
Ab initio prediction of protein interaction

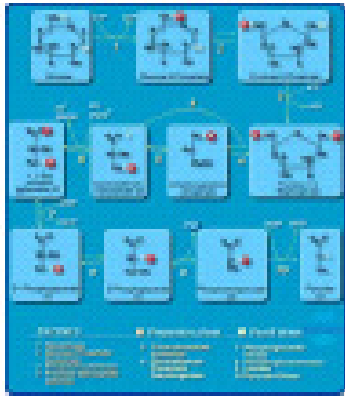
Dirk Husmeier

Biomathematics & Statistics Scotland (BioSS)
JCMB, The King's Buildings, Edinburgh EH9 3JZ
United Kingdom

<http://www.bioss.ac.uk/~dirk>

Pathways and systems biology

Glycolysis



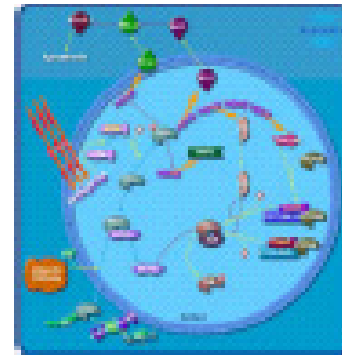
**Metabolic
Pathways**

Protein-Protein



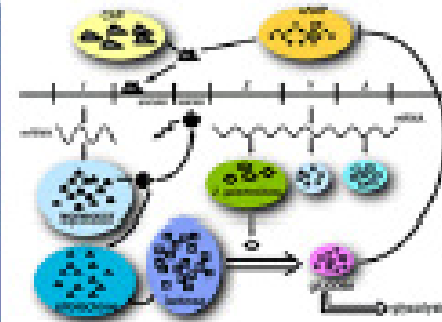
**Molecular
Interaction
Networks**

Apoptosis

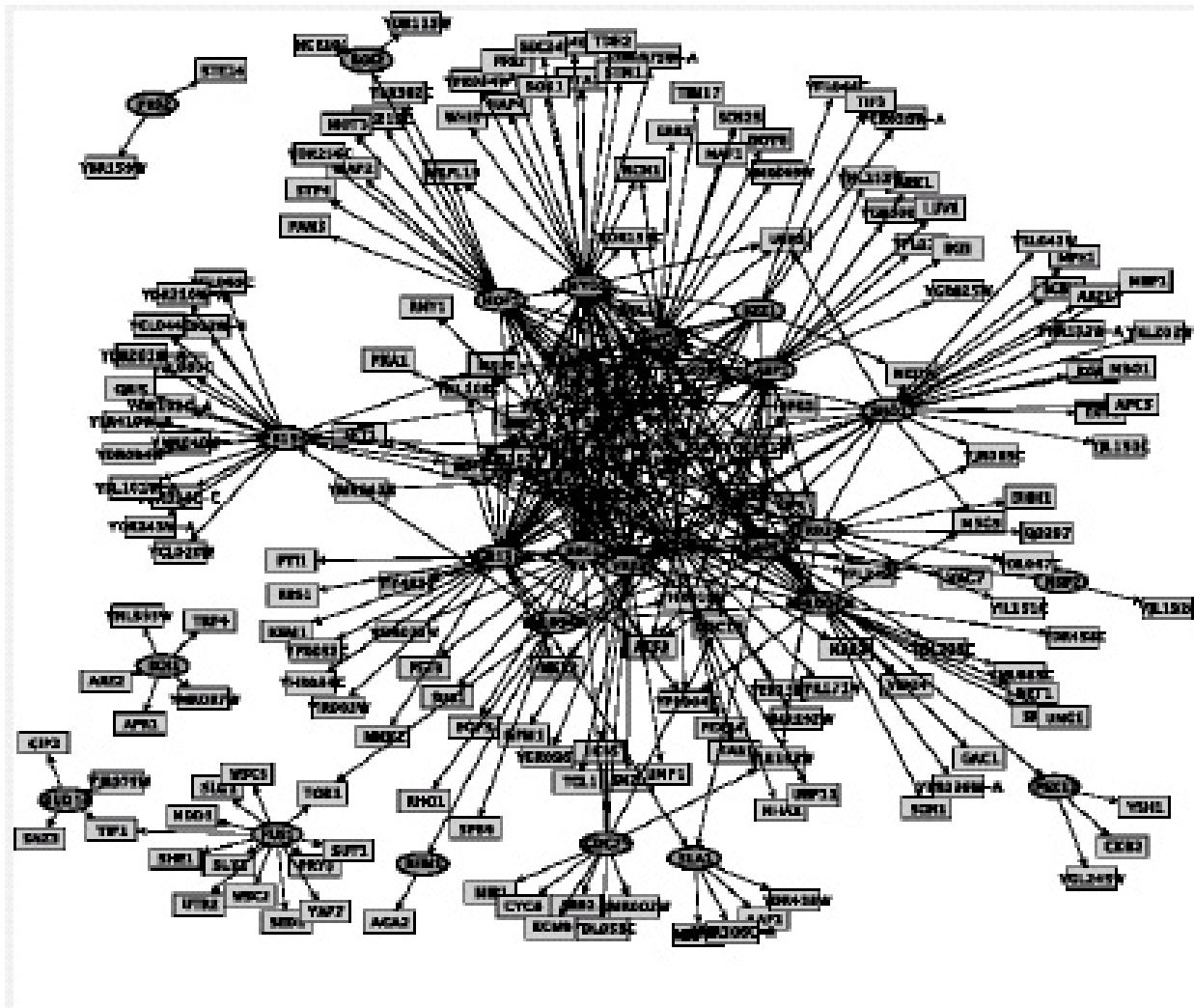


**Signaling
Pathways**

Lac Operon



**Gene
Regulation**



SH3 domain protein interaction network in *S. cerevisiae*; from Tong et al. (2002)

Experimental high-throughput techniques

Yeast two-hybrid

Phage display

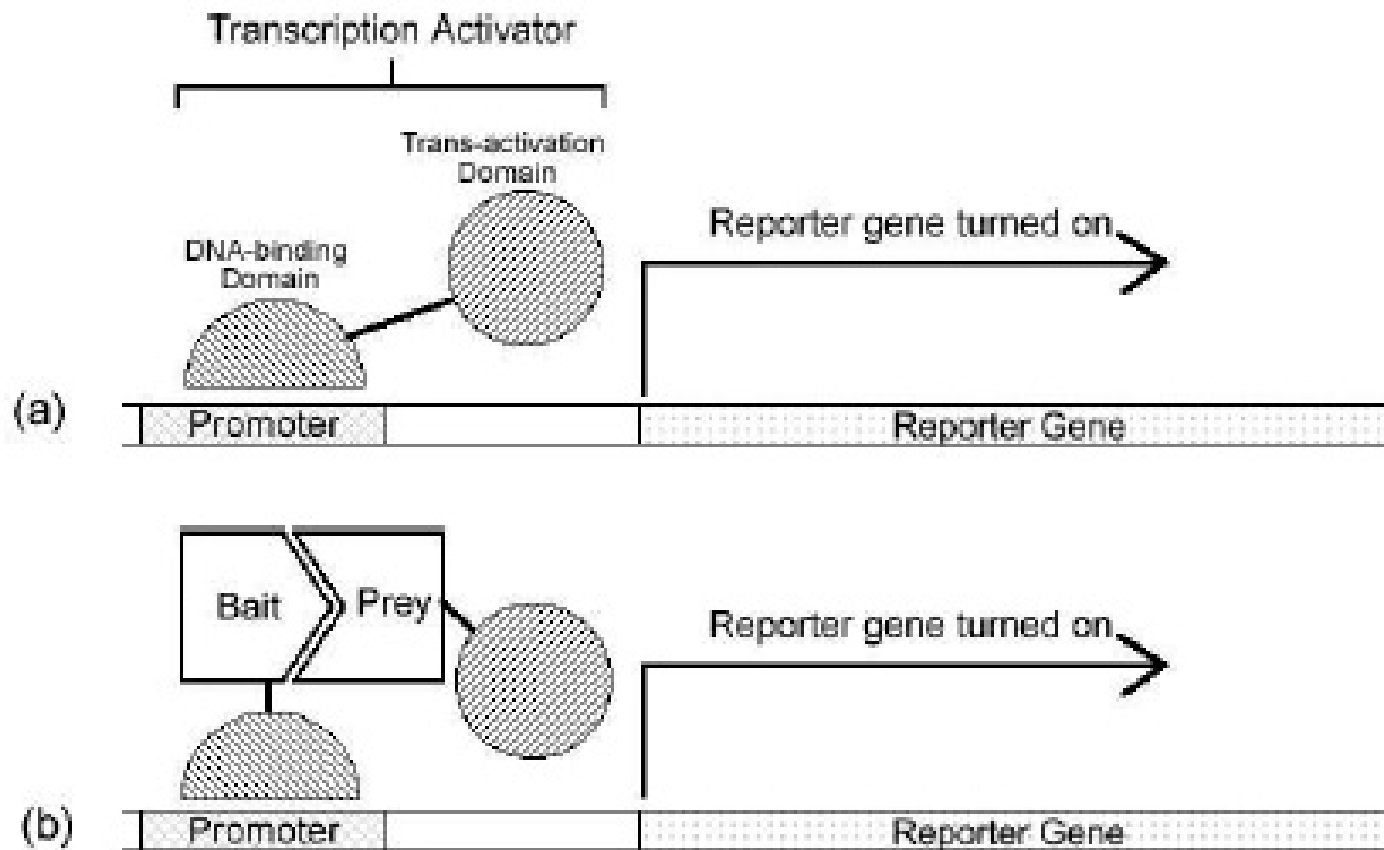


Fig. 1. Interaction detection by yeast two-hybrid assay. (a) Activation of reporter gene by transcriptional activator; (b) Activation of reporter gene by reconstituted transcriptional activator.

From See-Kiong Ng and Soon-Heng Tan, *J. Bioinf. Comp. Bio.* (2004)

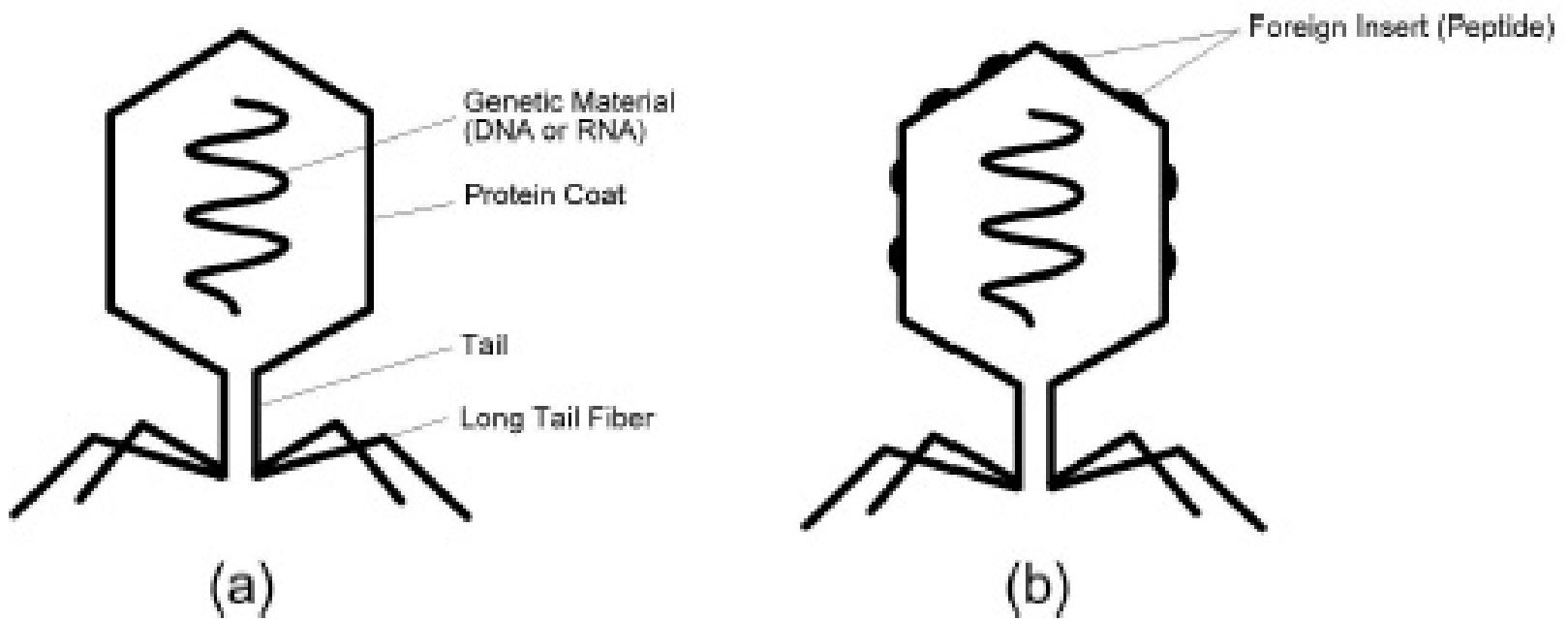


Fig. 2. Schematic diagrams of (a) a phage; and (b) interaction detection by phage display.

From See-Kiong Ng and Soon-Heng Tan, *J. Bioinf. Comp. Bio.* (2004)

Tong et al. (2002), Science 295, 321-324.

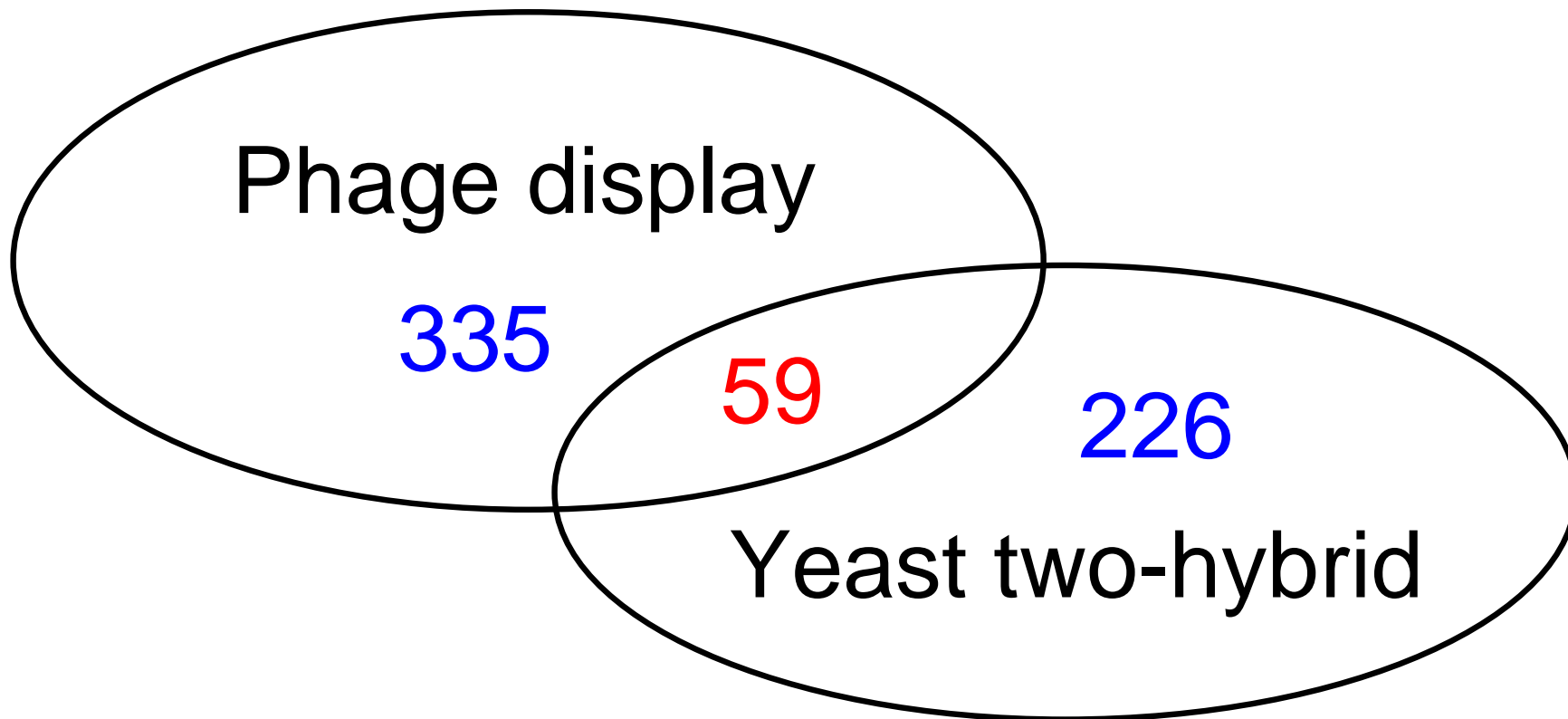
SH3 domain proteins in *Saccharomyces cerevisiae*.

Yeast two-hybrid interaction network

285 interactions between 28 SH3 proteins
and 143 binding peptides

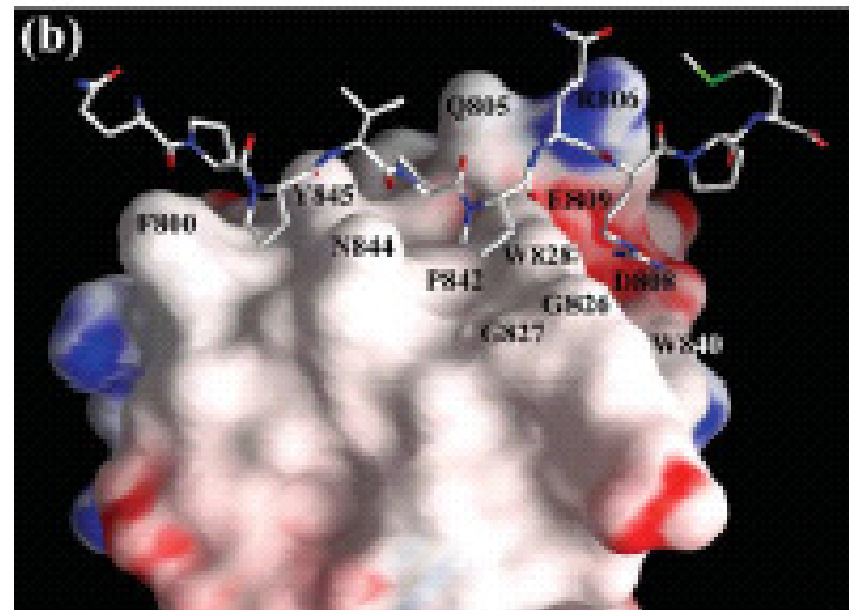
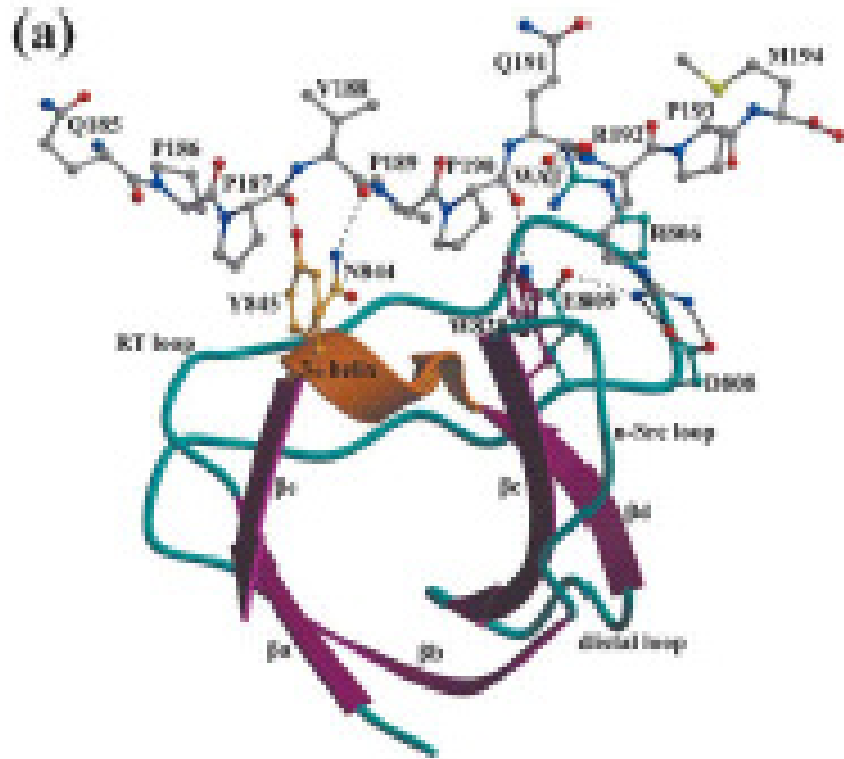
Phage display interaction network

394 interactions between 28 SH3 proteins
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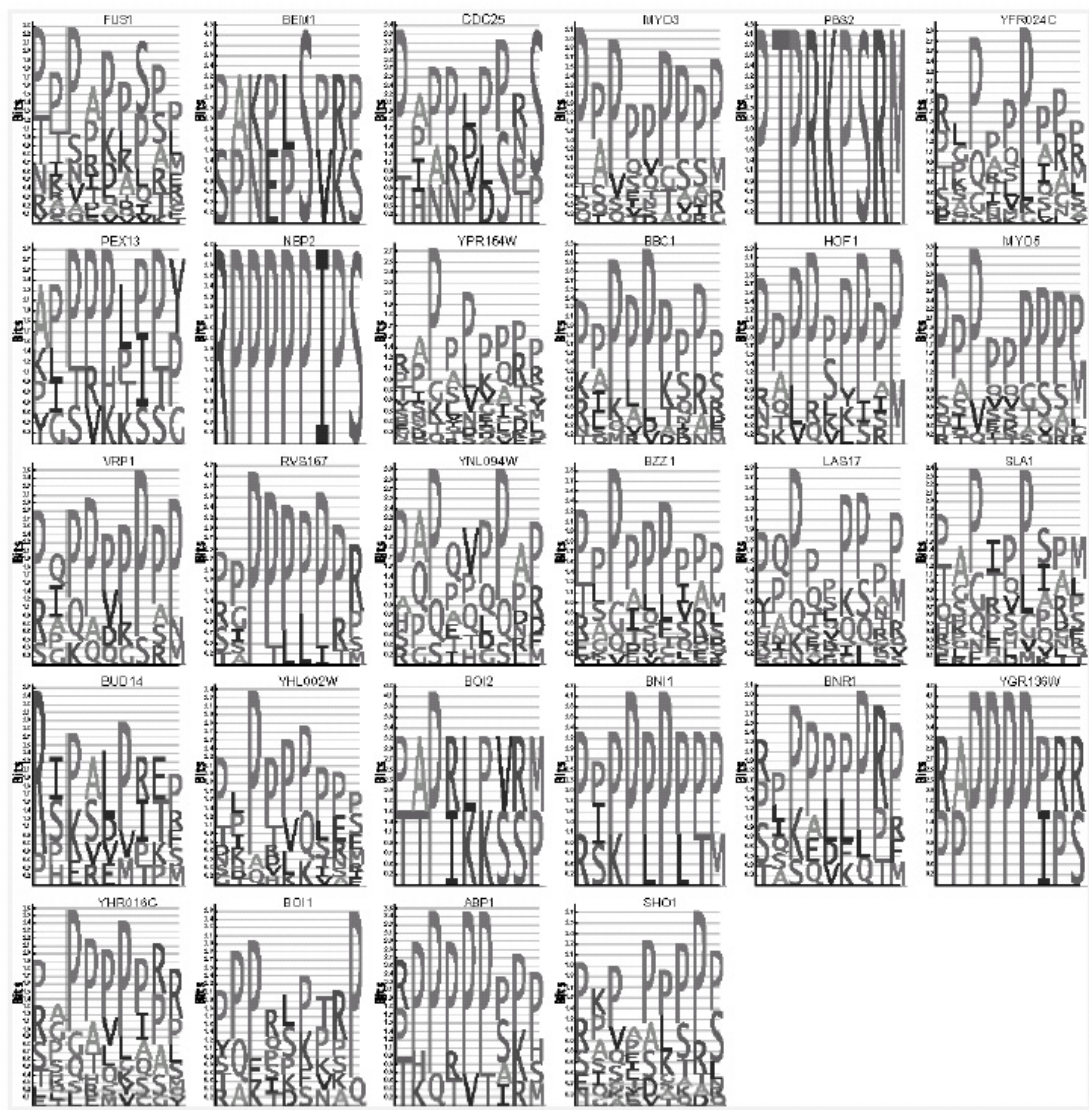
- **High-throughput experiments** (yeast two-hybrid, phage display) are **expensive** and **intrinsically noisy**.
- It would be desirable to more specifically target or partially bypass them with **complementary *in silico* approaches**.

- **High-throughput experiments** (yeast two-hybrid, phage display) are **expensive** and **intrinsically noisy**.
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- Objective: develop a **probabilistic model** to predict protein-protein interactions from sequence data.
- Method: We want to capture the way protein recognition modules **recognise** and bind to peptide ligands that contain a **specific binding motif**.



Peptide recognition modules

Example: SH3 domain





SH3 domains

Interacting proteins

Motif: T A T A

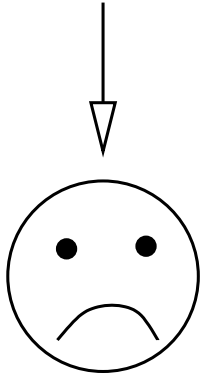
T C G A A T T C T A T A G C C A C

Motif: T A T A

T C G A A T T C T A T A G C C A C

Motif: T A^C T A^C G

T C G A A T T C T A T A G C C A C



Motif: T A^C T A^C G

T C G A A T T C T A T A G C C A C



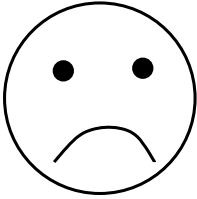
Motif: T A^C T A^C G

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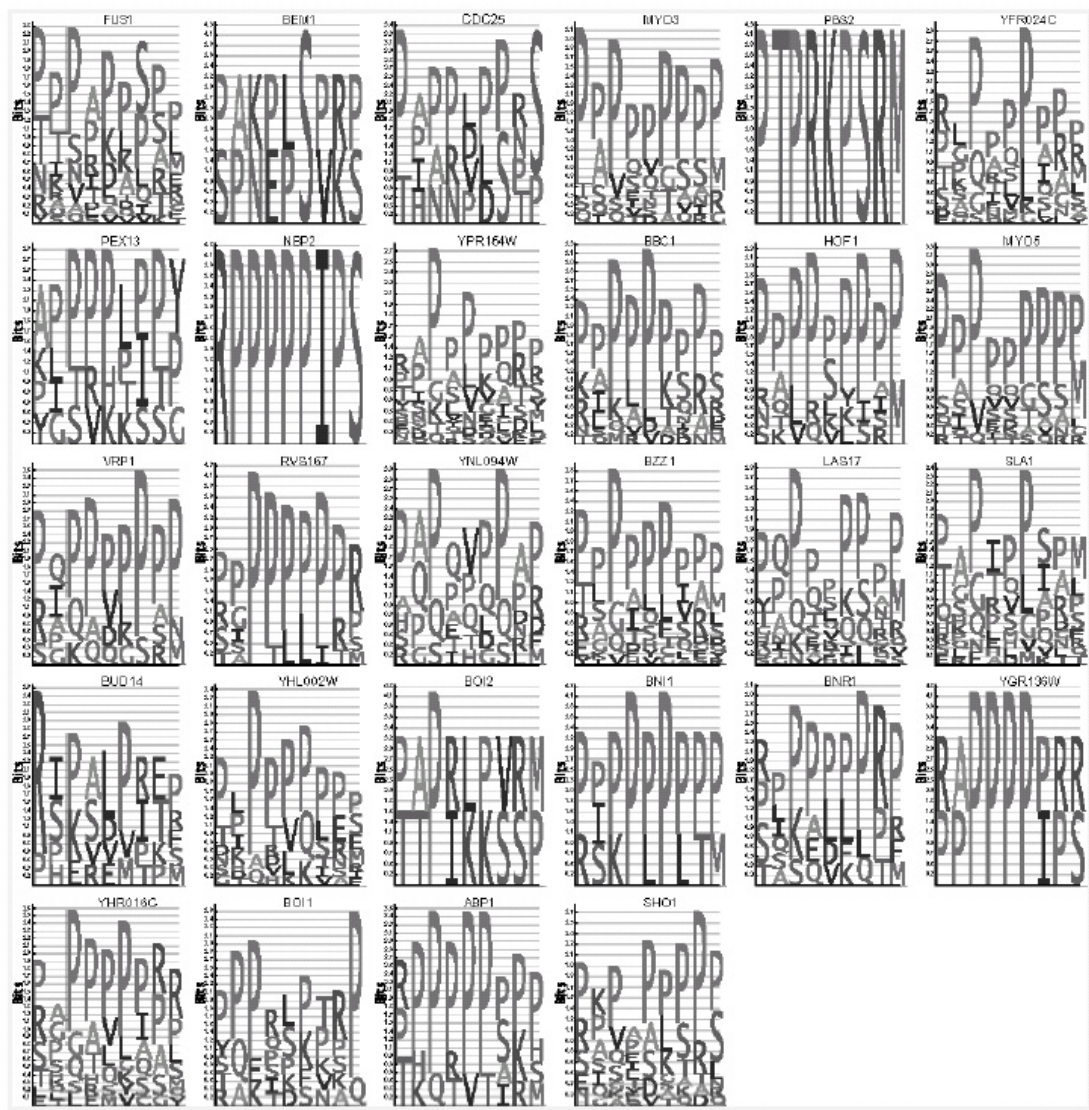
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$W \times 4$ matrix $\psi_k(l)$:

Probability that the nucleotide in the k th position,
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Background model

for **non-binding sequences**

4-dim vector $\theta_0(l)$:

Probability of nucleotide l ; this distribution is **position-independent**.

Sequence S_1, S_2, \dots, S_N

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Non-binding sequence: $R=0$

$$P(S_1, S_2, \dots, S_N | R = 0) = \prod_{t=1}^N \theta_0(S_t)$$

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Binding sequence: $R=1$, motif starting at position $m+1$

$$\begin{aligned} &P(S_1, S_2, \dots, S_N | R = 1, \text{start} = m + 1) \\ &= \prod_{t=1}^m \theta_0(S_t) \prod_{k=1}^W \psi_k(S_{m+k}) \prod_{t=m+W+1}^N \theta_0(S_t) \\ &= \prod_{t=1}^N \theta_0(S_t) \prod_{k=1}^W \frac{\psi_k(S_{m+k})}{\theta_0(S_{m+k})} \end{aligned}$$

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Binding sequence: $R=1$, motif starting anywhere

$$\begin{aligned} &P(S_1, S_2, \dots, S_N | R = 1) \\ &= \sum_{m=0}^{N-W} P(\text{start} = m + 1) P(S_1, S_2, \dots, S_N | R = 1, \text{start} = m + 1) \\ &= \prod_{t=1}^N \theta_0(S_t) \frac{1}{N - W + 1} \sum_{m=0}^{N-W} \prod_{k=1}^W \frac{\psi_k(S_{m+k})}{\theta_0(S_{m+k})} \end{aligned}$$

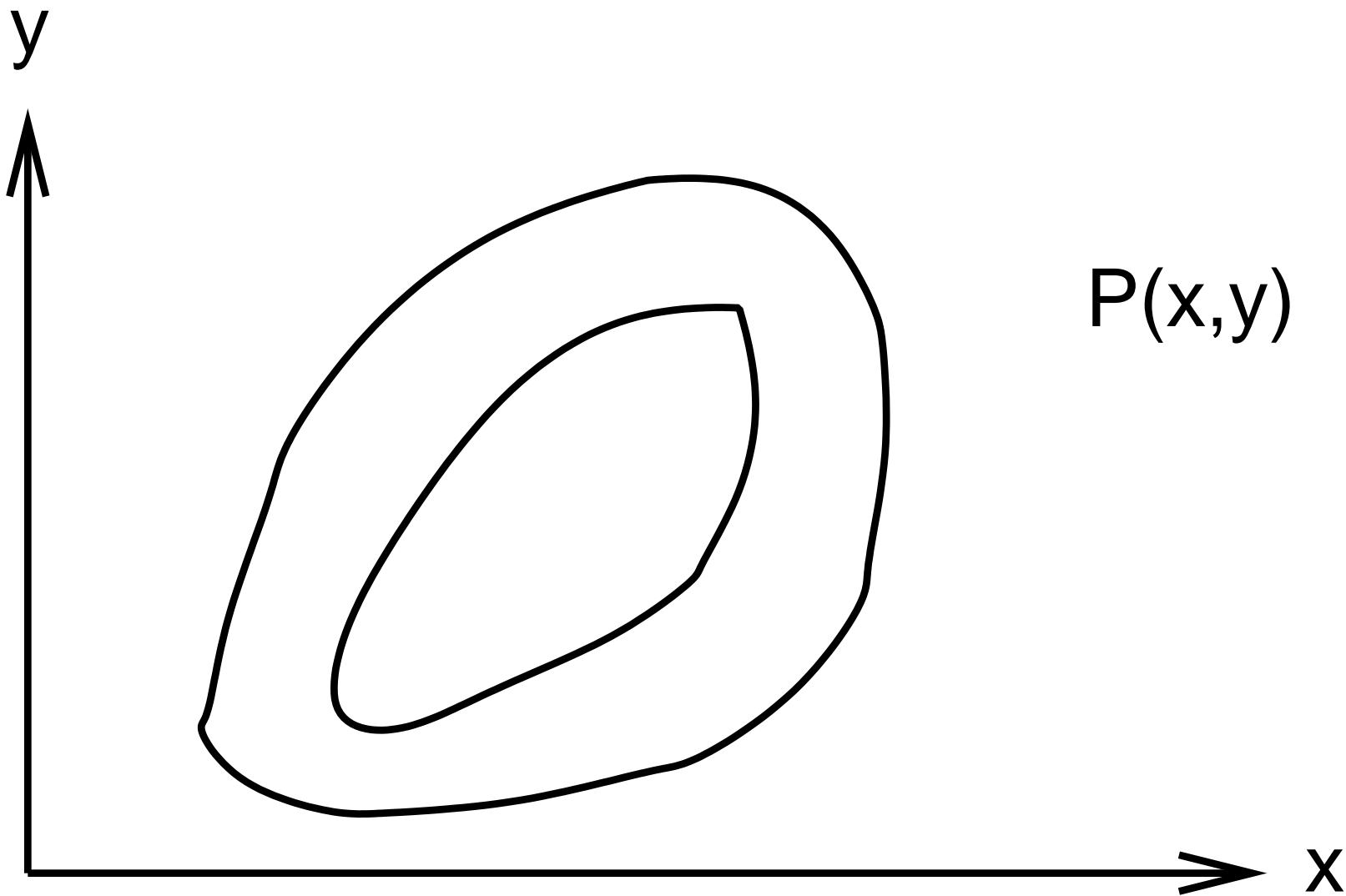
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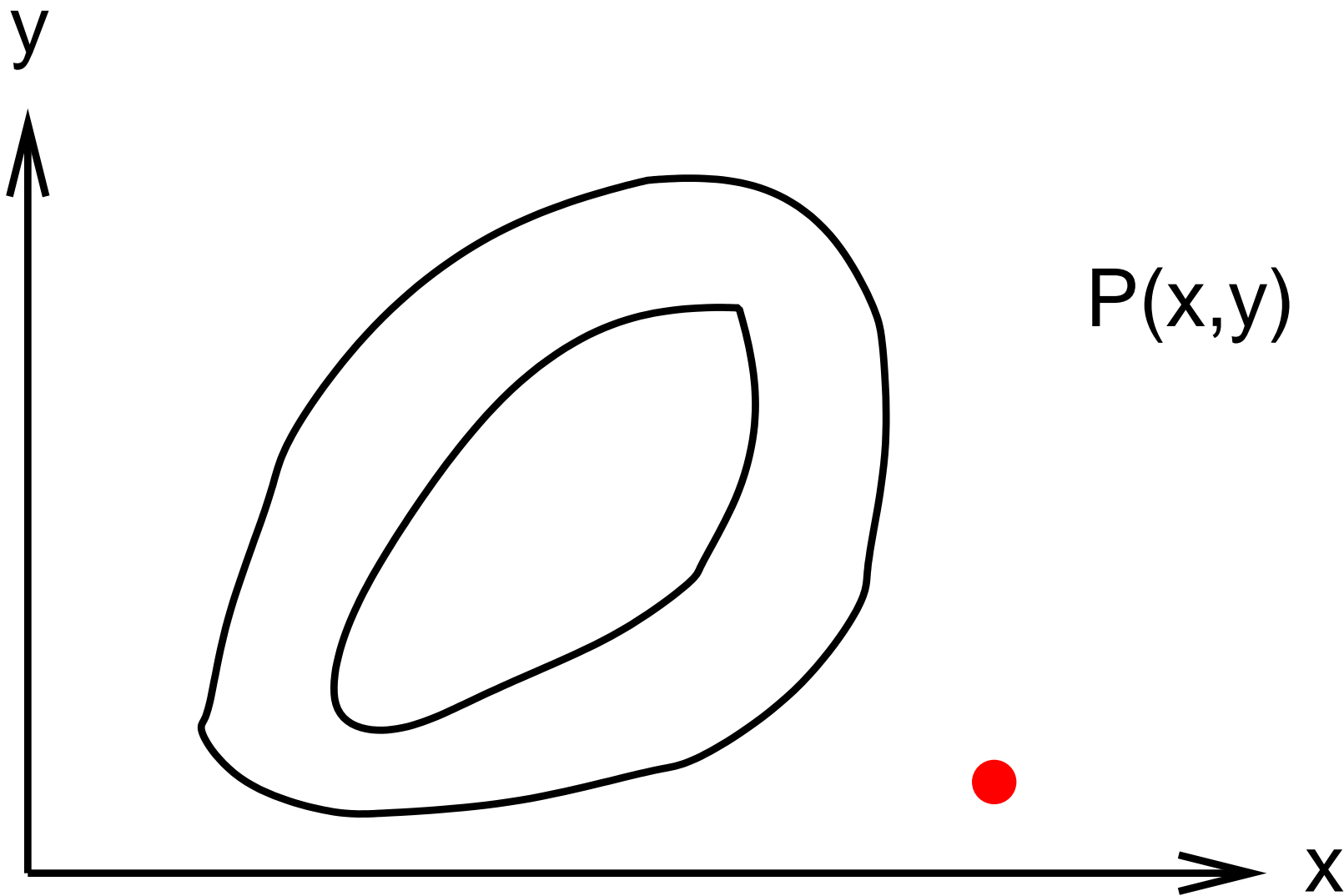
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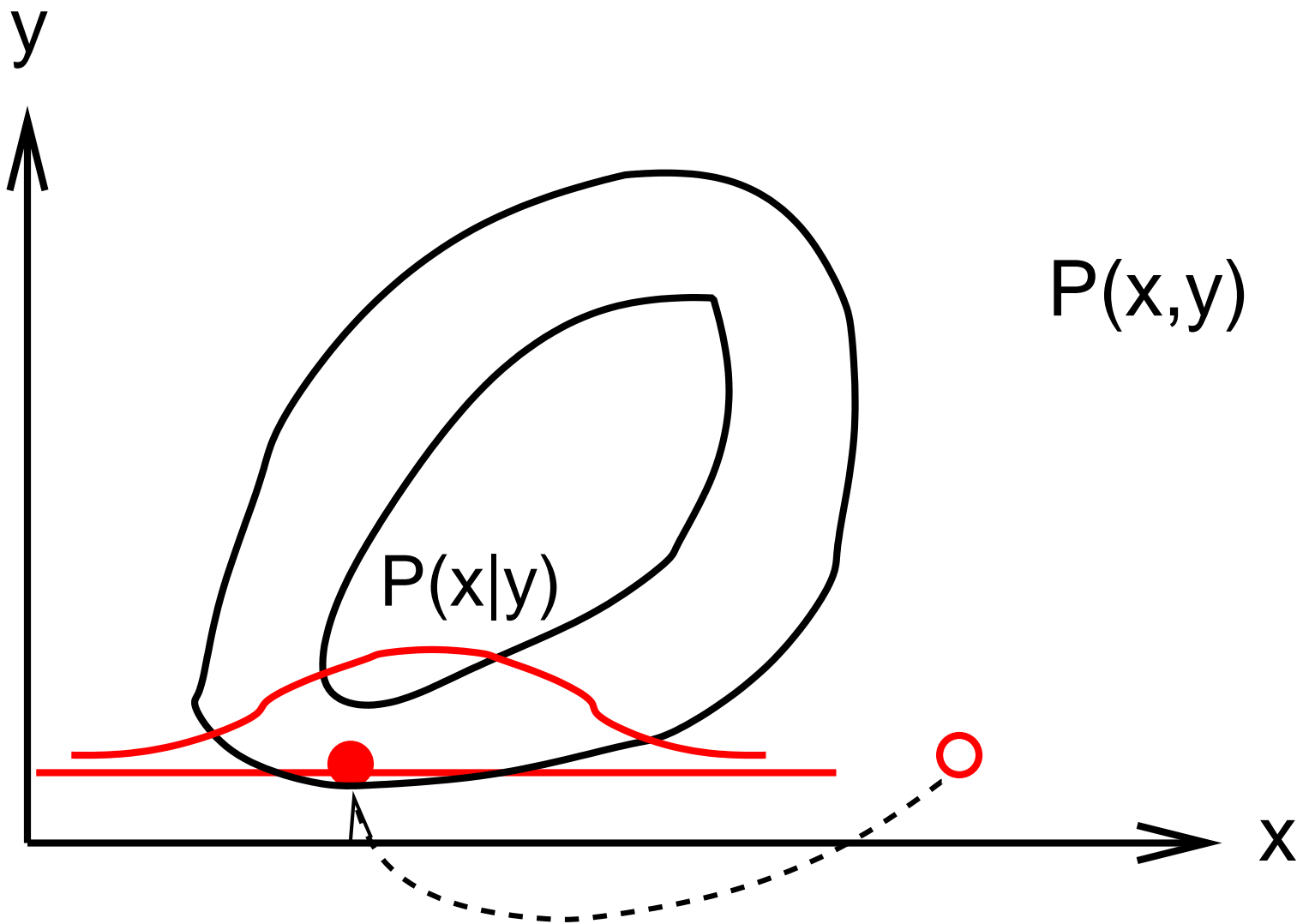
Binding sequence: $R=1$, motif starting anywhere

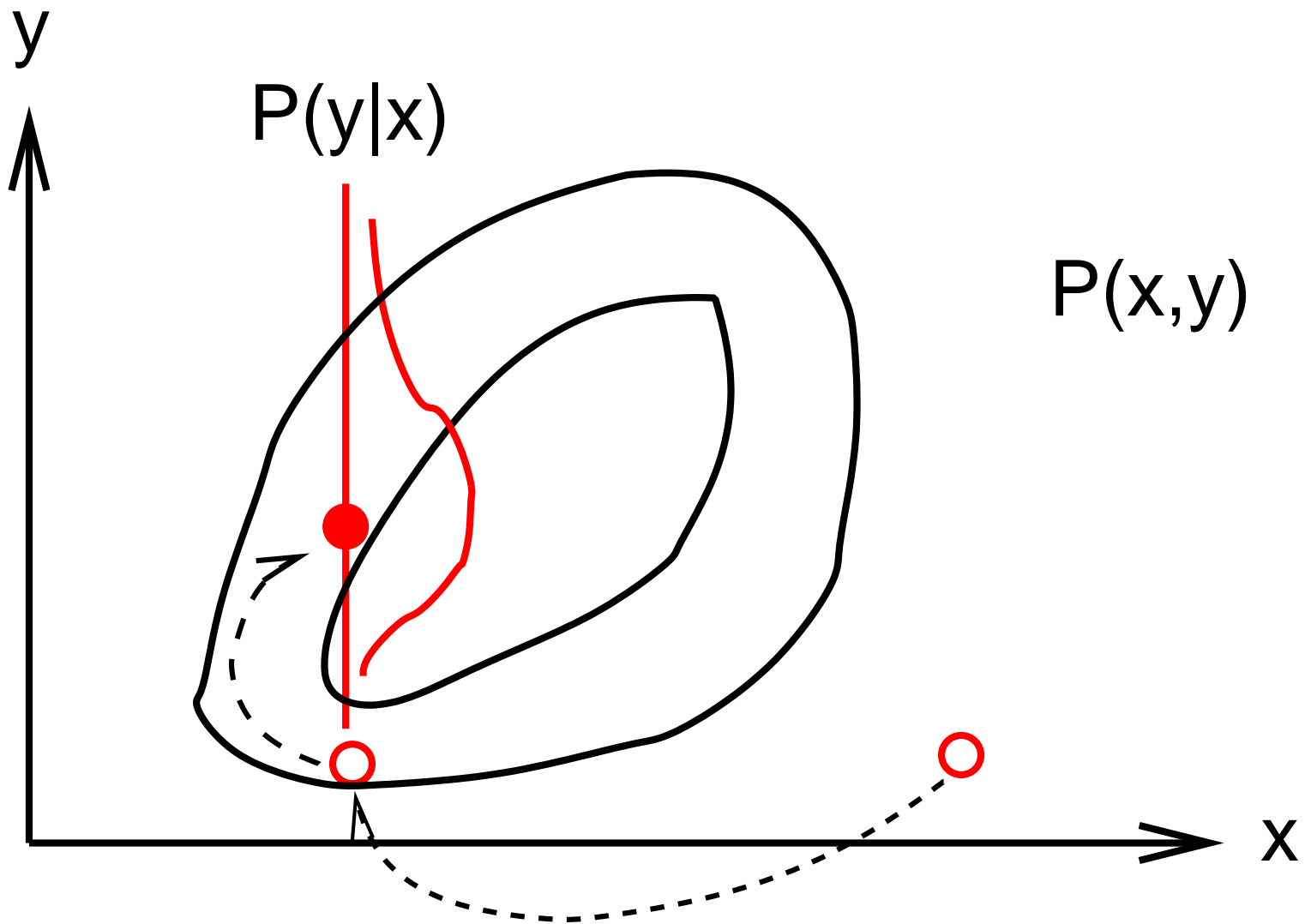
$$\begin{aligned} &P(S_1, S_2, \dots, S_N | R = 1) \\ &= \sum_{m=0}^{N-W} P(\text{start} = m + 1) P(S_1, S_2, \dots, S_N | R = 1, \text{start} = m + 1) \\ &= \prod_{t=1}^N \theta_0(S_t) \frac{1}{N - W + 1} \sum_{m=0}^{N-W} \prod_{k=1}^W \frac{\psi_k(S_{m+k})}{\theta_0(S_{m+k})} \end{aligned}$$

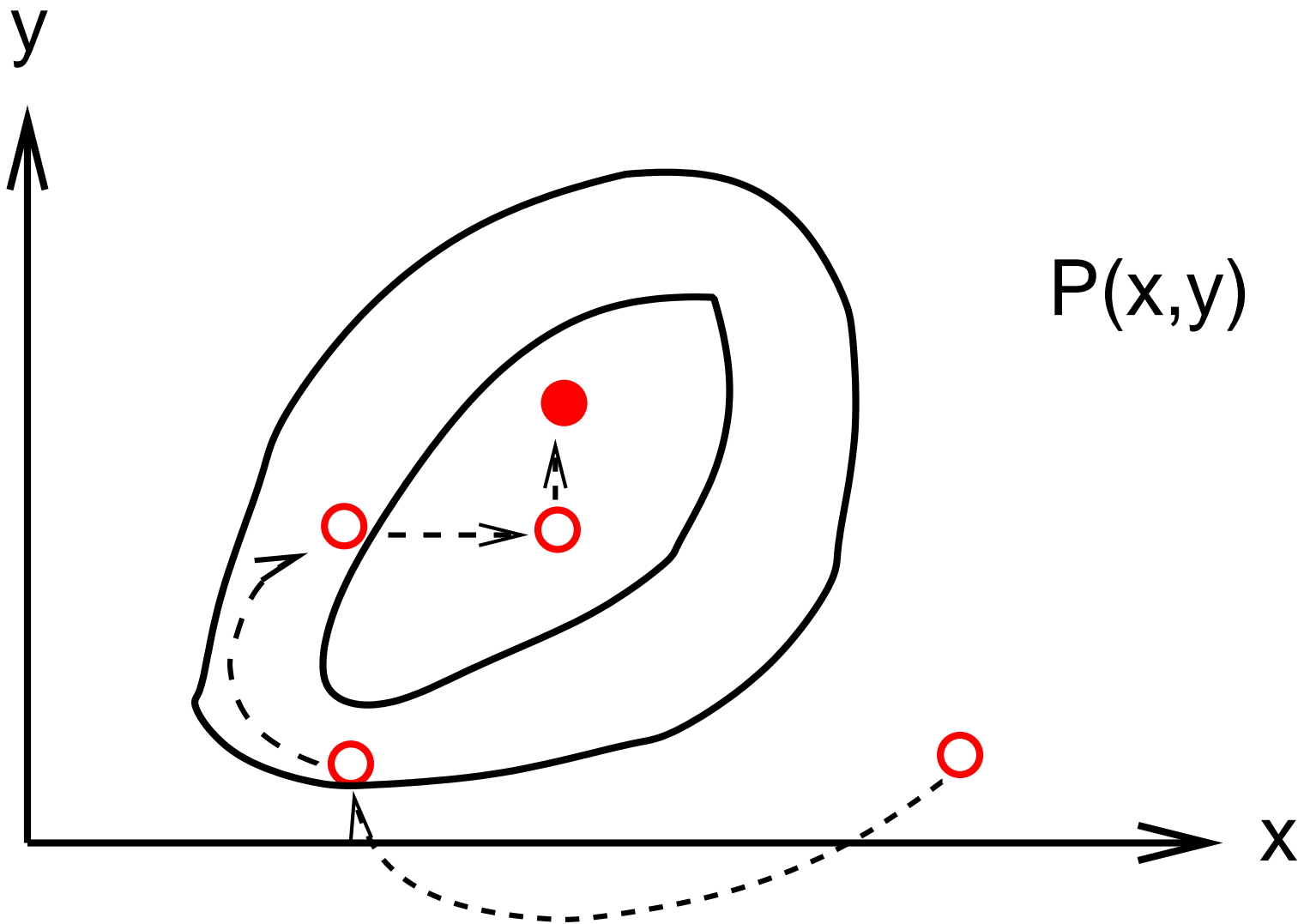
Gibbs sampling











Posterior probability of a binding location, given the parameters

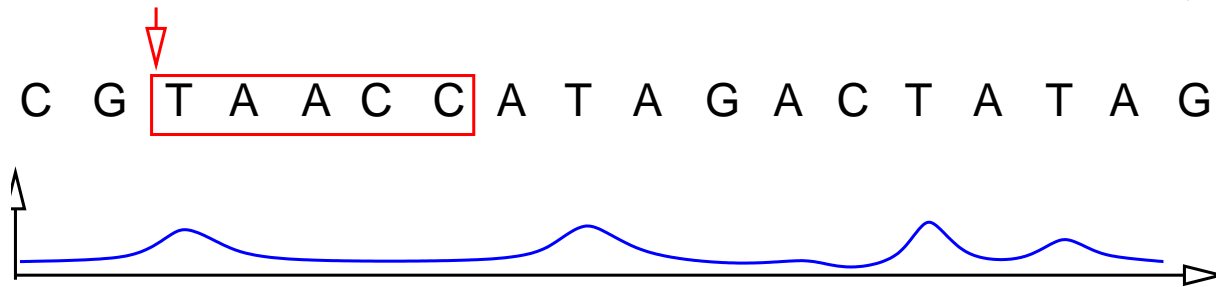
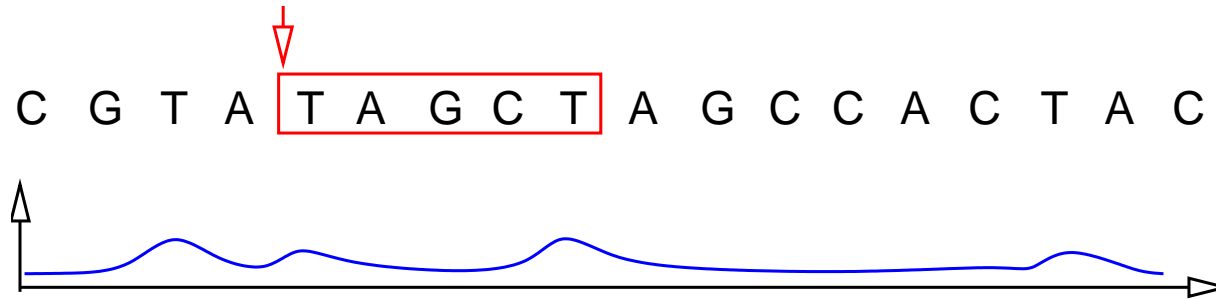
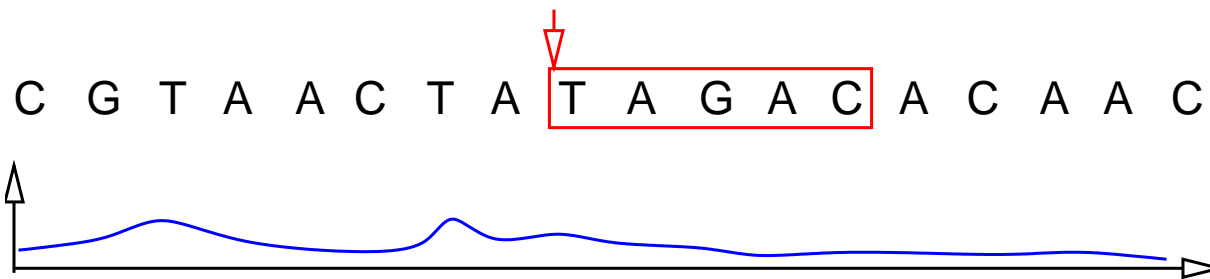
$$P(\textit{start} = m + 1 | S_1, S_2, \dots, S_N, \textit{Parameters}) = \frac{P(S_1, S_2, \dots, S_N | \textit{start} = m + 1) P(\textit{start} = m + 1)}{P(S_1, S_2, \dots, S_N)}$$

Motif starting at position $m+1$

$$P(S_1, S_2, \dots, S_N | \textit{start} = m + 1) = \prod_{t=1}^N \theta_0(S_t) \prod_{k=1}^W \frac{\psi_k(S_{m+k})}{\theta_0(S_{m+k})}$$

Motif starting anywhere

$$P(S_1, S_2, \dots, S_N) = \sum_{m=0}^{N-W} P(\textit{start} = m + 1) P(S_1, S_2, \dots, S_N | \textit{start} = m + 1)$$



Counts =

A	0	3	1	1	0
C	0	0	0	2	2
G	0	0	2	0	0
T	3	0	0	0	1
	1	2	3	4	5

Posterior probability of the parameters, given the binding locations

Sufficient statistics: Count matrix $C_{k,l}$

$C_{k,l}$: Number of times amino acid l appears in position k .

$$P(D, \text{binding locations} | \text{parameters}) = \prod_{k=1}^W \prod_{l=1}^{20} \psi_{k,l}^{C_{k,l}}$$

Conjugate prior distribution: Dirichlet

$$P(\text{parameters}) \propto \prod_{l=1}^{20} \psi_{k,l}^{\alpha_l - 1}$$

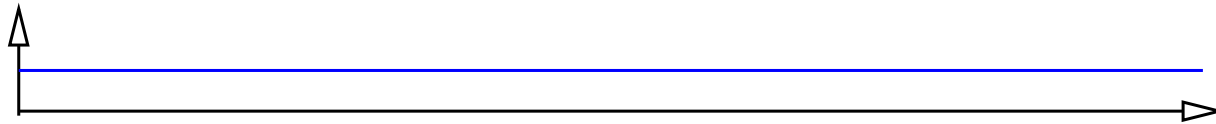
Posterior distribution

$$P(\text{parameters} | D, \text{binding locations}) \propto \prod_{k=1}^W \prod_{l=1}^{20} \psi_{k,l}^{C_{k,l} + \alpha_l - 1}$$

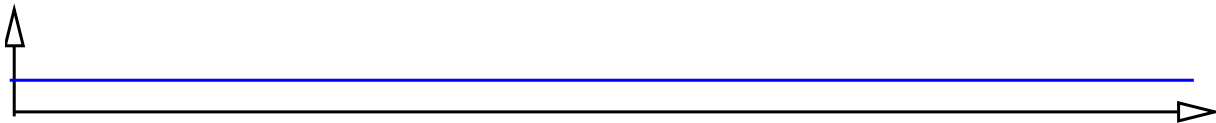
C G T A A C T A T A G A C A C A A C



C G T A T A G C T A G C C A C T A C

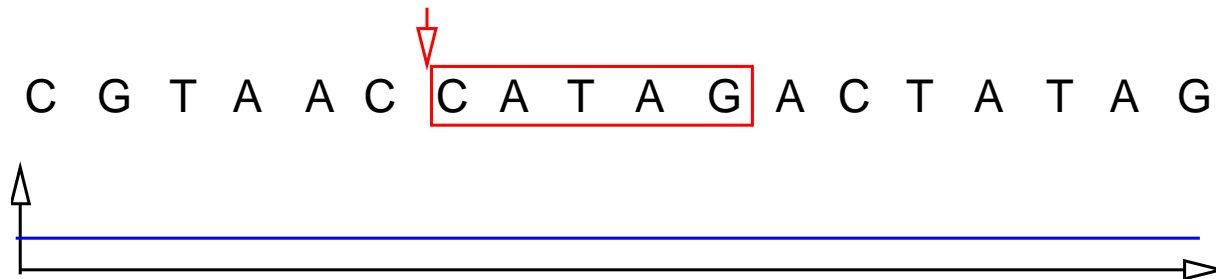
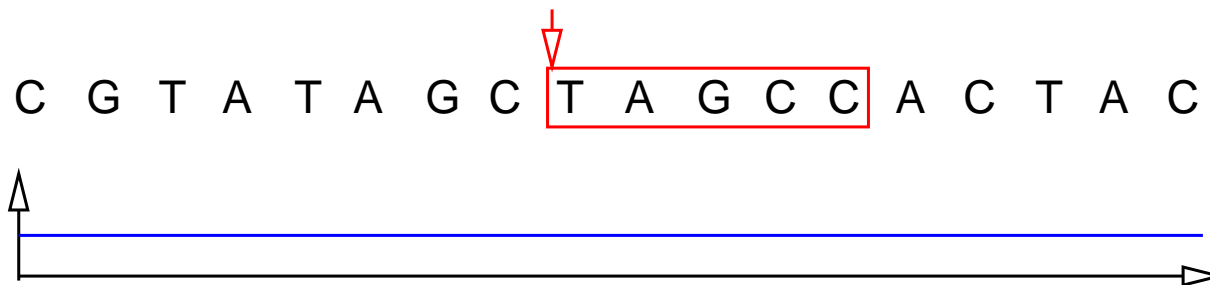
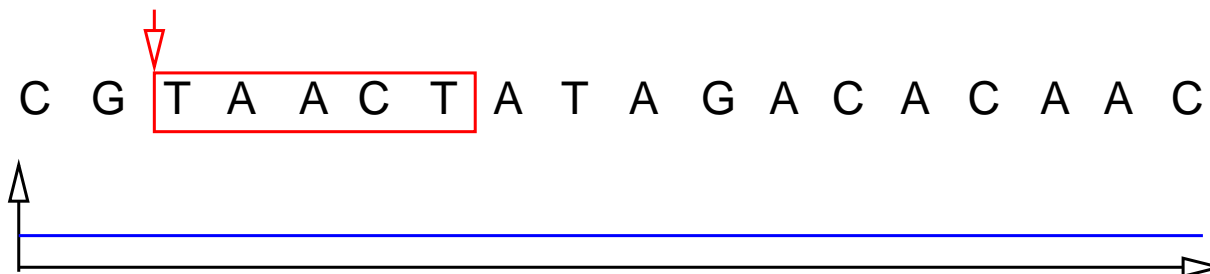


C G T A A C C A T A G A C T A T A G



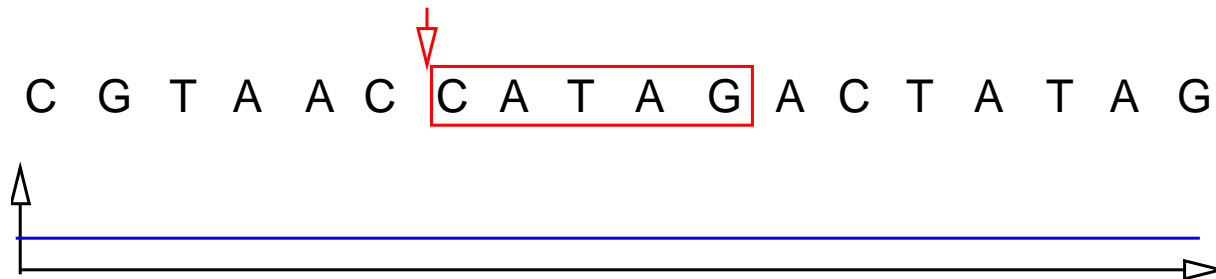
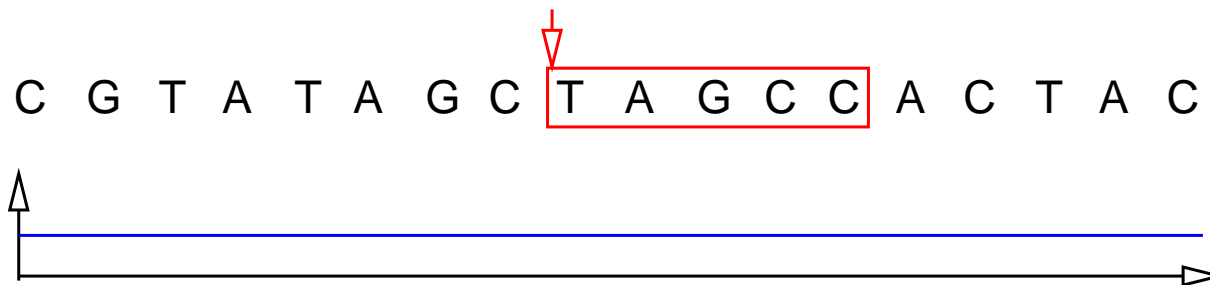
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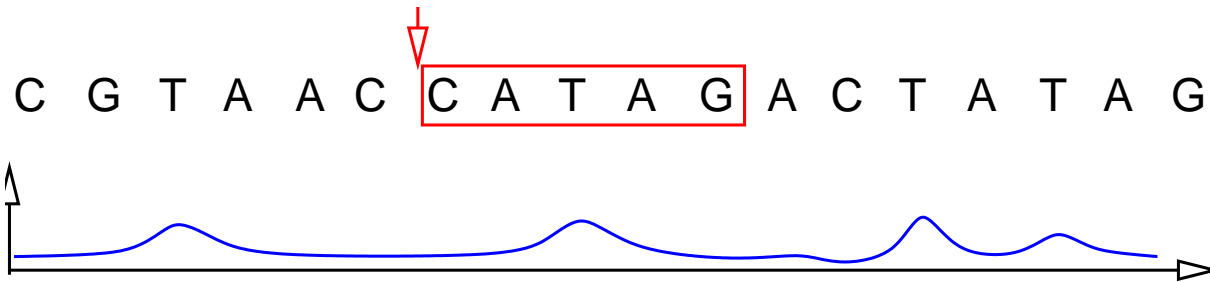
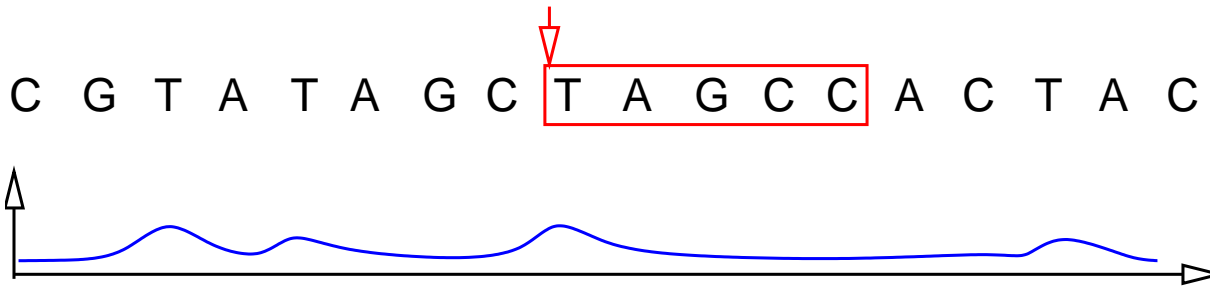
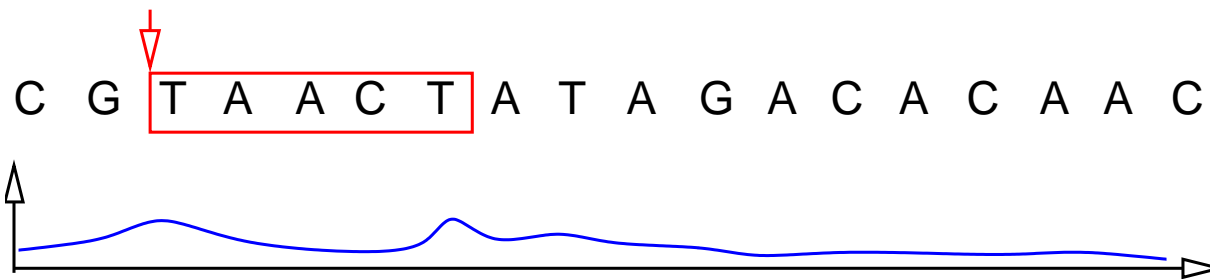
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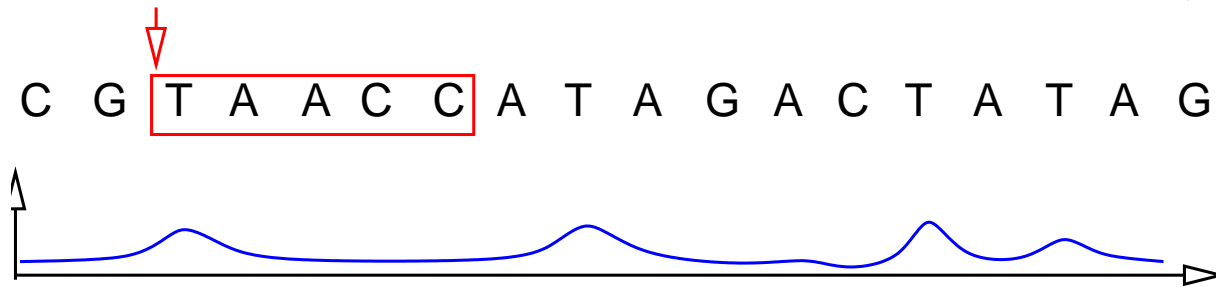
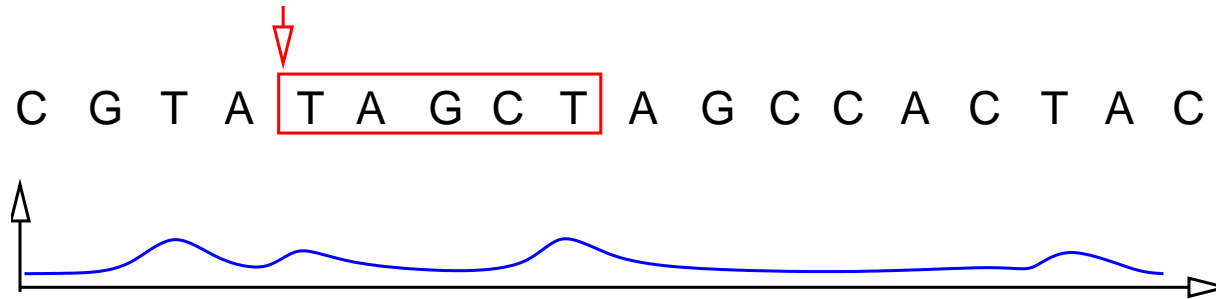
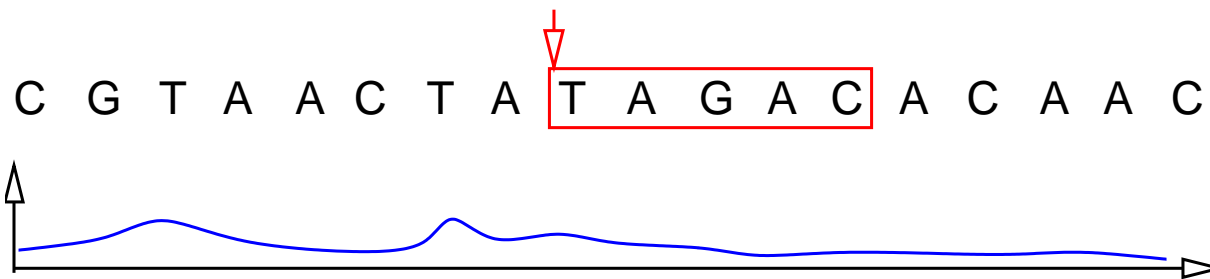
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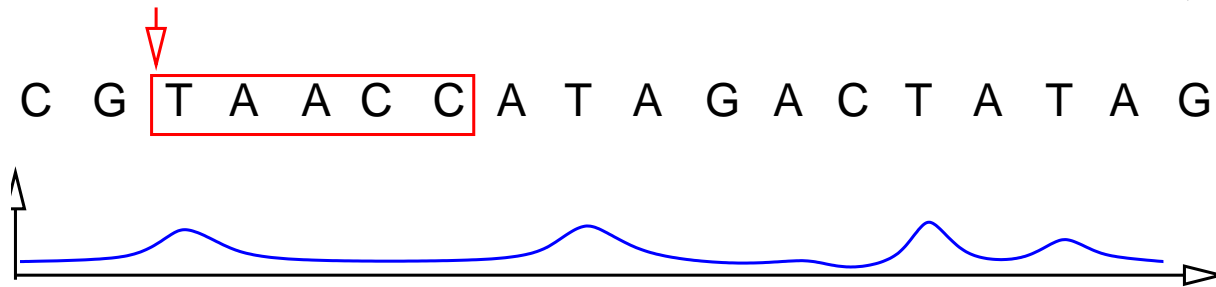
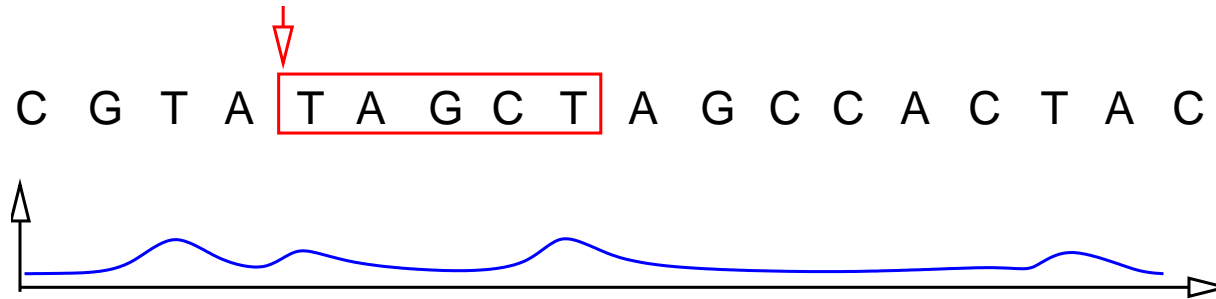
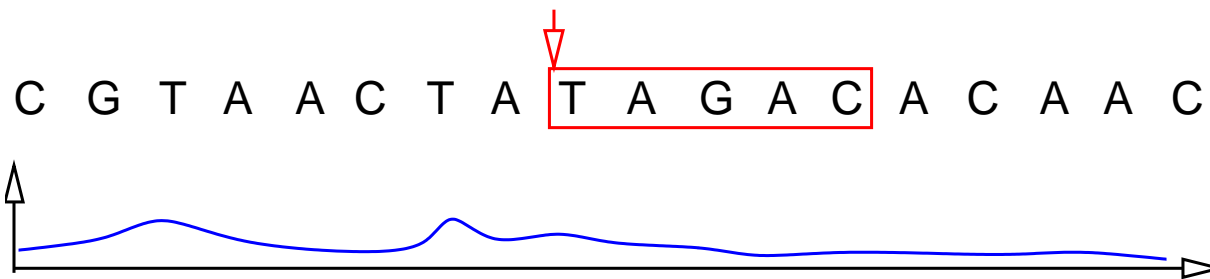
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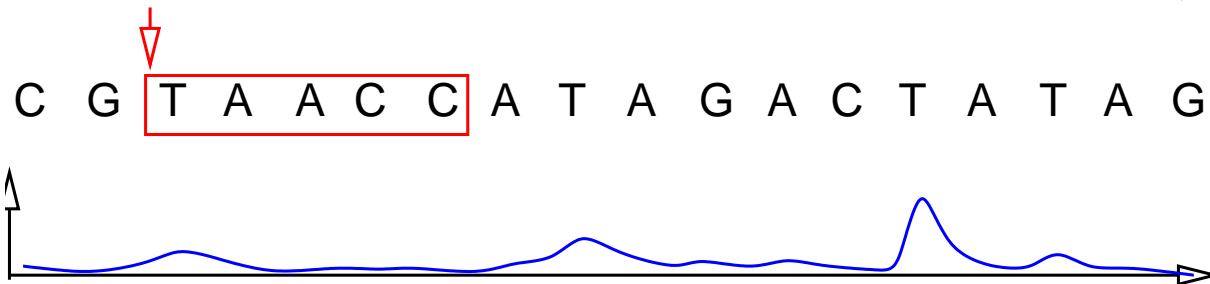
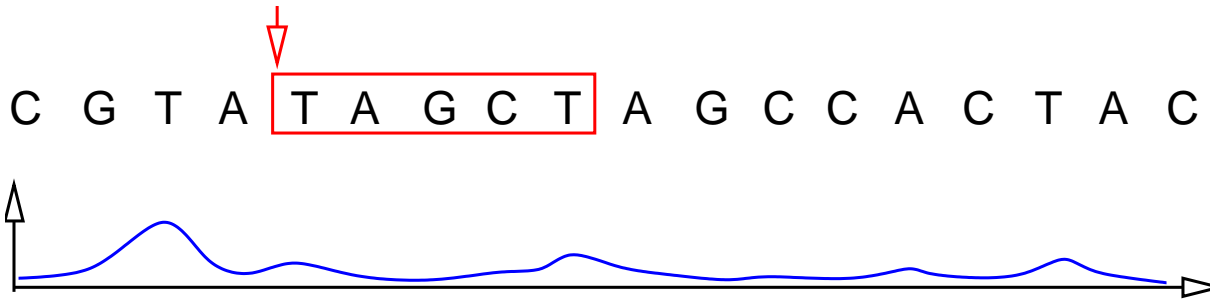
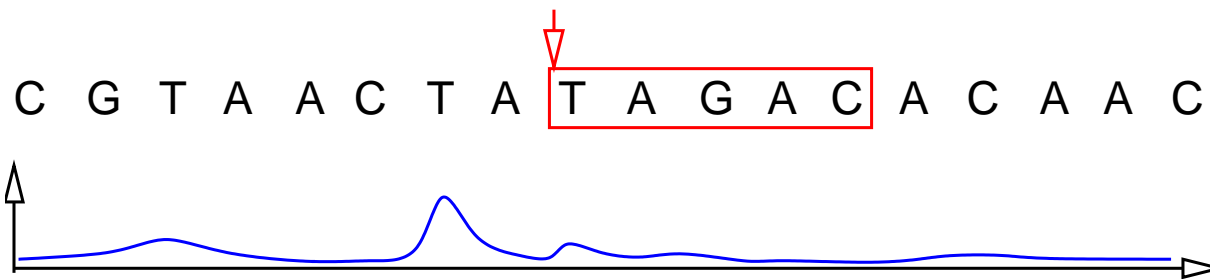
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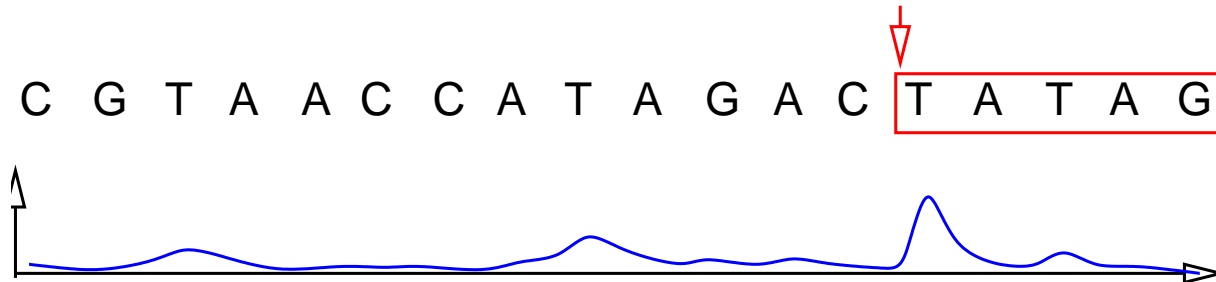
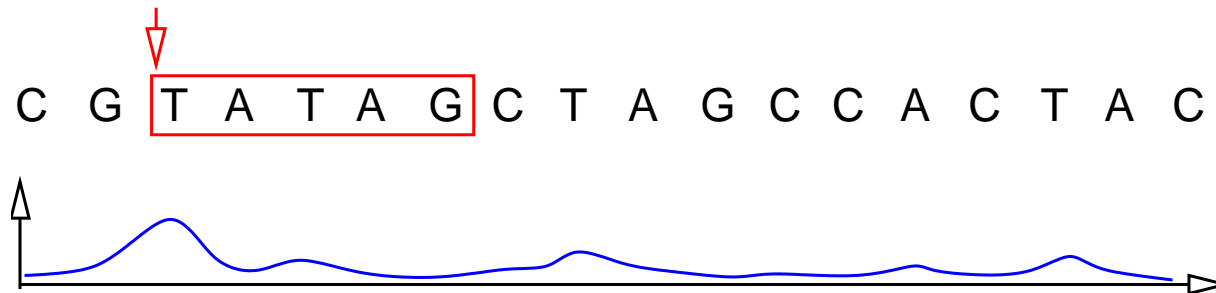
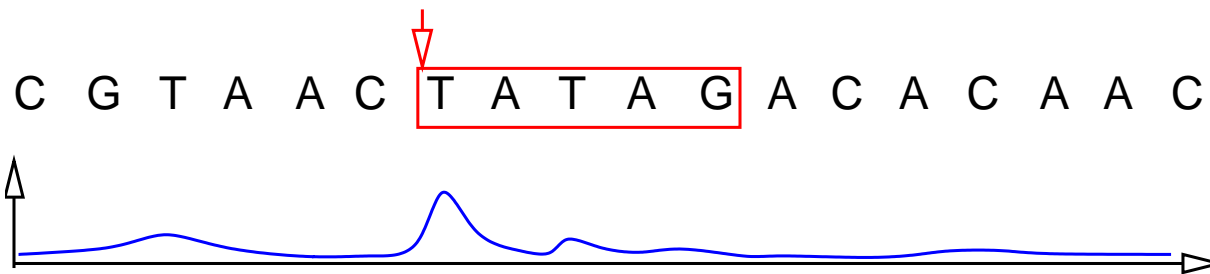
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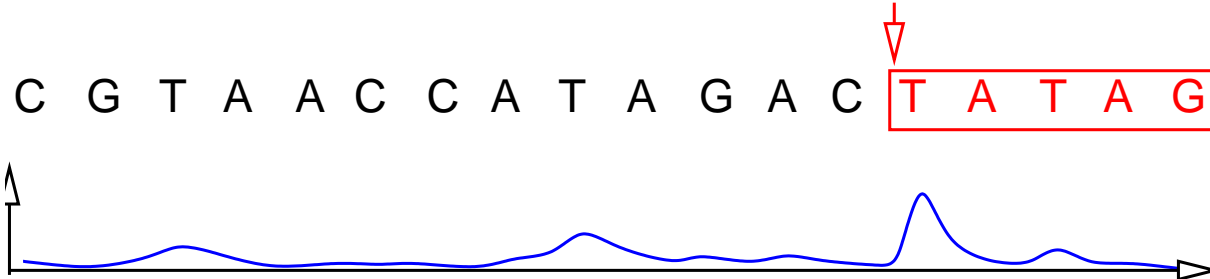
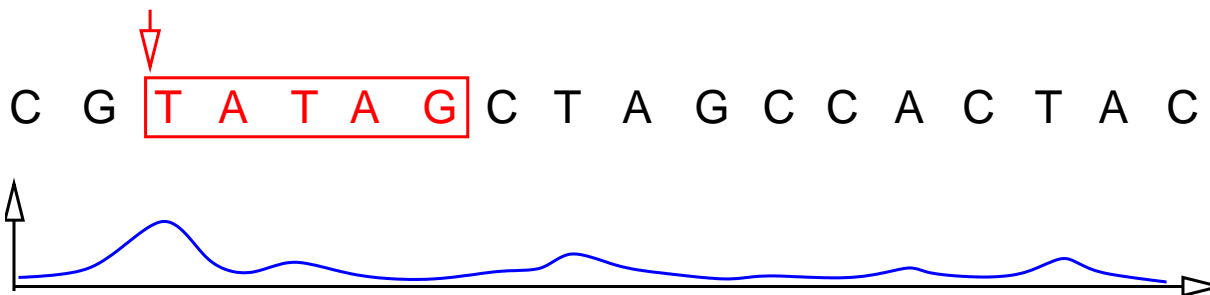
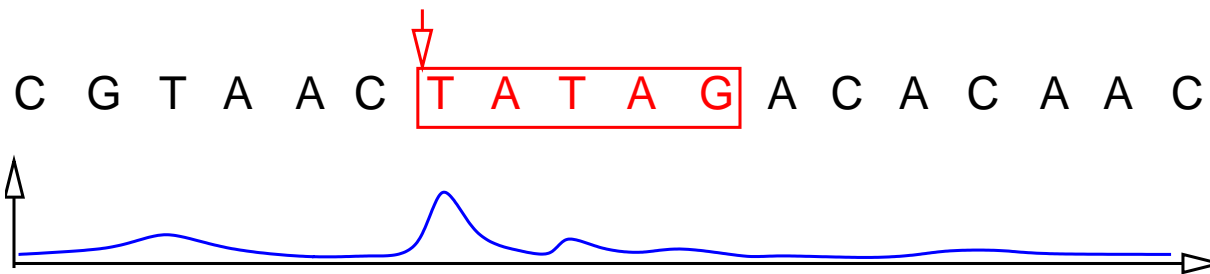
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Sufficient statistics: $\mathbf{C}_{d,s}$

$$C_{d,s,k,l} = \delta(\text{sequence}_{s,a_{d,s}+k} = l)$$

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Sequence s

H P K W S P L P P W H K

Sufficient statistics: $C_{d,s}$

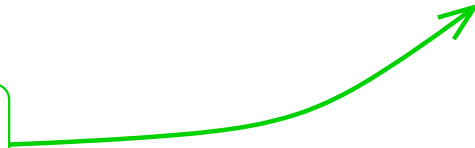
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Sequence s

H P K W S P L P P W H K

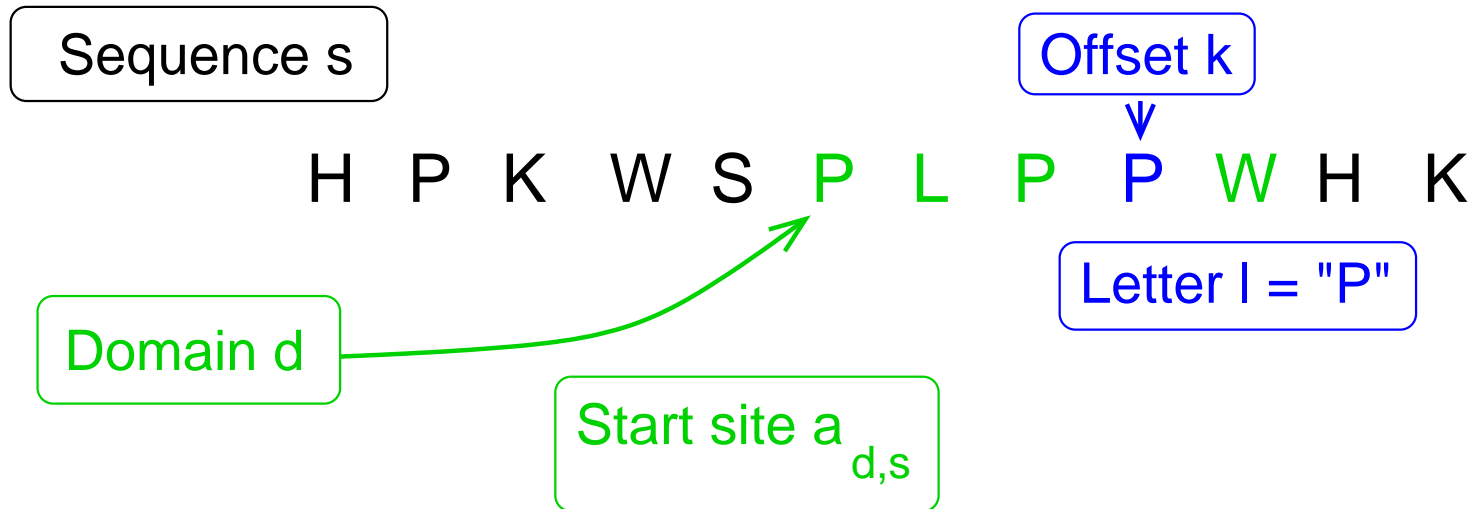
Domain d

Start site $a_{d,s}$



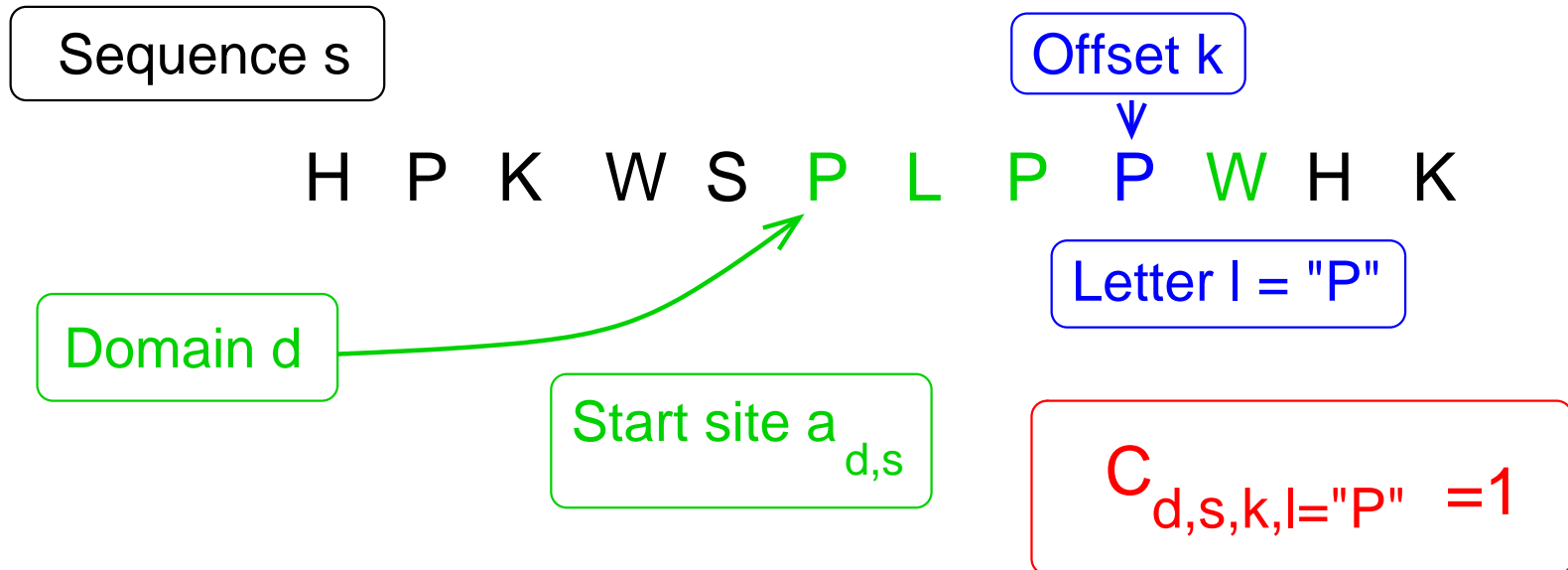
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In words: $C_{d,s,k,l}$ is 1 if the k th position of the binding motif in sequence s that binds to PRM domain d is amino acid l . Otherwise, it is zero.

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Problem:

There are too few binding peptide sequences (average: 9 sequences per domain) \Rightarrow high estimation uncertainty.



Predicting protein–peptide interactions via a network-based motif sampler

David J. Reiss and Benno Schwikowski*

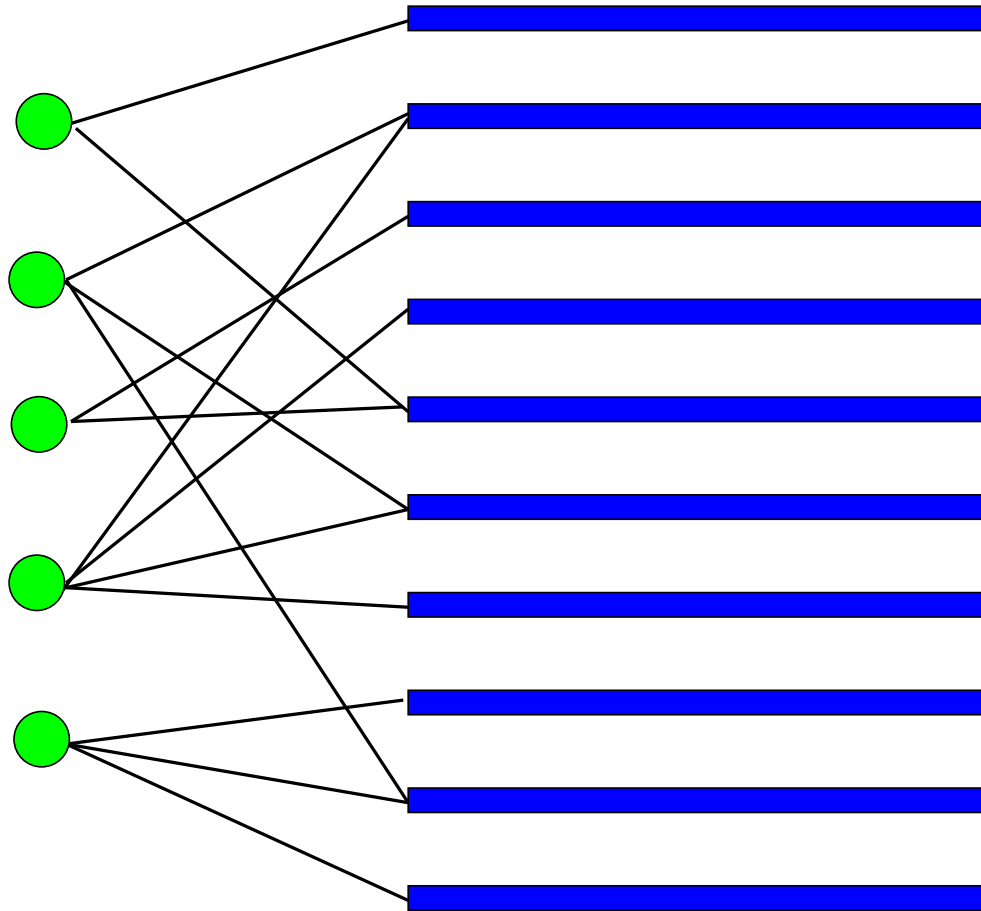
Institute for Systems Biology, 1441 North 34th street, Seattle, WA 98103-8904, USA

Received on January 15, 2004; accepted on March 1, 2004

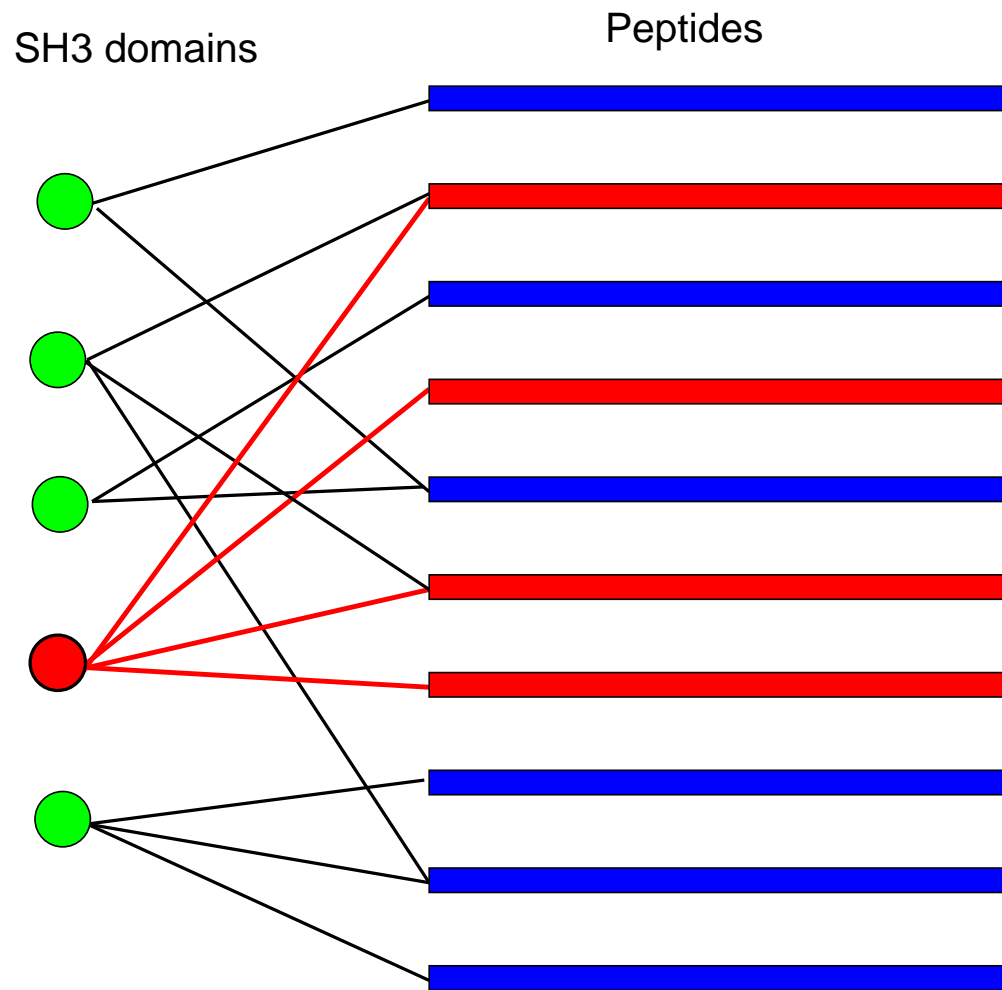
Modify the count matrix $C_{d,s}$, using the network topology.

SH3 domains

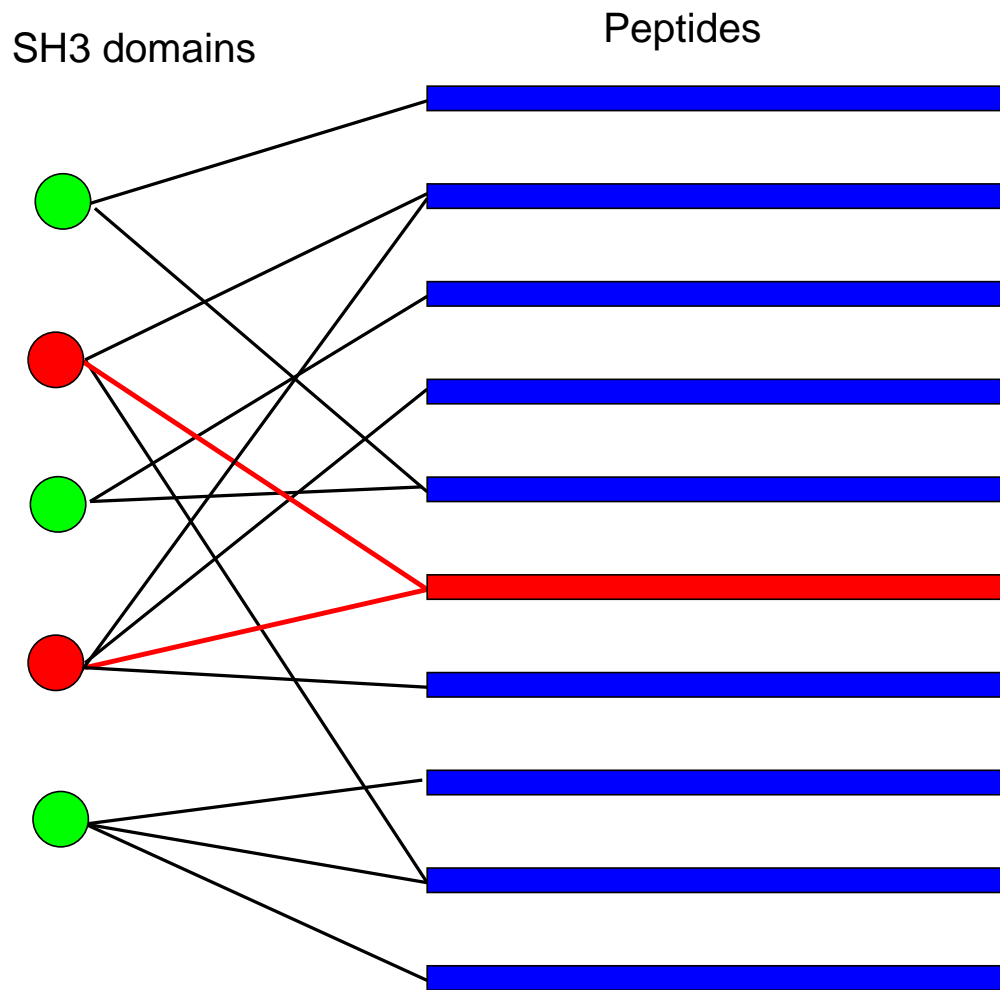
Peptides



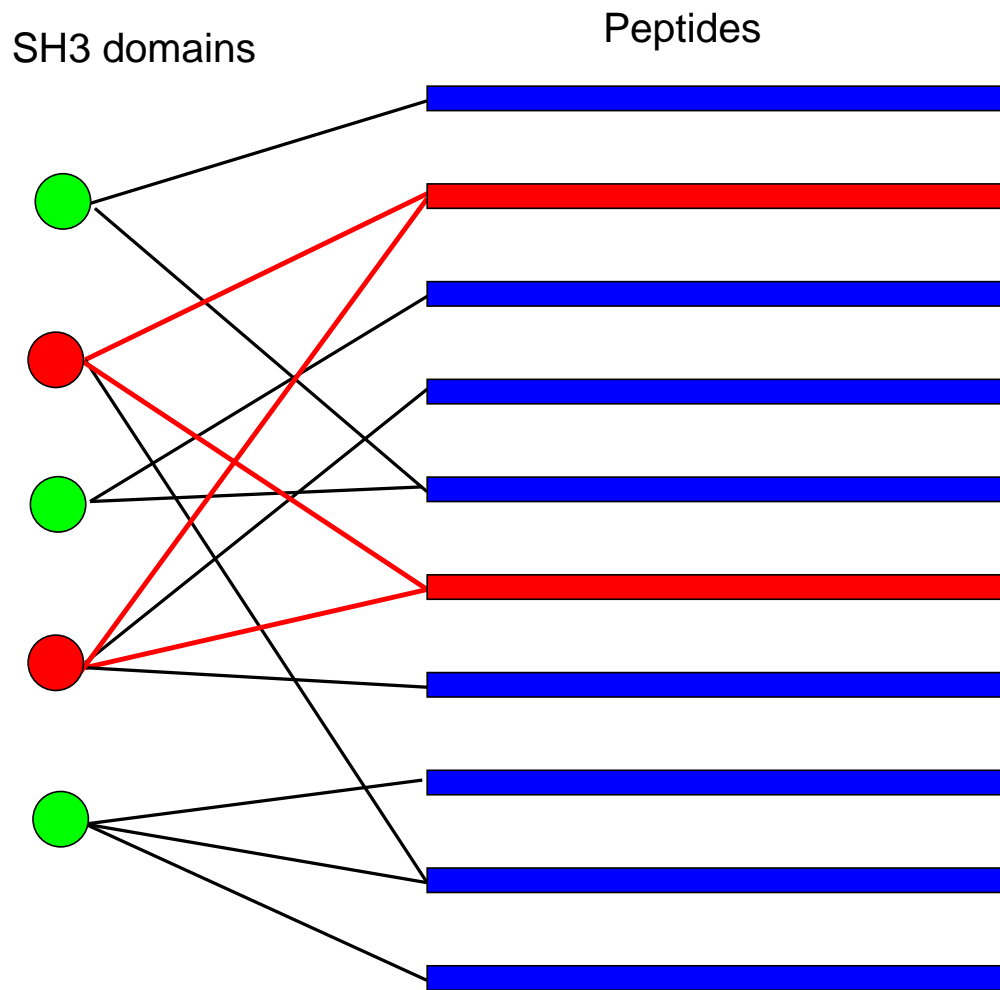
$\tilde{C}_{d,s}$



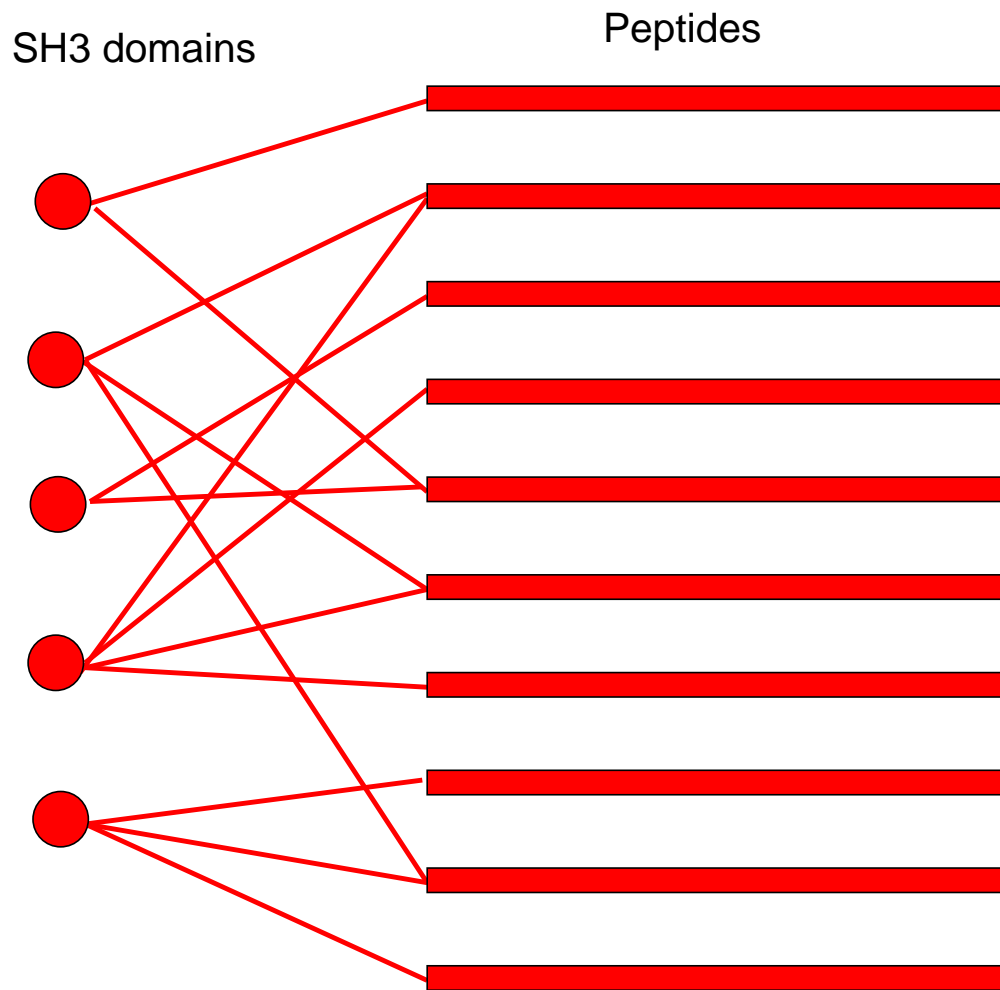
$$\tilde{\mathbf{C}}_{d,s} = \sum_s \varepsilon_{d,s} \mathbf{C}_{d,s}$$



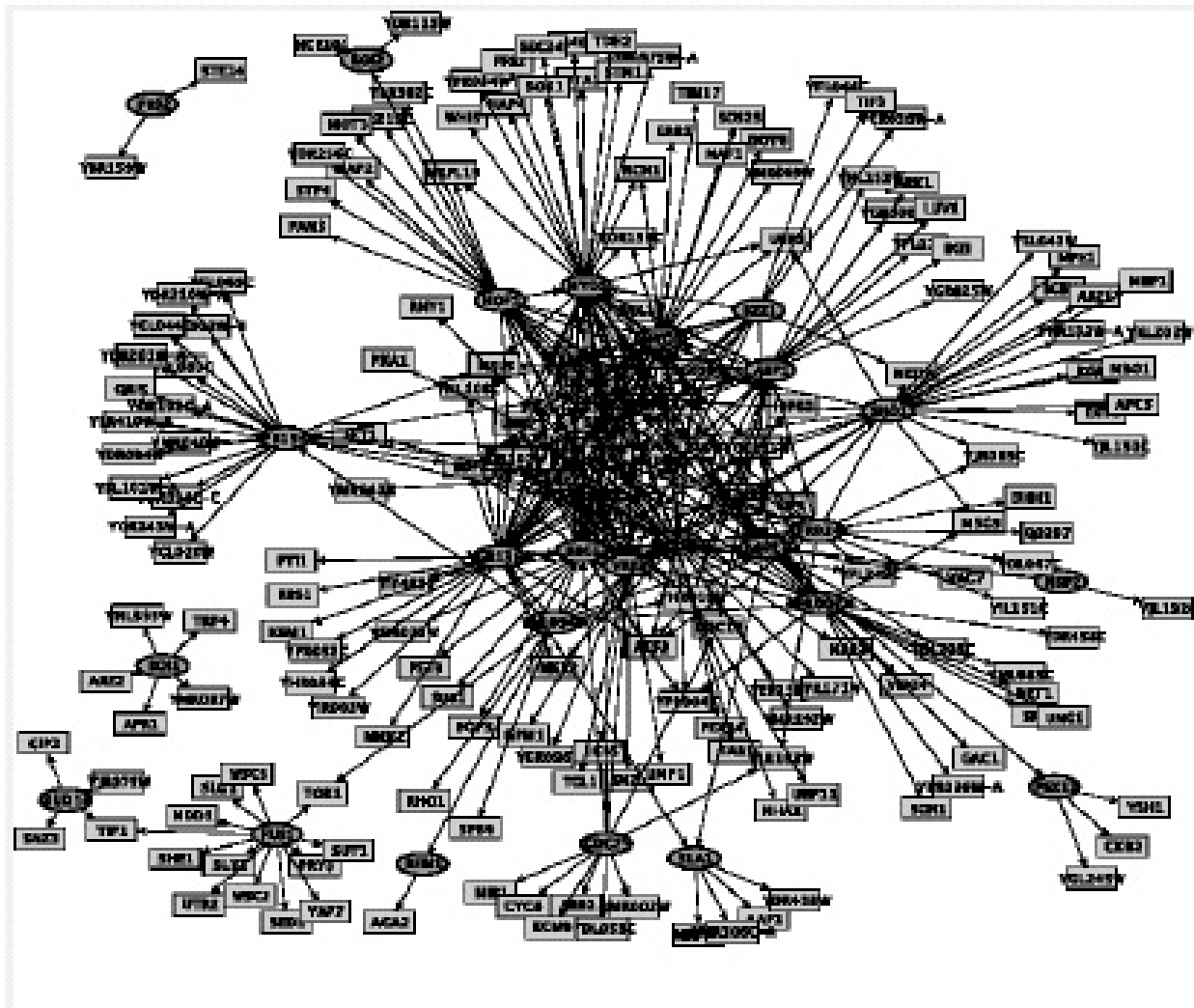
$$\tilde{\mathbf{C}}_{d,s} = \sum_s \varepsilon_{d,s} \mathbf{C}_{d,s} + \lambda_1 \sum_d \varepsilon_{d,s} \mathbf{C}_{d,s}$$



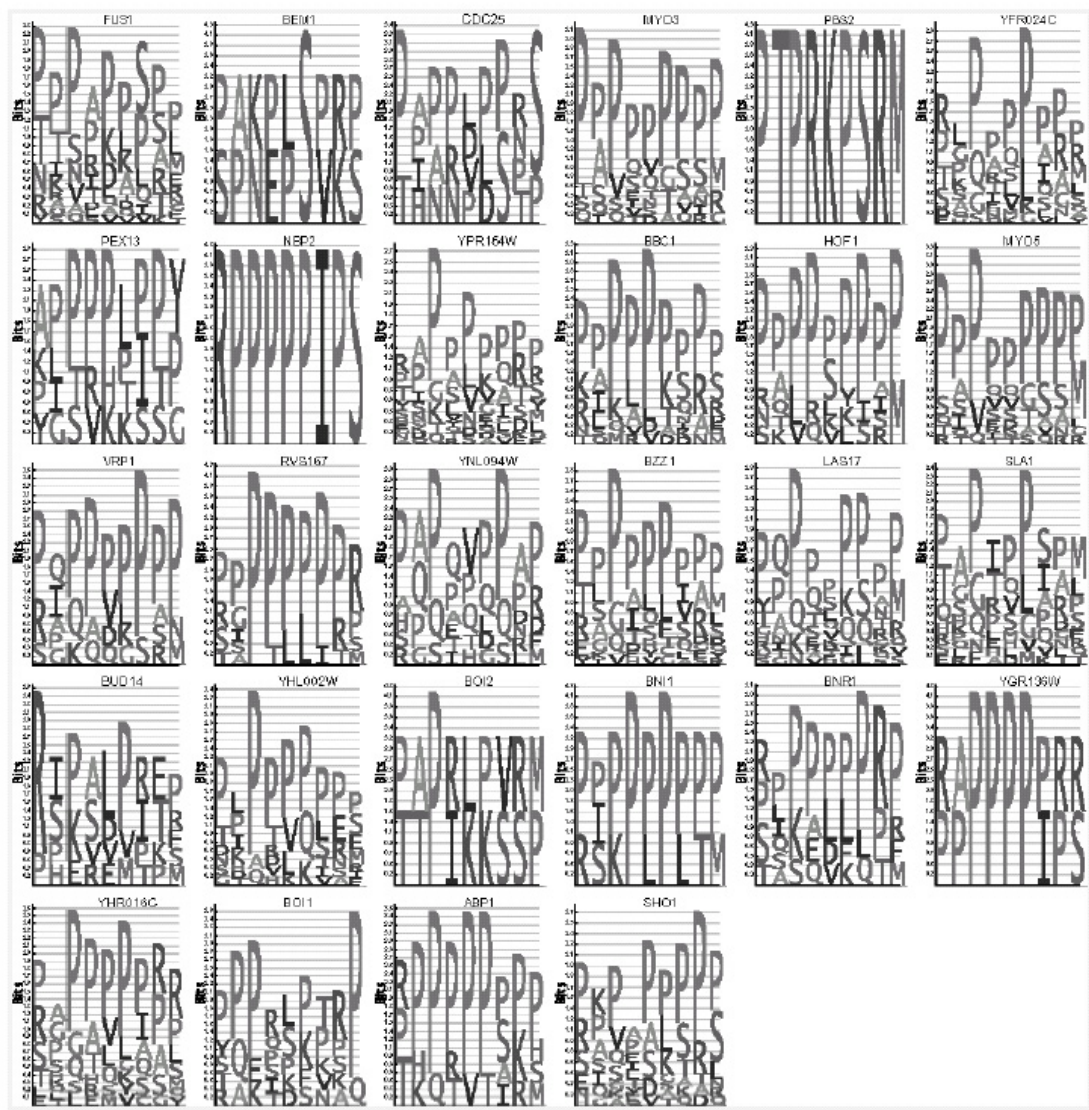
$$\tilde{\mathbf{C}}_{d,s} = \sum_s \varepsilon_{d,s} \mathbf{C}_{d,s} + \lambda_1 \sum_d \varepsilon_{d,s} \mathbf{C}_{d,s}$$



$$\tilde{\mathbf{C}}_{d,s} = \sum_s \varepsilon_{d,s} \mathbf{C}_{d,s} + \lambda_1 \sum_d \varepsilon_{d,s} \mathbf{C}_{d,s} + \lambda_2 \sum_s \sum_d \varepsilon_{d,s} \mathbf{C}_{d,s}$$



SH3 domain protein interaction network in *S. cerevisiae*; from Tong et al. (2002)



Reiss & Schwikowski (2004)

$$\tilde{\mathbf{C}}_{d,s} = \sum_s \varepsilon_{d,s} \mathbf{C}_{d,s} + \lambda_1 \sum_d \varepsilon_{d,s} \mathbf{C}_{d,s} + \lambda_2 \sum_s \sum_d \varepsilon_{d,s} \mathbf{C}_{d,s}$$

Reiss & Schwikowski (2004)

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Heuristic modification to make the model more discriminative: Give higher probability to sites that are distinct from non-binding motifs. New tuning parameter λ_3

Sequence analysis

A regularized discriminative model for the prediction of protein–peptide interactions

Wolfgang P. Lehrach^{1,2,*}, Dirk Husmeier² and Christopher K. I. Williams¹

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Binding sequence: $R=1$, motif starting at position $m+1$

$$P(S_1, S_2, \dots, S_N | R = 1, \text{start} = m + 1) = \prod_{t=1}^N \theta_0(S_t) \prod_{k=1}^W \frac{\psi_k(S_{m+k})}{\theta_0(S_{m+k})} \text{Binding}$$

sequence: $R=1$, motif starting anywhere

$$\begin{aligned} &P(S_1, S_2, \dots, S_N | R = 1) \\ &= \sum_{m=0}^{N-W} P(\text{start} = m + 1) P(S_1, S_2, \dots, S_N | R = 1, \text{start} = m + 1) \\ &= \prod_{t=1}^N \theta_0(S_t) \frac{1}{N - W + 1} \sum_{m=0}^{N-W} \prod_{k=1}^W \frac{\psi_k(S_{m+k})}{\theta_0(S_{m+k})} \end{aligned}$$

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Objective: Prediction of binding activity from sequence:

$$P(R = 1 | S_1, S_2, \dots, S_N)$$

Apply Bayes rule:

$$\begin{aligned} P(R = 1|S_1, S_2, \dots, S_N) &= \frac{P(S_1, S_2, \dots, S_N|R = 1)P(R = 1)}{P(S_1, S_2, \dots, S_N)} \\ &= \frac{P(S_1, S_2, \dots, S_N|R = 1)P(R = 1)}{P(S_1, S_2, \dots, S_N|R = 0)P(R = 0) + P(S_1, S_2, \dots, S_N|R = 1)P(R = 1)} \\ &= \left(1 + \frac{P(R = 0)P(S_1, S_2, \dots, S_N|R = 0)}{P(R = 1)P(S_1, S_2, \dots, S_N|R = 1)} \right)^{-1} \\ &= \left(1 + \left[\frac{P(R = 1)}{P(R = 0)} \frac{1}{(N - W + 1)} \sum_{m=0}^{N-W} \prod_{k=1}^W \frac{\psi_k(S_{m+k})}{\theta_0(S_{m+k})} \right]^{-1} \right)^{-1} \end{aligned}$$

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$$\begin{aligned} P(R = 1|S_1, S_2, \dots, S_N) &= \frac{P(S_1, S_2, \dots, S_N|R = 1)P(R = 1)}{P(S_1, S_2, \dots, S_N)} \\ &= \frac{P(S_1, S_2, \dots, S_N|R = 1)P(R = 1)}{P(S_1, S_2, \dots, S_N|R = 0)P(R = 0) + P(S_1, S_2, \dots, S_N|R = 1)P(R = 1)} \\ &= \left(1 + \frac{P(R = 0)P(S_1, S_2, \dots, S_N|R = 0)}{P(R = 1)P(S_1, S_2, \dots, S_N|R = 1)} \right)^{-1} \\ &= \left(1 + \left[\frac{P(R = 1)}{P(R = 0)} \frac{1}{(N - W + 1)} \sum_{m=0}^{N-W} \prod_{k=1}^W \frac{\psi_k(S_{m+k})}{\theta_0(S_{m+k})} \right]^{-1} \right)^{-1} \end{aligned}$$

Define:

$$w_k(l) = \log \frac{\psi_k(l)}{\theta_0(l)}, \quad w_0 = \frac{P(R=1)}{P(R=0)}, \quad \text{logit}(z) = \frac{1}{1+\exp(-z)}$$

$$P(R = 1 | S_1, S_2, \dots, S_N)$$
$$= \text{logit} \left(\log \left[\frac{w_0}{N - W + 1} \sum_{m=0}^{N-W} \exp \left(\sum_{k=1}^W w_k(S_{t+k}) \right) \right] \right)$$

$4 \times W + 1$ parameters: $w_k(l)$, w_0

Motif: T A T A

T C G A A T T C T A T A G C C A C

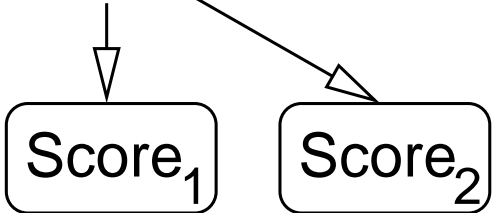
Motif: T A T^C A^C G

T C G A A T T C T A T A G C C A C

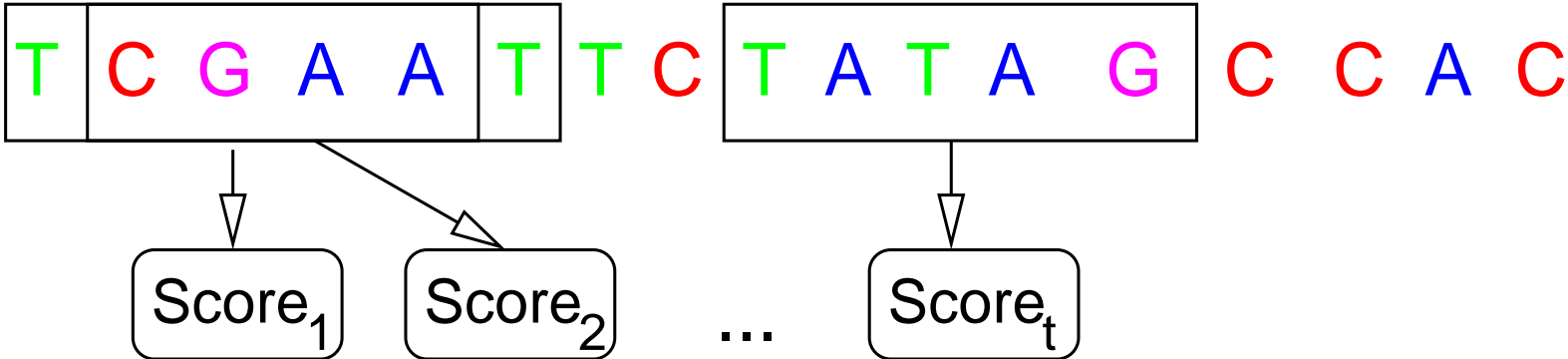
↓
Score₁

Motif: T A^C T A^C G

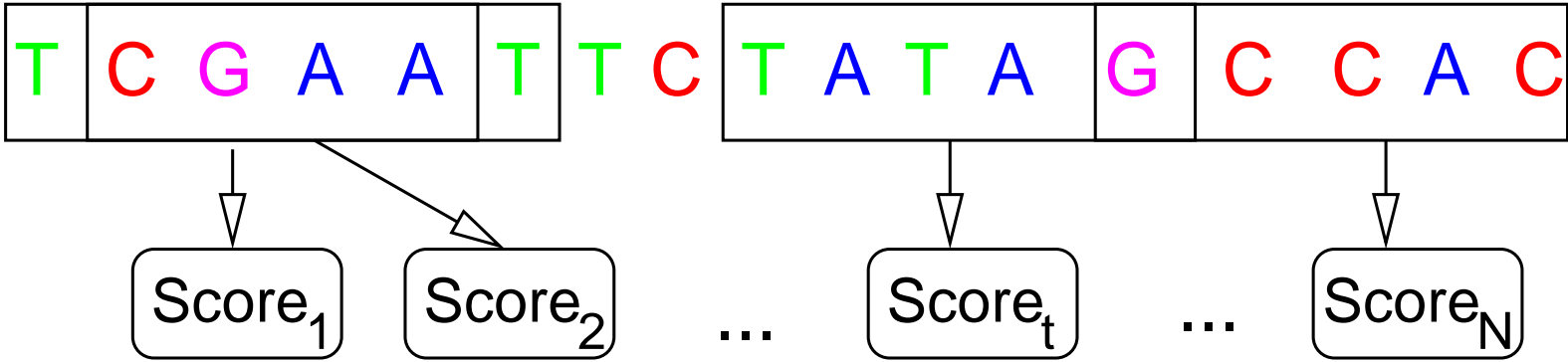
T C G A A T T C T A T A G C C A C



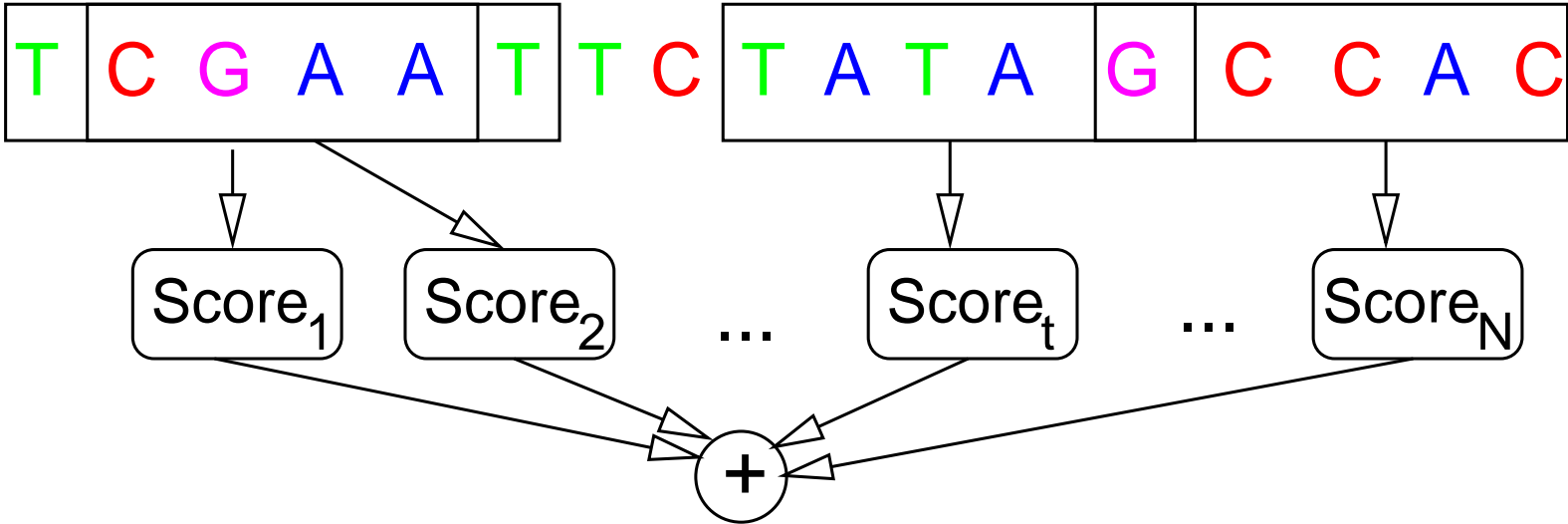
Motif: T A^C T A^C G



Motif: T A^C T A^C G



Motif: T A^C T A^C G



Motif: T A^C T A^C G

T C G A A T T C T A T A G C C A C

Score₁ Score₂ ... Score_t ... Score_N

+

Nonlinear transfer function

Motif: T A^C T A^C G

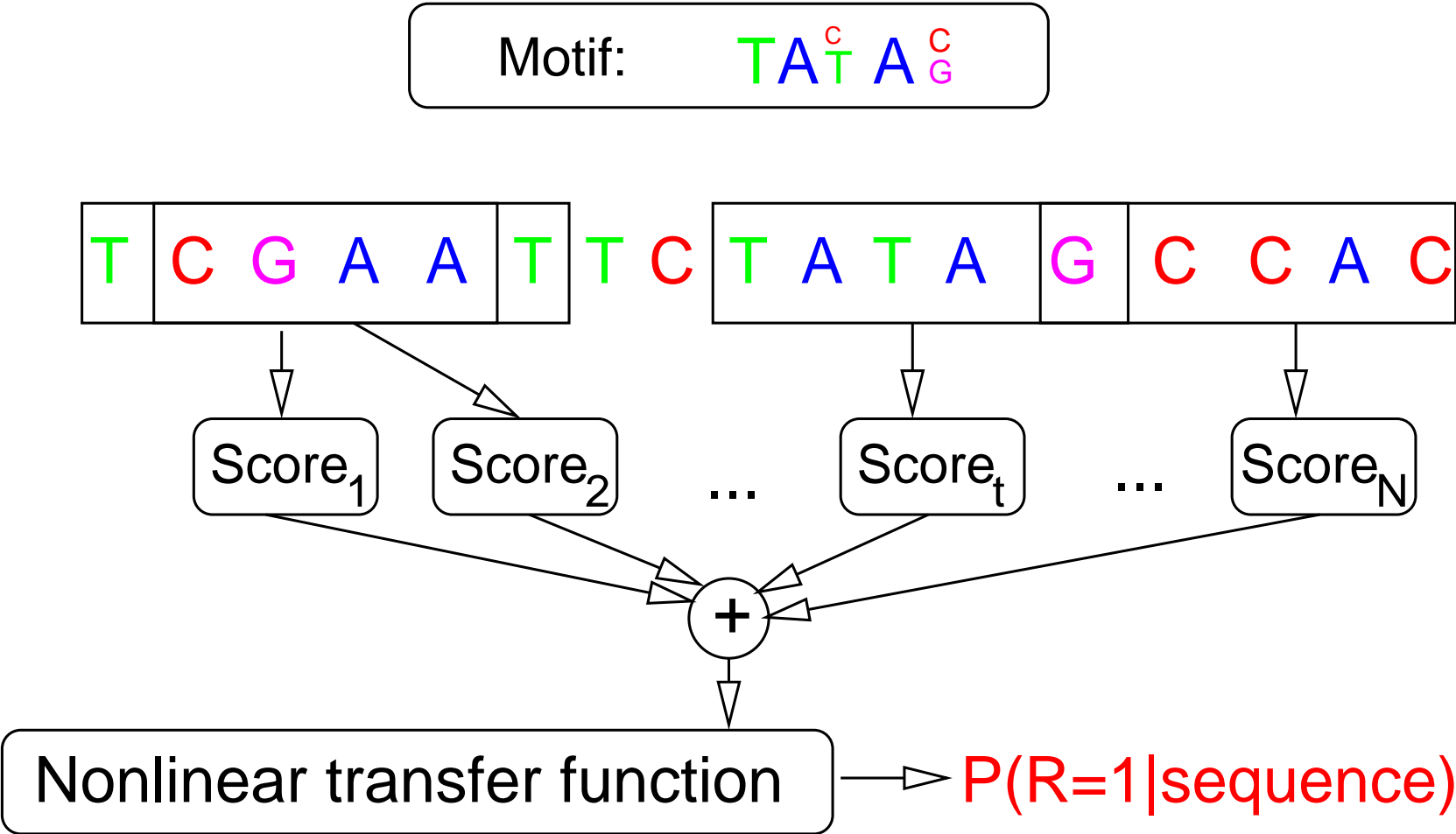
T C G A A T T C T A T A G C C A C

Score₁ Score₂ ... Score_t ... Score_N

+

Nonlinear transfer function

P(R=1|sequence)



$$P(R = 1 | S_1, S_2, \dots, S_N)$$
$$= \text{logit} \left(\log \left[\frac{w_0}{N - W + 1} \sum_{m=0}^{N-W} \exp \left(\sum_{k=1}^W w_k(S_{t+k}) \right) \right] \right)$$

$4 \times W + 1$ parameters: $w_k(l)$, w_0

Parameter estimation

Data D : Set of sequences \mathbf{x}_i with associated interaction indicators $R_i \in \{0, 1\}$

Model predicts an interaction R_i given the sequence \mathbf{x}_i :

$$y(\mathbf{x}_i, \mathbf{w}) = P(R_i = 1 | \mathbf{x}_i, \mathbf{w})$$

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Model predicts an interaction R_i given the sequence \mathbf{x}_i :

$$y(\mathbf{x}_i, \mathbf{w}) = P(R_i = 1 | \mathbf{x}_i, \mathbf{w})$$

$$P(D | \mathbf{w}) = \prod_i y(\mathbf{x}_i, \mathbf{w})^{R_i} [1 - y(\mathbf{x}_i, \mathbf{w})]^{(1-R_i)}$$

$$\log P(D | \mathbf{w}) = \sum_i R_i \log y(\mathbf{x}_i, \mathbf{w}) + (1 - R_i) \log [1 - y(\mathbf{x}_i, \mathbf{w})]$$

Parameter estimation

Maximum likelihood: $\operatorname{argmax}_{\mathbf{w}} P(D|\mathbf{w})$

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Iterative optimisation scheme with gradient descent:

$$E_D(\mathbf{w}) = -\log P(D|\mathbf{w})$$

$$\Delta\mathbf{w} \propto -\nabla_{\mathbf{w}} E_D(\mathbf{w})$$

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Problem: overfitting!

Parameter estimation

Maximum likelihood: $\operatorname{argmax}_{\mathbf{w}} P(D|\mathbf{w})$

Iterative optimisation scheme with gradient descent:

$$E_D(\mathbf{w}) = -\log P(D|\mathbf{w})$$

$$\Delta\mathbf{w} \propto -\nabla_{\mathbf{w}} E_D(\mathbf{w})$$

Problem: overfitting!

Regularisation:

$$P(\mathbf{w}) = \frac{1}{Z} \exp(-\alpha E_R(\mathbf{w}))$$

Maximum a posteriori:

$$\operatorname{argmax}_{\mathbf{w}} P(\mathbf{w}|D)$$

Bayes rule: $P(\mathbf{w}|D) \propto P(D|\mathbf{w})P(\mathbf{w})$

$$\operatorname{argmax}_{\mathbf{w}} [\log P(D|\mathbf{w}) + \log P(\mathbf{w})]$$

Maximum a posteriori:

$$\operatorname{argmax}_{\mathbf{w}} P(\mathbf{w}|D)$$

Bayes rule: $P(\mathbf{w}|D) \propto P(D|\mathbf{w})P(\mathbf{w})$

$$\operatorname{argmax}_{\mathbf{w}} [\log P(D|\mathbf{w}) + \log P(\mathbf{w})]$$

$$P(\mathbf{w}) \propto \exp[-\alpha E_R(\mathbf{w})]$$

$$P(D|\mathbf{w}) \propto \exp[-E_D(\mathbf{w})]$$

$$\Delta \mathbf{w} \propto -\nabla_{\mathbf{w}} E_D(\mathbf{w}) - \alpha \nabla_{\mathbf{w}} E_R(\mathbf{w})$$

Weight decay:

$$\Delta \mathbf{w} \propto -\nabla_{\mathbf{w}} E_D(\mathbf{w}) - \alpha \nabla_{\mathbf{w}} E_R(\mathbf{w})$$

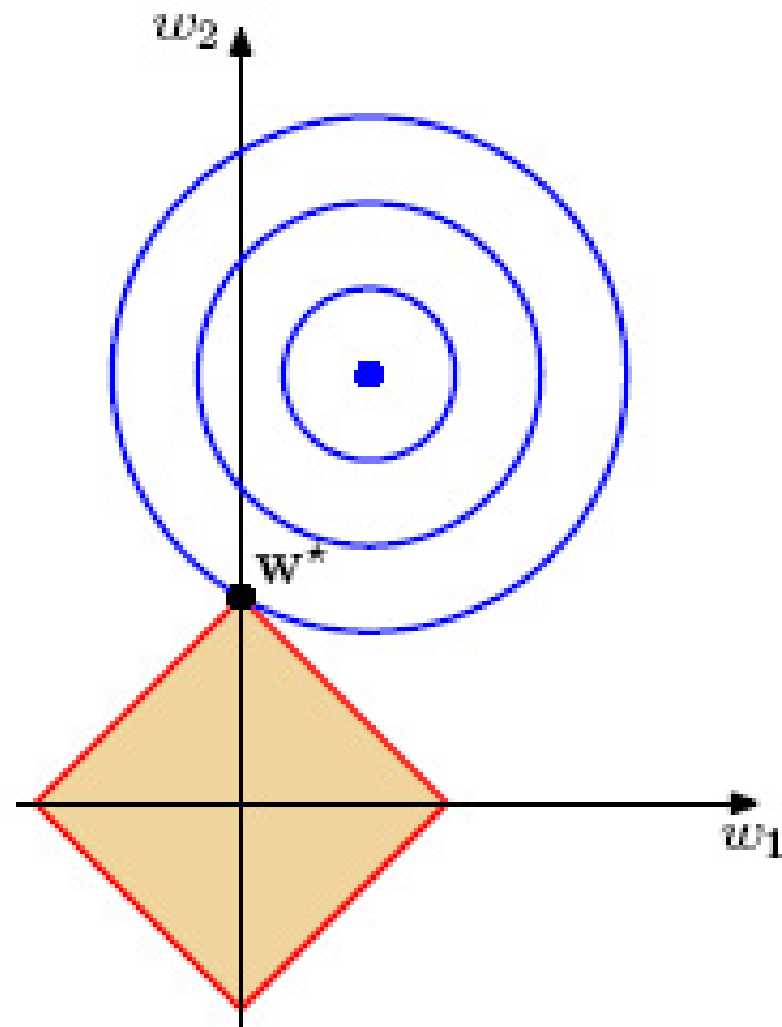
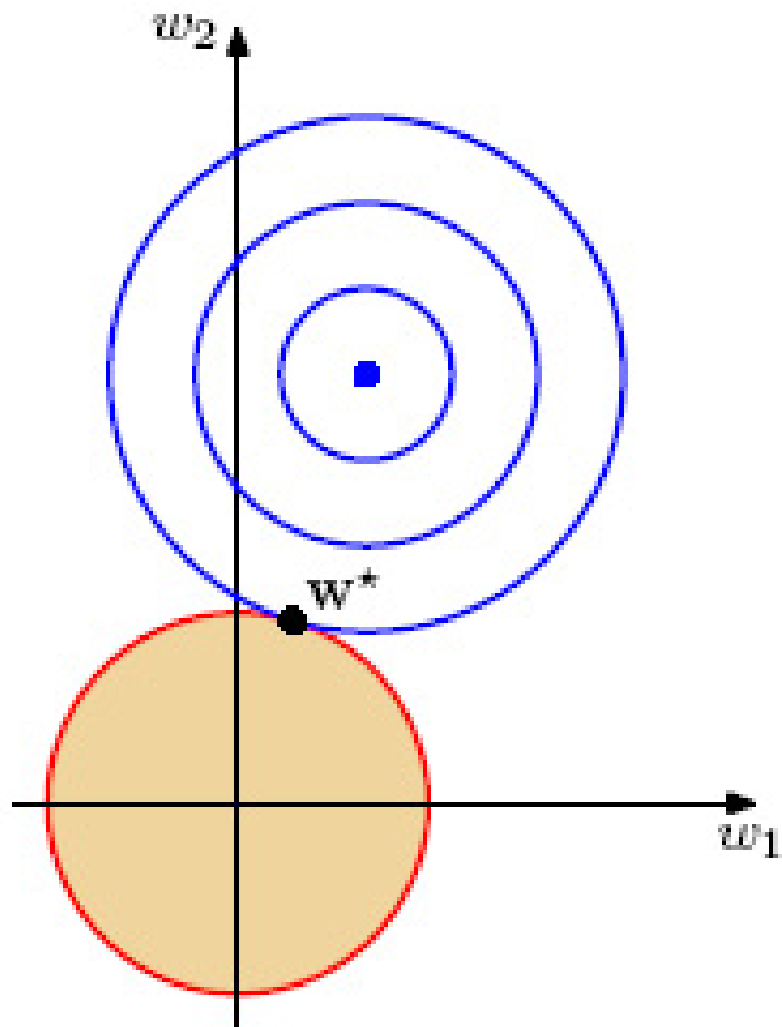
Gaussian prior: $E_R(\mathbf{w}) = \mathbf{w}^2$

Laplacian prior: $E_R(\mathbf{w}) = |\mathbf{w}|$

Justification of regularisation

$$\begin{aligned} P(R = 1|S_1, S_2, \dots, S_N) &= \frac{P(S_1, S_2, \dots, S_N|R = 1)P(R = 1)}{P(S_1, S_2, \dots, S_N)} \\ &= \frac{P(S_1, S_2, \dots, S_N|R = 1)P(R = 1)}{P(S_1, S_2, \dots, S_N|R = 0)P(R = 0) + P(S_1, S_2, \dots, S_N|R = 1)P(R = 1)} \\ &= \left(1 + \frac{P(R = 0)P(S_1, S_2, \dots, S_N|R = 0)}{P(R = 1)P(S_1, S_2, \dots, S_N|R = 1)} \right)^{-1} \\ &= \left(1 + \left[\frac{P(R = 1)}{P(R = 0)} \frac{1}{(N - W + 1)} \sum_{m=0}^{N-W} \prod_{k=1}^W \frac{\psi_k(S_{m+k})}{\theta_0(S_{m+k})} \right]^{-1} \right)^{-1} \end{aligned}$$

Define: $w_k(l) = \log \frac{\psi_k(l)}{\theta_0(l)}$, $w_0 = \log \frac{P(R=1)}{P(R=0)}$



Weight decay:

$$\Delta \mathbf{w} \propto -\nabla_{\mathbf{w}} E_D(\mathbf{w}) - \alpha \nabla_{\mathbf{w}} E_R(\mathbf{w})$$

$$\text{Gaussian prior: } E_R(\mathbf{w}) = \mathbf{w}^2$$

$$\text{Laplacian prior: } E_R(\mathbf{w}) = |\mathbf{w}|$$

The **hyperparameter** α can be integrated out analytically

$$P(\mathbf{w}) = \int_0^\infty P(\mathbf{w}|\alpha)P(\alpha)d\alpha$$

$$P(\mathbf{w}|\alpha) = \frac{\exp(-\alpha E_R)}{Z(\alpha)}$$

$$Z(\alpha) \propto \left(\frac{1}{\alpha}\right)^W$$

where W is the dimension of \mathbf{w} (number of weights).

$$P(\mathbf{w}) = \int_0^\infty P(\mathbf{w}|\alpha)P(\alpha)d\alpha$$

Scale parameter: uninformative prior $P(\alpha) \propto \frac{1}{\alpha}$

$$\begin{aligned}
P(\mathbf{w}) &= \int_0^\infty P(\mathbf{w}|\alpha)P(\alpha)d\alpha \\
&= C \int_0^\infty \exp(-\alpha E_R)\alpha^{W-1}d\alpha \\
&= C E_R^{-W} \int_0^\infty \exp(-\alpha E_R)(\alpha E_R)^{(W-1)}d(\alpha E_R) \\
&= C E_R^{-W} \int_0^\infty \exp(-u)u^{W-1}du \\
&= C E_R(\mathbf{w})^{-W} \Gamma(W)
\end{aligned}$$

$$\log P(\mathbf{w}) = -W \log E_R(\mathbf{w}) + \text{const}$$

$$\nabla_{\mathbf{w}} \log P(\mathbf{w}) = -\frac{W}{E_R} \nabla_{\mathbf{w}} E_R(\mathbf{w})$$

Weight decay:

$$\Delta \mathbf{w} \propto -\nabla_{\mathbf{w}} E_D(\mathbf{w}) - \tilde{\alpha} \nabla_{\mathbf{w}} E_R(\mathbf{w}); \quad \tilde{\alpha} = \frac{W}{E_R}$$

Gaussian prior: $E_R(\mathbf{w}) = \mathbf{w}^2$

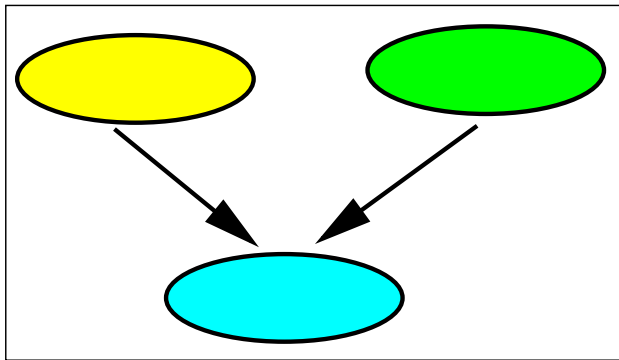
Laplacian prior: $E_R(\mathbf{w}) = |\mathbf{w}|$

Peter Williams (1995)

Bayesian regularisation and pruning
using a Laplacian prior

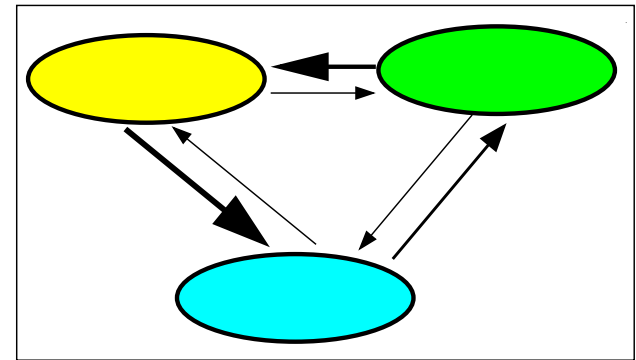
Neural Computation 7, 117–143

Evaluation



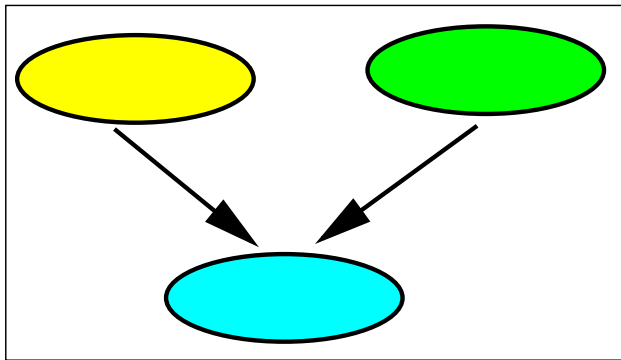
True network

← compare →



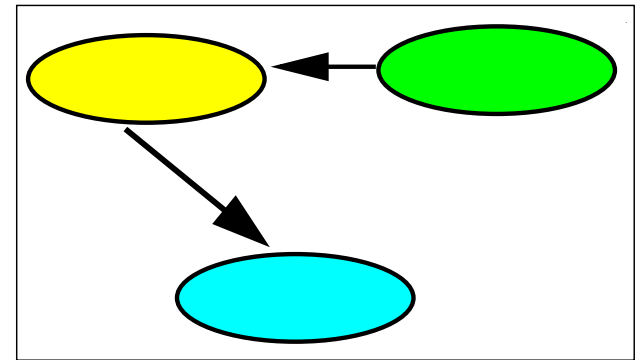
Predicted network

Probabilistic inference



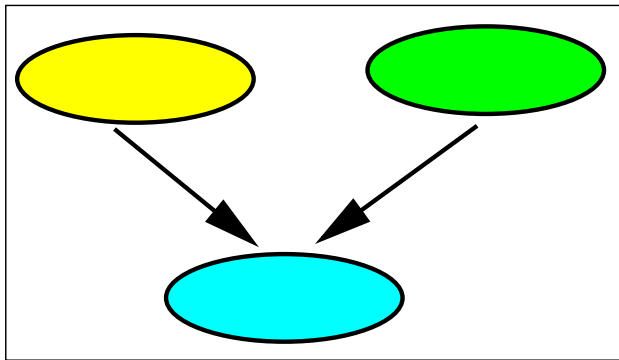
True network

compare



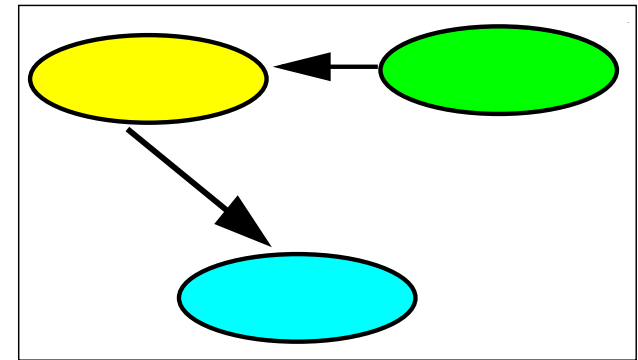
Predicted network

Thresholding



True network

compare



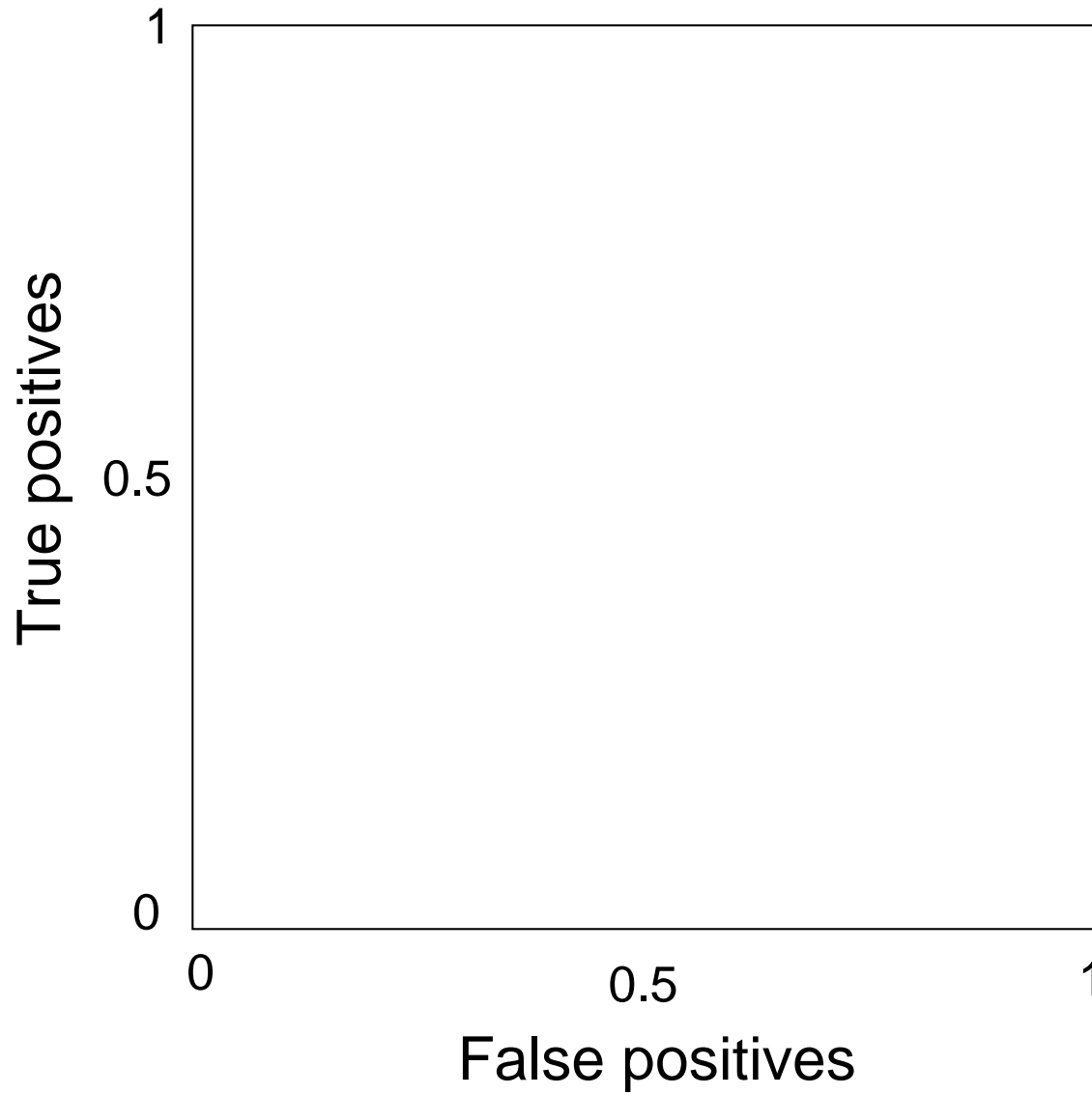
Predicted network

Thresholding

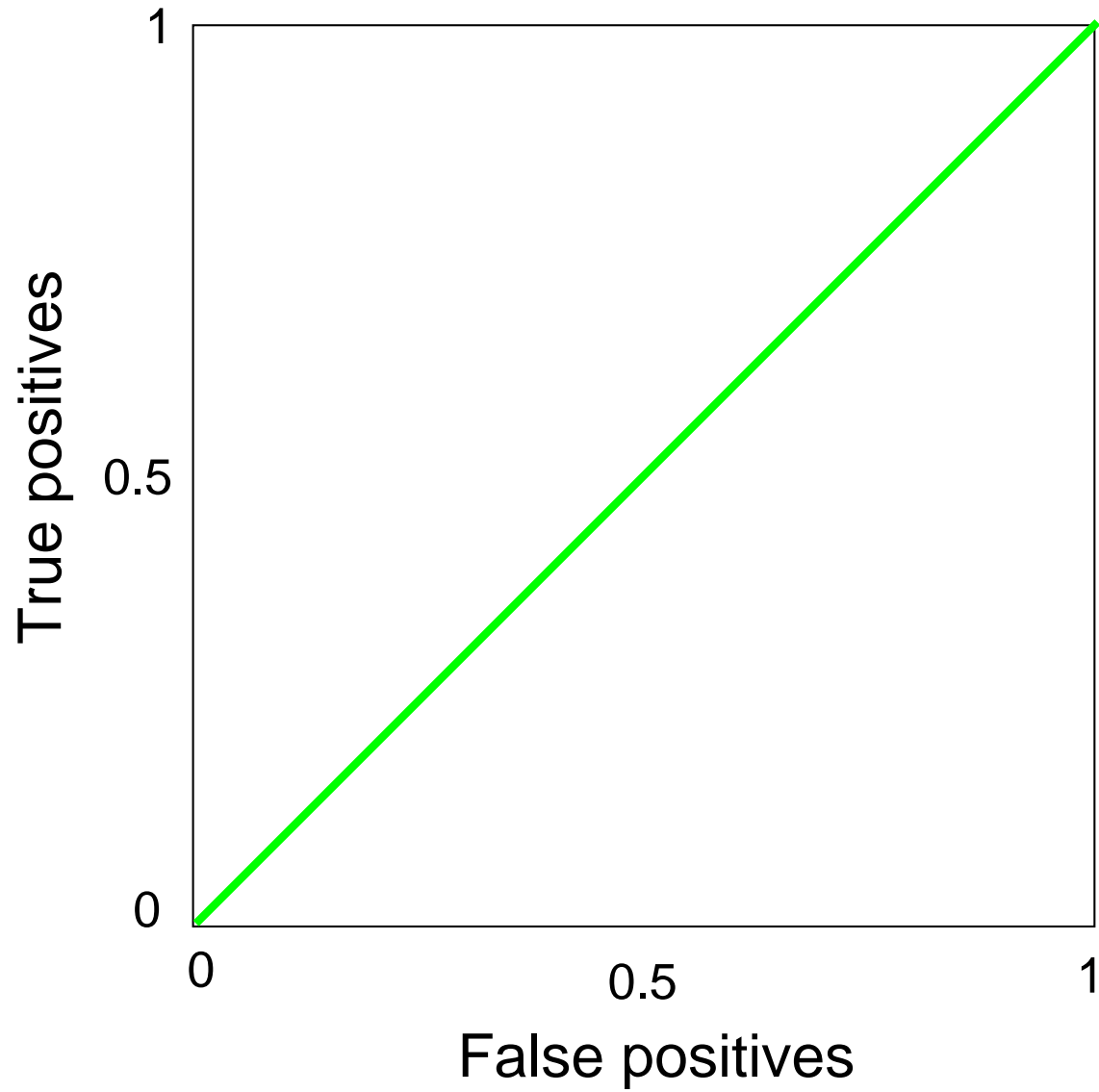
True positives

False positives

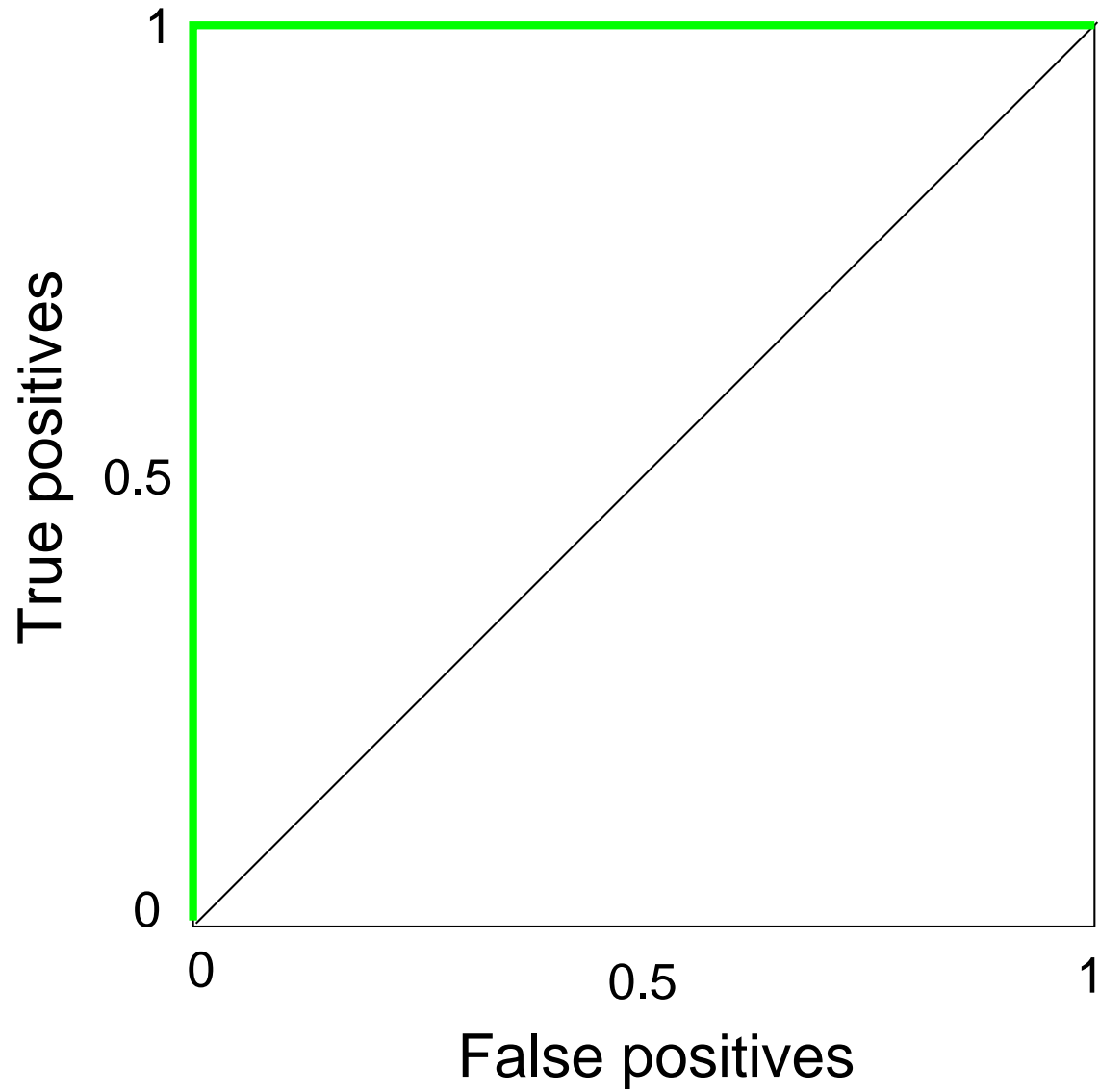
ROC curve



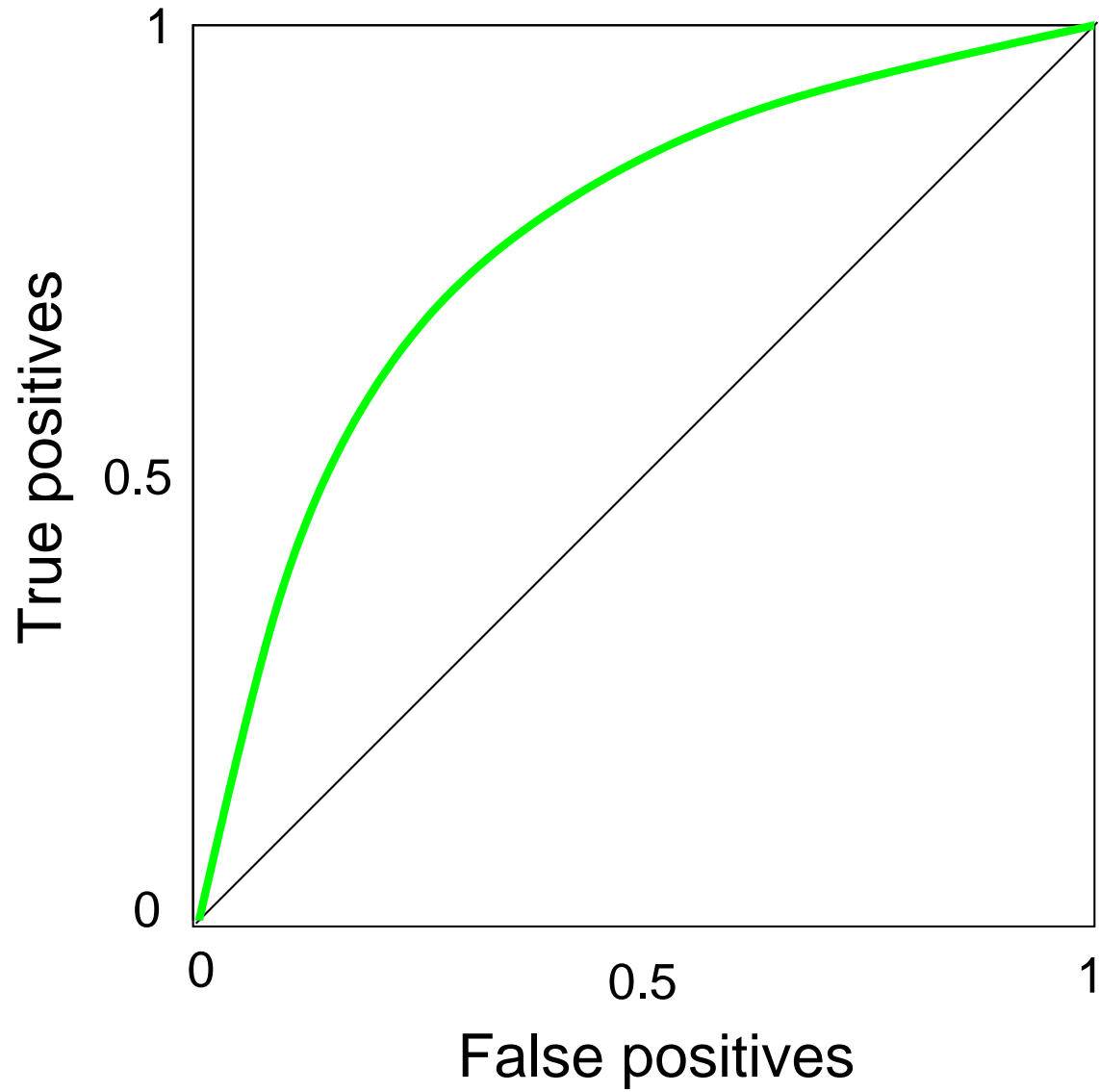
Random predictor



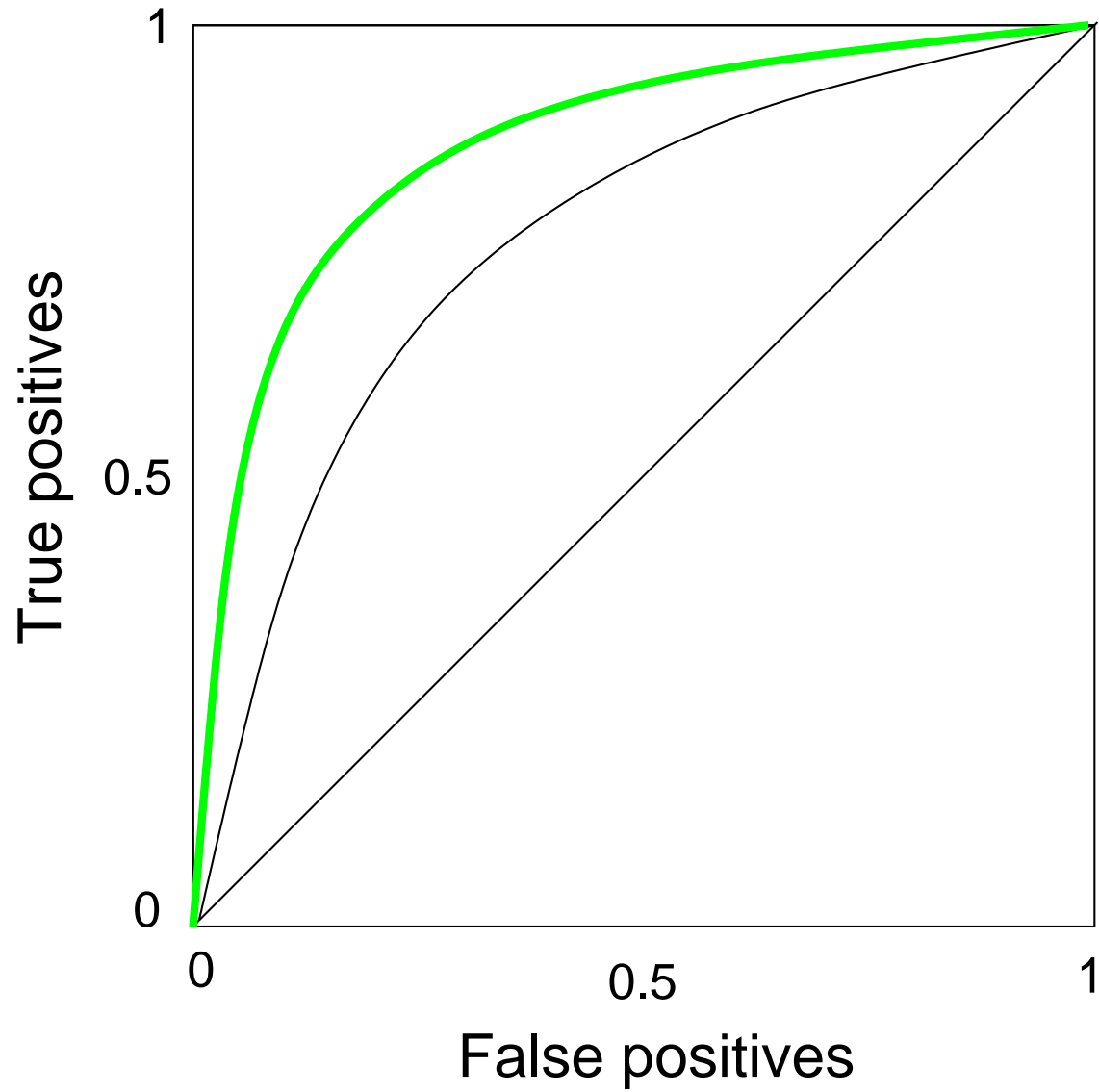
Perfect predictor



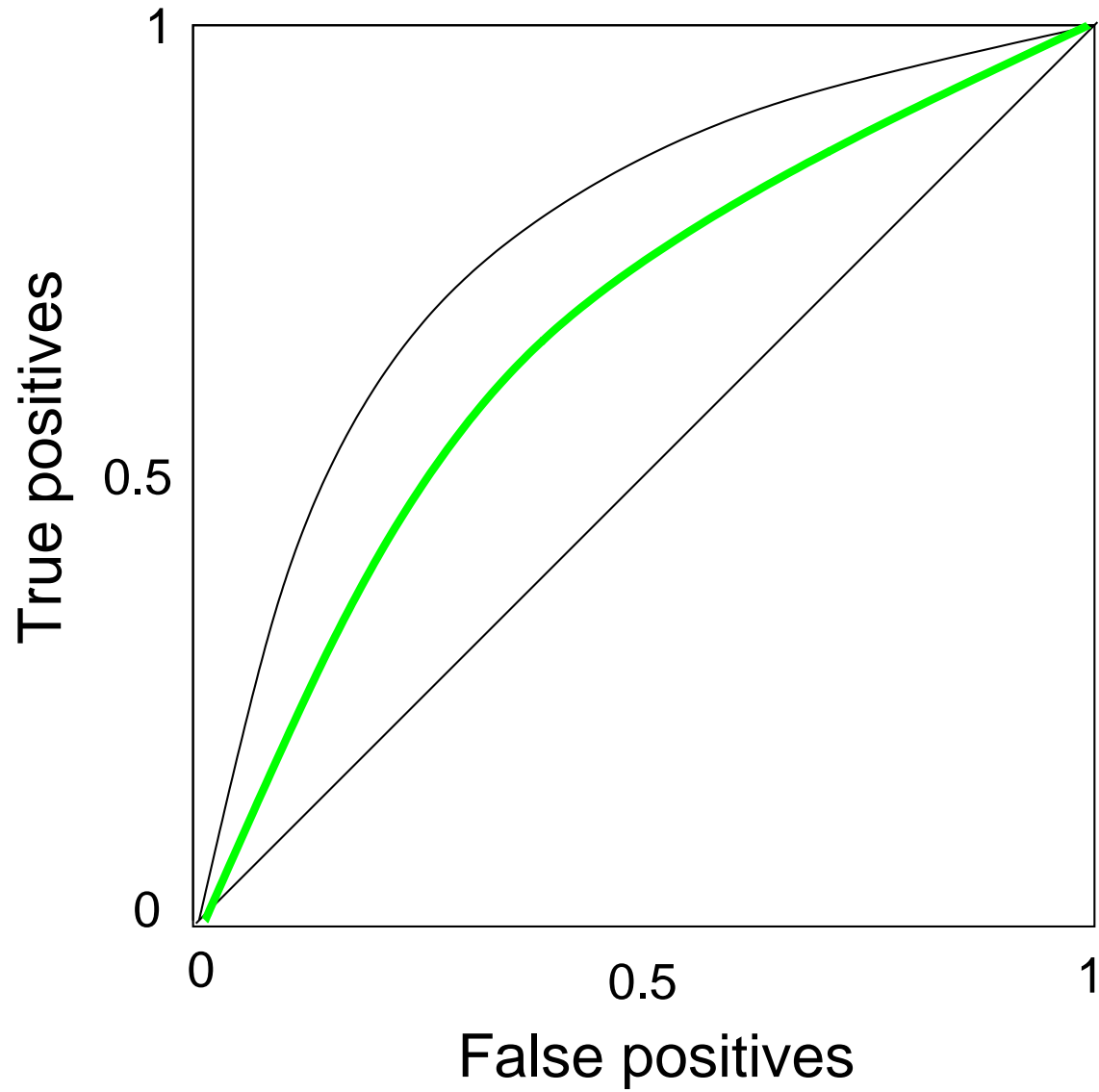
Realistic predictor



Better predictor



Poorer predictor

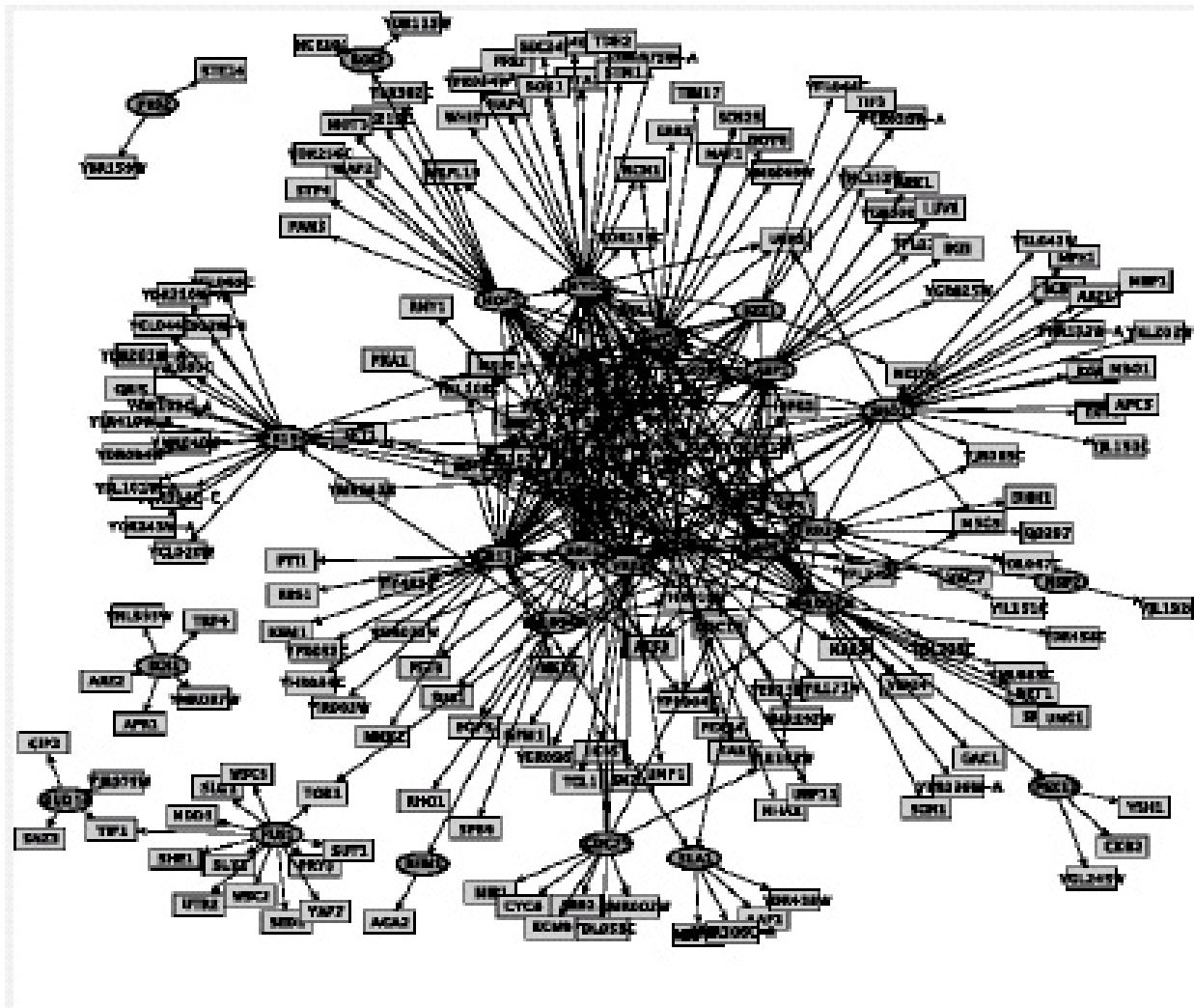


SH3 yeast two-hybrid interaction network

Tong et al. (2002), Science 295, 321-324

285 interactions between 28 SH3 proteins
and 143 binding peptides

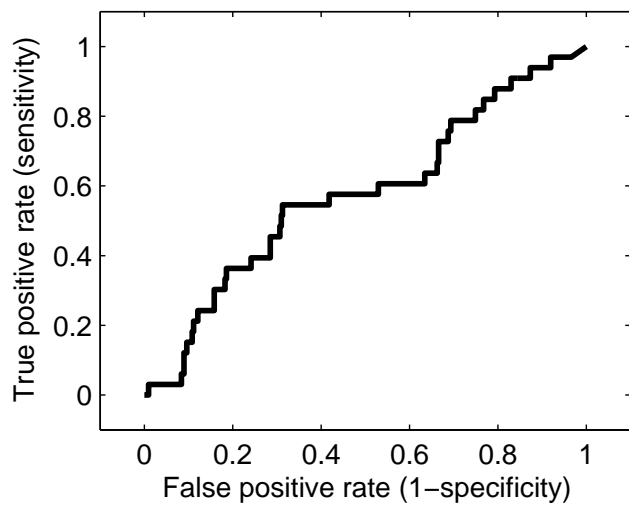
9 binding partners per SH3 domain on average



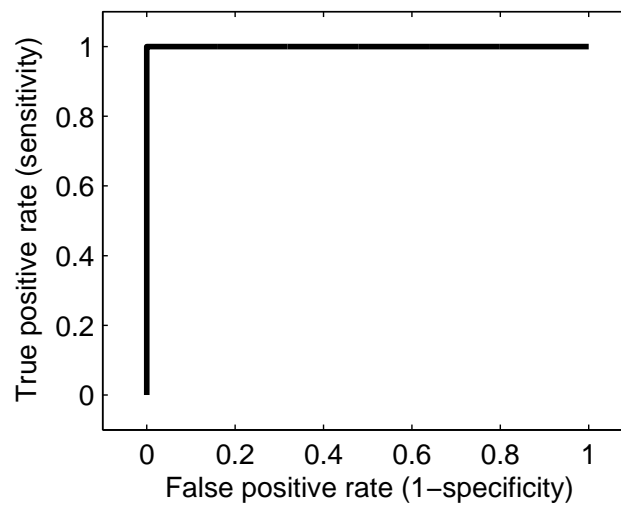
SH3 domain protein interaction network in *S. cerevisiae*; from Tong et al. (2002)

No regularisation

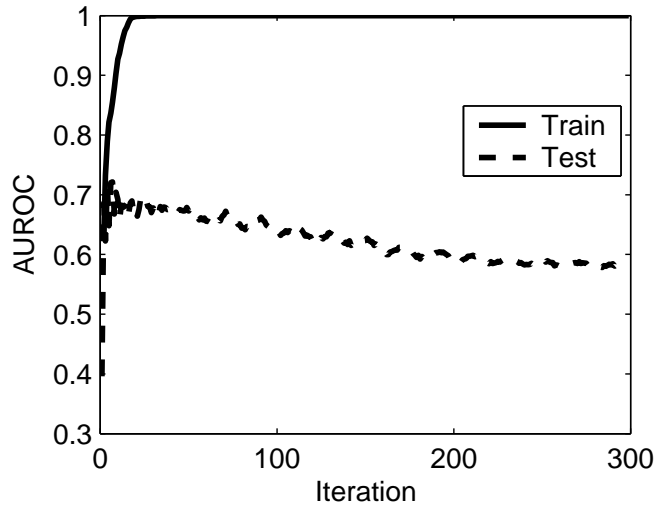
Test ROC curve AU 0.57562



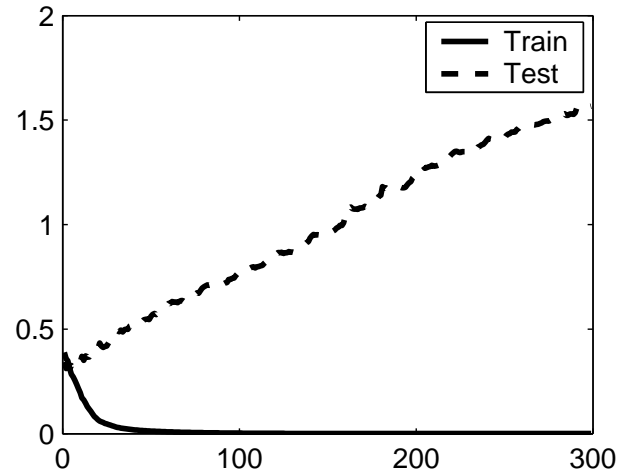
Train ROC curve AU 1



AUROC changes

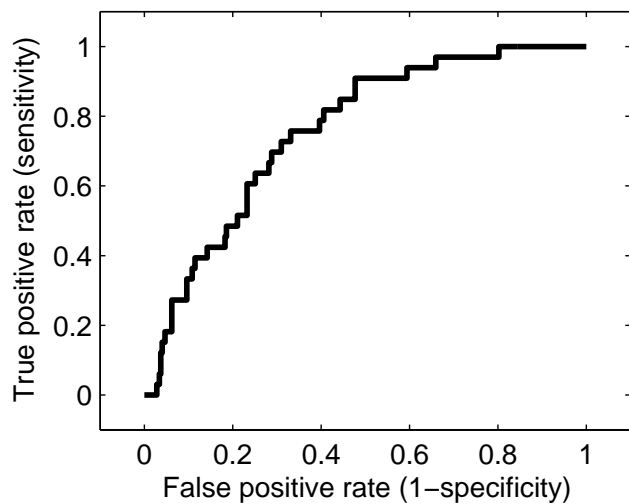


Train & test cross entropy

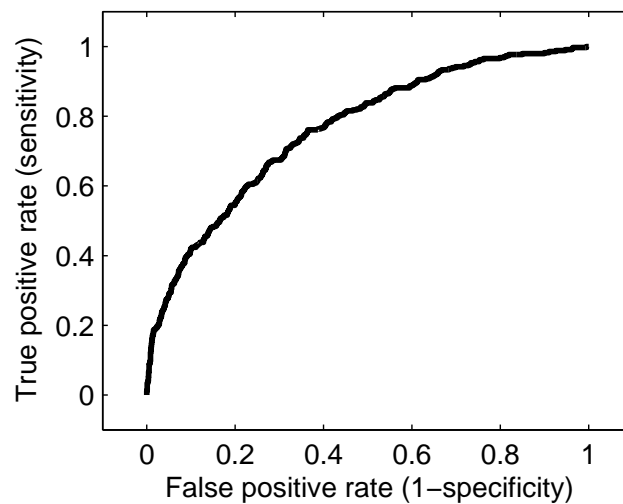


With regularisation

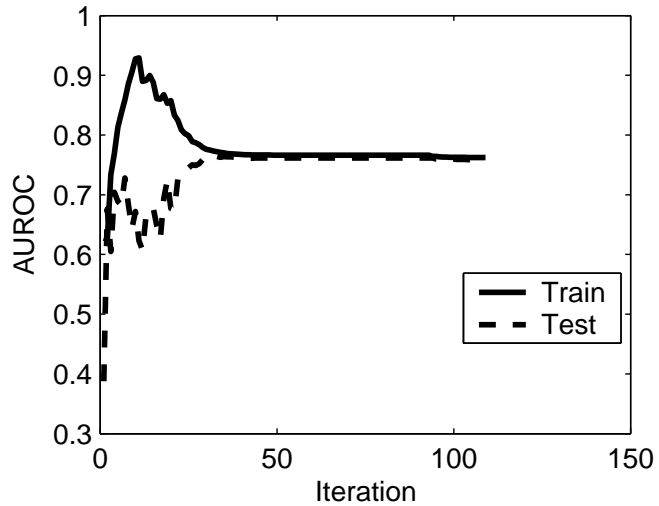
Test ROC curve AU 0.75889



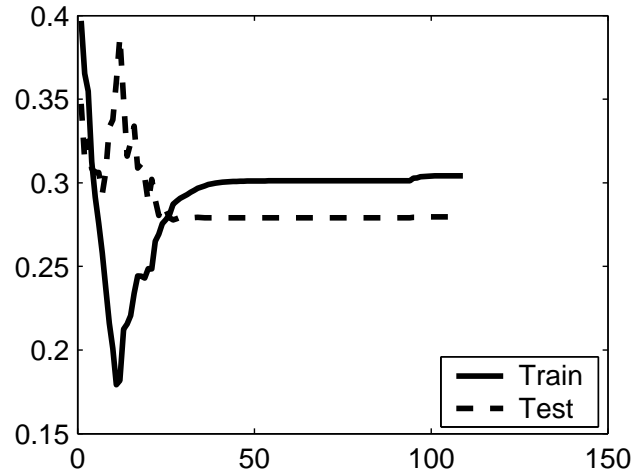
Train ROC curve AU 0.76237



AUROC changes



Train & test cross entropy



N-fold crossvalidation

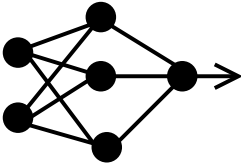
Training set

Monitoring set



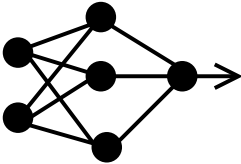
Training set

Monitoring set



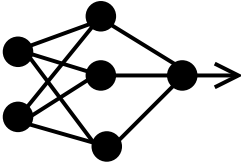
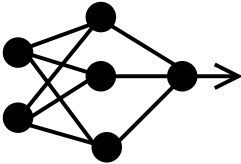
Training set

Monitoring set



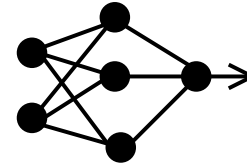
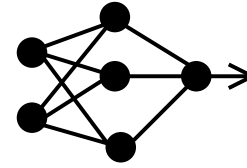
Training set

Monitoring set

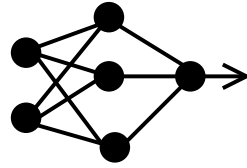


Training set

Monitoring set



⋮



Tong et al. (2002), Science 295, 321-324.

SH3 domain proteins in *Saccharomyces cerevisiae*.

Yeast two-hybrid interaction network

285 interactions between 28 SH3 proteins
and 143 binding peptides

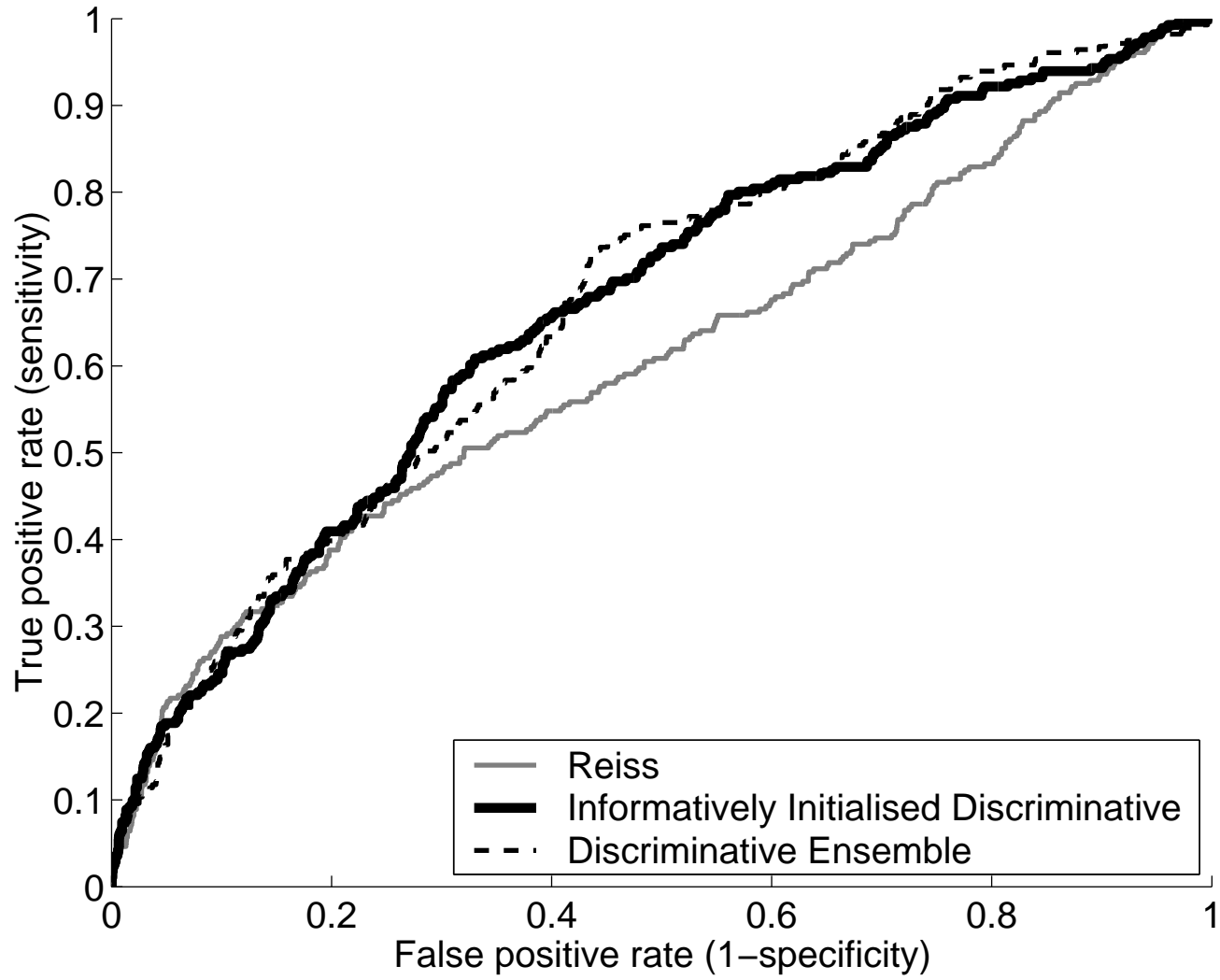
Phage display interaction network

394 interactions between 28 SH3 proteins
and 178 binding peptides

Models compared in our study

-
- Generative model of Reiss
 - Discriminative model,
informative initialisation
 - Ensemble of discriminative models,
random initialisations
-

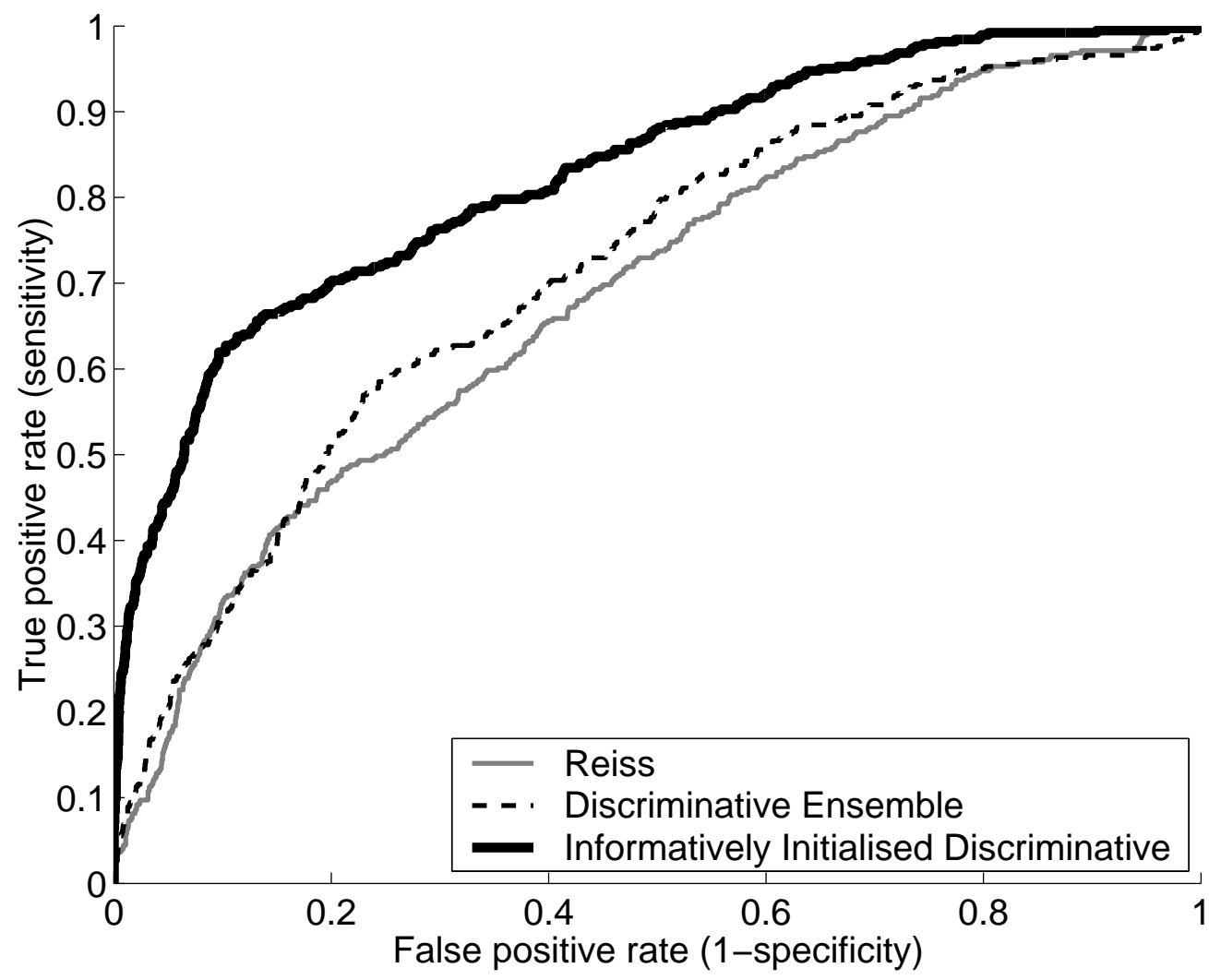
Yeast two-hybrid



AUROC scores

Model	→	Generative (Reiss et al.)	Discriminative, informative init	Discriminative, ensemble
Yeast	AUROC	0.61	0.67	0.67

Phage display



AUROC scores

Model	→	Generative (Reiss et al.)	Discriminative, informative init	Discriminative, ensemble
Yeast	AUROC	0.61	0.67	0.67
Phage	AUROC	0.69	0.83	0.71

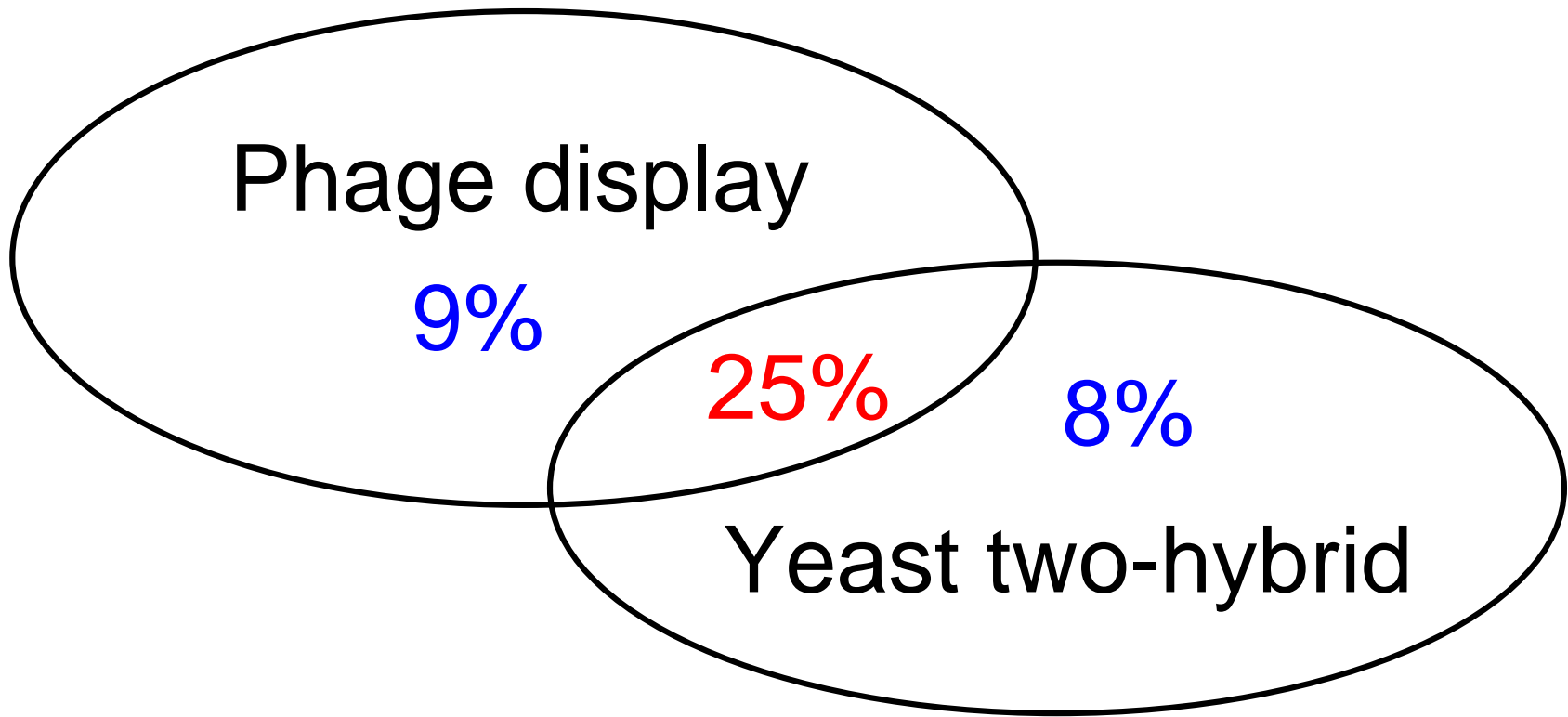
Biological validation

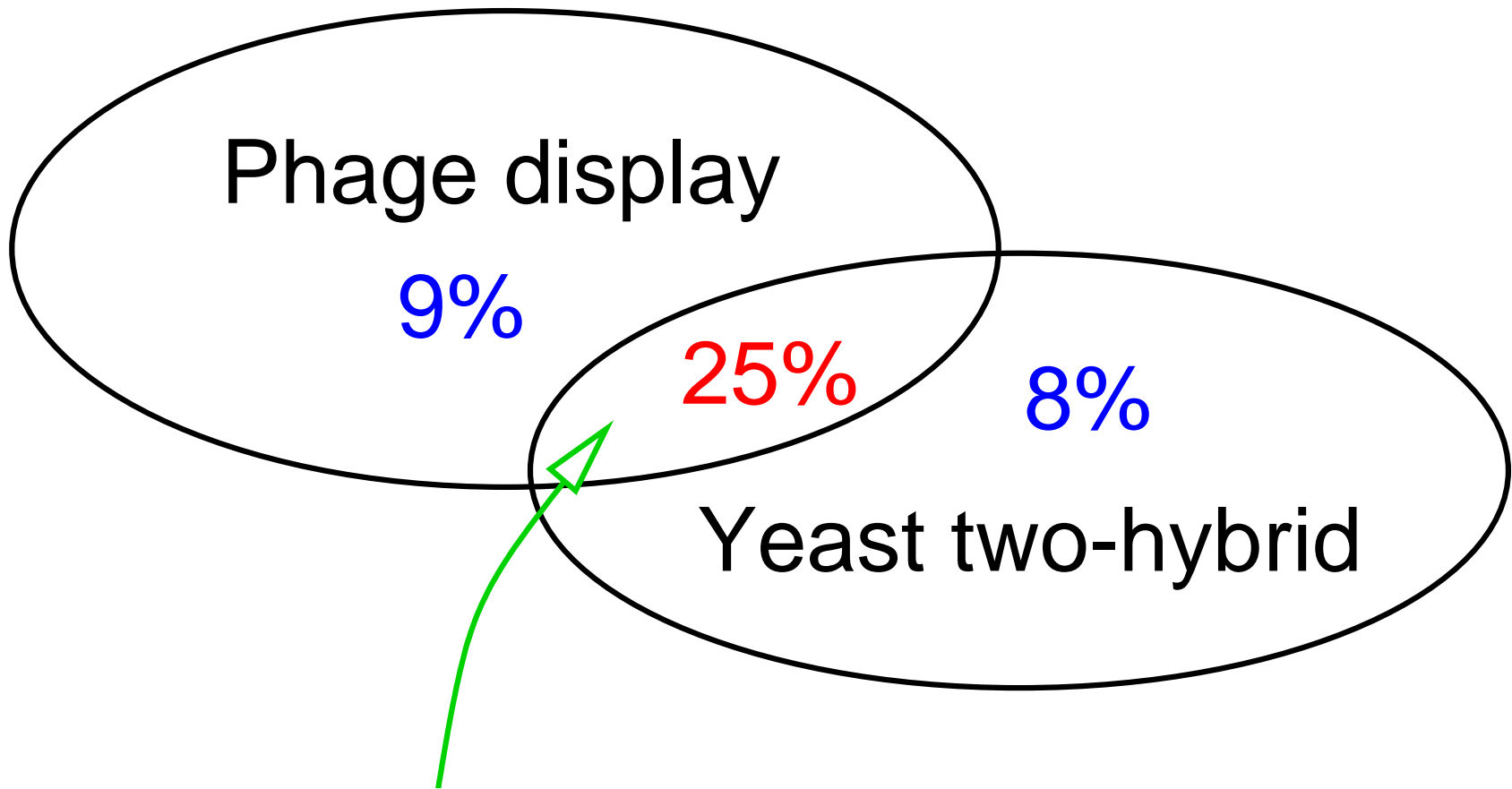
400 highest scoring interactions

Phage display

The diagram consists of two overlapping ovals. The left oval is labeled 'Phage display' and the right oval is labeled 'Yeast two-hybrid'. The two ovals overlap in the center, representing the intersection of the two methods.

Yeast two-hybrid





Enrichment for higher in silico scores,
filter for noisy high-throughput data.

Summary

- High-throughput interactomic data are noisy
→ Complement data with *in silico* predictions.
- Generative probabilistic model of Reiss & Schwikowski (2004): Several user-defined tuning parameters
- Discriminative probabilistic model of Segal et al. (2003):
Overfitting
- Regularisation with Laplacian prior (Williams 1995).