ascent hill climbing (SAHC)
- Next-ascent hill climbing (NAHC)
- Random-mutation hill climbing (RMHC)

Will the GA do better?

Hill Climbing

Steepest-ascent hill climbing (SAHC)

1. Let current-best be a random string.
2. From left to right flip each bit in the string. Record fitness of each one-bit mutant.
3. If any mutant is fitter than current-best, set current-best to fittest mutant and goto 2.
4. If no fitness increase, save current-best and goto 1.
5. After $N$ evaluations return fittest current-best.

Next-ascent hill climbing (NAHC)

1. Let current-best be a random string.
2. From left, flip each bit $i$ in string. If no fitness increase, flip bit back. If fitness increase, set current-best to new string and continue mutating new string from 1 bit after the bit at which fitness increase was found.
3. If no fitness increase, save current-best and goto 1.

Random-mutation hill climbing (RMHC)

1. Let current-best be a random string.
2. Flip a random bit in current-best. If no fitness decrease, set current-best to mutated string.
3. Repeat 2. until optimal string found or $N$ evaluations completed.

See Mitchell p.129 for these algorithms.
Results

<table>
<thead>
<tr>
<th></th>
<th>GA</th>
<th>SAHC</th>
<th>NAHC</th>
<th>RMHC</th>
</tr>
</thead>
<tbody>
<tr>
<td>Mean</td>
<td>61,334</td>
<td>&gt; max</td>
<td>&gt; max</td>
<td>6,179</td>
</tr>
<tr>
<td>Median</td>
<td>54,208</td>
<td>&gt; max</td>
<td>&gt; max</td>
<td>5,775</td>
</tr>
<tr>
<td></td>
<td>No. evaluations to max = 256000</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Why did the GA do worse than RMHC? When do GAs perform well?

- By Markov chain analysis, RMHC’s expected time is $\sim 6549$ evaluations. OK.
- What’s going wrong in the GA? Larger combinations of $s_i$ in the GA get broken up by crossover and disrupted by mutation.
- And the GA suffers from **hitch-hiking**: once an instance of a high-fitness schema is discovered, the “unfit” material, especially that just next to the fit parts, spreads along with the fit material. Slows discovery of good schemata in those positions.

Hitch-hiking

- Hitch-hikers prevent independent sampling particularly in those partitions falling between two closely-spaced others, e.g. hitch-hikers with $s_2$ and $s_4$ (0s near the ends of $s_2$ and $s_4$) drowned out instances of $s_3$. So sampling in $s_3$ region not independent of sampling in $s_2$ and $s_4$ regions.
- Early convergence to wrong schemata in a number of partitions of the string limits the effectiveness of crossover.
- Sampling of the different regions is not independent.

See Mitchell Fig. 4.2 p.133 for hitch-hiking effect.

Analysis

- Easy problem, no local maxima (so hill-climbing works, RMHC is systematic).
- GA will out-perform HC on parallel machines (why?)
- GA is not sampling evenly; schema theorem does not hold. If partitions are sampled independently, schema theorem ought to hold.

Mitchell proposes an idealised GA (IGA):

- sample a new string $s_i$ uniform-randomly
- if $s_i$ contains a new desired schema, keep it and cross it over with previous best string to incorporate new schema into the solution

IGA aims to sample each partition independently and tend to keep best schemata in each partition – **static Building Block Hypothesis**

- It works, and it’s $N$ times faster than HC
- IGA unusable in practice (why?) but gives us a lower bound on time GA needs to find optimal string
- In IGA each new string is an independent sample, whereas in RMHC each new sample differs from the previous by only one bit – so RMHC takes longer to construct building blocks

So we have some clues as to when GAs will do well...
When Do GAs Do Better Than Hill-climbing?

To act like an ideal GA and outperform hill-climbing (at least in this sort of landscape) need

- Independent samples: big enough population, slow enough selection, high enough mutation, so that no bit-positions are fixed at same value in every chromosome
- Keeping desired schemata: strong enough selection to keep desired schemata but slow enough selection to avoid hitch-hiking
- We want crossover to cross over good schemata quickly when they’re found to make better chromosomes (but we don’t want crossover to disrupt solutions)
- Large $N$/long string so speedup over RMHC is worth it.

Not possible to satisfy all constraints at once – tailor to your problem

Where Now?

- Schema theorem starts to give us an idea of how GAs work but is flawed $\rightarrow$ need better mathematical models of GA convergence . . .
- . . . but these better models don’t make our GA go faster
- Standard GA finds good areas, but lacks the killer instinct to find the globally best solution
- Standard crossover often disrupts good solutions late in the run
- Binary representations of non-binary problems often slow the GA down rather than allowing it to sample more freely. The “Hamming Cliff”.

The Killer Instinct

Want to get from good to best individuals.

[De Jong] Say range of payoff values is $[1,100]$. Quickly get population with fitness say in $[99,100]$. Selective differential between best individuals and rest, e.g. 99.988 and 100.000, is very small. Why should GA prefer one over another?

- Dynamically scale fitness function as a function of generations or fitness range
- Use rank-proportional selection to maintain a constant selection differential. Slows down initial convergence but increases killer instinct in final stages.
- Elitism. Keep best individual found so far, or, selectively replace worst members of population

Aim is to shift balance from exploration at start to exploitation at end.

The Killer Instinct and Memetic Algorithms

- Hill-climbing local neighbourhood search is a fast single solution method which quickly gets stuck in local optima (cf. SAHC, NAHC)
- Genetic algorithms are a multi-solution technique which find good approximate solutions which are non-local optima
- Hence: try applying local search to each member of a population after crossover/mutation has been applied
- GA + LS = Memetic Algorithm
Making It Better

- Start the GA from good initial positions: seeding. If you know roughly where a solution might lie, use this information.

- Use a representation close to the problem: does not have to be a fixed-length linear binary string

- Use operators that suit the representation chosen, e.g. crossover only in specific positions

- Run on parallel machines: island model GA (evolve isolated subpopulations, allow to migrate at intervals)

Reading: Mitchell Chapter 4