

Levels of analysis and ACT-R

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Reading: Marr (1982), pp. 19-29; Anderson (1996)

Outline

Two foundational people in cognitive modeling and their ideas:

- David Marr's levels of analysis: a way of thinking about cognitive models.
- John R. Anderson's ACT-R: a unified theory of mind.

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David Marr



- Born in Essex, 1945, died of leukemia, age 35.
- Worked in AI Lab and Psychology department at MIT.
- A founder of the field of cognitive neuroscience.
 - First paper (1969) proposed a theory of cerebellar function.
 - "Thirty years later, a significant proportion of researchers working on the cerebellum seem to consider this model as 'generally correct'" (Edelman, 2009).
- Developed influential computational theory of vision.
 - Collected in book, *Vision: A Computational Investigation into the Human Representation and Processing of Visual Information*, published posthumously in 1982.

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Image: amazon.co.uk

Marr's Vision

- Proposes a computational theory of vision:
 - Primal sketch, 2.5D sketch, 3D model.
- Describes three **levels of analysis** for studying information processing systems (dev. w/ T. Poggio):
 - **Computational theory**: what is the goal of the computation and the logical strategy needed to carry it out?
 - **Representation and algorithm**: how can the computation be implemented, and what input/output representations are needed?
 - **Hardware implementation**: what is the physical realization of the algorithm?

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Levels of analysis: example



- A cash register:
 - Computational level: what does it do, and why?
 - Computes sum of inputs using theory of addition.
 - Total money owed for goods follows rules of addition.
 - Algorithmic level: what is the representation and algorithm?
 - Arabic numerals.
 - Add least significant digits first, carry remainder, etc.
 - (Unary numerals, counting?)
 - Implementation level: what is the physical realization?
 - Mechanical device, silicon chip, etc.
 - (Matchsticks?)

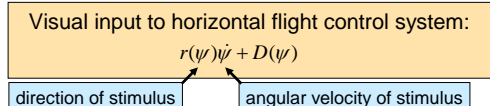
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Image: <http://www.tradebit.com/usr/manual/pub/9002/commoncashreg.jpg>

Cognitive example



- A fly's visual system:
 - Computational level: what does it do, and why?



- If objects in visual field "explode", triggers landing behavior.
- If a small patch appears (e.g., another fly), ψ and ψ' are delivered to motor system, which is designed to intercept.

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Image: <http://entopl.okstate.edu/ddd/IMAGES/fruifly.jpg>

Cognitive example



- A fly's visual system:
 - Algorithmic level: what is the representation and algorithm?
 - Not discussed.
 - Implementation level: what is the physical realization?
 - Visual receptor cells, neurons, etc.

Image: <http://entoplp.okstate.edu/ddd/IMAGES/fruittfly.jpg>

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To consider

- Which level of analysis do other cognitive models address?
 - Chomsky's generative grammar
 - Associative learning models (e.g., Rescorla-Wagner)
 - Braitenburg's *Vehicles*
 - Good old-fashioned AI (e.g., Shakey the robot)
- Can all information processing systems be analyzed in this way?
- Is it always easy to separate the three levels?

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John R. Anderson



- Born 1947, Vancouver.
- Professor of psychology at CMU since 1978.
- Early pioneer of work on intelligent tutoring.
- Influential work on cognitive architectures (ACT, ACT*)
- Introduced framework for rational analysis (Anderson, 1990)
- Now works with **ACT-R**, a hybrid approach.

Image: <http://act-r.psy.cmu.edu/people/ja/>

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ACT-R

- Provides "important new insights into the integration of cognition" (Anderson, 1996).
 - Unified theory of cognition realized as a production system.
 - Designed to predict human behavior by processing information and generating intelligent behavior.
 - Integrates theories of cognition, visual attention, and motor control.
 - Successfully models a variety of high-level phenomena, e.g., working memory, scientific reasoning, skill acquisition, HCI.

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A unified theory of mind

- ACT-R intended to be a single model to capture all aspects of cognitive processing.
 - Good for tackling applied problems.
 - Many other models address only isolated research questions.
- Ex: learning mathematics involves
 - Understanding mathematical expressions
 - Reading (visual and language processing)
 - Problem solving
 - Reasoning and skill acquisition

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Example application (Salvucci and Macuga, 2001)

What is the effect of mobile phone use on driving?

- Develop two separate ACT-R models for driving and dialing mobile phone.
- Put them together to predict effects of driving on phone use and vice versa.
 - Compared four ways of dialing.
 - Predicted that only full manual dialing has significant impact on steering abilities.
 - Predictions borne out through later experiments.

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Other domains

- **Perception and attention:** visual search, eye movements, task switching, driving behavior, situational awareness.
- **Learning and memory:** list memory, implicit learning, skill acquisition, category learning, arithmetic, learning by exploration and example.
- **Problem-solving and decision-making:** use and design of artifacts, spatial reasoning, game playing, insight and scientific discovery.
- **Language processing:** parsing, analogy and metaphor, learning, sentence memory, communication and negotiation.
- **Other:** cognitive development, emotion, individual differences.

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Basic theory

Cognition emerges from the interaction between very many small bits of **procedural** and **declarative** knowledge.

- Declarative knowledge: facts.
- Procedural knowledge: encodes processes and skills, represented as **production rules**.

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Declarative knowledge

- Units of declarative knowledge are called **chunks**.
- Chunks encode things remembered or perceived, as well as current goals:
 - $2+2 = 4$
 - Edinburgh is the capital of Scotland.
 - There is a car to my right.
 - I'm trying to get to class.

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Procedural knowledge

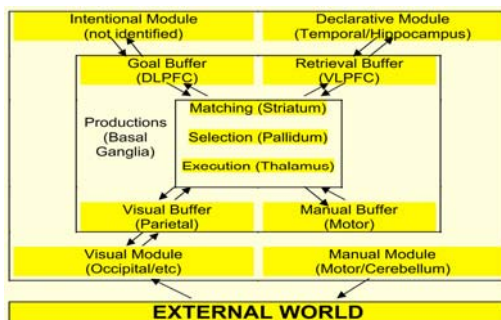
- Encoded as production rules, consisting of **conditions** and **actions**.

IF goal is to add two digits d_1 and d_2 in a column and $d_1+d_2=d_3$
THEN set a subgoal to write d_3 in the column.

- Conditions: may depend on declarative knowledge, buffer contents, and/or sensory input.
- Actions: can change declarative knowledge, goals, or buffer contents, or initiate motor actions.

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Modular organization



(Anderson et al., 2004)

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Modular organization

- **Modules:** store and process long-term information, which is deposited in **buffers**.
 - Goal buffer: tracks state in solving problems.
 - Retrieval buffer: holds information retrieved from long-term declarative memory.
 - Visual buffer: tracks visual objects and their identities.
 - Manual buffer: control and sensation of hands.
- **Central production system:** executive control and coordination of modules.
 - Not sensitive to activity in modules, only to buffer contents.

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Timing and coordination

- Within modules, processing is in **parallel**.
 - Ex: visual system processes entire visual field at once.
- Overall timing determined by **serial** processing in central production system. In one **critical cycle**:
 - Patterns in buffers are recognized and a production fires.
 - Buffers are updated for the next cycle.
- Assumptions:
 - Each buffer may contain only one chunk.
 - Only a single production fires each cycle.
 - Cycle takes about 50 ms (based on experimental data).

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Hybrid architecture

- Behavior determined by interaction between symbolic and sub-symbolic (statistical) systems.
 - Symbolic: production system.
 - Sub-symbolic: massively parallel processes summarized by mathematical equations.
- Each symbol (production/chunk) has sub-symbolic parameters that reflect past use and determine probability of current use.

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Ex: declarative memory module

- Purpose: retrieve chunks formed previously.
- Each chunk has a sub-symbolic activation level, the sum of
 - **Base level activation**, reflecting general usefulness in past.
 - **Associative activation**, reflecting relevance to current context.
- Total activation determines probability of being retrieved and speed of retrieval.

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Ex: procedural memory

- Many production rules may match at once, but only one can fire.
- Each rule has a sub-symbolic utility function combining
 - The probability that the current goal will be achieved if this rule is chosen (based on past experience).
 - The relative cost (time/effort) and benefit of achieving the current goal.
- The rule with the highest utility is executed.

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ACT-R summary

- Complex cognition emerges as the result of (procedural) production rules operating on (declarative) chunks.
- Independent modules encapsulate parallel processing functions, place single chunks in buffers.
- Central production system accesses buffers, detects when rule triggers are satisfied, fires one rule at a time.
- Chunks and rules are symbolic, but sub-symbolic activation levels determine which ones get used.
- Learning involves either acquiring new chunks and productions, or tuning their sub-symbolic parameters.

ACT-R features

- Can predict time-sharing between different tasks.
- Bridges short time-scale processes (retrieval, single productions) with long time-scale processes (e.g., learning to solve algebraic equations), with implications for education.
- Some evidence that modular structure corresponds to different brain regions.

Questionnaire

- Name, degree, and course/specialism.
- For MSc: undergraduate course.
- Background with machine learning, programming, probability theory, cognitive psychology.
- Are there any particular areas of interest to you, things you're hoping to learn about, or reasons for taking this course?

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