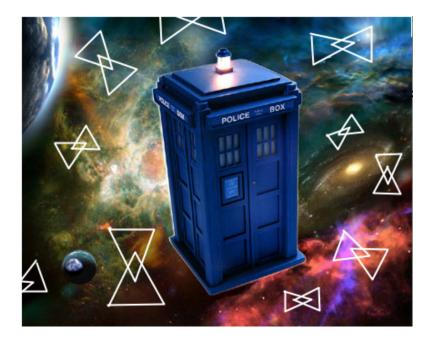
Rigorous and Random Adventures in Time and Space

Jane Hillston

21st November 2012





- Performance Modelling
- Stochastic Process Algebra

2 Tackling State Space Explosion

- Lumpability and Bisimulation
- Fluid approximation

3 Further Adventures in Space

- Spatial Challenge: Capturing logical space
- Spatial Challenge: Capturing physical space

4 Conclusions

5 Hamming

Outline

1 Introduction

- Performance Modelling
- Stochastic Process Algebra

2 Tackling State Space Explosion

Lumpability and Bisimulation

Fluid approximation

3 Further Adventures in Space

- Spatial Challenge: Capturing logical space
- Spatial Challenge: Capturing physical space

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5 Hamming

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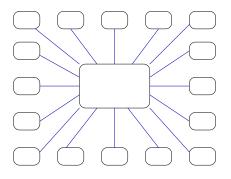
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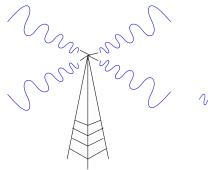


Capacity planning

How many clients can the existing server support and maintain reasonable response times?

Performance Modelling

Performance Modelling: Motivation

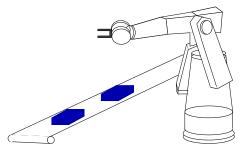


System Configuration

How many frequencies do you need to keep blocking probabilities low?

Mobile Telephone Antenna

Performance Modelling: Motivation



System Tuning

What speed of conveyor belt will minimize robot idle time and maximize throughput whilst avoiding lost widgets?

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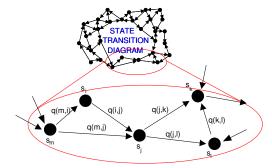
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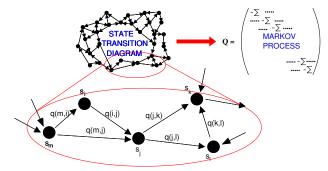
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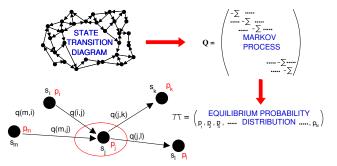




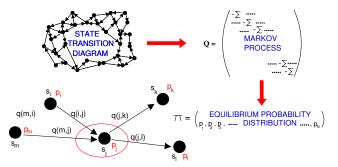
A negative exponentially distributed duration is associated with each transition.



these parameters form the entries of the infinitesimal generator matrix Q

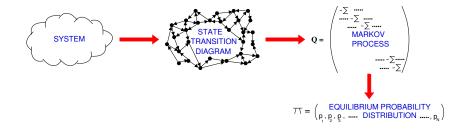


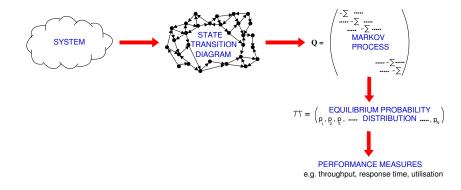
In steady state the probability flux out of a state is balanced by the flux in.



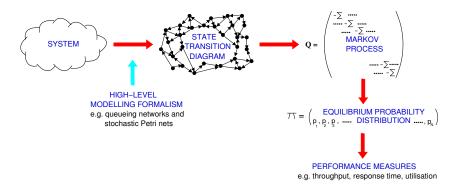
"Global balance equations" captured by $\pi Q = 0$ solved by linear algebra

Performance Modelling using CTMC





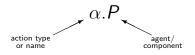
Performance Modelling using CTMC



High-level modelling languages are used to automatically generate the state transition diagram/infinitesimal generator matrix \mathbf{Q} , lifting the description to a level closer to the system behaviour.



Models consist of agents which engage in actions.



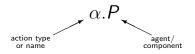
The structured operational (interleaving) semantics of the language is used to generate a labelled transition system.

Process algebra model

rules Labelled transition system



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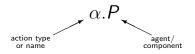


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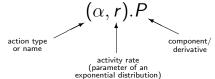


Stochastic process algebras

Process algebras where models are decorated with quantitative information used to generate a stochastic process are stochastic process algebras (SPA).

Stochastic Process Algebra

Models are constructed from components which engage in activities.

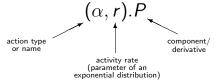


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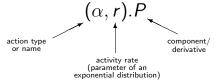


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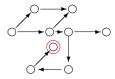


Qualitative verification can now be complemented by quantitative verification.

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Reachability analysis

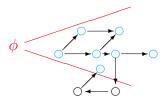
How long will it take for the system to arrive in a particular state?



Qualitative verification can now be complemented by quantitative verification.

Model checking

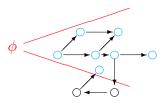
Does a given property ϕ hold within the system with a given probability?



Qualitative verification can now be complemented by quantitative verification.

Model checking

For a given starting state how long is it until a given property ϕ holds?



Performance Evaluation Process Algebra (PEPA)

$$\begin{array}{ll} (\alpha, f).P & \text{Prefix} \\ P_1 + P_2 & \text{Choice} \\ P_1 \Join P_2 & \text{Co-operation} \\ P/L & \text{Hiding} \\ X & \text{Variable} \end{array}$$

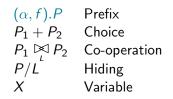
 $P_1 \parallel P_2$ is a derived form for $P_1 \bowtie P_2$.

When working with large numbers of entities, we write P[n] to denote an array of n copies of P executing in parallel.

 $P[5] \equiv (P \parallel P \parallel P \parallel P \parallel P)$

Stochastic Process Algebra

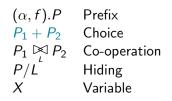
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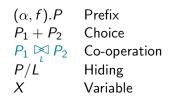
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A simple example: processors and resources

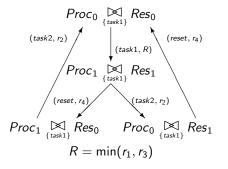
$$\begin{array}{lll} \textit{Proc}_{0} & \stackrel{\textit{def}}{=} & (\textit{task1}, \textit{r}_{1}).\textit{Proc}_{1} \\ \textit{Proc}_{1} & \stackrel{\textit{def}}{=} & (\textit{task2}, \textit{r}_{2}).\textit{Proc}_{0} \\ \textit{Res}_{0} & \stackrel{\textit{def}}{=} & (\textit{task1}, \textit{r}_{3}).\textit{Res}_{1} \\ \textit{Res}_{1} & \stackrel{\textit{def}}{=} & (\textit{reset}, \textit{r}_{4}).\textit{Res}_{0} \end{array}$$

 $Proc_0 \bigotimes_{\substack{\{task1\}}} Res_0$



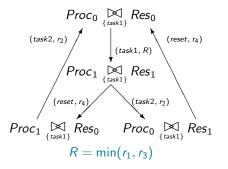
$$\mathbf{Q} = \begin{pmatrix} -R & R & 0 & 0 \\ 0 & -(r_2 + r_4) & r_4 & r_2 \\ r_2 & 0 & -r_2 & 0 \\ r_4 & 0 & 0 & -r_4 \end{pmatrix}$$

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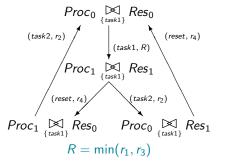
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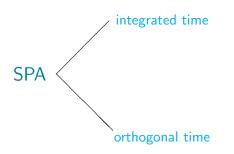
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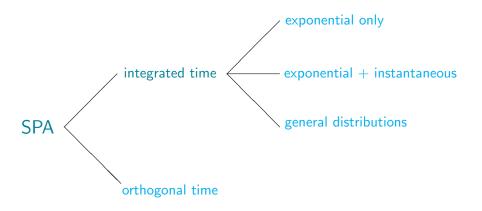
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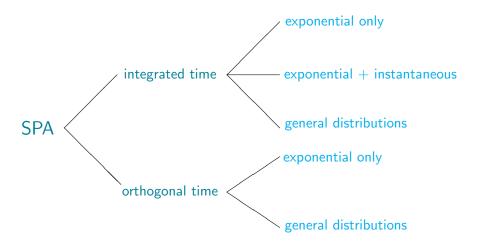


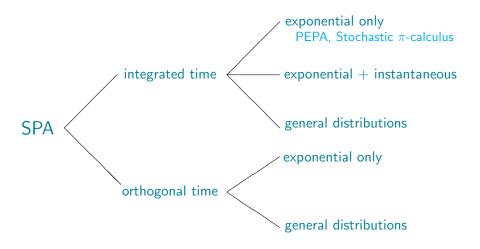
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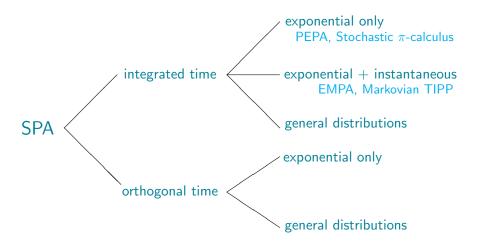
SPA

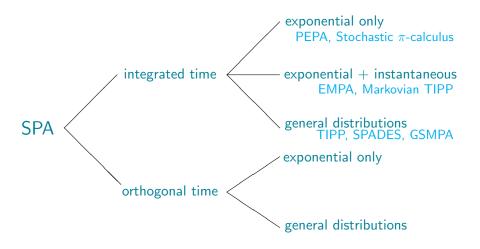


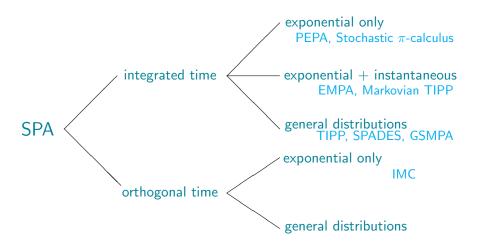


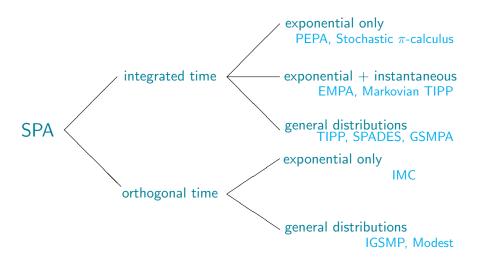












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What has been the impact?

The interplay between performance modelling/quantitative modelling and formal methods has stimulated a lot of exciting work.

Major conferences in the field now regularly include probabilistic and stochastic model checking, stochastic logics, bisimulations and other equivalence relations.

Most benefit is gained when properties of models can be established in terms of the model language and its semantics, allowing techniques to be applied without recourse to having to prove applicability on a model-by-model basis.

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Benefits of process algebra

For example,

- The correspondence between the congruence, Markovian bisimulation, in the process algebra and the lumpability condition in the CTMC, allows exact model reduction to be carried out compositionally.
- Characterisation of product form structure at the process algebra level allows decomposed model solution based on the process algebra structure of the model.
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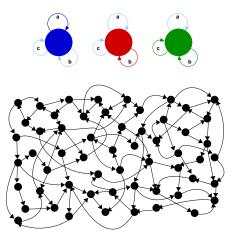
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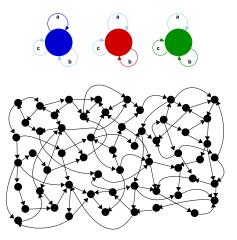
3 Further Adventures in Space

- Spatial Challenge: Capturing logical space
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Under the SOS semantics a SPA model is mapped to a CTMC with global states determined by the local states of all the participating components.



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When the size of the state space is not too large they are amenable to numerical solution (linear algebra) to determine a steady state or transient probability distribution.



	$q_{1,1}$	$q_{1,2}$	$q_{1,N}$	
Q =	$q_{2,1}$	$q_{2,2}$	$q_{2,N}$	
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 $\pi(t) = (\pi_1(t), \pi_2(t), \ldots, \pi_N(t))$

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	÷	÷		÷	
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Solving discrete state models

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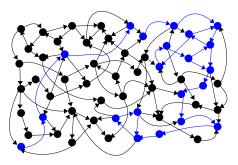


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Solving discrete state models

Alternatively they may be studied using stochastic simulation. Each run generates a single trajectory through the state space. Many runs are needed in order to obtain average behaviours.



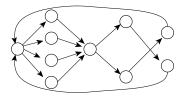
State space explosion

As the size of the state space becomes large it becomes infeasible to carry out numerical solution and extremely time-consuming to conduct stochastic simulation.

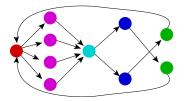
- Model aggregation: use a state-state equivalence to establish a partition of the state space of a model, and replace each set of states by one macro-state
- This is not as straightforward as it may seem if we wish the aggregated process to still be a Markov process — an arbitrary partition will not in general preserve the Markov property.
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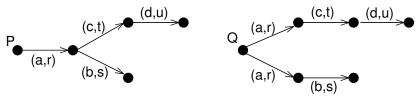


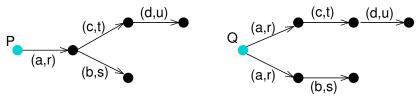
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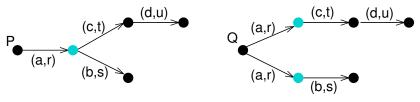
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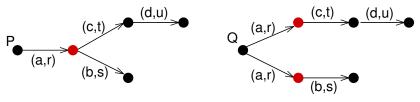
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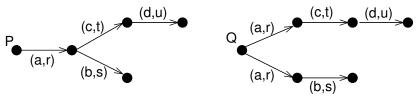






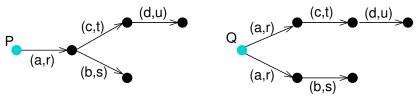


Strong equivalence in PEPA is a bisimulation in the style of Larsen of Skou.



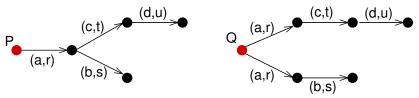
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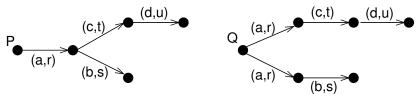
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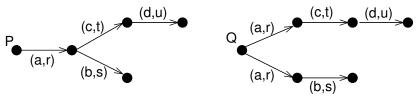
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Expressed as rates to equivalence classes of processes.

Strong Equivalence and Lumpability

- We can establish that if we consider strong equivalence of states within a single model, it induces a lumpable partition on the state space of the underlying Markov chain.
- Moreover it can be shown that strong equivalence is a congruence.
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$$r = \frac{r_{1}}{3r_{1}} \frac{r_{2}}{2r_{3}} \min(3r_{1}, 2r_{3}) = \frac{1}{6} \min(3r_{1}, 2r_{3}) \qquad (P_{1} \parallel P_{0} \parallel P_{0}) \bigotimes_{\{\text{task}I\}} (R_{1} \parallel R_{0})$$

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Counting abstraction to generate the Lumped CTMC

$$(P_{1} || P_{0} || P_{0}) \bigotimes_{\{task1\}} R_{1} || R_{0})$$

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$$(3,0,2,0) \xrightarrow{\min(3r_{1},2r_{3})} (2,1,1,1)$$

$$(P_{1} \parallel P_{0} \parallel P_{0}) \underset{\{zask1\}}{\boxtimes} (R_{1} \parallel R_{0})$$

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Aggregation is not enough!

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Large scale software systems

Issues of scalability are important for user satisfaction and resource efficiency but such issues are difficult to investigate using discrete state models.

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Biochemical signalling pathways

Understanding these pathways has the potential to improve the quality of life through enhanced drug treatment and better drug design.

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Epidemiological systems

Improved modelling of these systems could lead to improved disease prevention and treatment in nature and better security in computer systems.

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This is particularly a problem for population models — systems where we are interested in interacting populations of entities:

Crowd dynamics

Technology enhancement is creating new possibilities for directing crowd movements in buildings and urban spaces, for example for emergency egress, which are not yet well-understood.

Process algebras are well-suited to constructing such models:

- Developed to represent concurrent behaviour compositionally;
- Represent the interactions between individuals explicitly;
- Stochastic extensions allow the dynamics of system behaviour to be captured;
- Incorporate formal apparatus for reasoning about the behaviour of systems.

But solution techniques which rely on explicitly building the state space, such as numerical solution, are hampered by space complexity...

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A shift in perspective allows us to model the interactions between individual components but then only consider the system as a whole as an interaction of populations.

This allows us to model much larger systems than previously possible but in making the shift we are no longer able to collect any information about individuals in the system.

To characterise the behaviour of a population we count the number of individuals within the population that are exhibiting certain behaviours rather than tracking individuals directly.

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Use continuous state variables to approximate the discrete state space.

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Use continuous state variables to approximate the discrete state space.

Use ordinary differential equations to represent the evolution of those variables over time.

Use a counting abstraction rather than the CTMC complete state space.

- 2 Assume that these state variables are subject to continuous rather than discrete change.
- 3 No longer aim to calculate the probability distribution over the entire state space of the model.
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Appropriate for models in which there are large numbers of components of the same type, i.e. models of populations and situations of collective dynamics.

In the PEPA language multiple instances of components are represented explicitly — we write P[n] to denote an array of n copies of P executing in parallel.

$P[5] \equiv (P \parallel P \parallel P \parallel P \parallel P)$

- The impact of an action of a counting variable is
 - decrease by 1 if the component participates in the action
 increase by 1 if the component is the result of the action
 zero if the component is not involved in the action

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Models suitable for counting abstraction

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$$\begin{array}{lll} \textit{Proc}_{0} & \stackrel{\text{def}}{=} & (\textit{task1}, \textit{r}_{1}).\textit{Proc}_{1} \\ \textit{Proc}_{1} & \stackrel{\text{def}}{=} & (\textit{task2}, \textit{r}_{2}).\textit{Proc}_{0} \\ \textit{Res}_{0} & \stackrel{\text{def}}{=} & (\textit{task1}, \textit{r}_{3}).\textit{Res}_{1} \\ \textit{Res}_{1} & \stackrel{\text{def}}{=} & (\textit{reset}, \textit{r}_{4}).\textit{Res}_{0} \end{array}$$

 $Proc_0[N_P] \bigotimes_{_{\{task1\}}} Res_0[N_R]$

$$Proc_0 \stackrel{\text{def}}{=} (task1, r_1).Proc_1$$

 $Proc_1 \stackrel{def}{=} (task2, r_2).Proc_0$

- $Res_0 \stackrel{\text{def}}{=} (task1, r_3).Res_1$
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 $Proc_0[N_P] \bigotimes_{_{\{task1\}}} Res_0[N_R]$

- *task*1 decreases *Proc*₀ and *Res*₀
- *task*1 increases *Proc*₁ and *Res*₁
- task2 decreases Proc1
- task2 increases Proc₀
- reset decreases Res₁
- reset increases Res₀

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$$\frac{dx_1}{dt} = -\min(r_1 x_1, r_3 x_3) + r_2 x_2 x_1 = \text{no. of } Proc_1$$

- *task*1 decreases *Proc*₀
- *task*1 is performed by *Proc*₀ and *Res*₀
- task2 increases Proc₀
- task2 is performed by Proc1

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$$Proc_0[N_P] \bigotimes_{\{task1\}} Res_0[N_R]$$

ODE interpretation

$$\frac{dx_1}{dt} = -\min(r_1 x_1, r_3 x_3) + r_2 x_2 x_1 = \text{no. of } Proc_1 \frac{dx_2}{dt} = \min(r_1 x_1, r_3 x_3) - r_2 x_2 x_2 = \text{no. of } Proc_2 \frac{dx_3}{dt} = -\min(r_1 x_1, r_3 x_3) + r_4 x_4 x_3 = \text{no. of } Res_0 \frac{dx_4}{dt} = \min(r_1 x_1, r_3 x_3) - r_4 x_4 x_4 = \text{no. of } Res_1$$

Scalable Differential Semantics

Whilst fluid approximation has been used for many years in large scale performance models, e.g. fluid queues as an abstraction of routers in communication networks, in general the validity of the abstraction and convergence result must be proved on a case-by-case basis.

In his recent thesis, Mirco Tribastone developed a novel operational semantics for PEPA which can be used to prove the convergence result for all suitably scaled PEPA models.

Moreover the set of ODEs are automatically derived from the semantics.

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Extraction of the ODE from f

Generator Function

$$\begin{array}{lll} f(\xi,(-1,1,-1,1),\textit{task1}) &=& \min(r_1\xi_1,r_3\xi_3) \\ f(\xi,(1,-1,0,0),\textit{task2}) &=& r_2\xi_2 \\ f(\xi,(0,0,1,-1),\textit{reset}) &=& r_4\xi_4 \end{array}$$

Differential Equation

$$\frac{dx}{dt} = F_{\mathcal{M}}(x) = \sum_{l \in \mathbb{Z}^d} l \sum_{\alpha \in \mathcal{A}} f(x, l, \alpha)$$
$$= (-1, 1, -1, 1) \min(r_1 x_1, r_3 x_3) + (1, -1, 0, 0) r_2 x_2$$
$$+ (0, 0, 1, -1) r_4 x_4$$

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Differential Equation

$$\frac{dx_1}{dt} = -\min(r_1x_1, r_3x_3) + r_2x_2$$

$$\frac{dx_2}{dt} = \min(r_1x_1, r_3x_3) - r_2x_2$$

$$\frac{dx_3}{dt} = -\min(r_1x_1, r_3x_3) + r_4x_4$$

$$\frac{dx_4}{dt} = \min(r_1x_1, r_3x_3) - r_4x_4$$

- The vector field *F*(*x*) is Lipschitz continuous i.e. all the rate functions governing transitions in the process algebra satisfy local continuity conditions.
- The generated ODEs are the fluid limit of the family of CTMCs generated by f(ξ, l, α): this family forms a sequence as the initial populations are scaled by a variable n.
- We can prove this using Kurtz's theorem: Solutions of Ordinary Differential Equations as Limits of Pure Jump Markov Processes, T.G. Kurtz, J. Appl. Prob. (1970).
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Mobile devices and mobile computation

The location of components of a software system can have dramatic effect on the performance, particularly as communication is often slow compared with computation. Thus capturing whether components are co-located or communicating over a distance became important.

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Biochemical signalling pathways

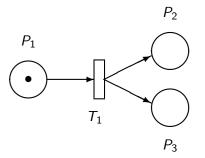
Far from being a well-mixed soup, the inside of a cell is highly structured and divided into distinct compartments. This physical organisation can have a strong impact on the dynamic behaviour.

Mobile computation: PEPA nets

- The PEPA nets formalism uses the stochastic process algebra PEPA as the inscription language for coloured Petri nets.
- The combination naturally represents applications with two classes of change of state (global and local).
- For example, in a mobile code system PEPA terms are used to model the program code which moves between network hosts (the places in the net).

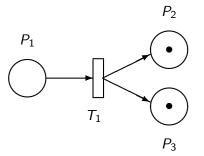
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- Petri nets provide a graphical presentation of a model which has an easily accessible interpretation and like process algebras they are supported by an unambiguous formal interpretation.
- Coloured Petri nets are a high-level form of classical Petri nets. The plain (indistinguishable) tokens of a classical Petri net are replaced by arbitrary terms which are distinguishable.
- In stochastic Petri nets the transitions from one marking to another are associated with a random variable drawn from an exponential distribution.
- PEPA nets are coloured stochastic Petri nets where the colours used as the tokens of the net are PEPA components.

- Firings in a PEPA net (at the Petri net level) model macro-step changes of state such as a mobile software agent moving from one network host to another.
- A token/PEPA component will move from one place/context to another.
- Firings have global effect because they involve components at more than one place in the net.
- A transition occurs whenever an action (individual or shared) of a PEPA component can occur.
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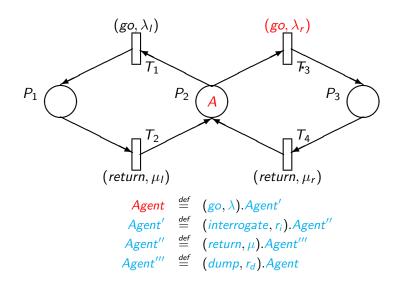
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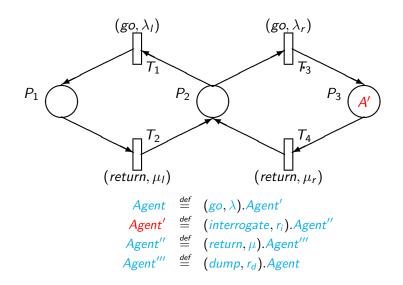
Example: a mobile agent system

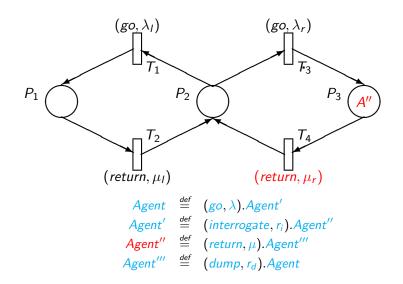
- A roving agent visits three sites. It interacts with static software components at these sites and has two kinds of interactions.
- When visiting a site where a network probe is present it interrogates the probe for the data which it has gathered on recent patterns of network traffic.
- When it returns to the central co-ordinating site it dumps the data which it has harvested to the master probe. The master probe performs a computationally expensive statistical analysis of the data.
- The structure of the system allows this computation to be overlapped with the agent's communication and data gathering.

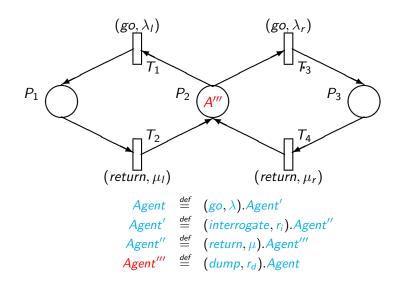
PEPA components

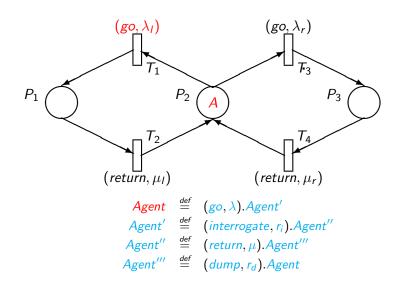
Agent Agent' Agent'' Agent'''	def def def def def def	(go, λ).Agent' (interrogate, r _i).Agent" (return, μ).Agent" (dump, r _d).Agent
Master Master'	def Ⅲ Ⅲ	(dump,⊤).Master′ (analyse, r _a).Master
Probe	def —	$(monitor, r_m)$.Probe + $(interrogate, \top)$.Probe



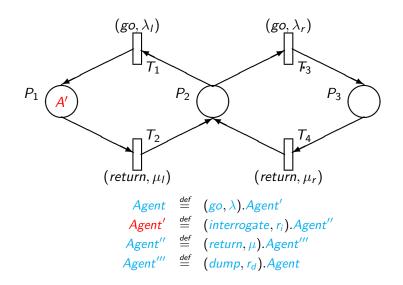




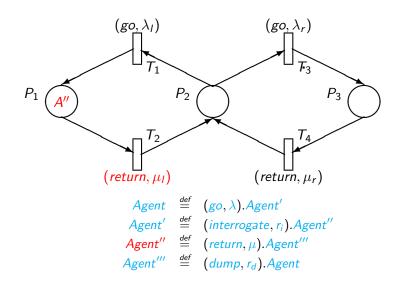




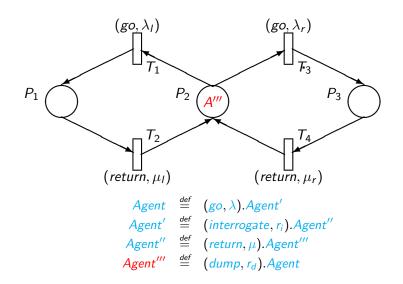
PEPA net example



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Bio-PEPA

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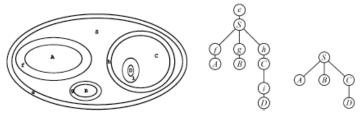
Modelling biological locations

Bio-PEPA considers locations which can be either compartments or membranes.

Reactions can then be considered to be

- internal to one compartment or membrane
- involving elements in one compartment and one membrane
- transport between compartments.

A location tree is used to represent the hierarchy of locations.



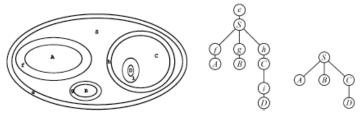
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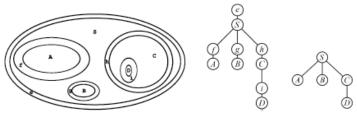
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Locations in Bio-PEPA

Components in Bio-PEPA are known as species, and in essence, a species in a different location is treated as a distinct species.

However to ease the representation of models, high-level syntax allows some compact representations e.g.

 $S \stackrel{\text{\tiny def}}{=} (\gamma[L_1 \to L_2], \kappa) \odot S$ for transport from location L_1 to location

 $S \stackrel{\text{\tiny def}}{=} (\alpha, \kappa) op S@L_1$ for reaction α at location L_1

Both PEPA Nets and Bio-PEPA allow logical locations to be captured within a process algebra model.

However, for analysis they currently rely on an expansion that treats each component, at each location, as distinct.

This exacerbates the problem of state space explosion and can limit the size of models that can be analysed.

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Moving on to physical space

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QUANTICOL Examples



The most expensive aspect of the Paris bike sharing system is relocating bikes to where they are needed.

In smart grids and sustainable energy production with limited storage capacity the location of production and demand become important.



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The hybrid process algebra HYPE captures both continuously varying values and discrete changes in behaviour.

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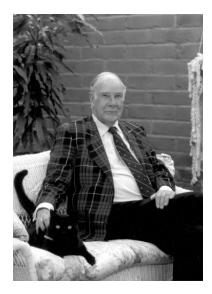
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Some thoughts about Hamming and his advice





• "Say to yourself, "Yes, I would like to do first-class work"."

- "One of the characteristics of successful scientists is having courage."
- "It's not the consequence that makes a problem important, it is that you have a reasonable attack."
- Don't let success make you feel you can only work on great problems.
- Look on the positive side and not on the negative side.
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He says "...most great scientists have tremendous drive", and sees it as an inevitable consequence that he sometimes neglected his wife.

Even more strongly, he says it is not sufficient to "dabble" which he interprets as "...work during the day and go home and do other things and come back and work the next day..."

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...but, reflecting on Hamming from an Athena perspective

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