

Advances in Programming Languages

APL10: State Transformers

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Some Types in Haskell

This is the last of four lectures about some features of types and typing in Haskell types, specifically:

- Type classes
- Multiparameter type classes, constructor classes,
- Monads and interaction with the outside world
- Encapsulating stateful computation

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This is the last of four lectures about some features of types and typing in Haskell types, specifically:

- Type classes
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- Monads and interaction with the outside world
- Encapsulating stateful computation

In this lecture we shall see two applications of monads, one a refinement of the other.

- The `State` monad from the `Control.Monad.State` library.
This makes it possible to describe sequential stateful computation within a lazy functional language.
- The `ST` and its `runST` operation from `Control.Monad.ST`
This allows more general stateful computation, allocating and updating storage, with efficient in-place implementation; but encapsulated so that it becomes indistinguishable from purely functional code.

- 1 The State monad
- 2 Encapsulating imperative computation
- 3 Close

There's a place for state

Purely functional languages are able to express many algorithms in concise and modular fashion.

However, there remain some cases where known efficient (and convenient) algorithms rely on *mutable state* of some kind:

- Memoization, incrementally-modified hash tables;
- Union/find;
- Graph traversal and manipulation.

For these, we would like some way to:

- Naturally express the imperative algorithm in Haskell;
- Wrap it up so it can be combined with other, purely functional, components.

The State monad

```
module Control.Monad.State
```

```
newtype State s a = State { runState :: (s -> (a, s)) }
```

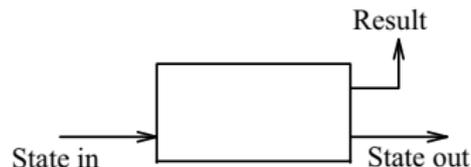
A value of type “`State s a`” represents a computation which manipulates a state component of type “`s`” to return a result of type “`a`”.

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A stateful computation taking inputs and returning results would have a type like “`Bool -> String -> State s (Int,Int)`”.

Monad operations

```
module Control.Monad.State
```

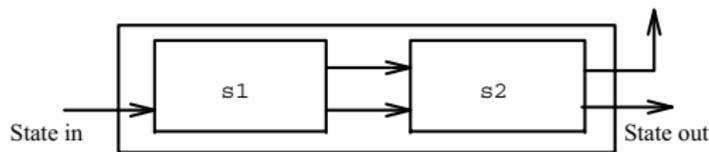
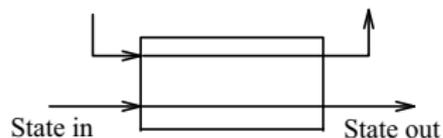
```
newtype State s a = State { runState :: (s -> (a, s)) }
```

```
instance Monad (State s a) where
```

```
return :: a -> State s a
```

```
(>>=) :: State s a -> (a -> State s b) -> State s b
```

The monad “`return`” simply gives back the value, leaving the state unchanged; and “`(>>=)`” sequences two stateful computations, passing the output state and result of the first as input to the second.



```
module Control.Monad.State
```

```
newtype State s a = State { runState :: (s -> (a, s)) }
```

```
get :: State s s           -- Fetch contents of state
```

```
put :: s -> State s ()    -- Update contents
```

```
modify :: (s -> s) -> State s () -- Modify contents
```

```
evalState :: State s a -> s -> a -- Run to result
```

```
execState :: State s a -> s -> s -- Run to final state
```

Example

```
import Control.Monad.State
```

```
data Tree a = Leaf a | Node (Tree a) (Tree a) deriving (Show, Eq)
```

```
number :: Tree a -> Tree Int           -- Number the leaves of  
number t = evalState (walk t) 0       -- a tree from left to right
```

```
walk :: Tree a -> State Int (Tree Int) -- Number using state
```

```
walk (Leaf _) = do i <- get  
                  put (i+1)  
                  return (Leaf i)
```

```
walk (Node l r) = do l' <- walk l  
                    r' <- walk r  
                    return (Node l' r')
```

Outline

- 1 The State monad
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- 3 Close



J. Launchbury and S. L. Peyton Jones.

Lazy functional state threads.

In *Proceedings of the 1994 ACM SIGPLAN Conference on Programming Language Design and Implementation*, SIGPLAN Notices, 29(6), pages 24–35. ACM Press, June 1994.

The “**State**” monad makes it possible to write stateful computations in an imperative style, but does not enforce this: code might duplicate or reset the state.

This paper showed how to build a richer “**ST**” (state transformer) monad which supports more operations, while guaranteeing that the state is single-threaded, allowing for general imperative algorithms *and* efficient implementation.

The ST monad is a State monad

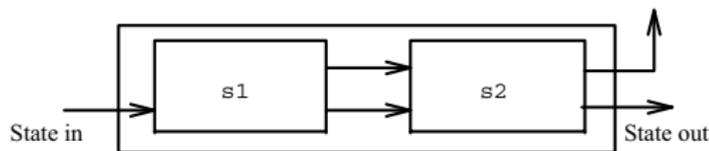
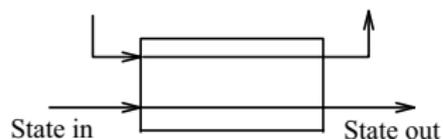
```
module Control.Monad.ST
```

```
data ST s a
```

```
instance Monad (ST s a) where
```

```
return :: a -> State s a
```

```
(>>=) :: State s a -> (a -> State s b) -> State s b
```



Mutable variables in the ST monad

```
module Control.Monad.ST
```

```
data ST s a
```

```
newVar :: a -> ST s (MutVar s a)
```

```
readVar :: MutVar s a -> ST s a
```

```
writeVar :: MutVar s a -> a -> ST s ()
```

A value of type “**MutVar s a**” is a reference to a mutable variable, storing type “**a**” in a state of type “**s**”.

Operation “**newVar**” creates and initialises a fresh variable, “**readVar**” reports its current value, and “**writeVar**” updates it.

Any state thread can create any number of “**MutVar**” variables.

Example with mutable variables

```
import Control.Monad.ST
```

```
swapVar :: MutVar s a -> MutVar s a -> ST s ()
```

```
swapVar p q = do x <- readVar p  
                 y <- readVar q  
                 writeVar p y  
                 writeVar q x  
                 return ()
```

Here “`swapVar`” will take two variables return the computation that exchanges their contents.

Notice that the variables must share the same state type “`s`”.

Running a state transformer

```
module Control.Monad.ST
```

```
runST :: ST s a -> a  -- Can we do this?
```

We might try to write an operation that creates a fresh state of type “s”, and then runs a computation within that. But there is a problem.

Running a state transformer

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We might try to write an operation that creates a fresh state of type “s”, and then runs a computation within that. But there is a problem.

```
let v = runST (newVar True) -- Create a fresh variable here ...
```

```
in
```

```
runST (readVar v)          -- ... best not to try and read it here
```

A better type for runST

```
module Control.Monad.ST
```

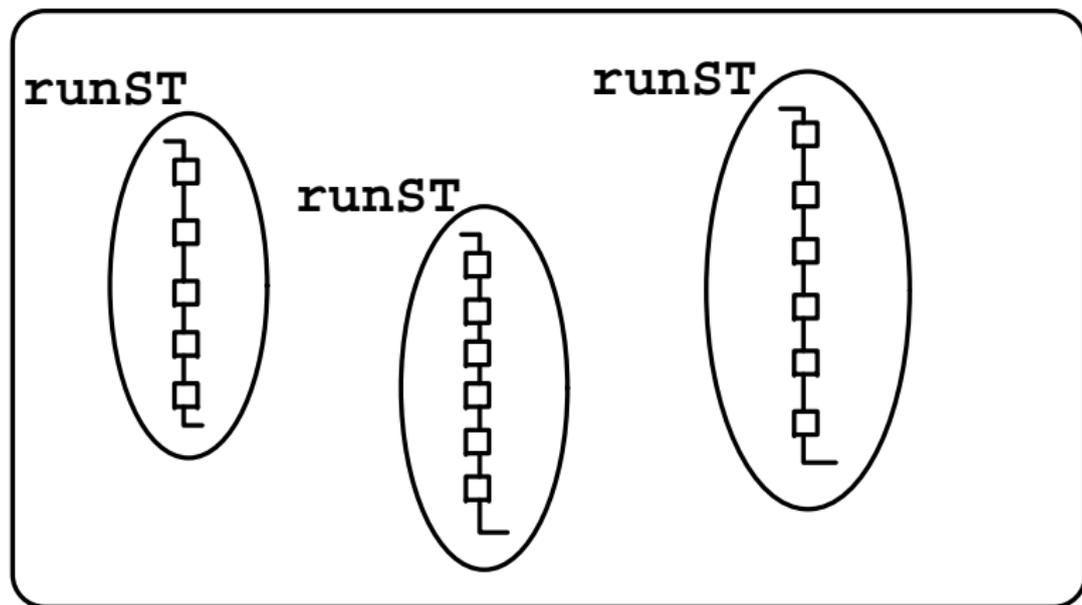
```
runST :: (forall s. ST s a) -> a  -- Rank 2 polymorphism
```

The solution is to require that “runST” is only ever applied to computations that are polymorphic in the state type — they don’t require any specific structure in the state, or export it.

An ST-computation can create fresh variables, read and write them, but everything must stay local.

Higher rank polymorphism is an extension to regular Haskell: types like this can be checked, but in general not inferred.

Isolated state threads



Arrays in ST

data MutArray s i e

newArr :: $\lambda x\ i \Rightarrow (i,i) \rightarrow e \rightarrow \text{ST } s\ (\text{MutArray } s\ i\ e)$

readArr :: $\lambda x\ i \Rightarrow \text{MutArray } s\ i\ e \rightarrow i \rightarrow \text{ST } s\ e$

writeArr :: $\lambda x\ i \Rightarrow \text{MutArray } s\ i\ e \rightarrow i \rightarrow e \rightarrow \text{ST } s\ ()$

freezeArr :: $\lambda x\ i \Rightarrow \text{MutArray } s\ i\ e \rightarrow \text{ST } s\ (\text{Array } i\ e)$

Mutable variables and imperative arrays are enough to implement classic imperative algorithms, both simple and complex.

Externally, code that uses “`ST s a`” and “`runST`” can be used exactly as it was purely functional, and the polymorphic typing requirements of “`runST`” ensure that its state will neither escape nor be disrupted by other code.

Arrays in ST

data MutArray s i e

newArr :: !x i => (i,i) -> e -> ST s (MutArray s i e)

readArr :: !x i => MutArray s i e -> i -> ST s e

writeArr :: !x i => MutArray s i e -> i -> e -> ST s ()

freezeArr :: !x i => MutArray s i e -> ST s (Array i e)

Because type “`ST s a`” is only accessible through these effects, it is certain that the state component “`s`” will be single-threaded: which allows for efficient implementation and in-place update.

What is more, this can be handled entirely by standard compiler rewriting optimisations: passing a single token around will ensure data dependencies are respected; yet the actual variables and arrays can be allocated in memory and updated in place. We even get lazy evaluation of these state threads.

IO is ST

data RealWorld *— No constructors, entirely abstract*

type IO a = ST RealWorld a *— IO computations act on the real world*

This is exactly how the “IO” monad is implemented: with an entirely abstract state type, whose concrete realisation is the external world.

Because “IO a” specifies a specific state type “RealWorld”, there is no possibility of applying “runST”, whose argument must be state-independent.

This is good, because Haskell has no operation to create or destroy the “RealWorld” at will. Instead, the whole program has type “IO a”, and it is run in the actual “RealWorld”.

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Summary

In this lecture we saw two applications of monads, one a refinement of the other.

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- The `ST` and its `runST` operation from `Control.Monad.ST`
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Homework

Read the following paper, describing `runST`, its applications and implementation.



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Lazy functional state threads.

In Proceedings of the 1994 ACM SIGPLAN Conference on Programming Language Design and Implementation, SIGPLAN Notices, 29(6), pages 24–35. ACM Press, June 1994.

Also available in a longer version, with additional examples:



J. Launchbury and S. L. Peyton Jones.

State in Haskell.

LISP and Symbolic Computation, 8(4):293–342, December 1995.