

Curves and Surfaces 2

Computer Graphics

Lecture 17

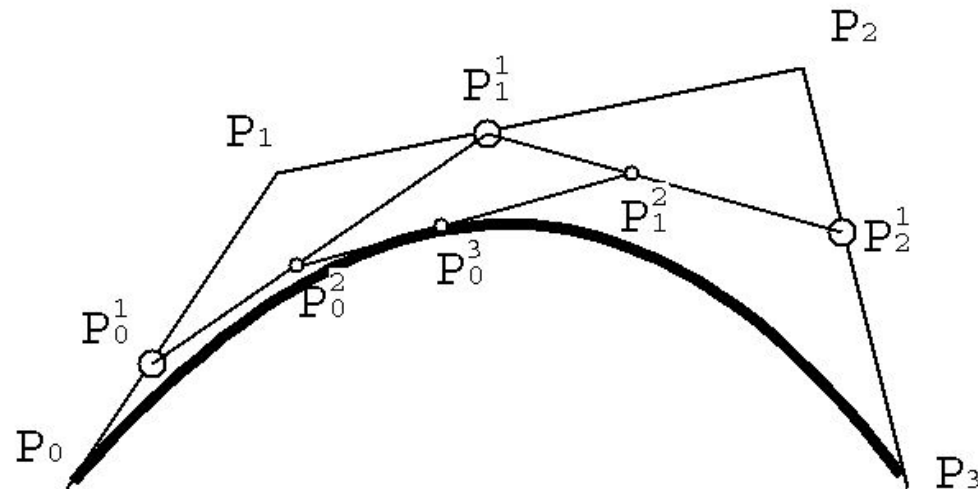
Taku Komura

Today

- **More about Bezier and Bsplines**
 - **de Casteljau's algorithm**
 - BSpline : General form
 - de Boor's algorithm
 - Knot insertion
- NURBS
- Subdivision Surface

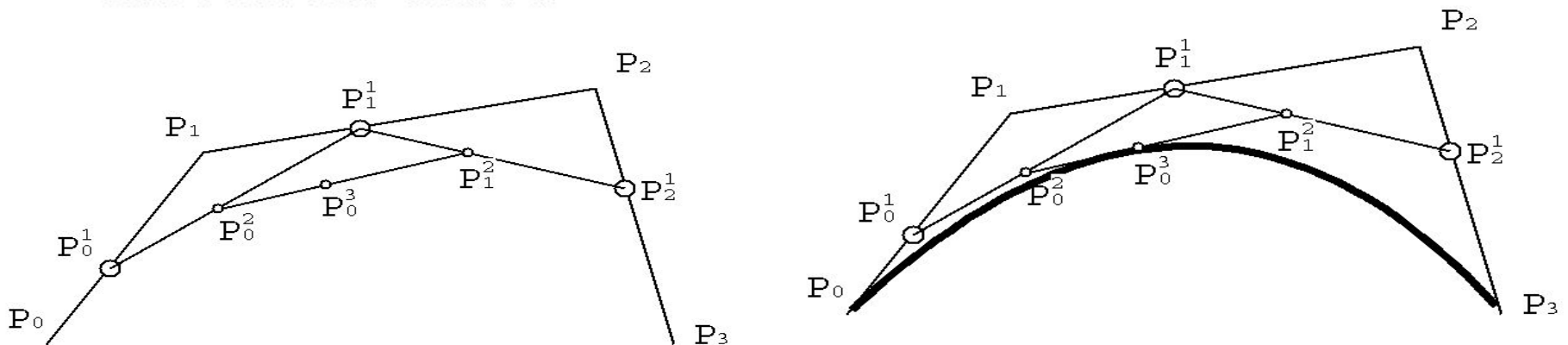
de Casteljau's Algorithm

- A method to evaluate (sample points in) or draw the Bezier curve
- The Bezier curve of any degree can be handled
- A precise way to evaluate the curves



de Casteljau's Algorithm

- Given the control points P_1, \dots, P_n and the parameter value $0 \leq t \leq 1$,
- Repeat the following procedure
 - Set $P^r_i(t) = (1 - t) P^{r-1}_i(t) + t P^{r-1}_{i+1}(t)$
 - $P^0_i(t) = P_i$
 - Then, $P^n_0(t)$ is the point with parameter value t on the Bezier curve

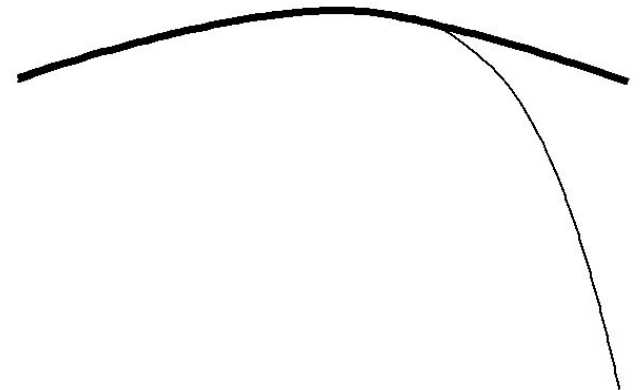


Why does this result in the polynomial?

- Let's think of a quadratic case that there are three points P_0, P_1, P_2 .
- $P^1_0(t) = (1 - t) P_0 + tP_1$
- $P^1_1(t) = (1 - t) P_1 + tP_2$
- $P^2_0(t) = (1 - t)P^1_0 + tP^1_1$
- By inserting the first two equations into the third one, we obtain
- $P^2_0(t) = (1 - t)^2 P_0 + 2t(1 - t)P_1 + t^2 P_2$
- Doing this for 4 control points will give the cubic formula I presented last week

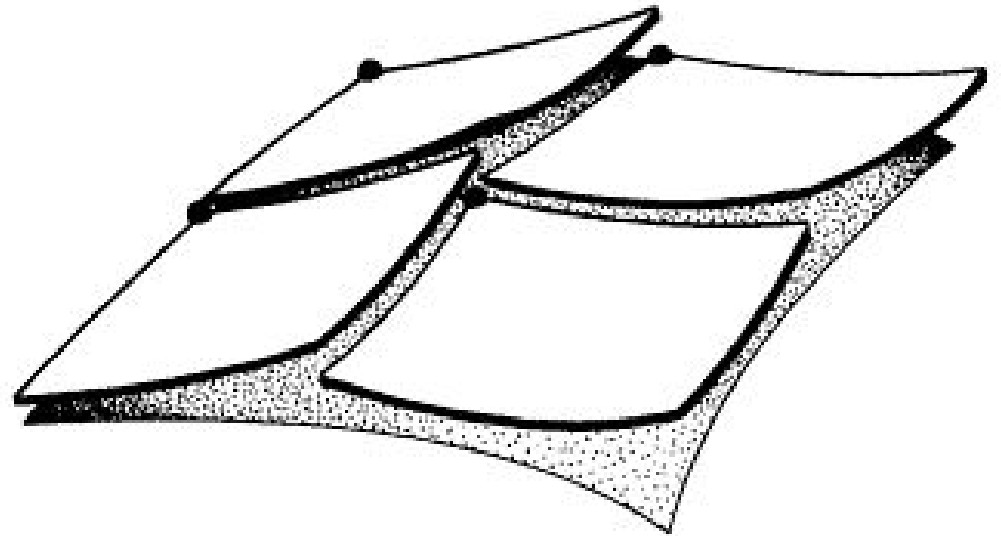
Why do we need this?

- The explicit representation (monomial form) that I presented last week can result in some instability
- Say the control points are randomly changed for 0.001.
- The curve computed by the de Casteljau's algorithm stays almost the same.
- The curve by the polynomial basis form can deviate from the original curve if the degree is high



Connecting many Bezier Patches in the polynomial form

- The same story applies to surfaces
- The degree of surface can easily go high, as they are the multiplication of two curves
- Bicubic $\rightarrow 6$
- The error of 16 control points will be accumulated



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B-Spline : A General Form

A Bspline is a parametric curve composed of a linear combination of basis B-splines $B_{i,n}$

P_i ($i=0, \dots, m$) the control points

$$p(t) = \sum_{i=0}^m P_i B_{i,k}(t)$$

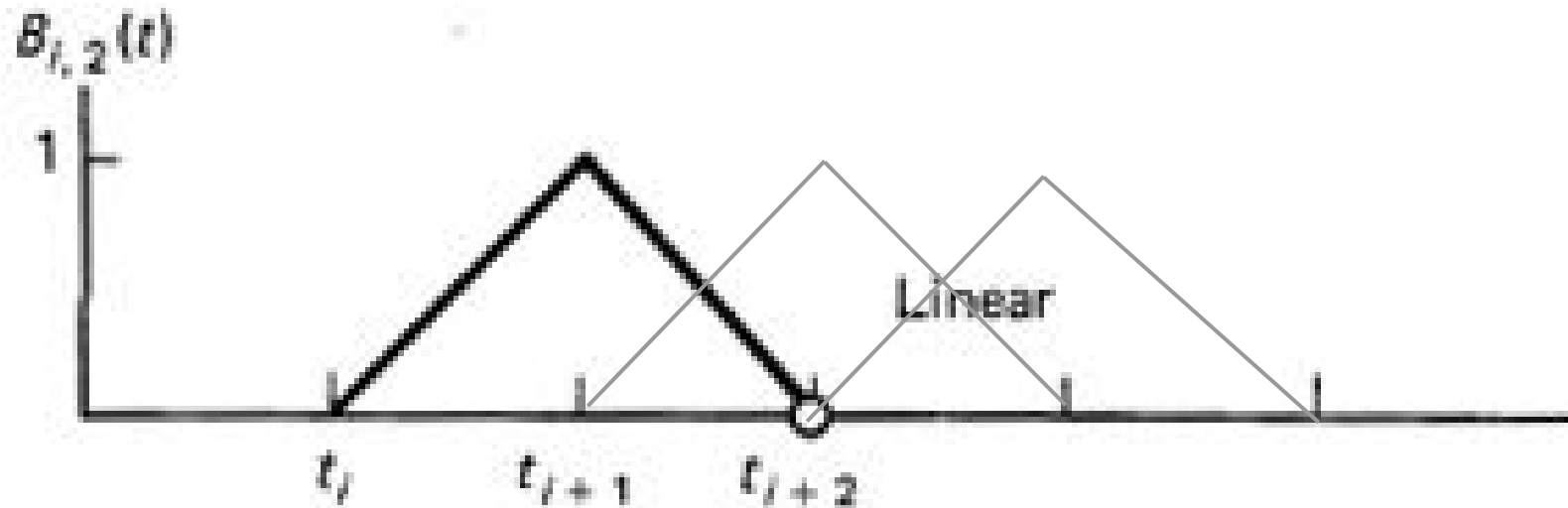
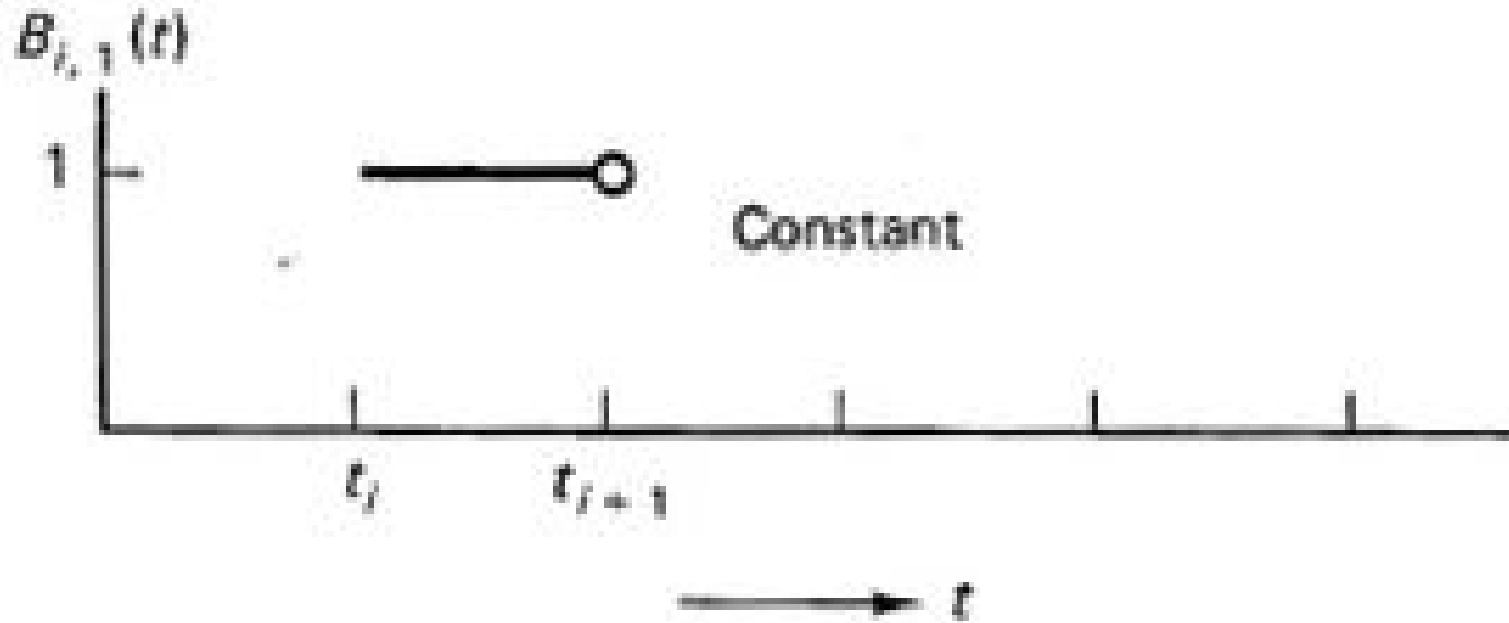
Knots: $t_0 \leq t_1 \leq \dots \leq t_{k+m}$ - subdivide the domain of the B-spline curve into a set of knot spans $[t_i, t_{i+1})$

The B-splines can be defined by

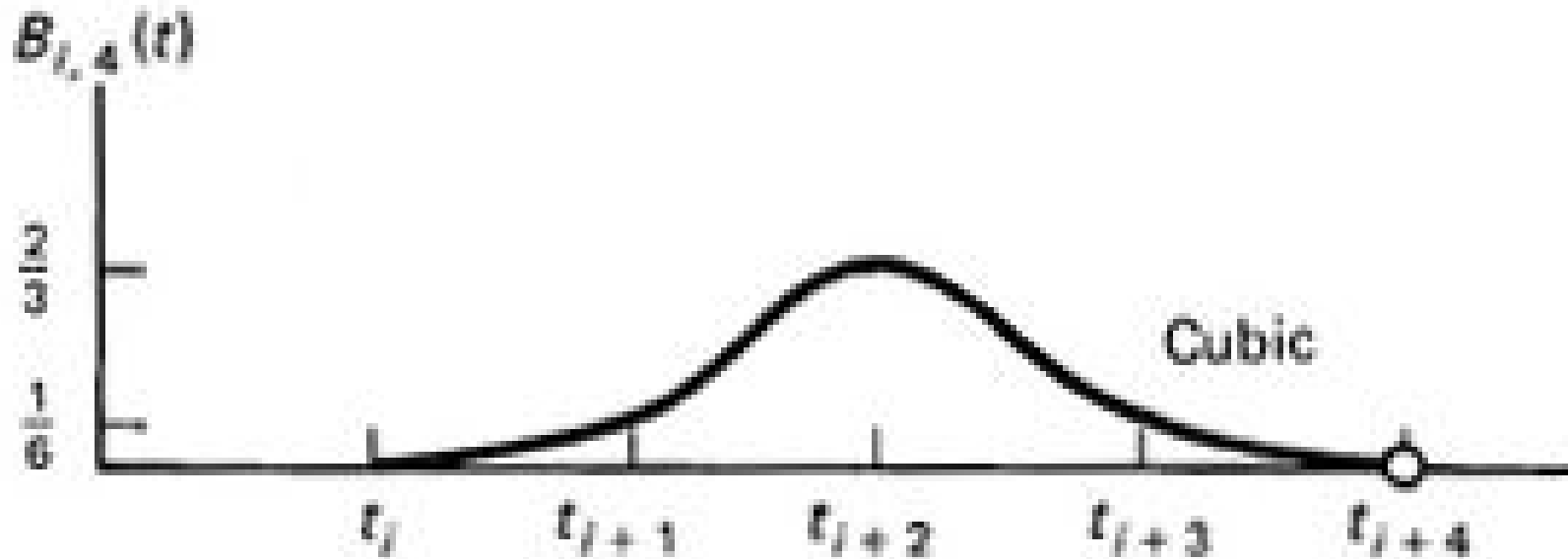
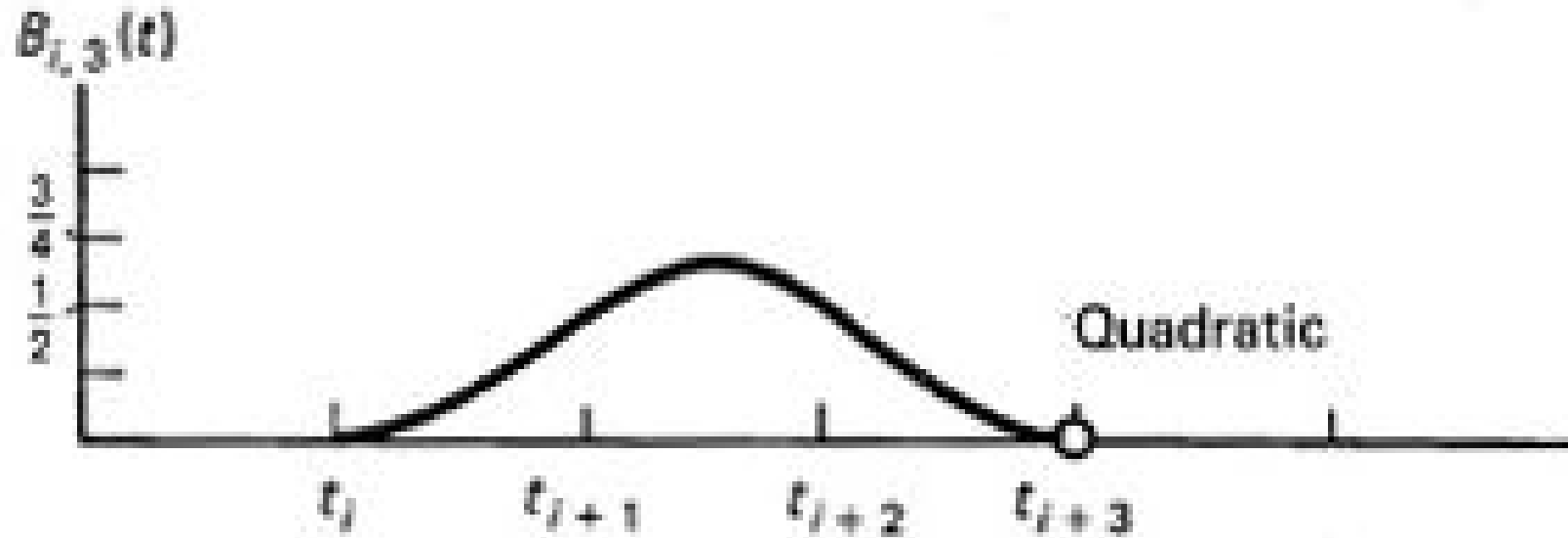
$$B_{i,1}(t) = \begin{cases} 1, & t_i \leq t < t_{i+1} \\ 0, & \text{otherwise} \end{cases}$$

$$B_{i,k}(t) = \frac{t - t_i}{t_{i+k-1} - t_i} B_{i,k-1}(t) + \frac{t_{i+k} - t}{t_{i+k-1} - t_i} B_{i+1,k-1}(t)$$

Bspline Basis

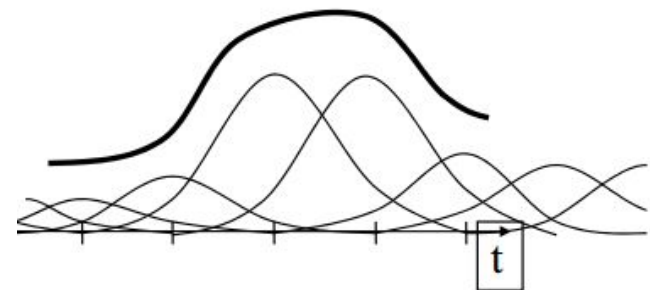
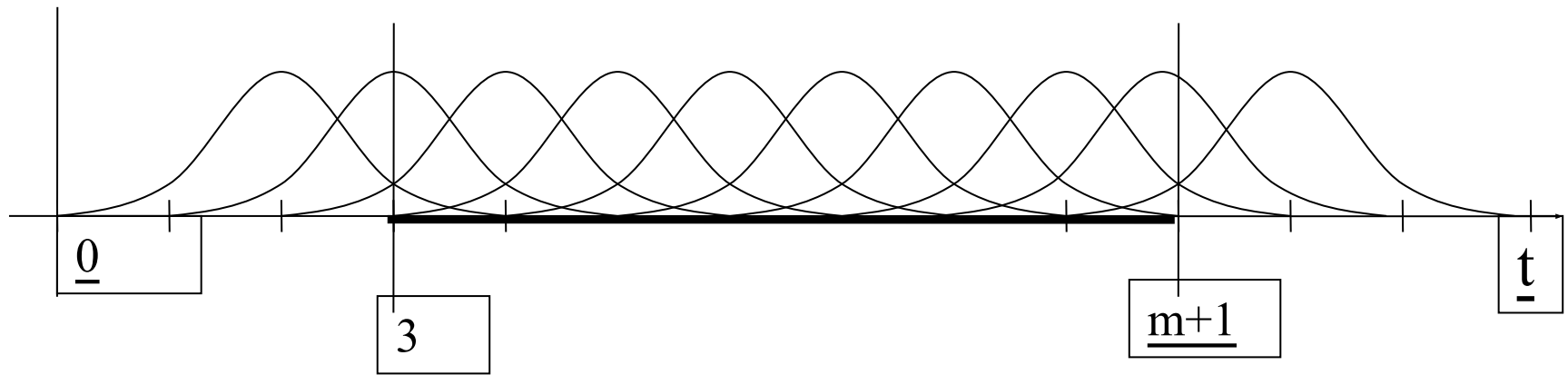


Bspline Basis (2)



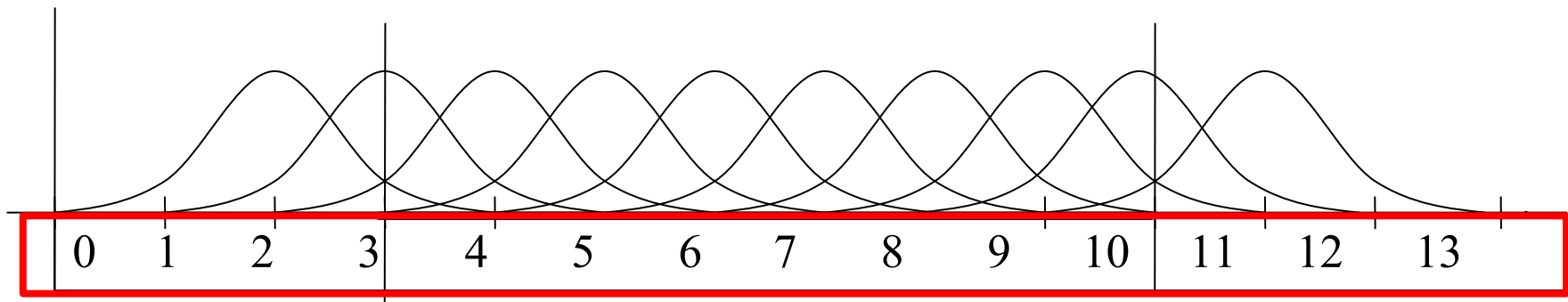
Producing Curves by B-Splines

- The basis functions are multiplied to the control points and to define arbitrary curves



Knots

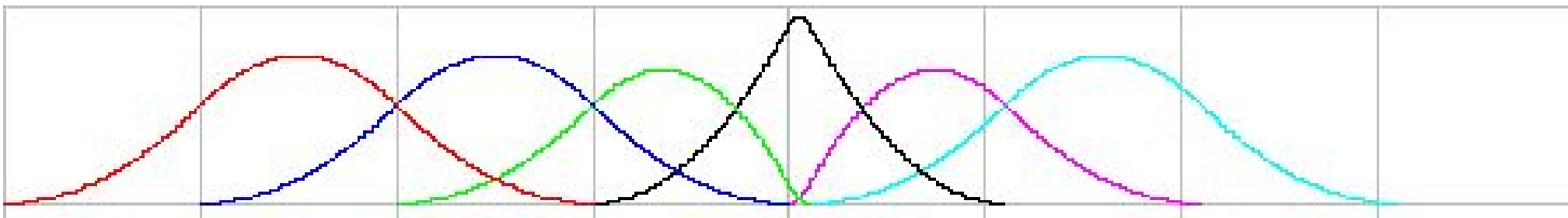
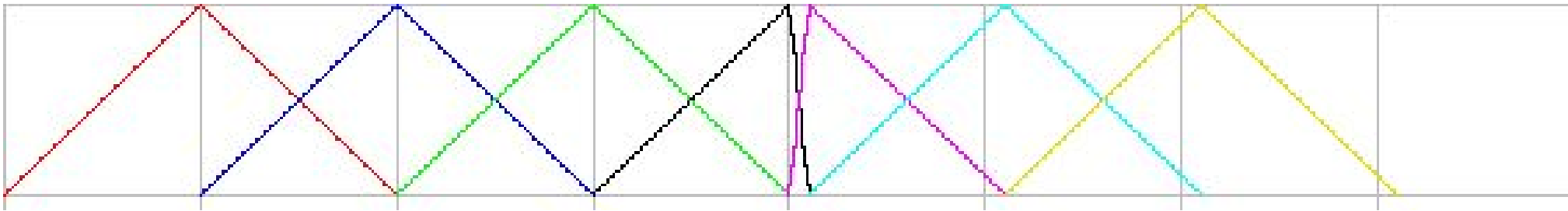
- The knots produce a vector that defines the domain of the curve
- The knots must be in the increasing order
- But not necessarily uniform
- If uniformly sampled and the degree is 3
→ uniform cubic bspline



knots

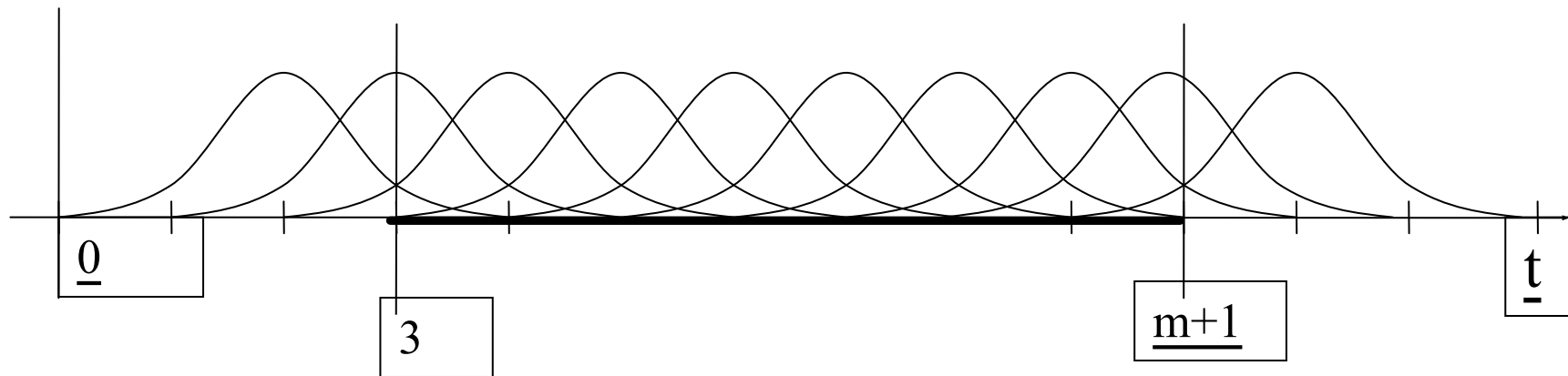
Knots

Here is an example of non-uniform knots



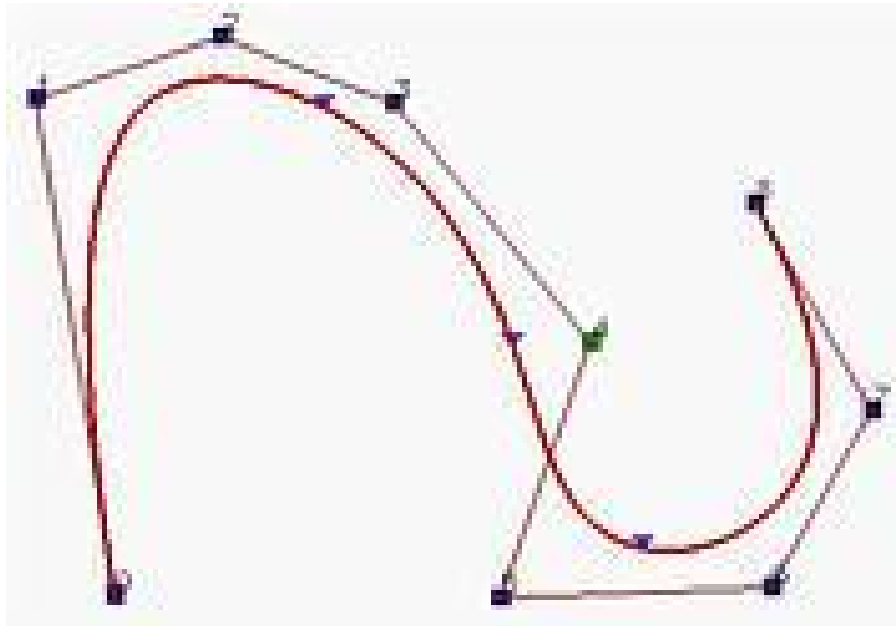
Some Terms

- Order k : the number of control points that affect the sampled value
- Degree $k-1$ (the basis functions are polynomials of degree $k-1$)
- Control points P_i ($i=0, \dots, m$)
- Knots : t_j , ($j=0, \dots, n$)
- An important rule : $n - m = k$
- The domain of function $t_{k-1} \leq t \leq t_{m+1}$
 - Below, $k = 4$, $m = 9$, domain, $t_3 \leq t \leq t_{10}$



Clamped Bsplines

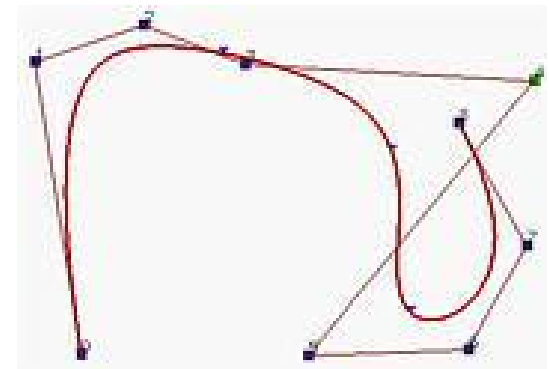
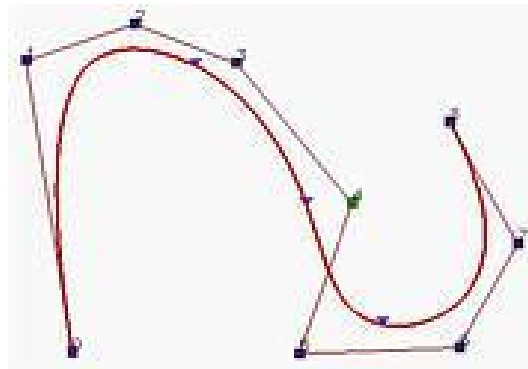
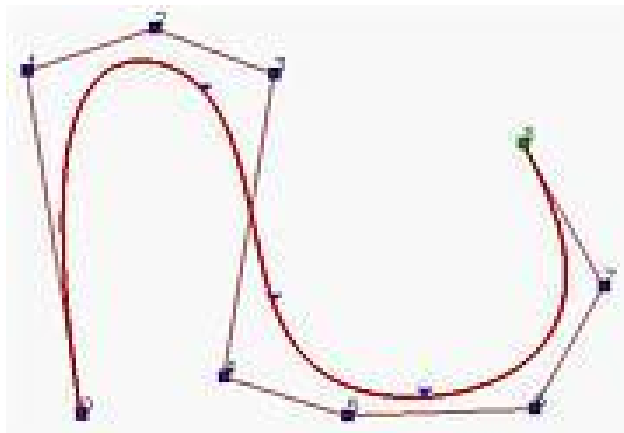
- The first and last knot values are repeated with multiplicity equal to the order (= degree + 1)
- The end points pass the control point
- For cubic Bsplines, the multiplicity of the first / last knots must be 4 (repeated four times)



Controlling the shape of B-splines

- Moving the control points is the most obvious way to control B-spline curves
- Changing the position of control point \mathbf{P}_i only affects the local region

<http://www.ibiblio.org/e-notes/Splines/basis.html>



Today

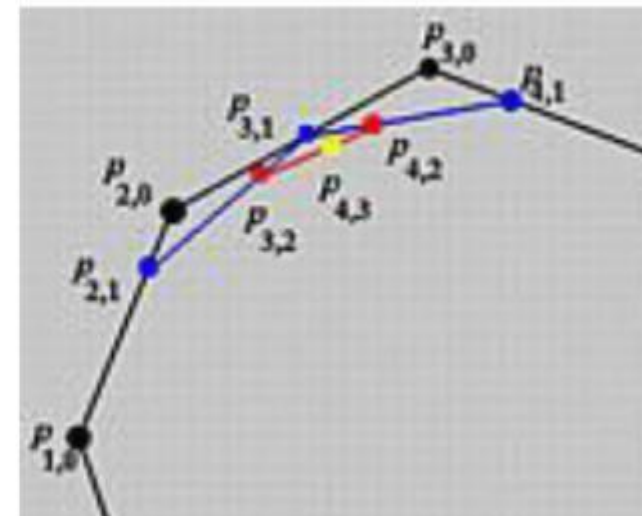
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De Boor's Algorithm

- A B-spline version of the de Casteljau's algo
- A precise method to evaluate the curve
- Starting from the control points P_0, \dots, P_n and parameter value t , recursively solve the following problem

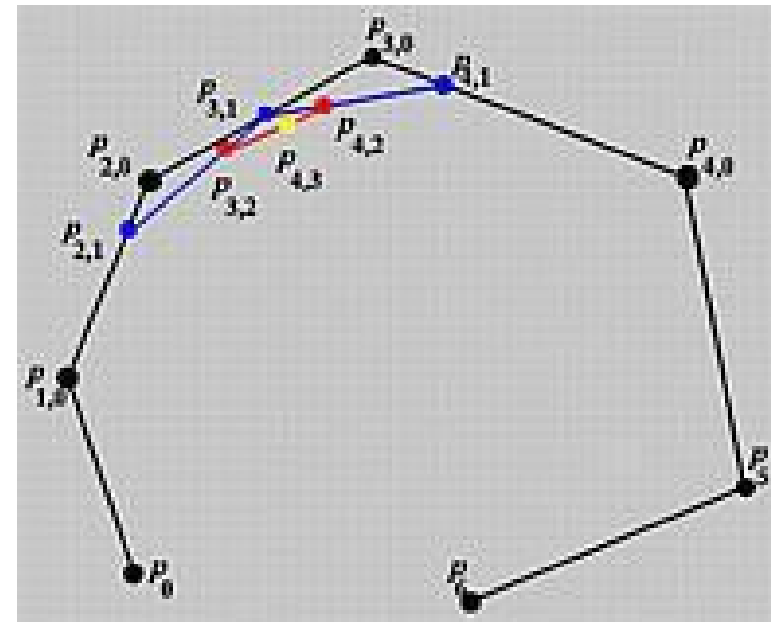
$$\mathbf{P}_i^r = (1 - a_{i,r})\mathbf{P}_{i-1}^{r-1} + a_{i,r}\mathbf{P}_i^{r-1}$$

$$a_{i,r} = \frac{t - t_i}{t_{i+k-1-r} - t_i}$$

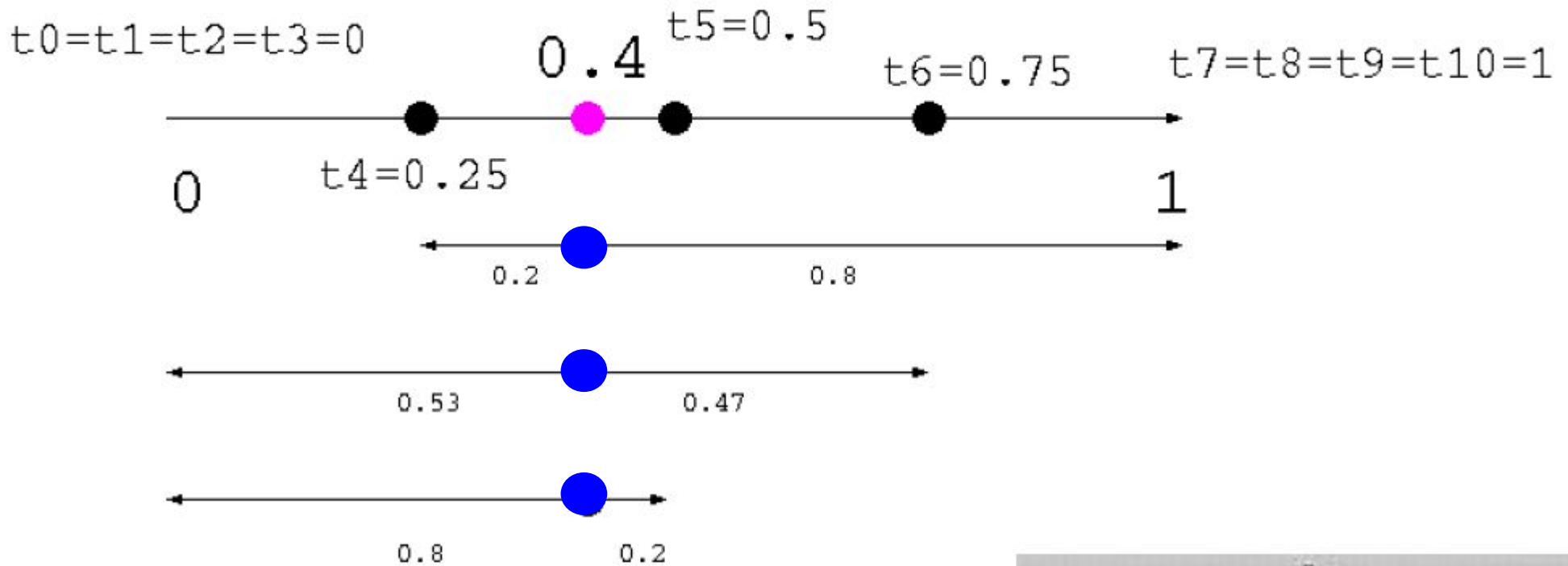


Example

- Assume we have a cubic B-spline whose knot vector is $\{0, 0, 0, 0, 0.25, 0.5, 0.75, 1, 1, 1, 1\}$
- Let's compute a point at $t = 0.4$
- Then, $t_4 < t < t_5$, and the control points that affect the final position are P_4, P_3, P_2, P_1



Example



$$a_{4,1} = (t - t_4) / (t_{4+3} - t_4) = 0.2$$

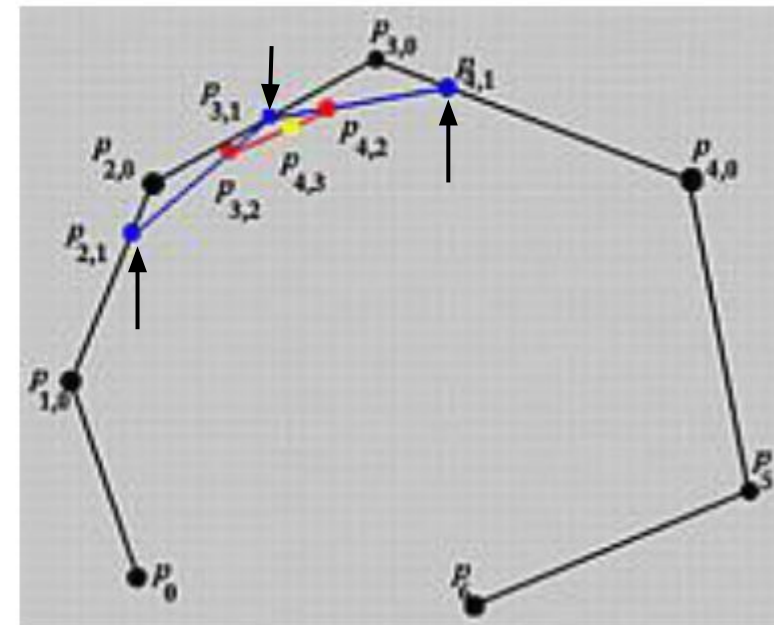
$$a_{3,1} = (t - t_3) / (t_{3+3} - t_3) = 0.53$$

$$a_{2,1} = (t - t_2) / (t_{2+3} - t_2) = 0.8$$

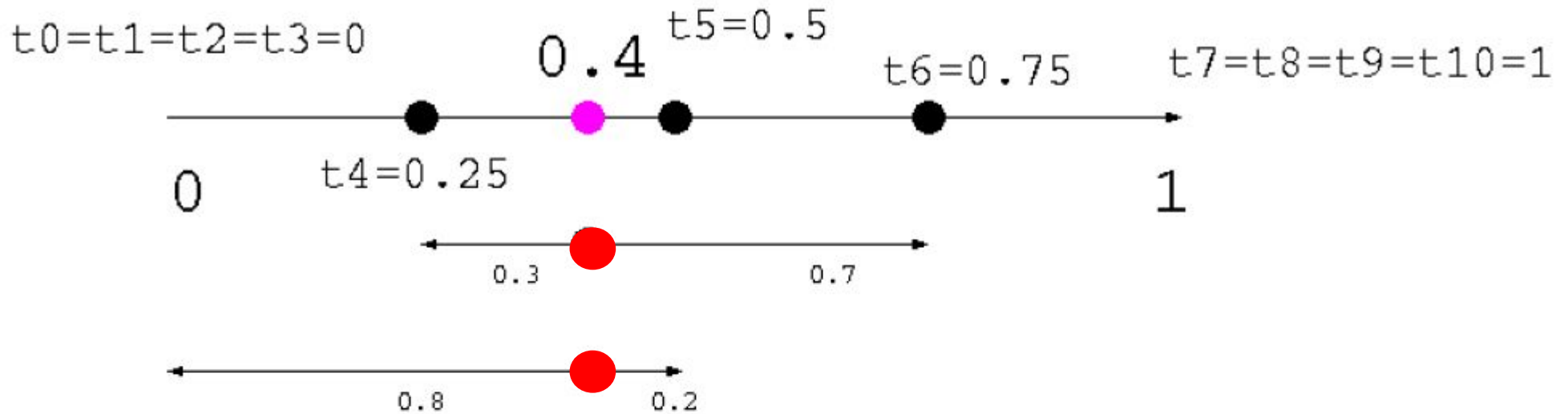
$$\mathbf{P}_{4,1} = (1 - a_{4,1})\mathbf{P}_{3,0} + a_{4,1}\mathbf{P}_{4,0}$$

$$\mathbf{P}_{3,1} = (1 - a_{3,1})\mathbf{P}_{2,0} + a_{3,1}\mathbf{P}_{3,0}$$

$$\mathbf{P}_{2,1} = (1 - a_{2,1})\mathbf{P}_{1,0} + a_{2,1}\mathbf{P}_{2,0}$$



Example

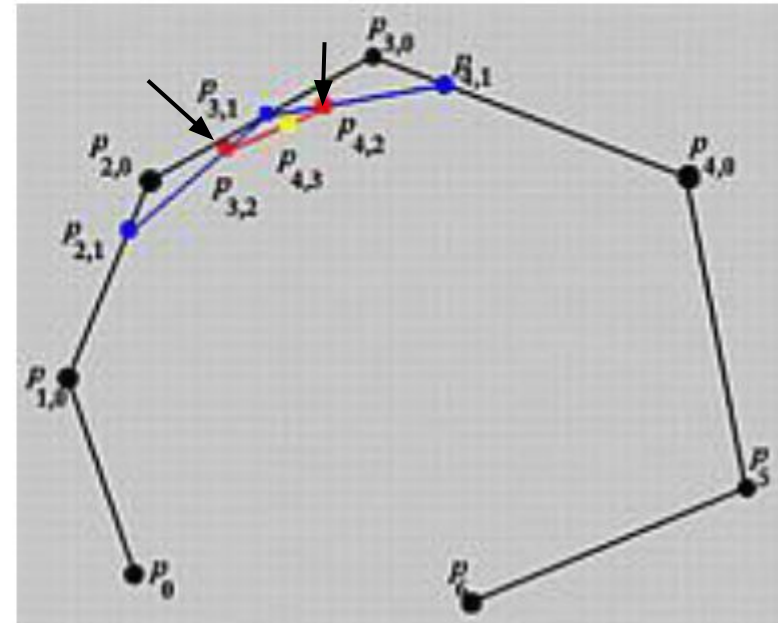


$$a_{4,2} = (t - t_4) / (t_{4+3-1} - t_4) = 0.3$$

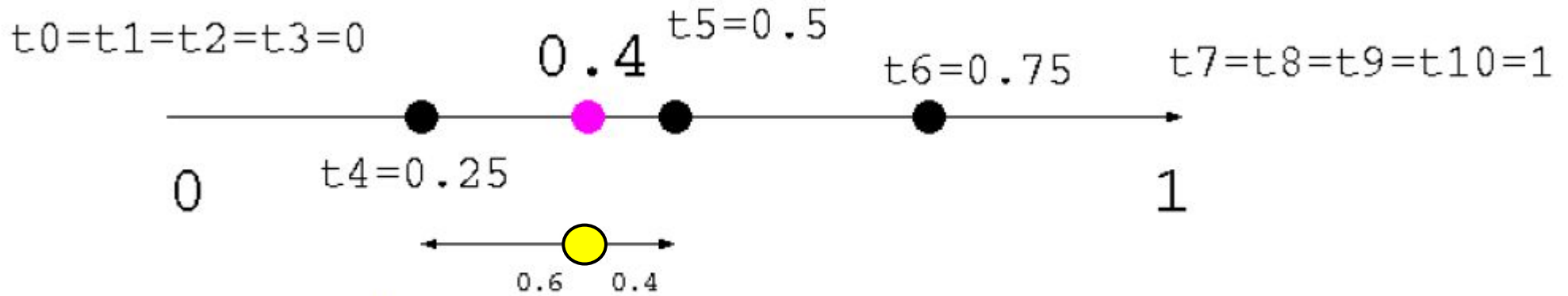
$$a_{3,2} = (t - t_3) / (t_{3+3-1} - t_3) = 0.8$$

$$\mathbf{P}_{4,2} = (1 - a_{4,2})\mathbf{P}_{3,1} + a_{4,2}\mathbf{P}_{4,1}$$

$$\mathbf{P}_{3,2} = (1 - a_{3,2})\mathbf{P}_{2,1} + a_{3,2}\mathbf{P}_{3,1}$$



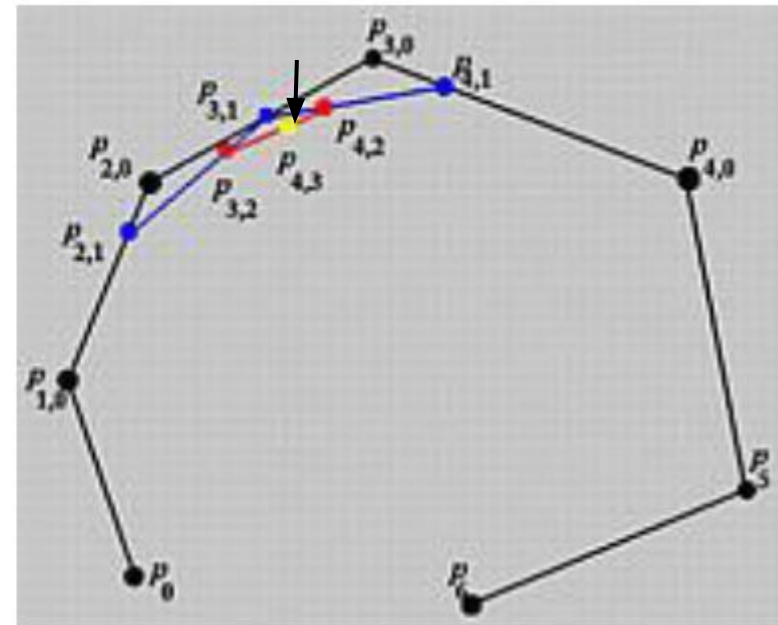
Example



$$a_{4,3} = (u - u_4) / (u_{4+3-2} - u_4) = 0.6$$

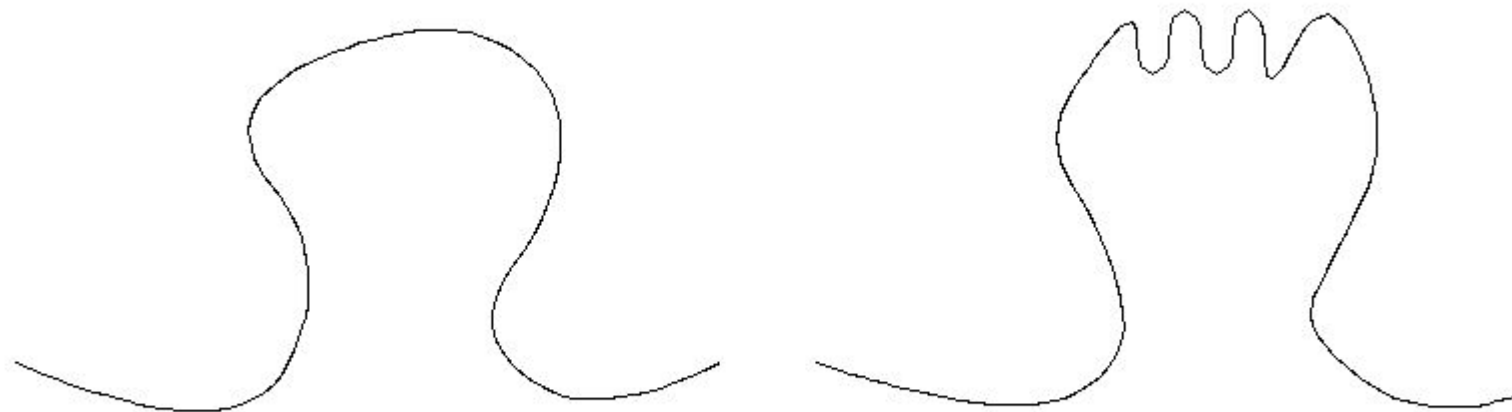
$$\mathbf{P}_{4,3} = (1 - a_{4,3})\mathbf{P}_{3,2} + a_{4,2}\mathbf{P}_{4,2}$$

$$= 0.4\mathbf{P}_{3,2} + 0.6\mathbf{P}_{4,2}$$



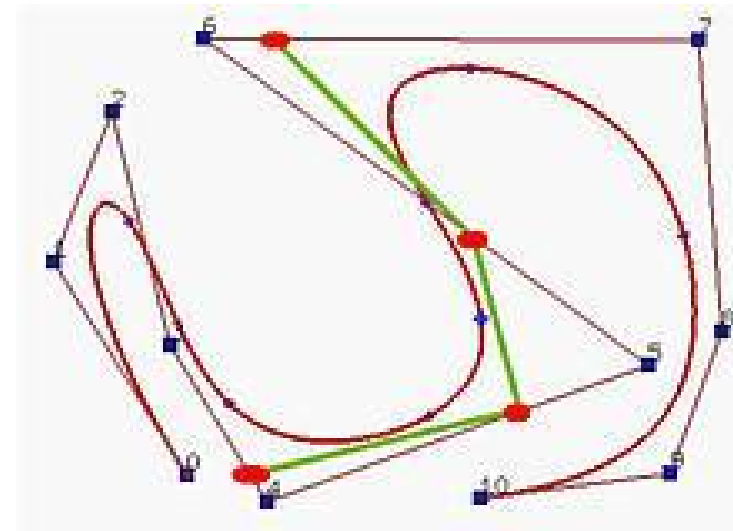
What if you want to edit some details?

- You might want to add some high resolution details at a particular area while keeping the rest the same



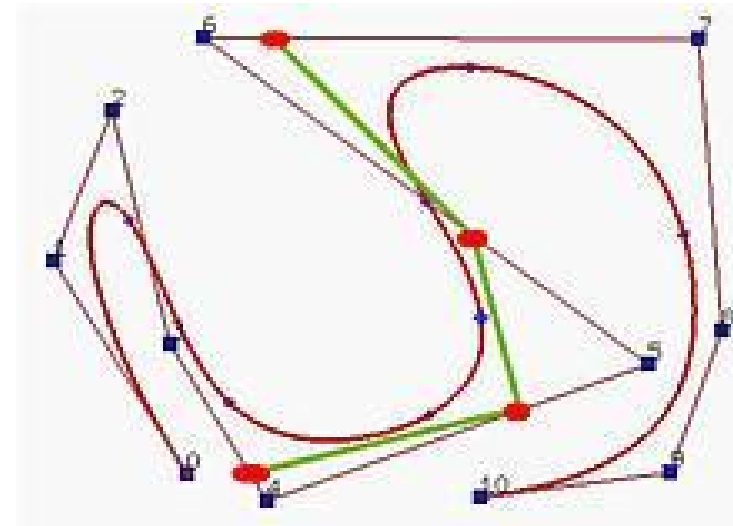
Knot insertion

- We can do this by knot Insertion
 - increase the resolution for some area
- New knots and control points can be added without changing the shape of the curve
- Both the knots and control points are going to increase



Knot insertion

- For a curve of degree f , we remove $f-1$ points and add f points
- i.e., for a cubic B-spline, remove 2 points and add 3 points



Knot insertion

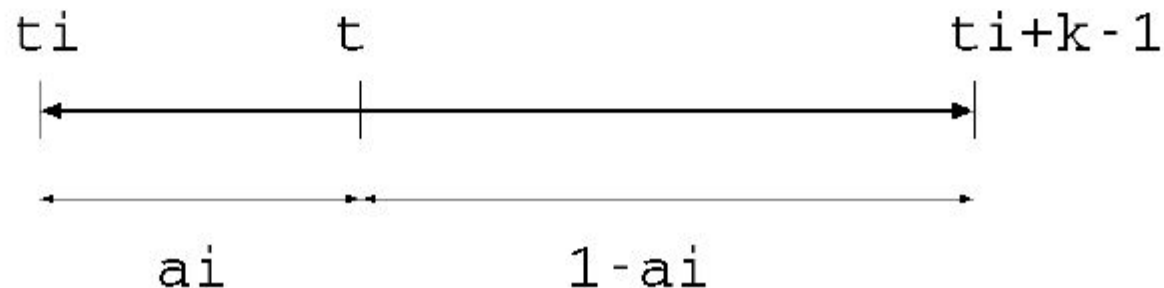
- If the new knot t is inserted into the span $[t_j, t_{j+1})$, the new control points can be computed by

$$\mathbf{Q}_i = (1 - a_i)\mathbf{P}_{i-1} + a_i\mathbf{P}_i$$

where \mathbf{Q}_i is the new control point and a_i is computed by

$$a_i = \frac{t - t_i}{t_{i+k-1} - t_i} \quad \text{for } j-k+2 \leq i \leq j$$

The polyline $\mathbf{P}_{j-k+1}, \mathbf{P}_{j-k+2}, \dots, \mathbf{P}_{j-1}, \mathbf{P}_j$ is replaced with $\mathbf{P}_{j-k+1}, \mathbf{Q}_{j-k+2}, \dots, \mathbf{Q}_{j-1}, \mathbf{Q}_j, \mathbf{P}_j$.

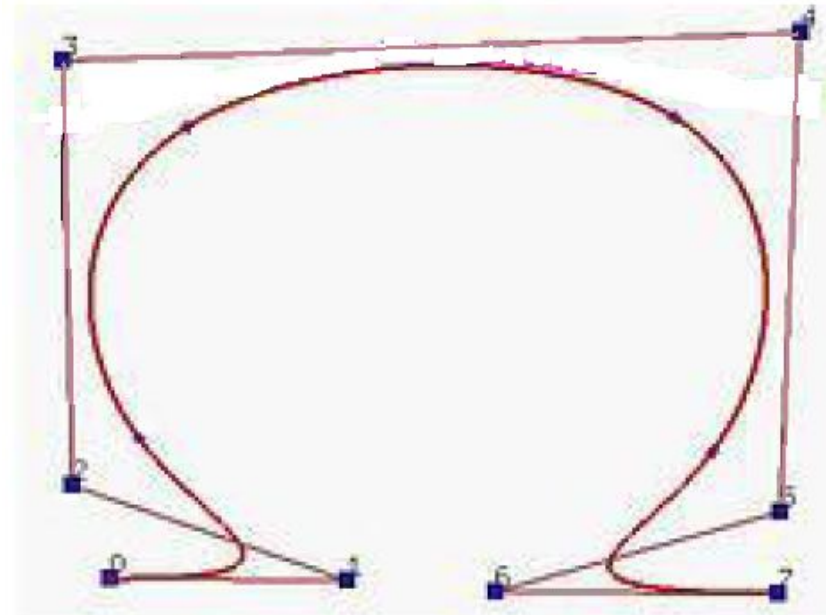


Example

- A Bspline curve of degree 3 ($k=4$) having the following knots
- $t=0.5$ inserted

t_0 to t_3	t_4	t_5	t_6	t_7	t_8 to t_{11}
0	0.2	0.4	0.6	0.8	1

t_0 to t_3	t_4	t_5	t_6	t_7	t_8	t_9 to t_{12}
0	0.2	0.4	0.5	0.6	0.8	1



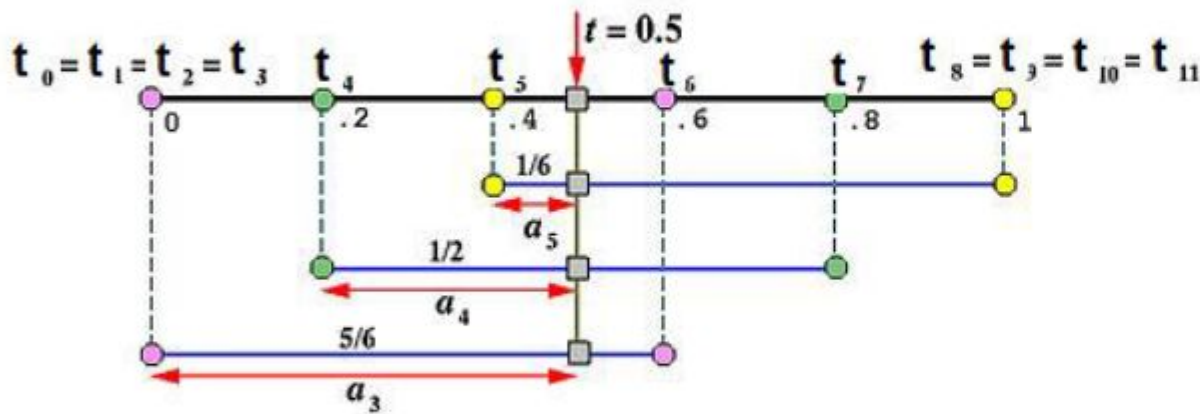
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0	0.2	0.4	0.6	0.8	1

- $t=0.5$ inserted

t_0 to t_3	t_4	t_5	t_6	t_7	t_8	t_9 to t_{12}
0	0.2	0.4	0.5	0.6	0.8	1



$$a_5 = \frac{t - t_5}{t_8 - t_5} = \frac{0.5 - 0.4}{1 - 0.4} = \frac{1}{6}$$

$$a_4 = \frac{t - t_4}{t_7 - t_4} = \frac{0.5 - 0.2}{0.8 - 0.2} = \frac{1}{2}$$

$$a_3 = \frac{t - t_3}{t_6 - t_3} = \frac{0.5 - 0}{0.6 - 0} = \frac{5}{6}$$

Example

<http://geom.ibds.kit.edu/applets/mocca/html/noplugin/IntBSpline/AppInsertion/index.html>

- A bspline curve of degree 3 ($k=4$) having the following knots

t_0 to t_3	t_4	t_5	t_6	t_7	t_8 to t_{11}
0	0.2	0.4	0.6	0.8	1

- $t=0.5$ inserted

t_0 to t_3	t_4	t_5	t_6	t_7	t_8	t_9 to t_{12}
0	0.2	0.4	0.5	0.6	0.8	1

$$a_5 = \frac{t - t_5}{t_8 - t_5} = \frac{0.5 - 0.4}{1 - 0.4} = \frac{1}{6}$$

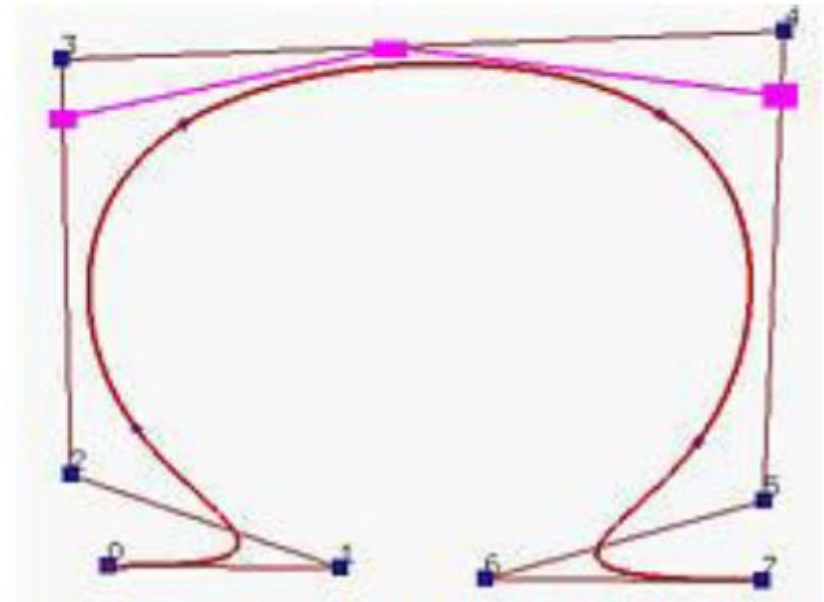
$$a_4 = \frac{t - t_4}{t_7 - t_4} = \frac{0.5 - 0.2}{0.8 - 0.2} = \frac{1}{2}$$

$$a_3 = \frac{t - t_3}{t_6 - t_3} = \frac{0.5 - 0}{0.6 - 0} = \frac{5}{6}$$

$$Q_5 = \left(1 - \frac{1}{6}P_4\right) + \frac{1}{6}P_5$$

$$Q_4 = \left(1 - \frac{1}{2}P_3\right) + \frac{1}{2}P_4$$

$$Q_3 = \left(1 - \frac{5}{6}P_2\right) + \frac{5}{6}P_3$$



Summary of B-splines

- Knot vector defines the domain
- Evaluation by de Boor's algorithm
- Controlling the shape by the control points
- Clamping the points by increasing the multiplicity of the knots at the end points
- Increase the resolution by knot insertion

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- **NURBS**
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NURBS (Non-uniform rational B-spline)

- Standard curves/surface representation in computer aided design

$$C(t) = \frac{\sum_{i=0}^n B_{i,k}(t) w_i \mathbf{P}_i}{\sum_{i=0}^n B_{i,k}(t) w_i}$$

\mathbf{P}_i : control points

$B_{i,k}$: Bspline basis of order k

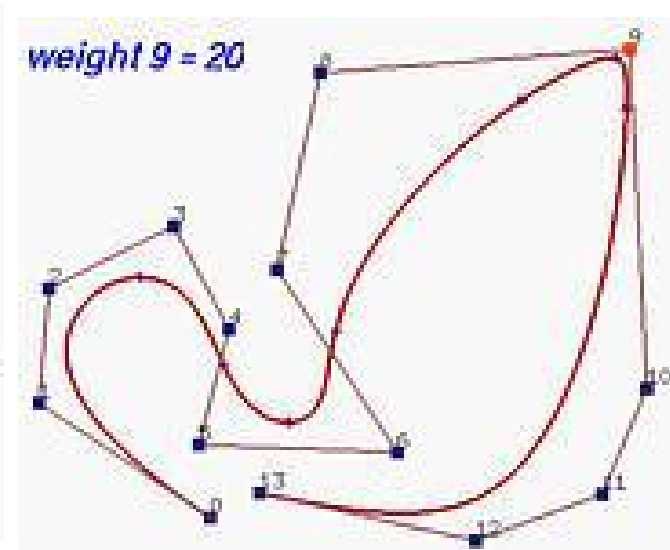
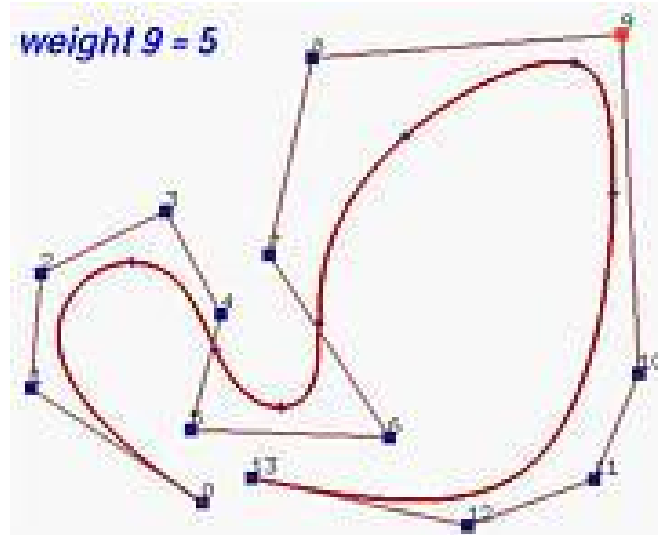
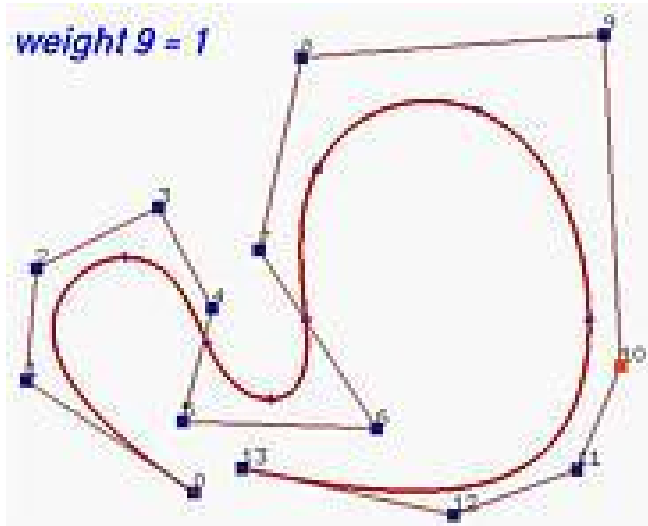
w_i : weights

Benefits of using NURBS

- More degrees of freedom to control the curve (can control the weights)
- Invariant under perspective transformation
 - Can project the control points onto the screen and draw the NURBS on the screen
 - Don't need to apply the perspective transformation to all the sample-points on the curve
- Can model conic sections such as circles, ellipses and hyperbolas

Example of changing weights

- Increasing the weight will bring the curve closer to the corresponding control point

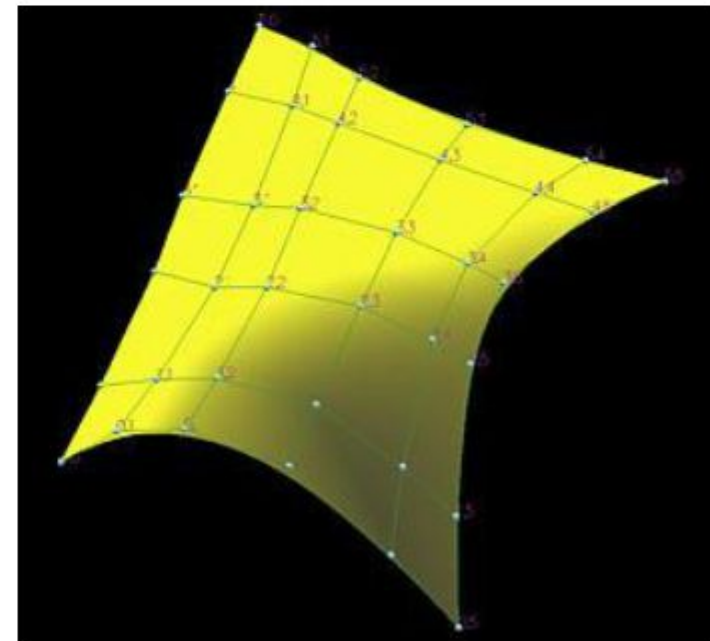


Bspline Surfaces

- Given the following information:
- a set of $m+1$ rows and $n+1$ control points $\mathbf{p}_{i,j}$, where $0 \leq i \leq m$ and $0 \leq j \leq n$;
- Corresponding knot vectors in the u and v direction,

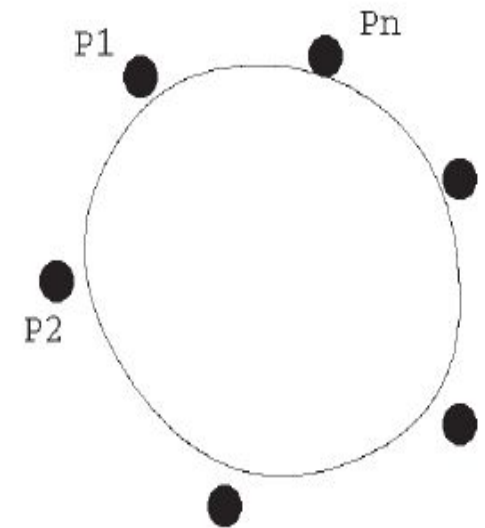
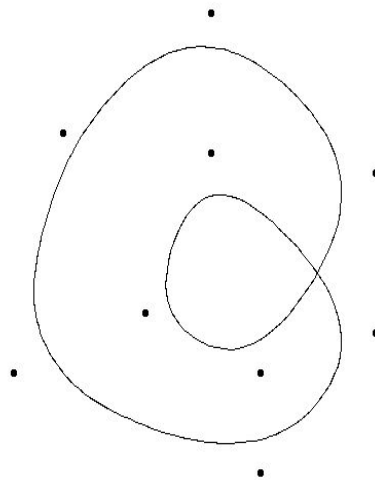
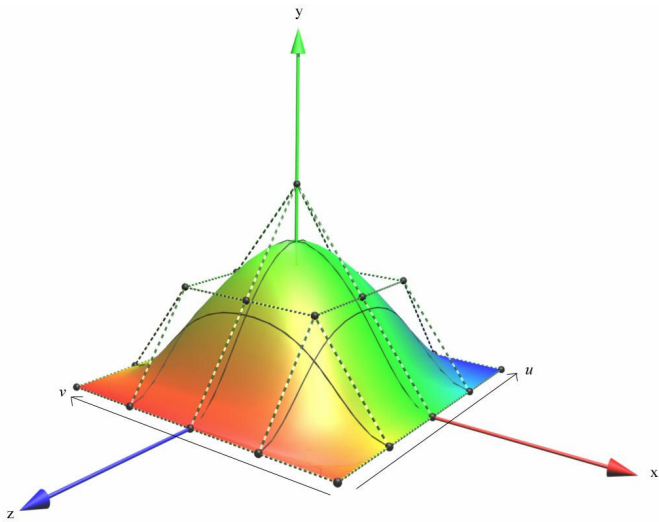
$$p(u, v) = \sum_{i=0}^m \sum_{j=0}^n B_{i,p}(u) B_{j,q}(v) \mathbf{P}_{i,j} : \text{non-rational B-spline}$$

$$p(u, v) = \frac{\sum_{i=0}^m \sum_{j=0}^n w_{i,j} B_{i,p}(u) B_{j,q}(v) \mathbf{P}_{i,j}}{\sum_{i=0}^m \sum_{j=0}^n w_{i,j} B_{i,p}(u) B_{j,q}(v)} : \text{NURBS}$$



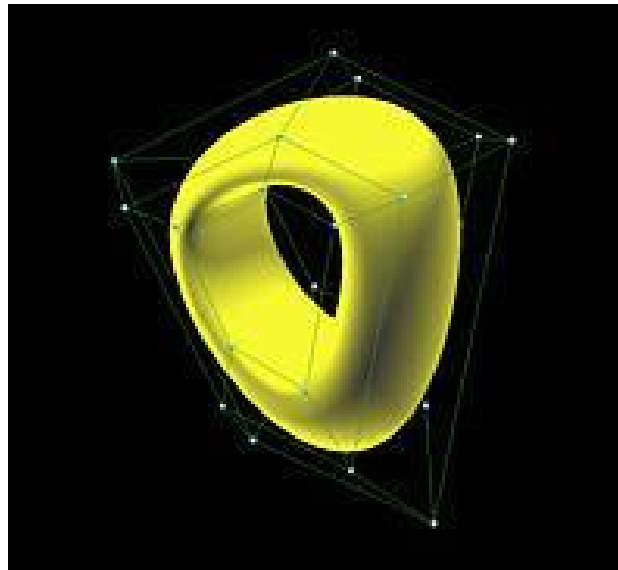
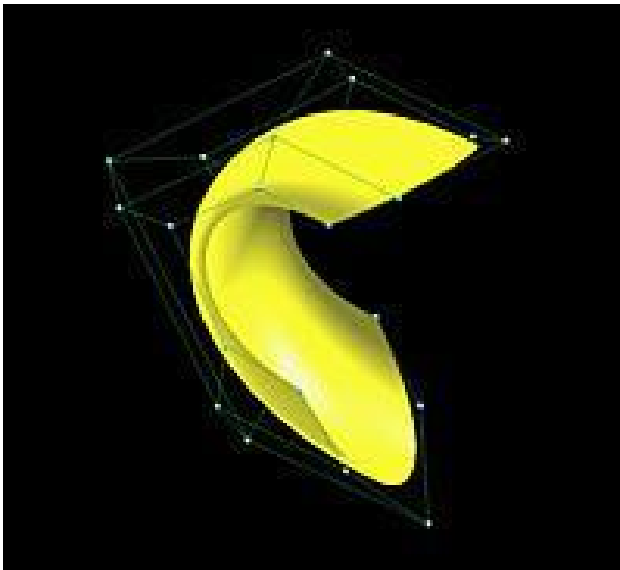
Clamping, Closing B-spline Surfaces

- The B-spline surfaces can be clamped by repeating the same knot values in one direction of the parameters (u or v)
- We can also close the curve / surface by recycling the control points



Closed B-spline Surfaces

- If a B-spline surface is closed in one direction, then the surface becomes a tube.
- Closed in two direction : torus
 - Problems handling objects of arbitrary topology, such as a ball, double torus



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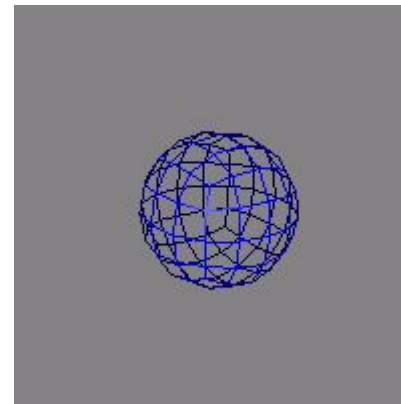
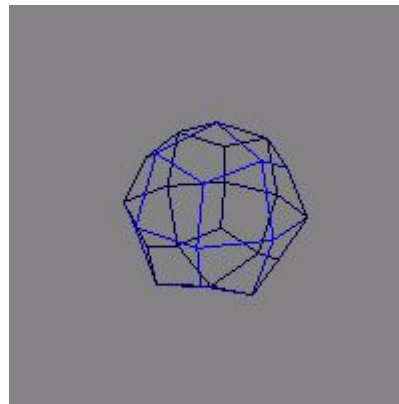
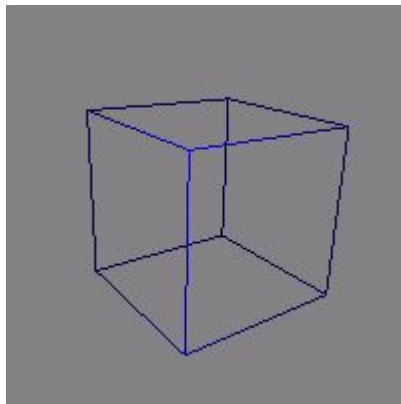
Subdivision Surface



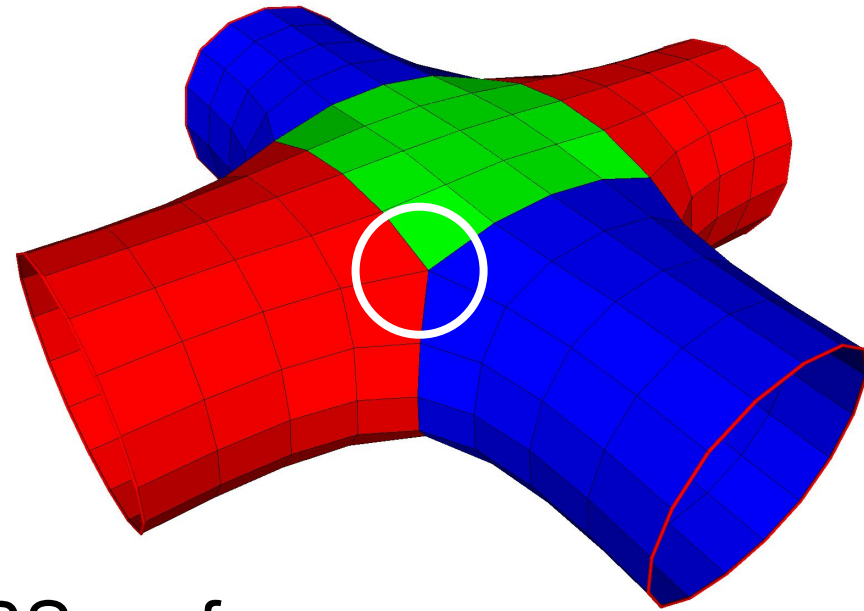
- A method to model smooth surfaces

3D subdivision surface

- Giving a rough shape first and subdivide it recursively
- Stop when the shape is smooth enough
- Used for modeling smooth surfaces



Motivation



- Shape modelling

- Topological restrictions of NURBS surfaces

- Plane, Cylinder, and Torus

- It is difficult to maintain smoothness at seams of patchwork.

- Example: hiding seams in Woody (*Toy Story*) [DeRose98]

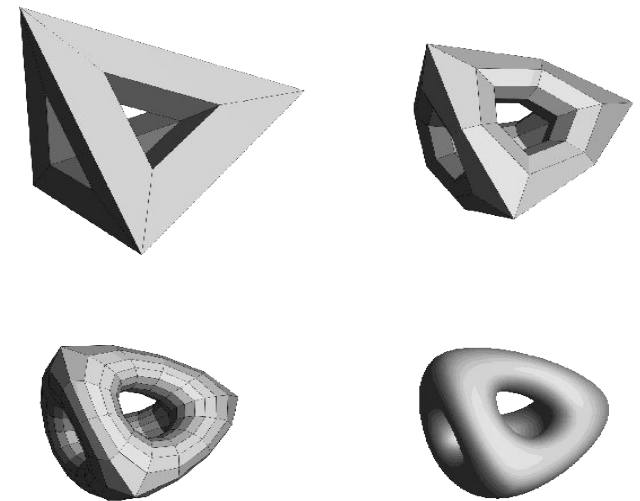
- NURBS also require the control nets consist of a regular rectangular grid of control points

- LOD in a scene

- A coarse shape when far away, a smooth dense surface when closer to the camera

Subdivision surface

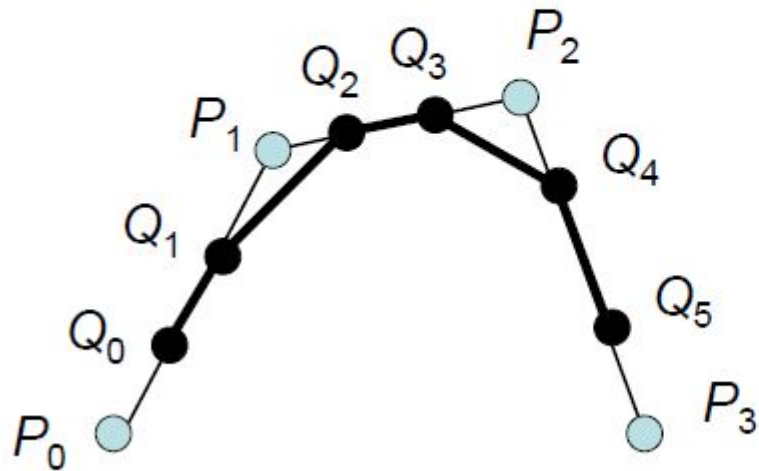
- Can handle arbitrary topology



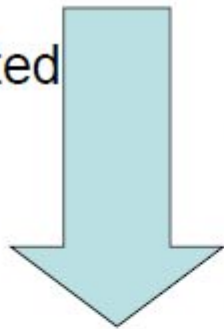
Different Schemes

- Doo-Sabin '78
- Catmull-Clark '78
- Etc (Loop, Butterfly, and many others)

A Primer: Chaiken's Algorithm

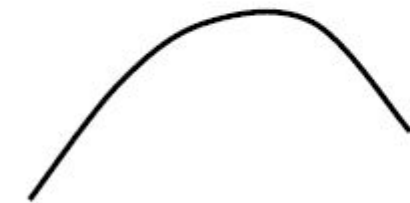


Apply Iterated
Function
System



$$Q_i = \frac{3}{4}P_i + \frac{1}{4}P_{i+1}$$

$$Q_{i+1} = \frac{1}{4}P_i + \frac{3}{4}P_{i+1}$$



Limit Curve Surface

$$Q_0 = \frac{3}{4}P_0 + \frac{1}{4}P_1$$

$$Q_1 = \frac{1}{4}P_0 + \frac{3}{4}P_1$$

$$Q_2 = \frac{3}{4}P_1 + \frac{1}{4}P_2$$

$$Q_3 = \frac{1}{4}P_1 + \frac{3}{4}P_2$$

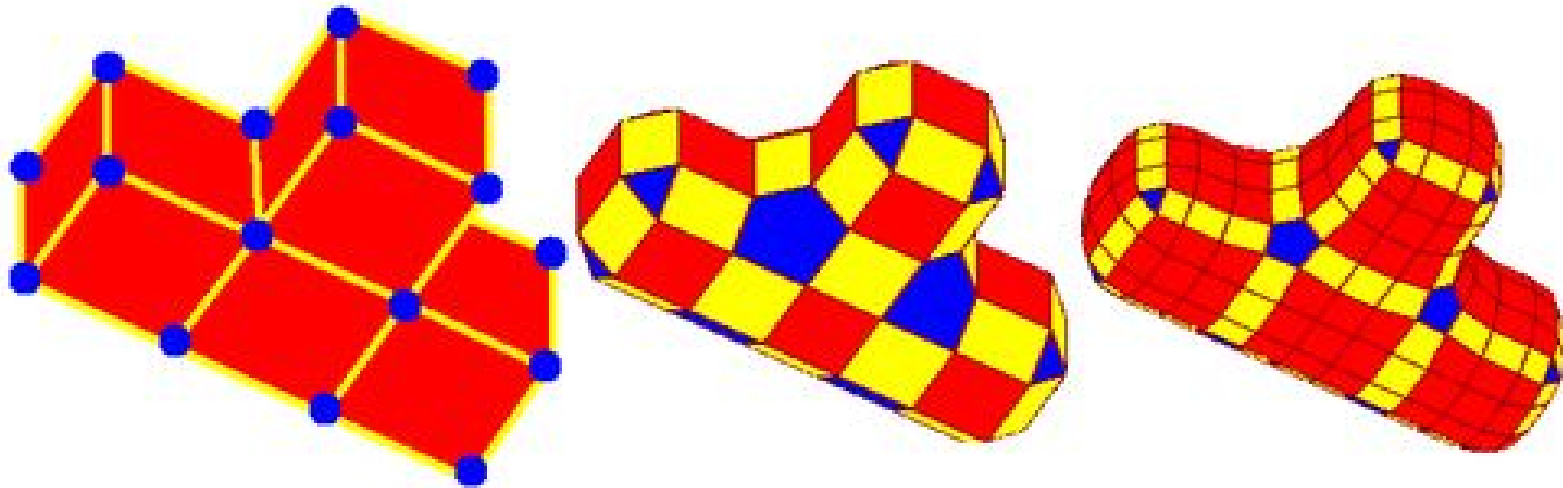
$$Q_4 = \frac{3}{4}P_2 + \frac{1}{4}P_3$$

$$Q_5 = \frac{1}{4}P_2 + \frac{3}{4}P_3$$

<http://www.multires.caltech.edu/teaching/demos/java/chaikin.htm>

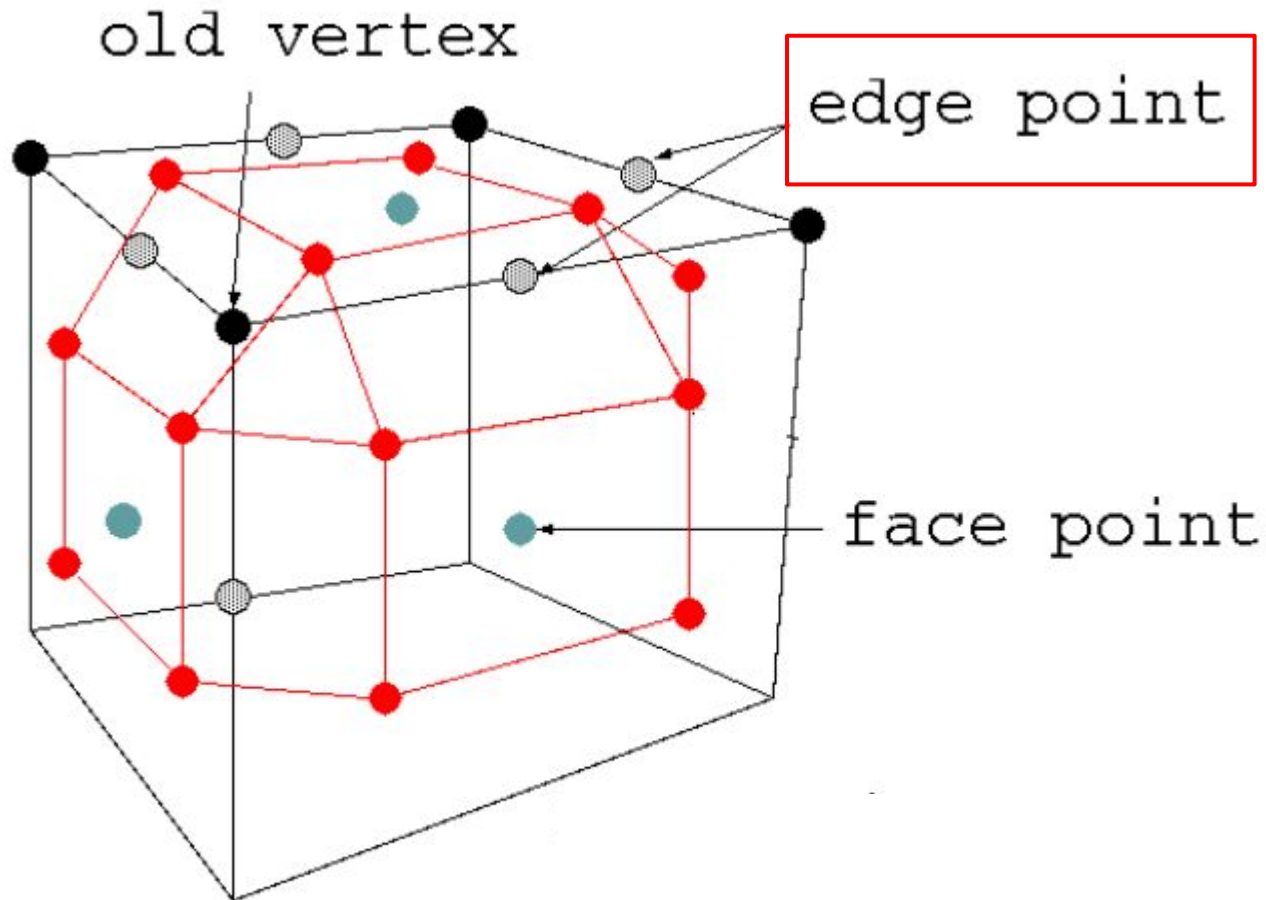
Doo-Sabin Subdivision

- Proposed by Doo and Sabin in 1978
- An extension of Chaiken's algorithm to 3D mesh surfaces



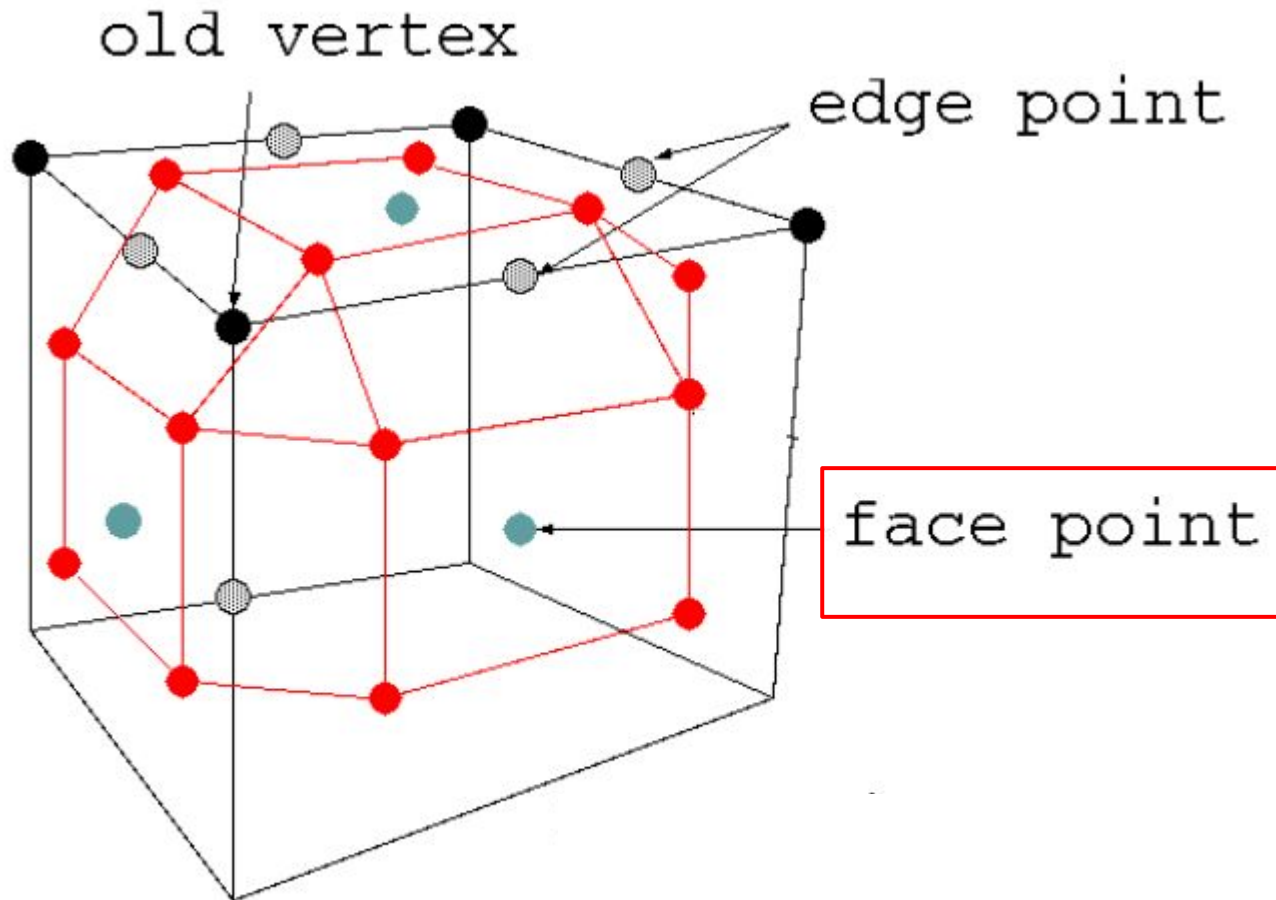
Doo-Sabin Subdivision (2)

- **An *edge point*** is formed from the midpoint of each edge
- A *face point* is formed as the centroid of each polygon of the mesh.



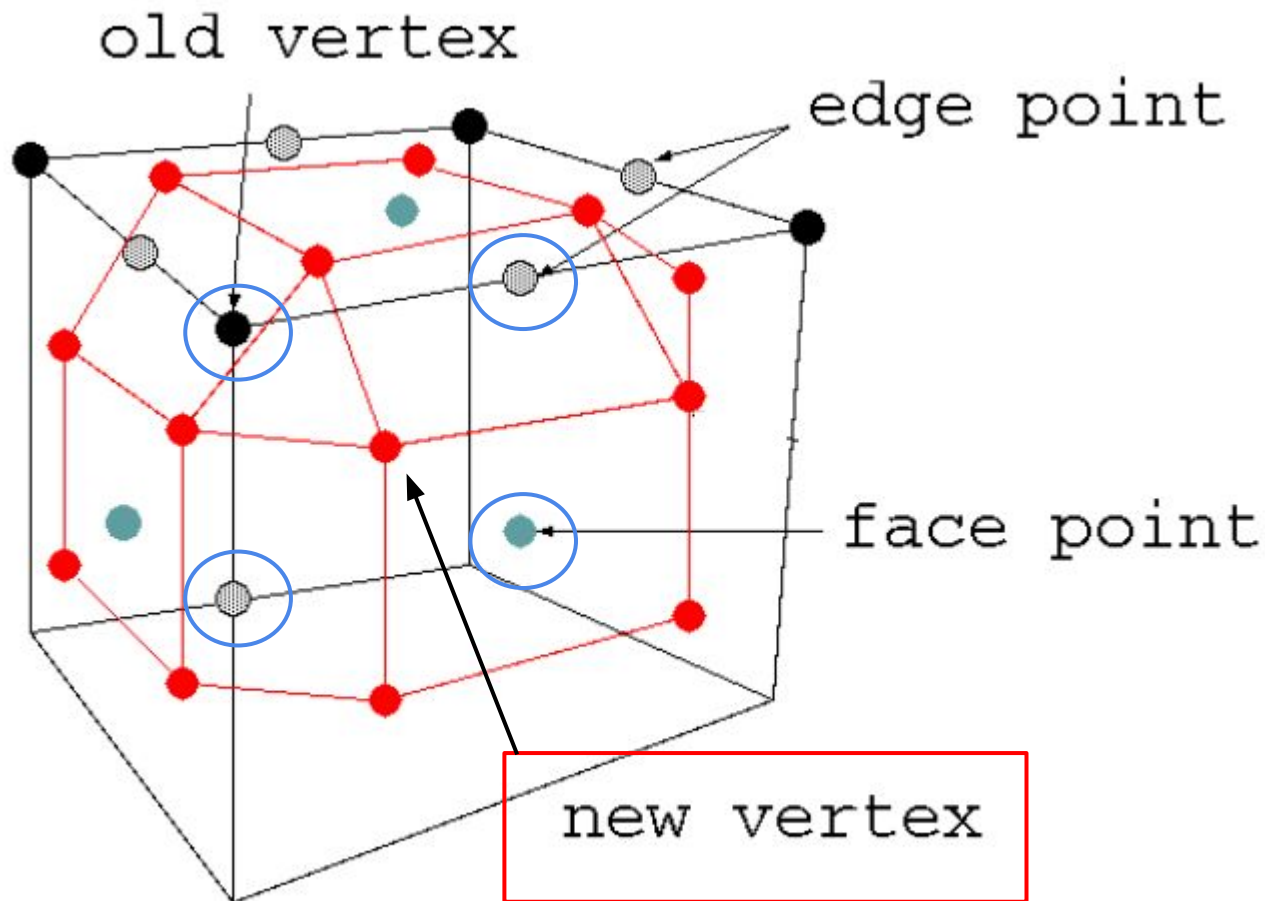
Doo-Sabin Subdivision (2)

- An *edge point* is formed from the midpoint of each edge
- **A *face point* is formed as the centroid of each polygon of the mesh.**

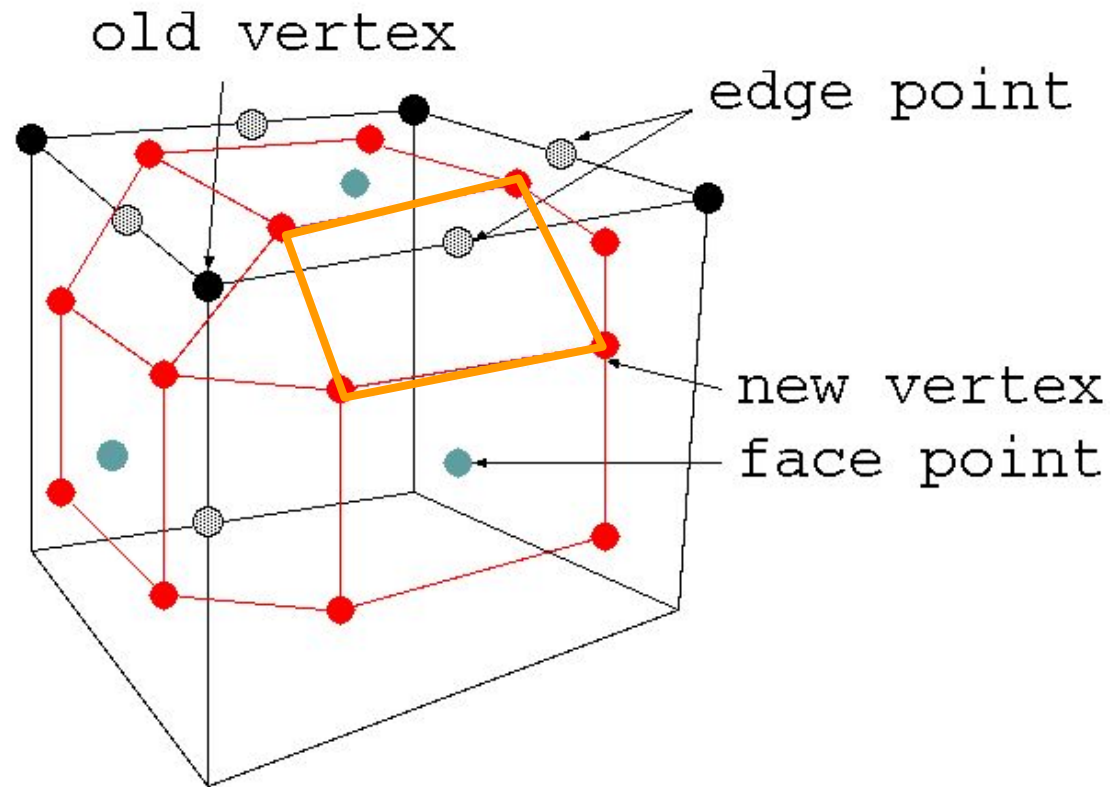


Doo-Sabin Subdivision (2)

- Finally, each vertex in new mesh is formed as average of
 - a vertex in the old mesh,
 - a face point for a polygon that touches that old vertex, and
 - the edge points for the two edges that belong to that polygon and touch that old vertex.



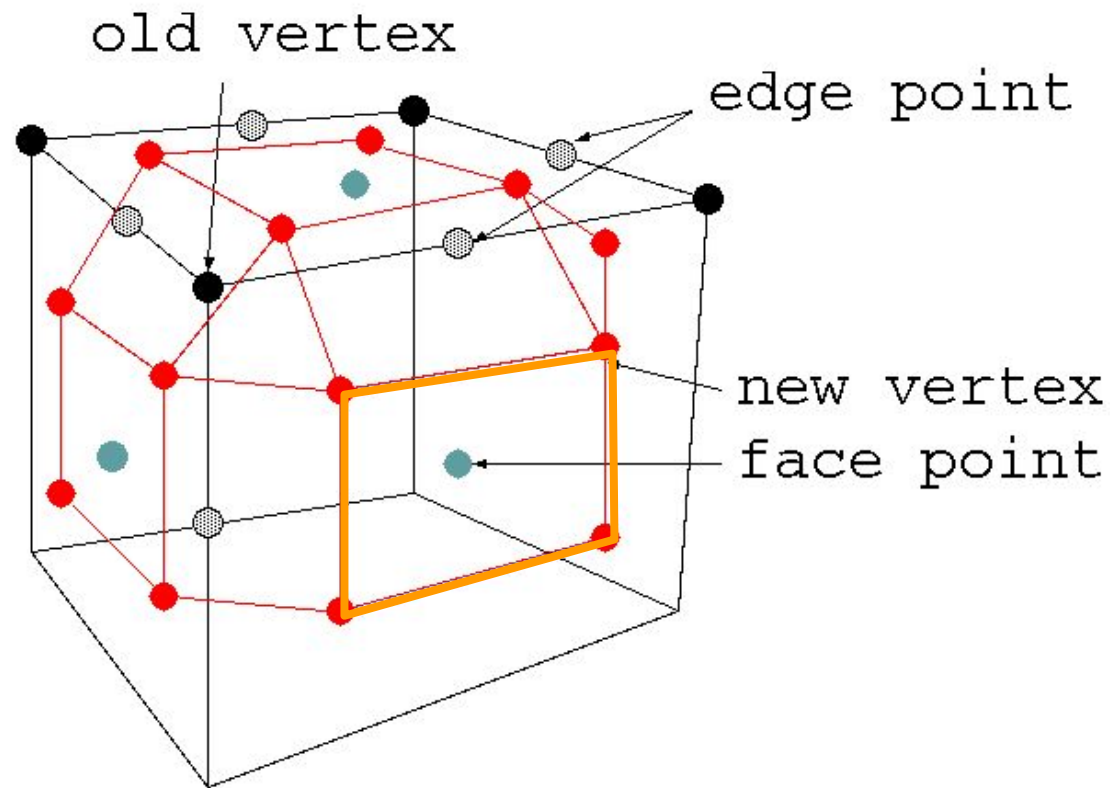
Doo-Sabin Subdivision (3)



The new mesh will be composed of

- **quadrilaterals for each edge in the old mesh,**
- a smaller n-sided polygon for each n-sided polygon in the old mesh, and
- an n-sided polygon for each n-valence vertex (Valence being the number of edges that touch the vertex).

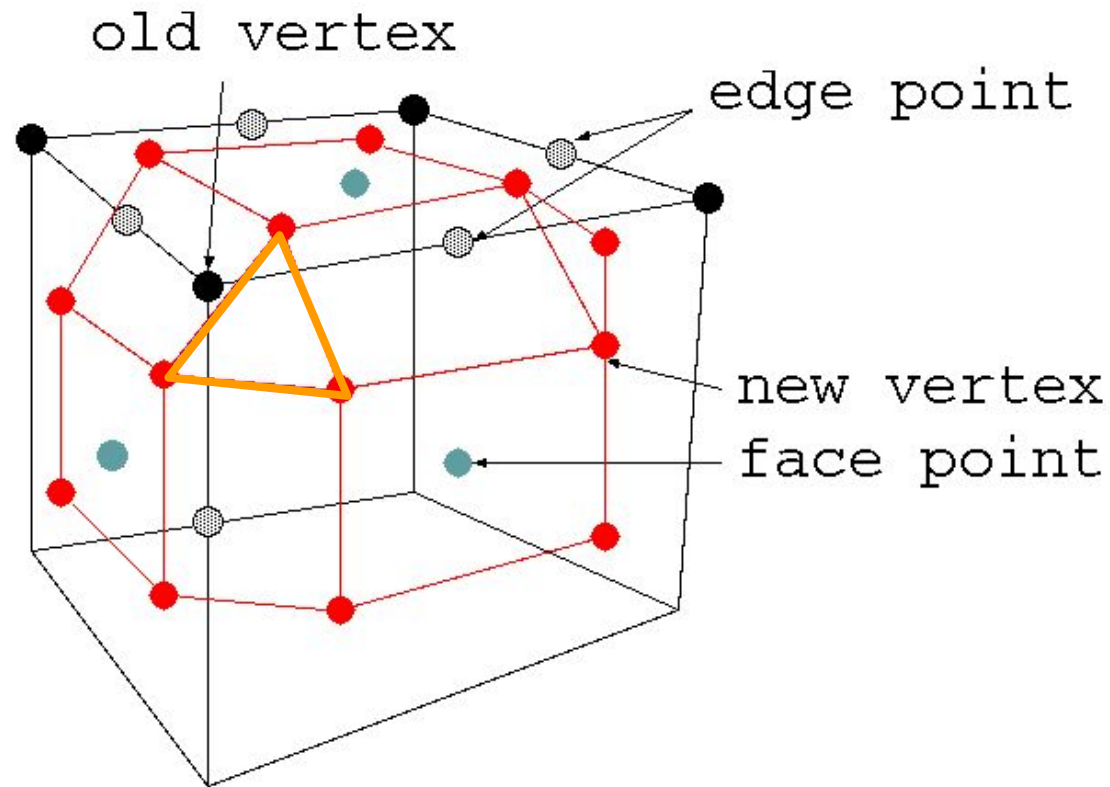
Doo-Sabin Subdivision (3)



The new mesh will be composed of

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Doo-Sabin Subdivision (3)

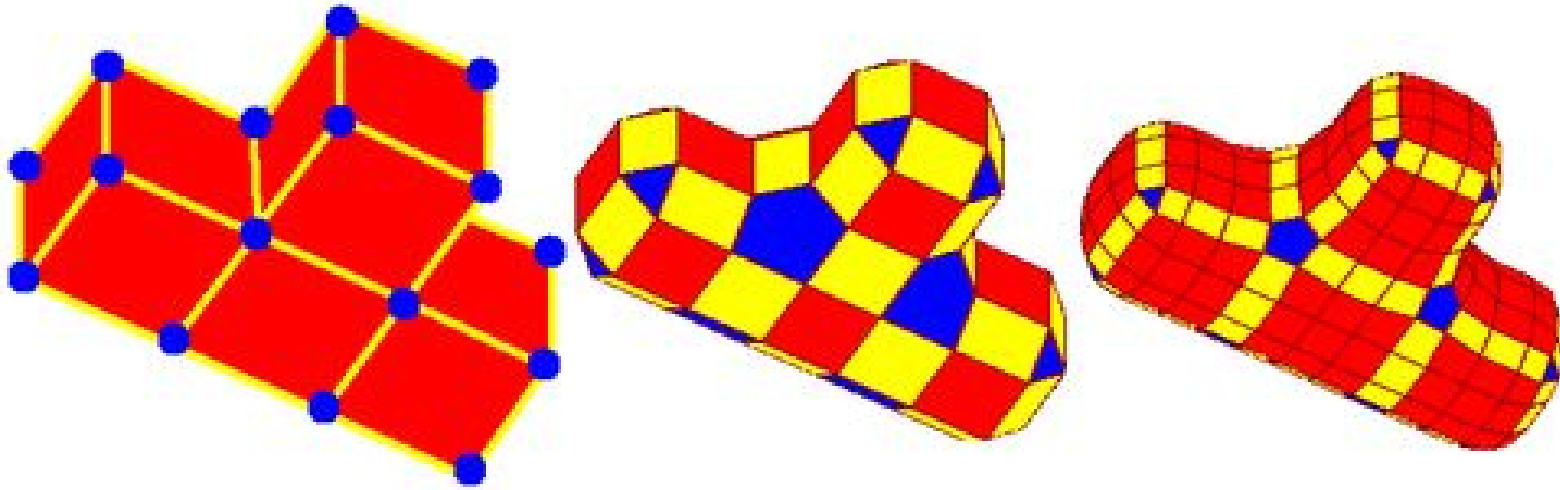


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Doo-Sabin Subdivision

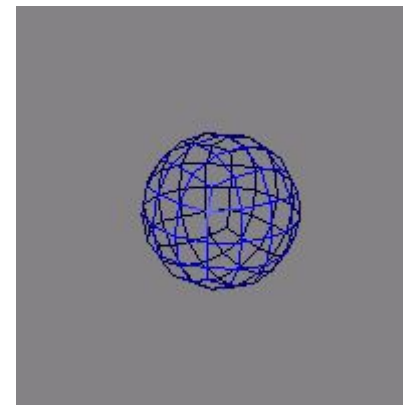
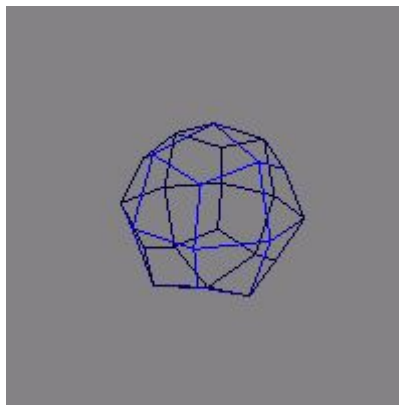
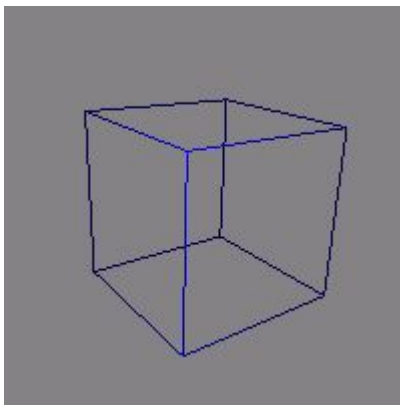
- Proposed by Doo and Sabin in 1978
- An extension of Chaiken's algorithm to 3D mesh surfaces



<http://www.rose-hulman.edu/~finn/CCLI/Applets/DooSabinApplet.html>

Catmull-Clark Subdivision

- A face with n edges are subdivided into n quadrilaterals
- Quads are better than triangles at capturing the symmetries of natural and man-made objects.



Catmull-Clark Subdivision

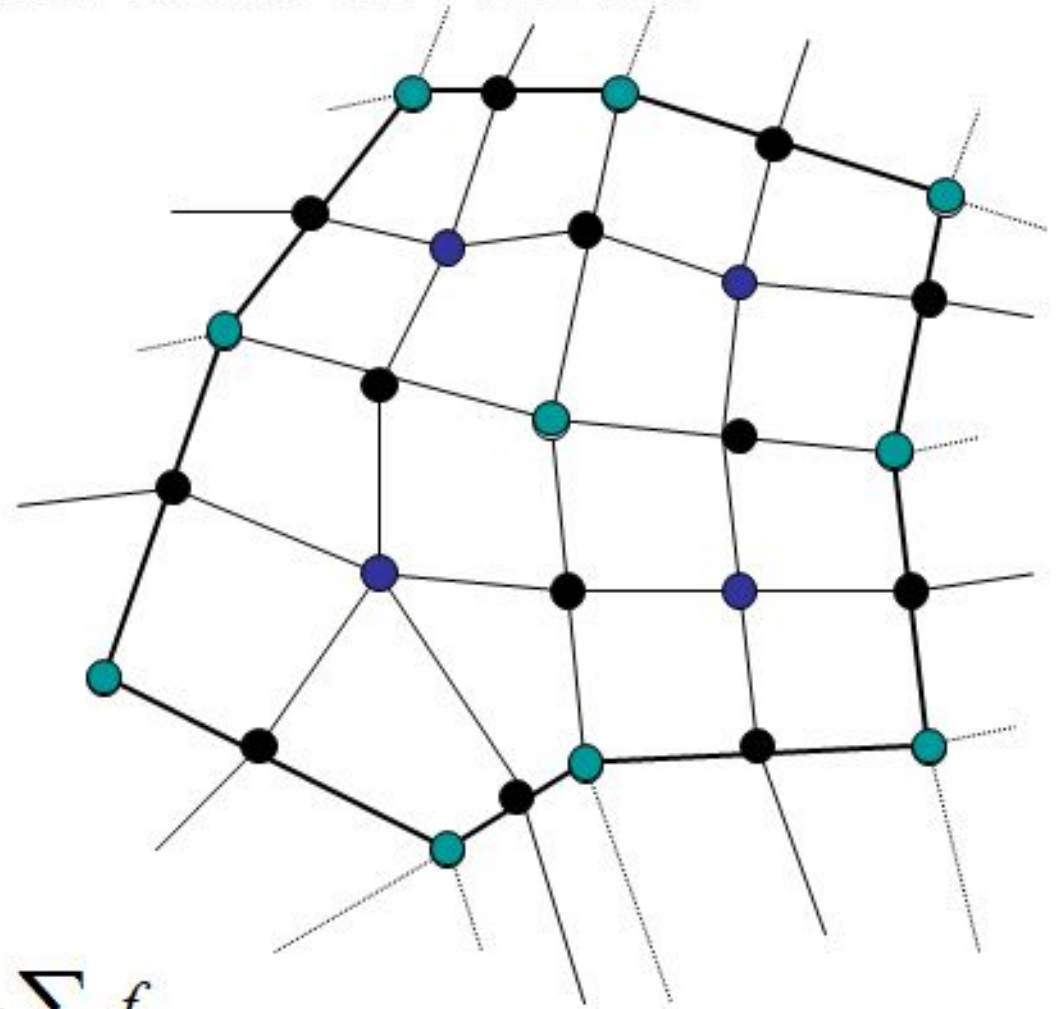
● FACE

● EDGE $f = \frac{1}{n} \sum_{i=1}^n v_i$

$$e = \frac{v_1 + v_2 + f_1 + f_2}{4}$$

○ → ● VERTEX

$$v_{i+1} = \frac{n-2}{n} v_i + \frac{1}{n^2} \sum_j e_j + \frac{1}{n^2} \sum_j f_j$$



Modeling with Catmull-Clark

- Subdivision produces smooth continuous surfaces.
- How can “sharpness” and creases be controlled in a modeling environment?

ANSWER: Define new subdivision rules for “creased” edges and vertices.

- Tag Edges sharp edges.
- If an edge is sharp, apply new sharp subdivision rules.
- Otherwise subdivide with normal rules.



Sharp Edges...

- Tag Edges as “**sharp**” or “**not-sharp**”
 - $n = 0$ – “**not sharp**”
 - $n > 0$ – **sharp**

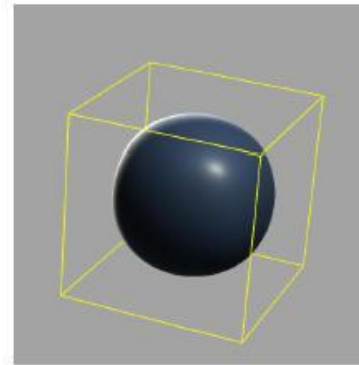
During Subdivision,

- if an edge is “**sharp**”, use sharp subdivision rules. Newly created edges, are assigned a sharpness of $n-1$.
- If an edge is “**not-sharp**”, use normal smooth subdivision rules.

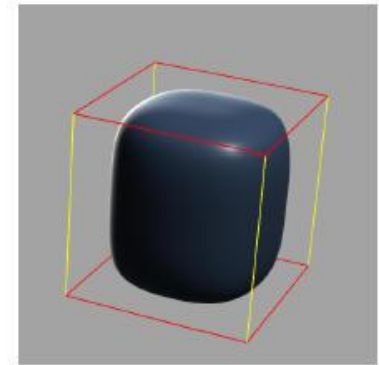
IDEA: Edges with a sharpness of “ n ” do not get subdivided smoothly for “ n ” iterations of the algorithm.

.In the picture on the right, the control mesh is a unit cube

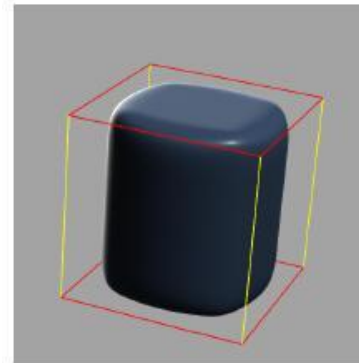
.Different sharpness applied



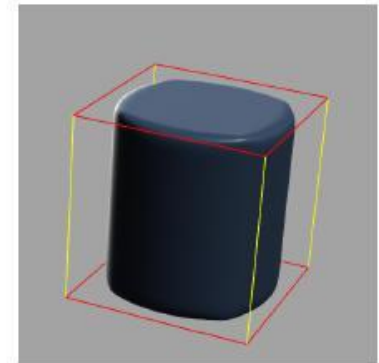
(a)



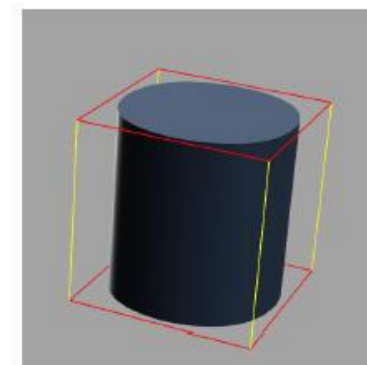
(b)



(c)



(d)



(e)

Sharp Rules

● FACE (unchanged)

$$f = \frac{1}{n} \sum_1^n v_i$$

● EDGE

$$e = \frac{v_1 + v_2}{2}$$

○ → ● VERTEX

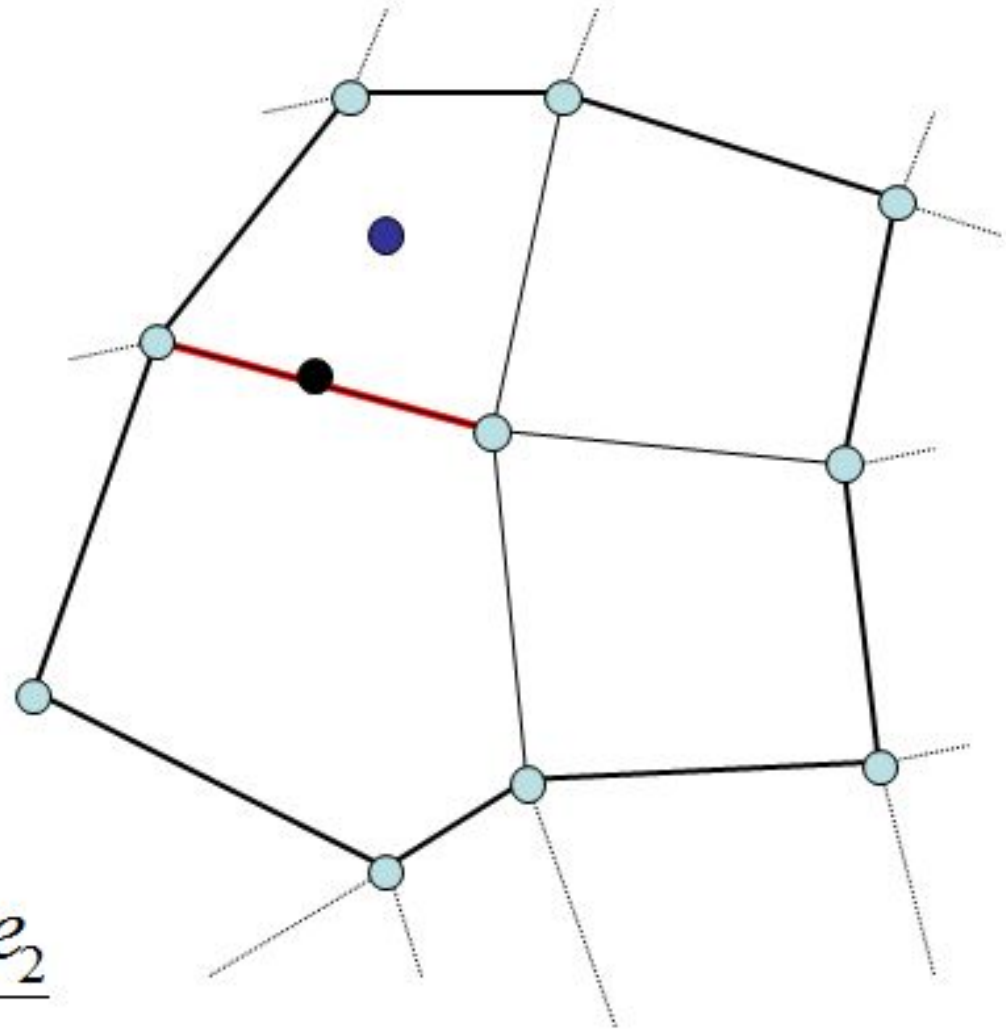
adj. Sharp edges

corner >2

$$v_{i+1} = v_i$$

crease 2

$$v_{i+1} = \frac{e_1 + 6v_i + e_2}{8}$$

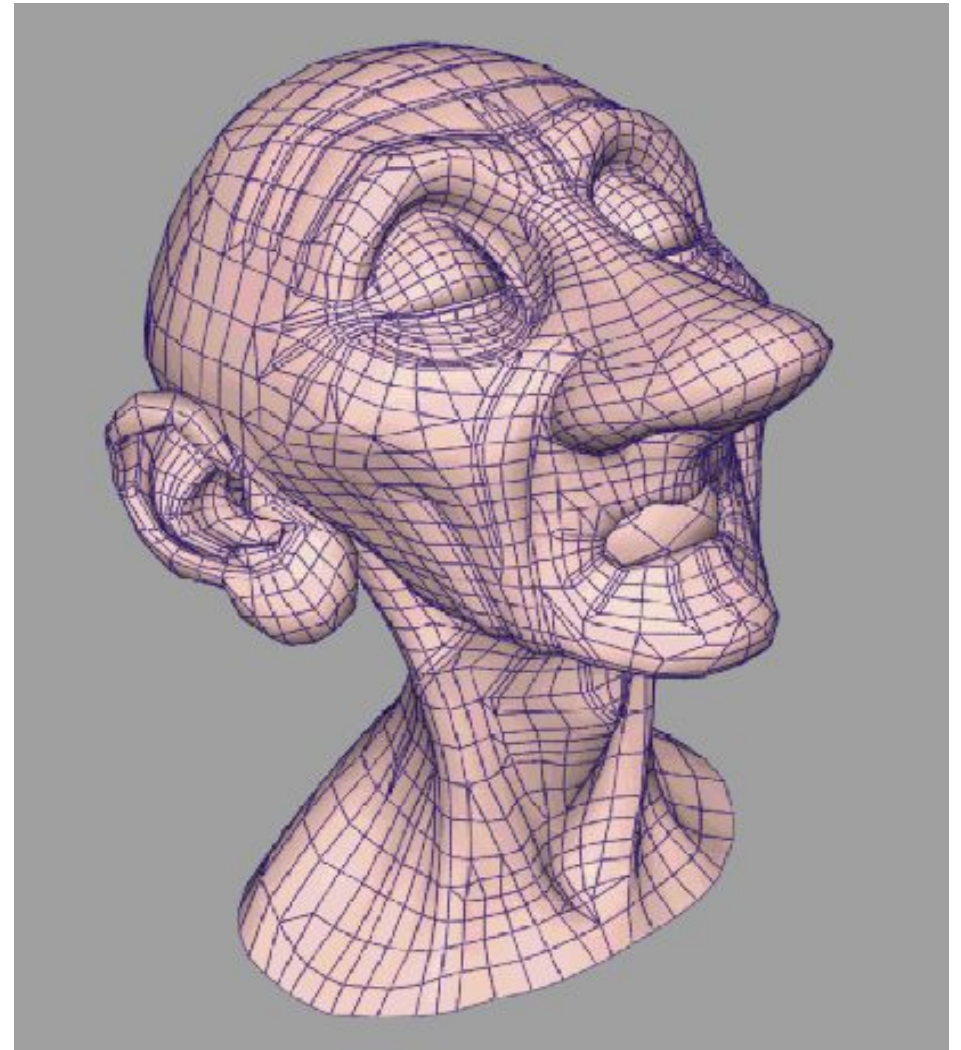


Another example of creases



Subdivision Surfaces in character animation [DeRose98]

- Used for first time in Geri's game to overcome topological restriction of NURBS
- Modeled Geri's head, hands, jacket, pants, shirt, tie, and shoes



Geri's Game

- Academy Award winning movie by Pixar
 - Made by subdivision surface

[<http://www.youtube.com/watch?v=1m7dcbIKvlw>]

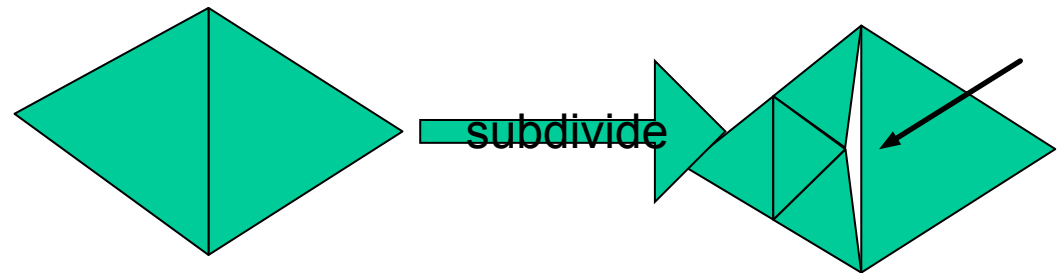
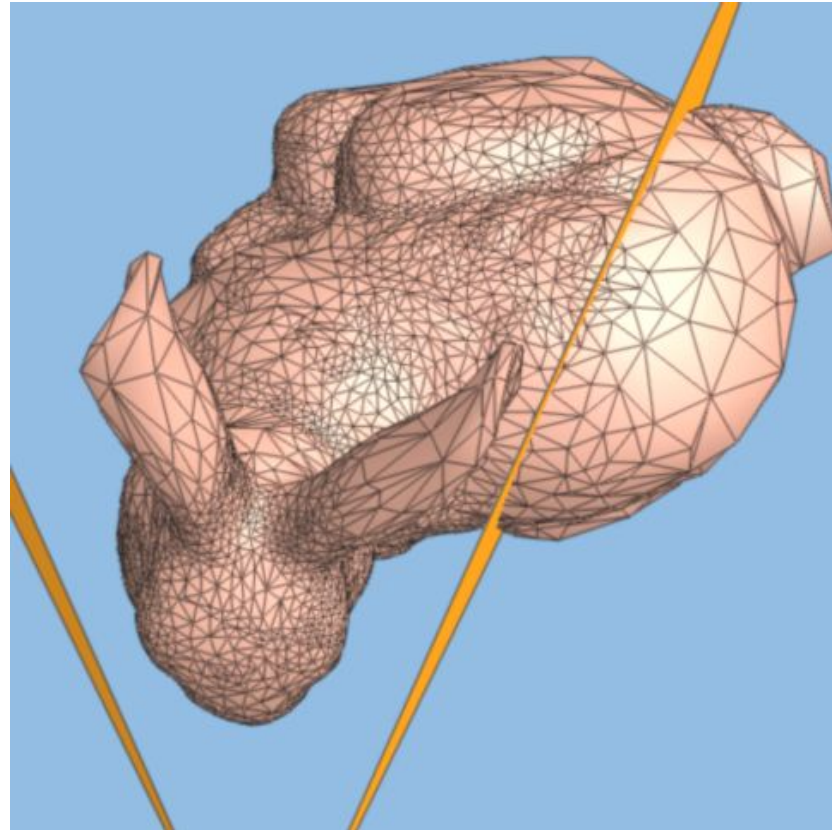


Demo of Catmull-Clark subdivision surface

- <http://www.youtube.com/watch?v=IU8f0honorU8&feature=related>

Adaptive Subdivision

- Not all regions of a model need to be subdivided.
- Idea: Use some criteria and adaptively subdivide mesh where needed.
 - Curvature
 - Screen size (make triangles < size of pixel)
 - View dependence
 - Distance from viewer
 - Silhouettes
 - In view frustum
 - Careful! Must ensure that “cracks” aren’t made



Subdivision Surface Summary

- Advantages
 - Simple method for describing complex surfaces
 - Relatively easy to implement
 - Arbitrary topology
 - Local support
 - Guaranteed continuity
 - Multi-resolution
- Difficulties
 - Intuitive specification
 - Parameterization
 - Intersections

- Edwin Catmull

Utah – NYIT – Lucas Films – Pixar -
present: President of Disney Animation
Studios and Pixar Animation Studios

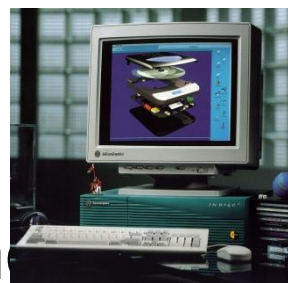


- Jim Clark

Utah – UCSC - Stanford – Silicon Graphics -
Netscape - ...



He also co-produced the movie



[Cove](#).

Readings

- Shirley - 15.6.3, 15.6.4
- Akenine-Möller - 13.5.4 (Catmull-Clark subdivision)
- A very good website for parametric curves / surfaces
<http://www.cs.mtu.edu/~shene/COURSES/cs3621/>
- DeRose, Tony, Michael Kass, and Tien Truong. Subdivision Surfaces in Character Animation. *SIGGRAPH 98*.
- Clark, E., and J. Clark. Recursively generated B-spline surfaces on arbitrary topological meshes. *Computer Aided Geometric Design*, Vol. 10, No. 6, 1978.
- Doo, D. and M. Sabin. Behavior of Recursive Division Surfaces Near Extraordinary Points. *Computer-Aided Design*. Vol. 10, No. 6, 1978.